Holm Forests

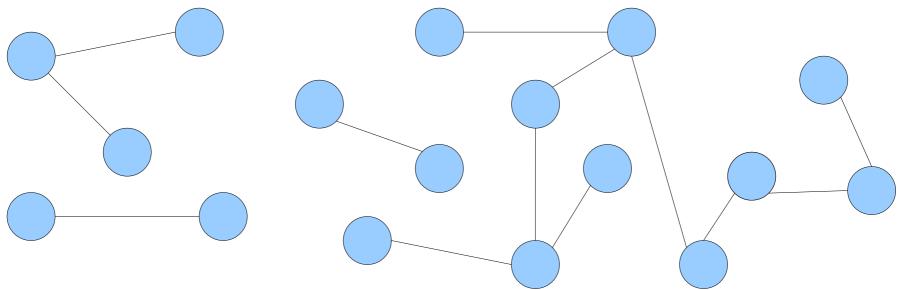
Outline for Today

- **Recap from Last Time**
 - Reviewing Euler tour trees and their augmentations.
- Why Fully Dynamic Connectivity is Hard
 - Seeing how this differs from the forest case.
- Localizing Edges
 - And bringing in some CS161 topics in clever ways.
- "Blame It On The Little Guy"
 - A very creative way to decrease runtime costs.
- The Holm Forest
 - A brilliant way to solve dynamic connectivity.

Recap from Last Time

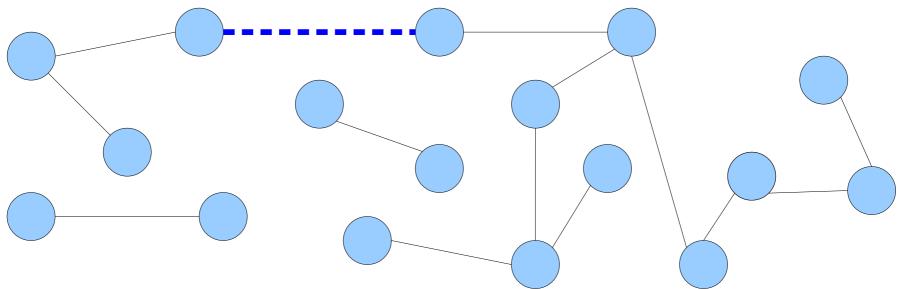
• Consider the following special-case of the dynamic connectivity problem:

Maintain an undirected **forest** F so that edges may be inserted an deleted and connectivity queries may be answered efficiently.



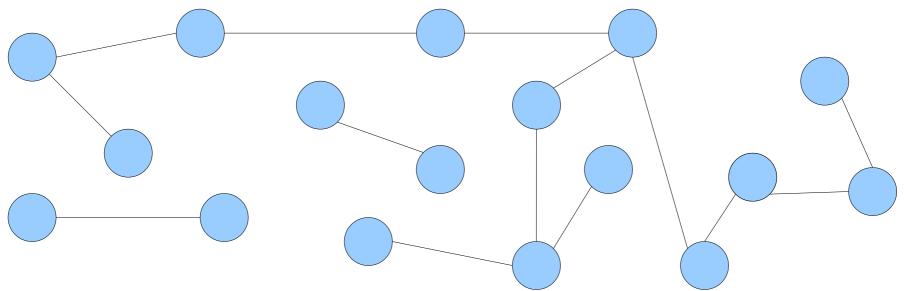
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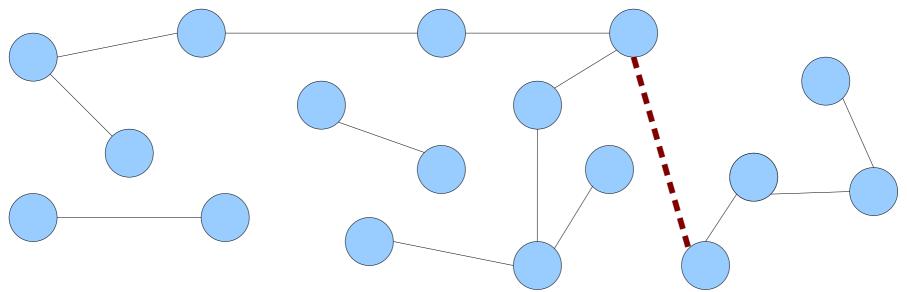
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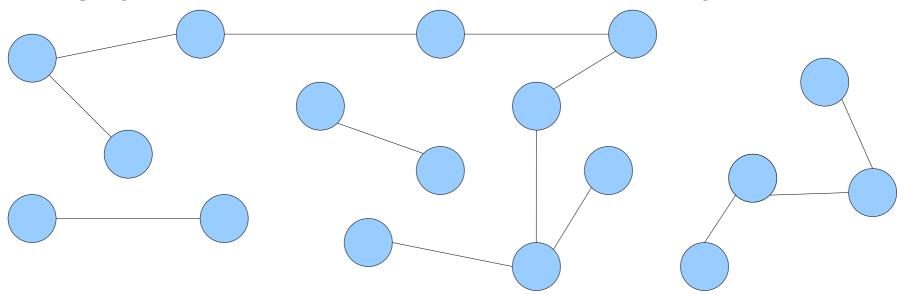
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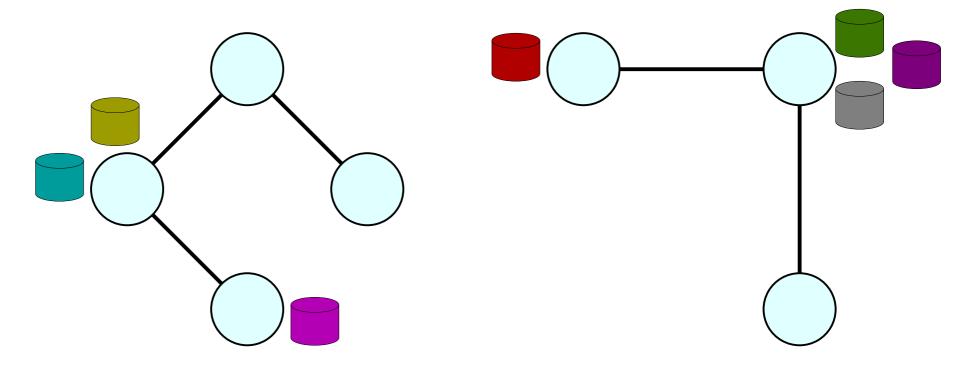
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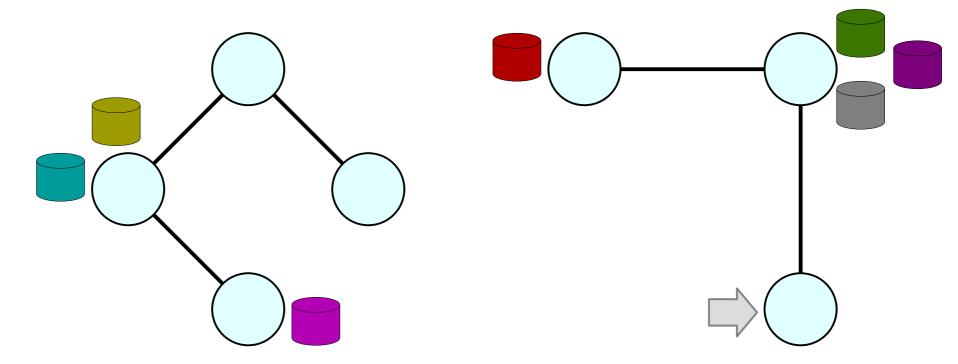
Euler Tour Trees

- The *Euler tour tree* data structure solves dynamic connectivity in forests with these (amortized) costs:
 - *are-connected*: O(log *n*)
 - *link*: O(log *n*)
 - *cut*: O(log *n*)
- These bounds can be made worst-case efficient using different types of balanced BSTs instead of splay trees.

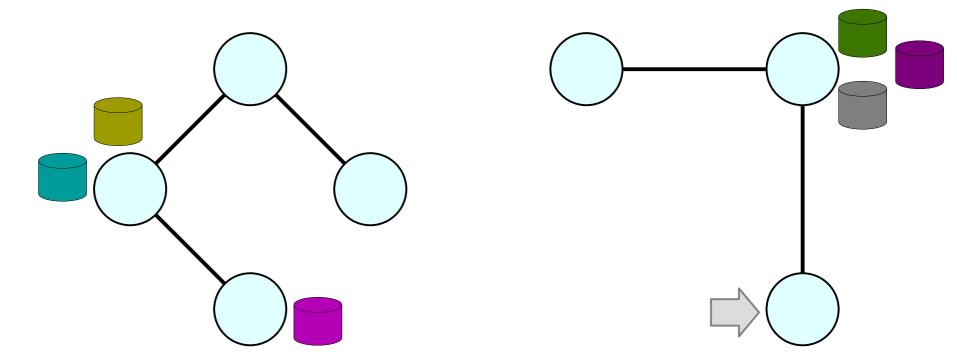
- Euler tour trees can be augmented to aggregate information about the trees in the forest. With the right augmentations, we can support the following operations in (amortized) $O(\log n)$ time each.
 - size(x), which returns the number of nodes in x's tree.
 - *add-packet*(*x*, *p*), which attaches packet *p* to node *x*; and
 - **remove-packet**(*x*), which removes and returns some packet reachable from *x*, chosen arbitrarily from all the options.



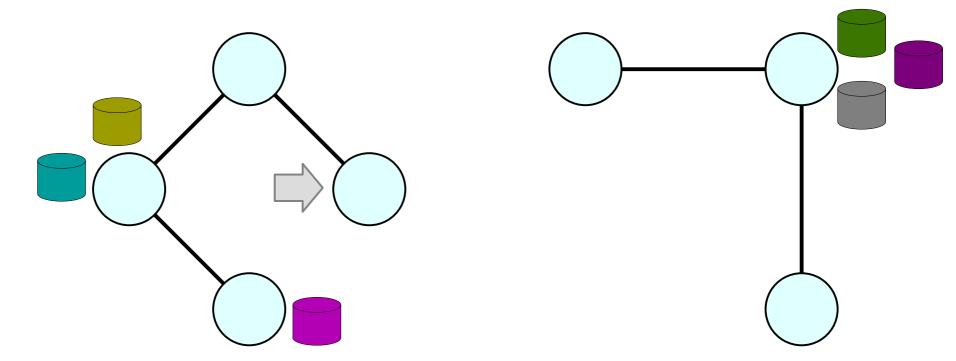
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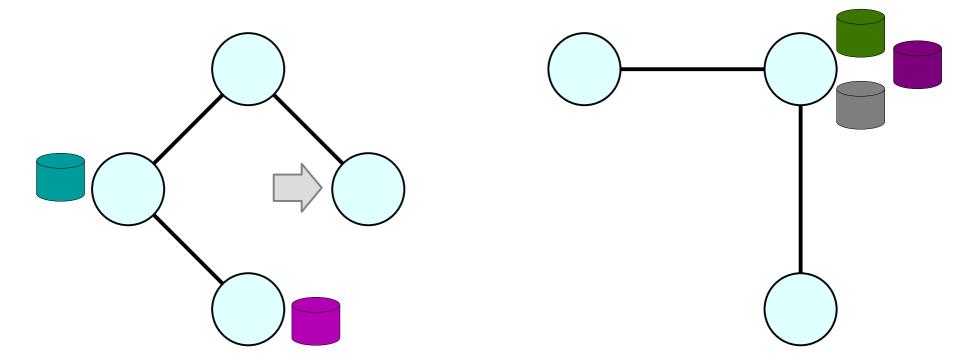
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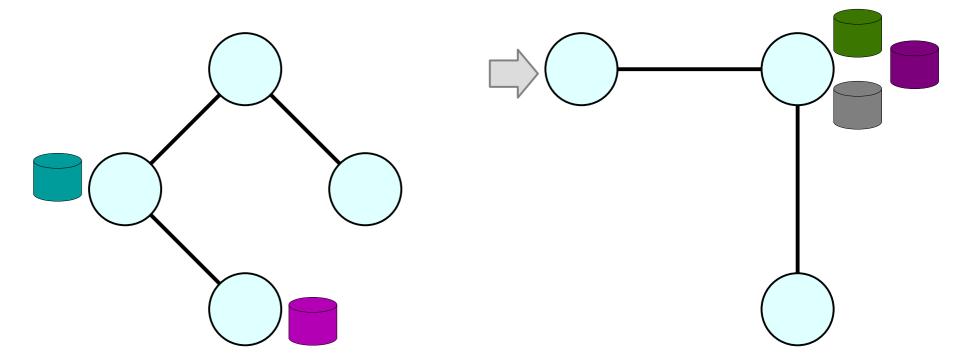
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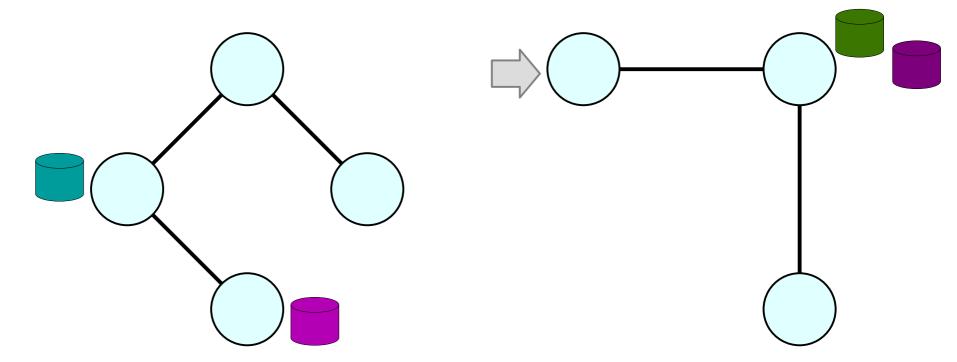
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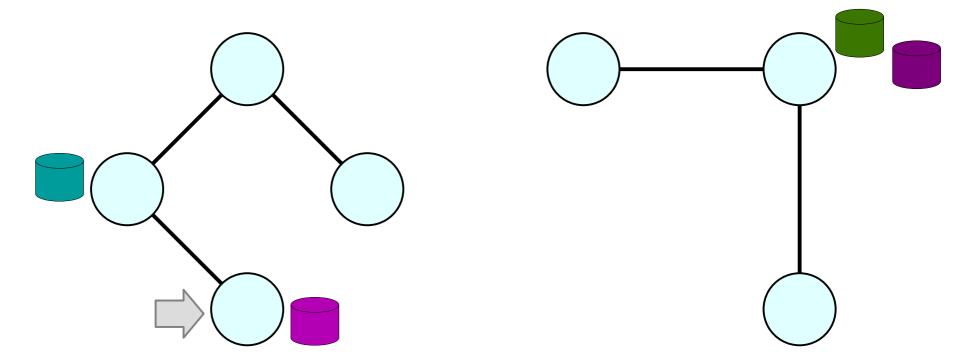
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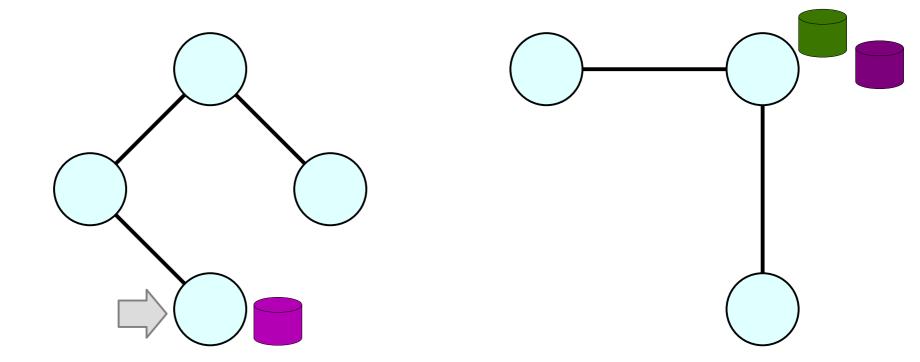
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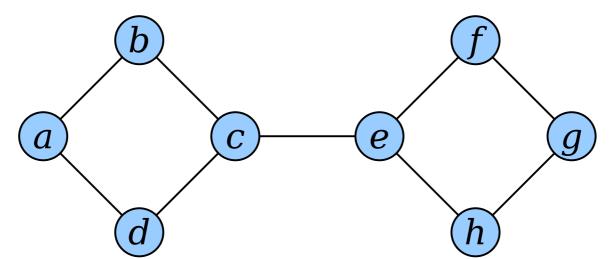


New Stuff!

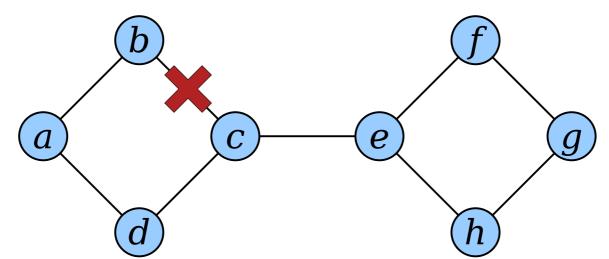
Goal: Solve dynamic connectivity on arbitrary undirected graphs.

Why is Fully-Dynamic Connectivity Hard?

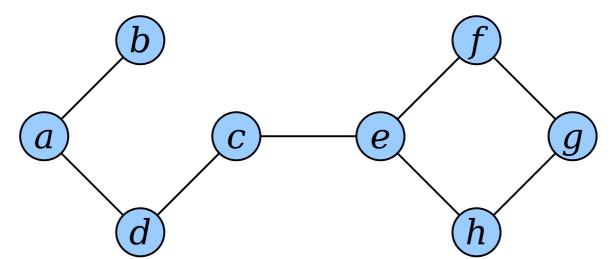
- In the case of maintaining a forest, we represented each tree as an Euler tour.
- Can we do something like that for general graphs?
- **Problem:** While we can form Euler tours in the general case, the behavior during a cut depends on whether the cut disconnects the graph.



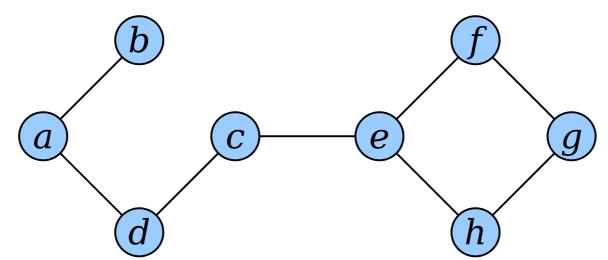
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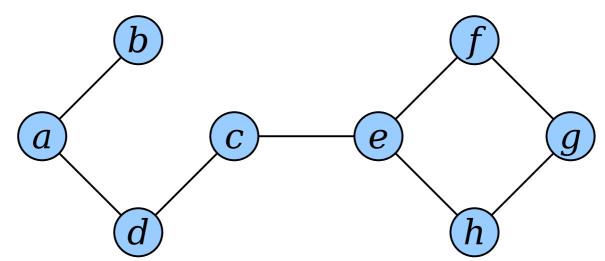
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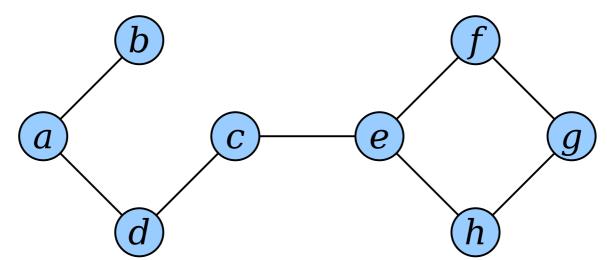
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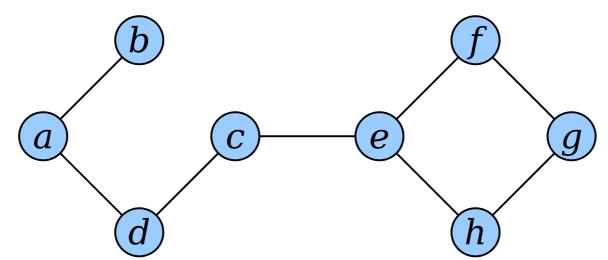
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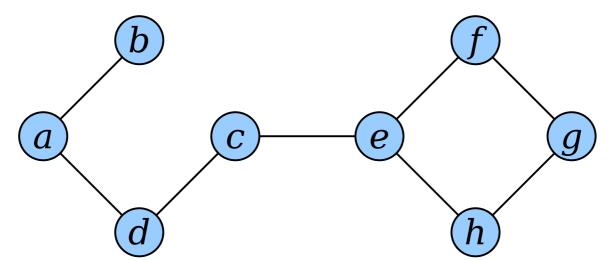
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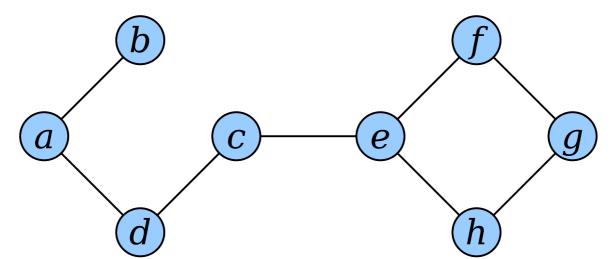


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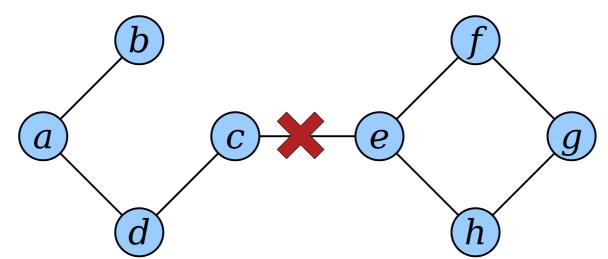
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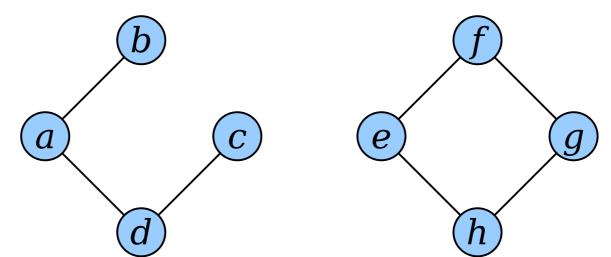
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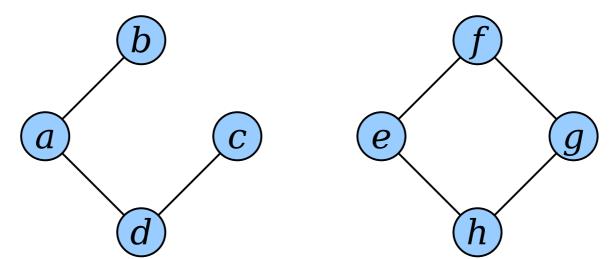
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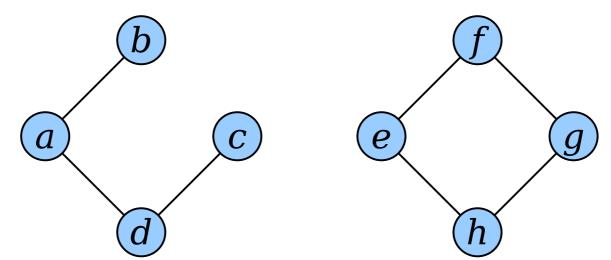
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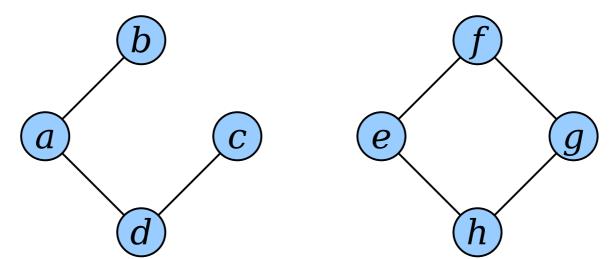
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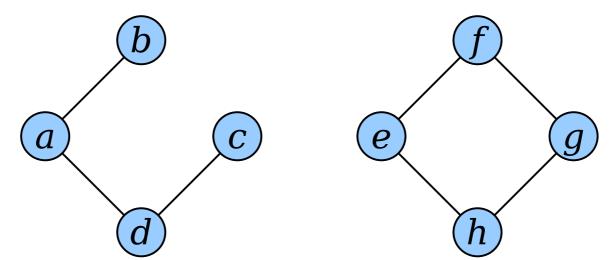
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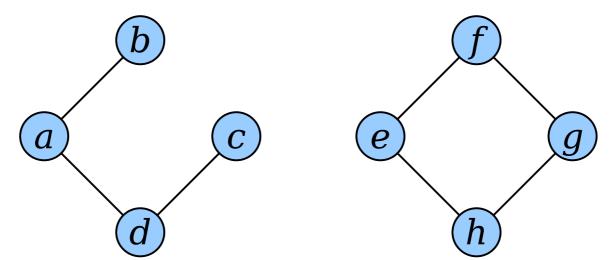


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Can We Use Euler Tours?

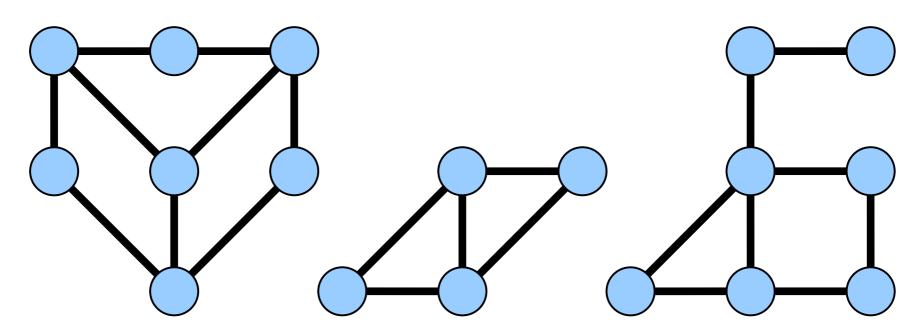
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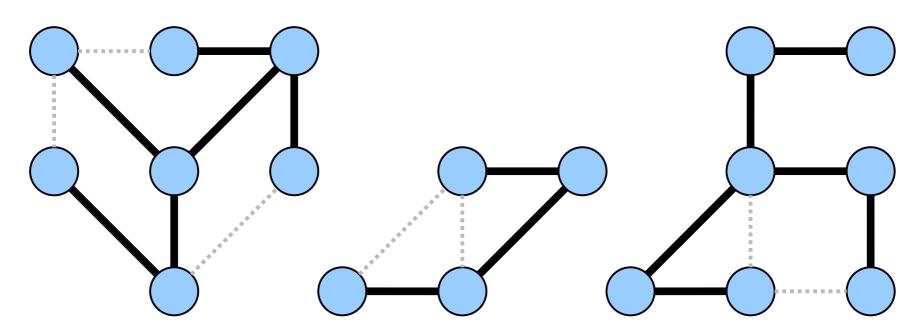
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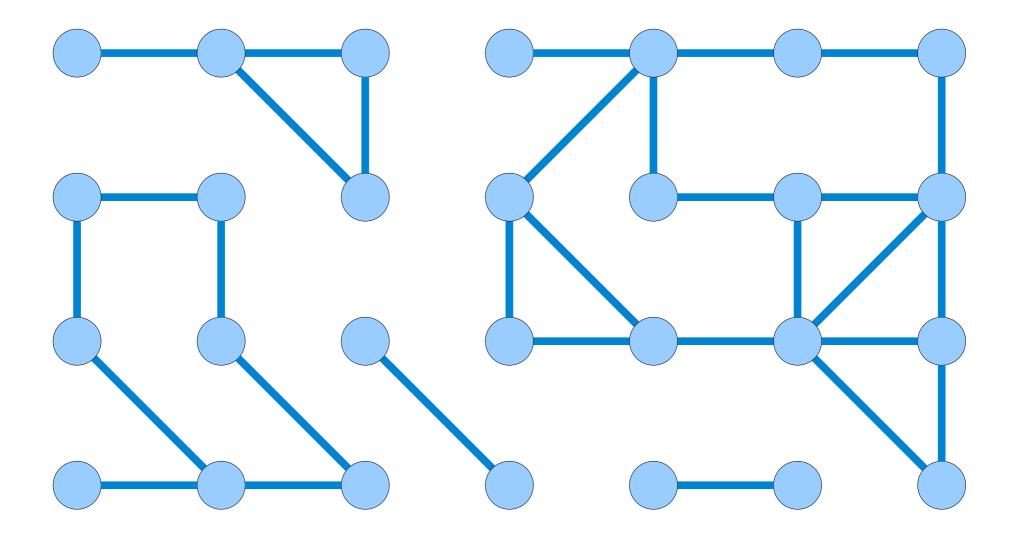
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- *Key Insight:* If all we care about is connectivity, we just need to maintain a spanning forest of the graph.

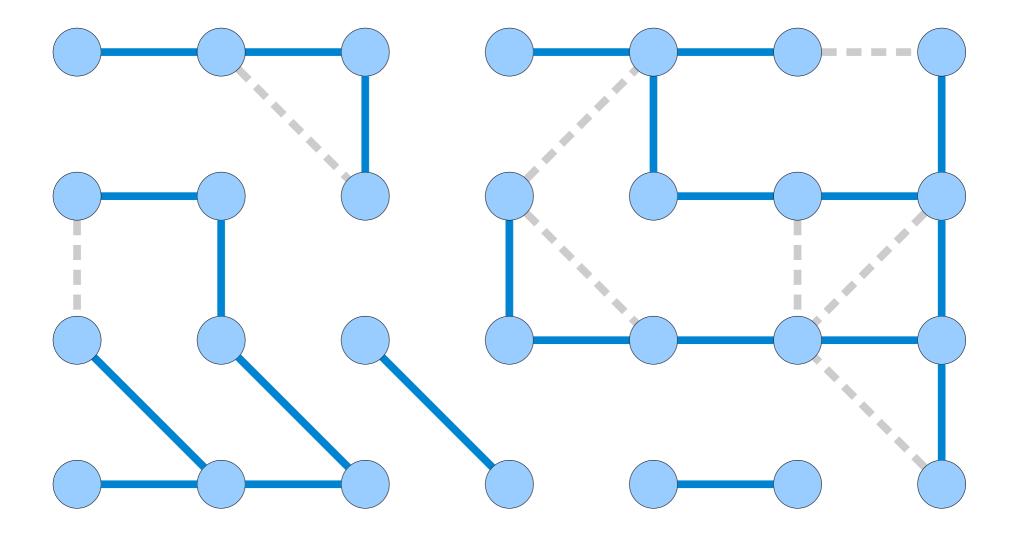


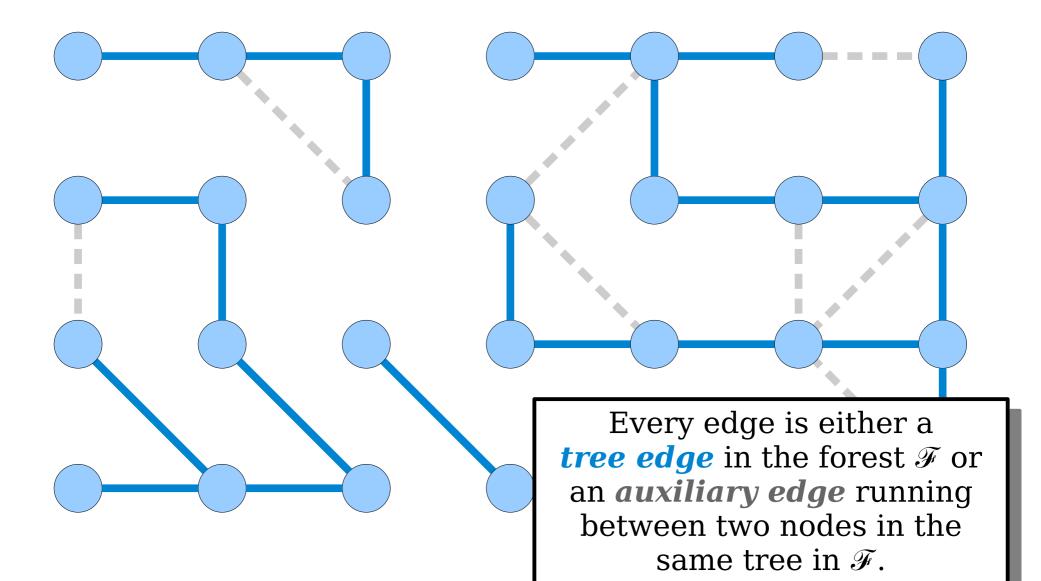
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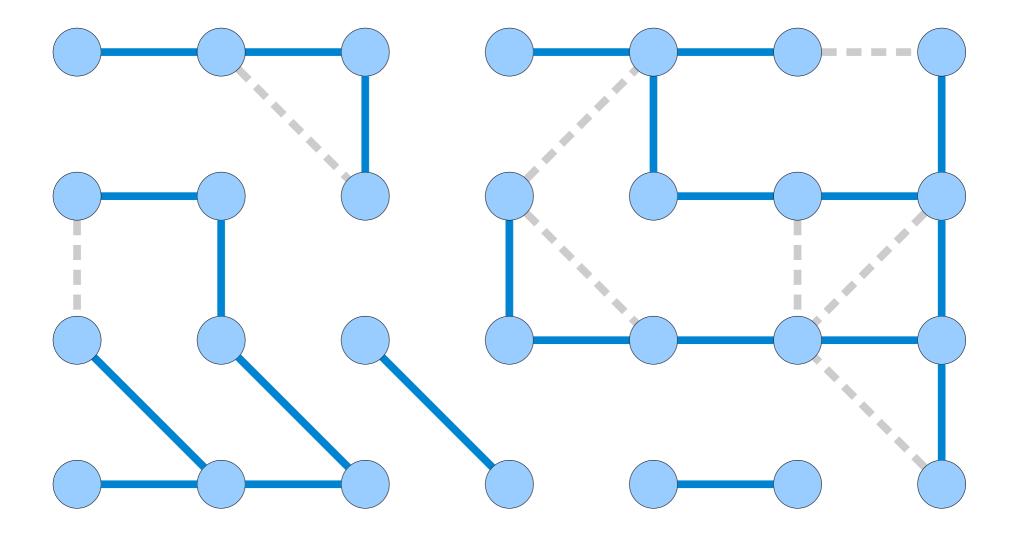
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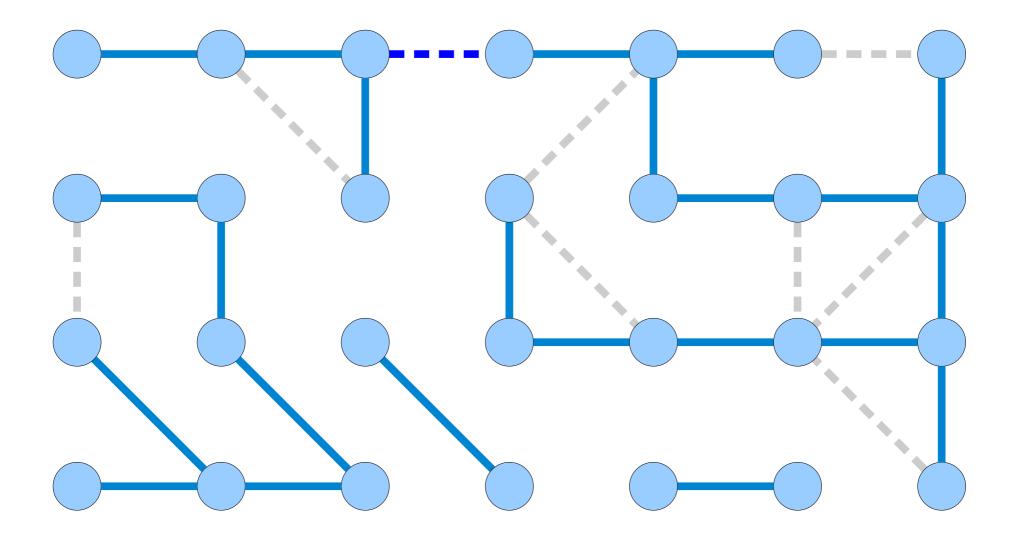


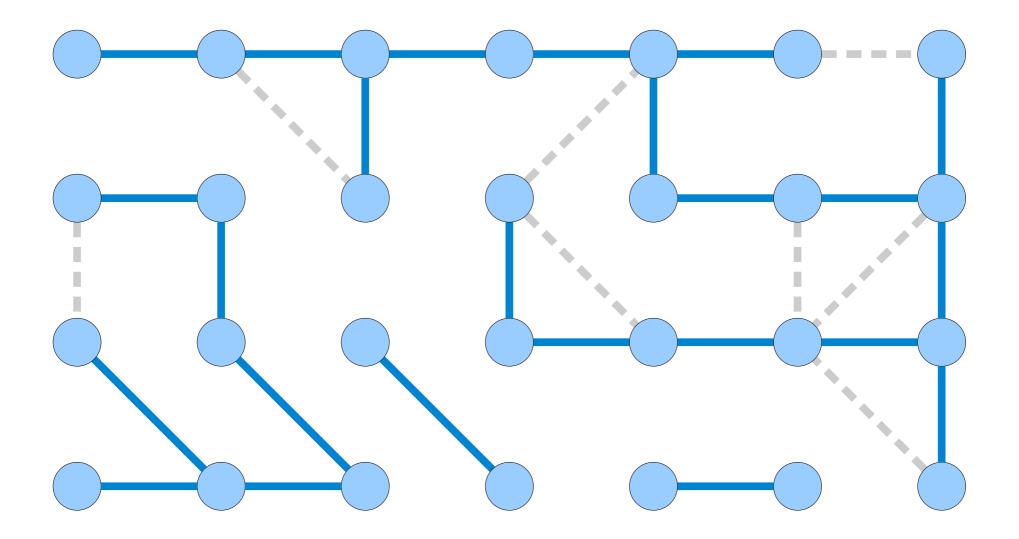


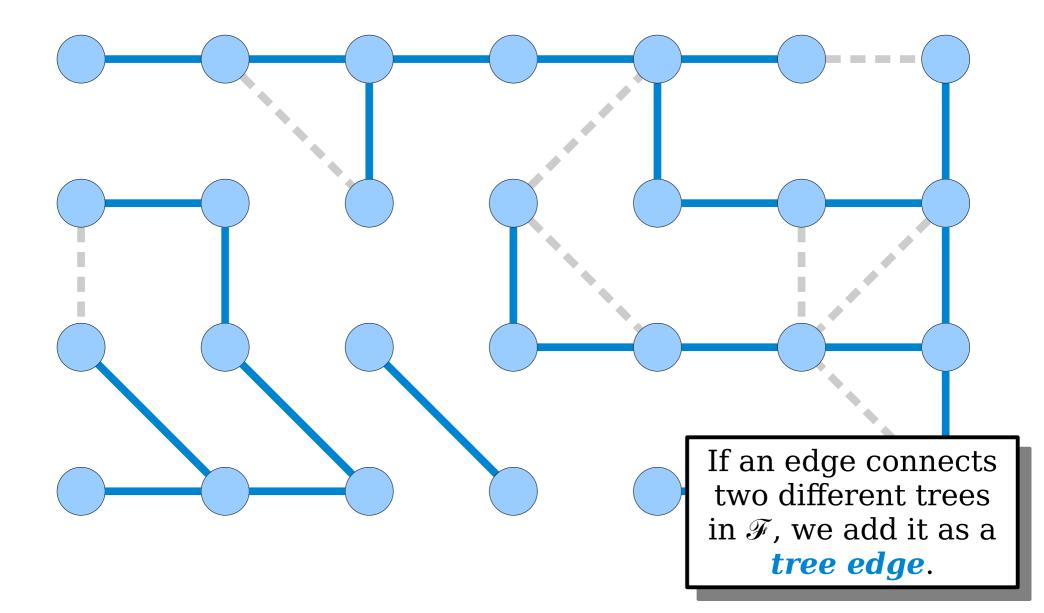


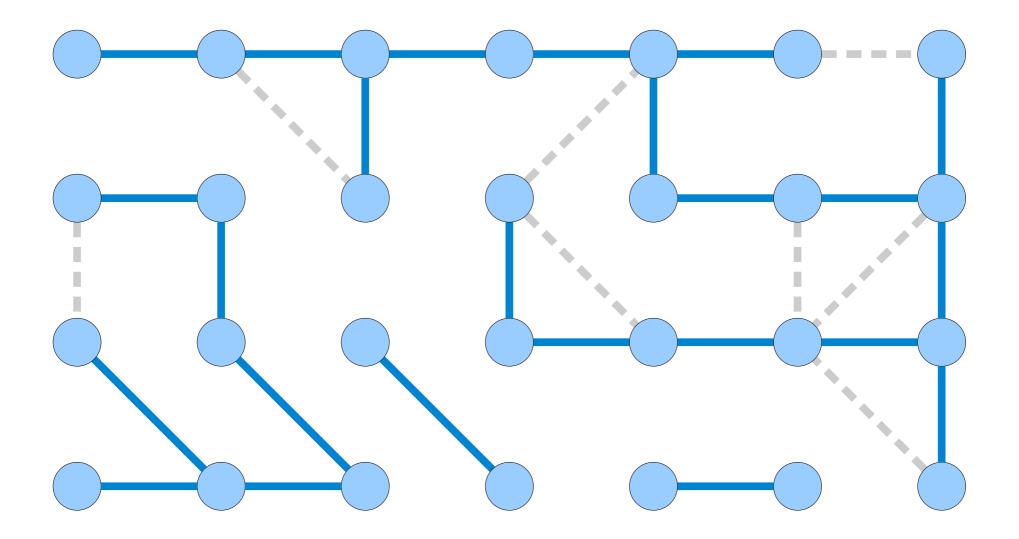


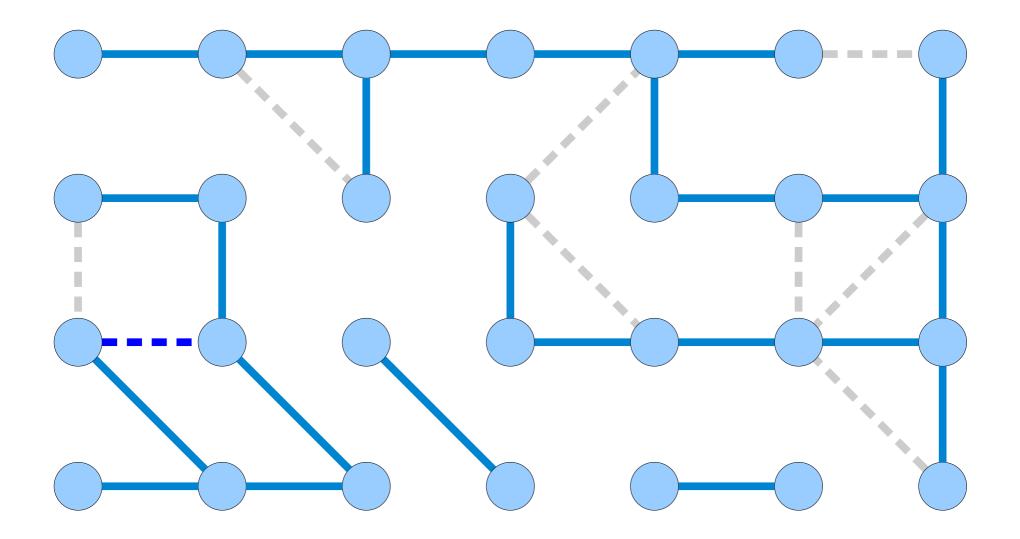


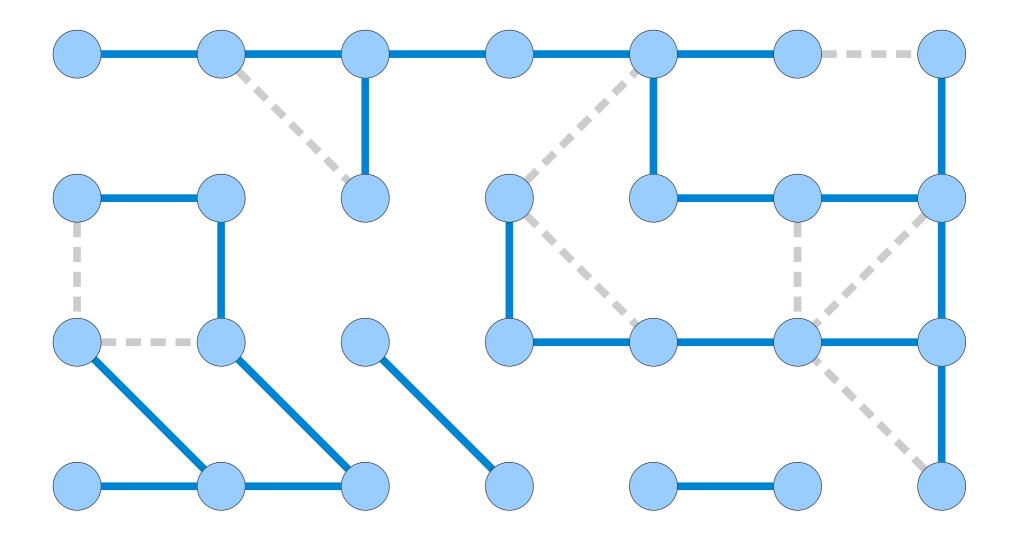


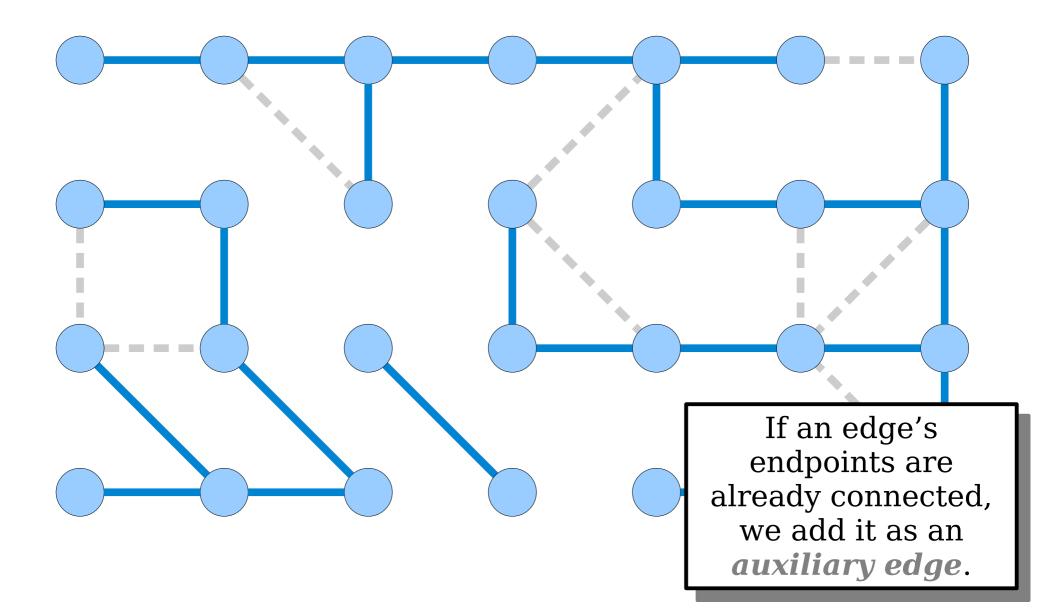


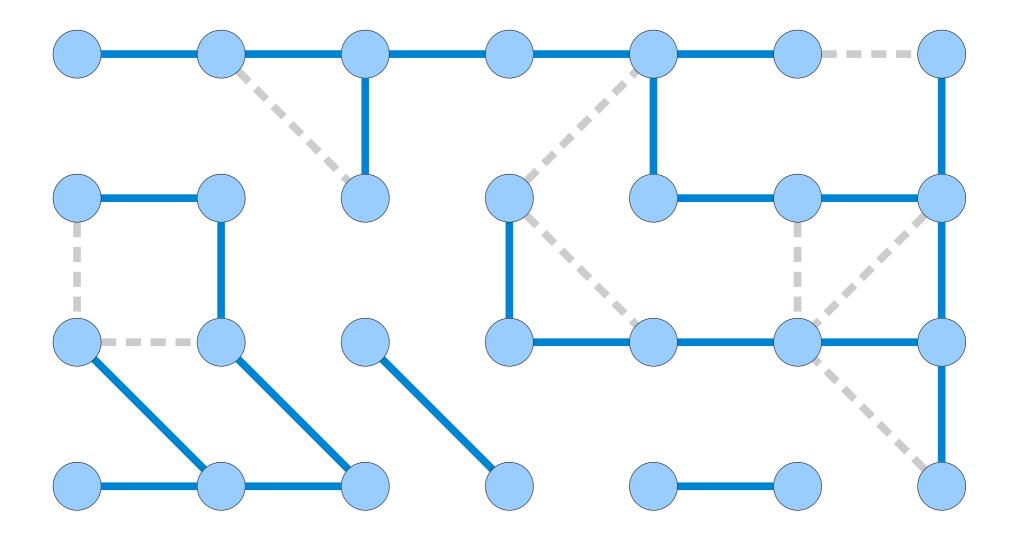


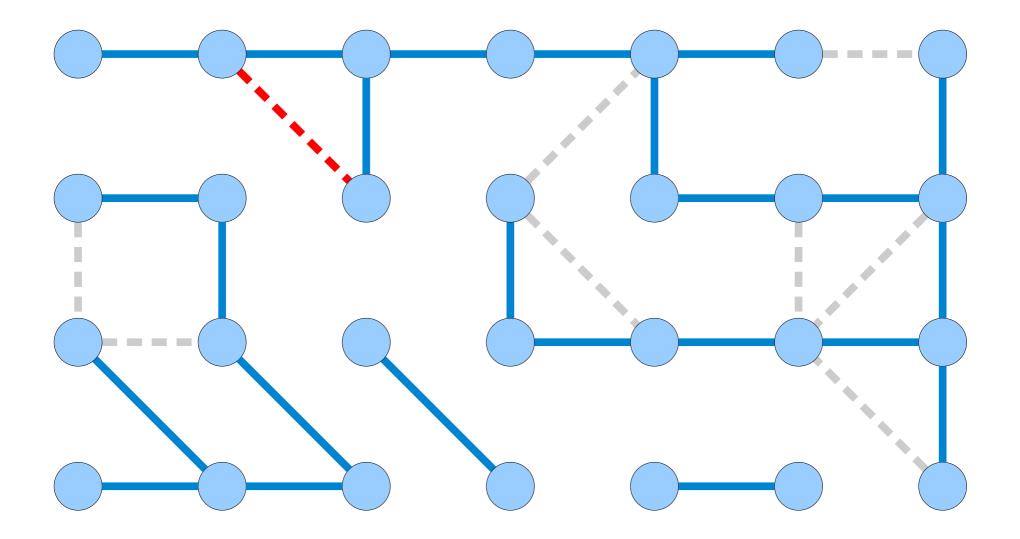


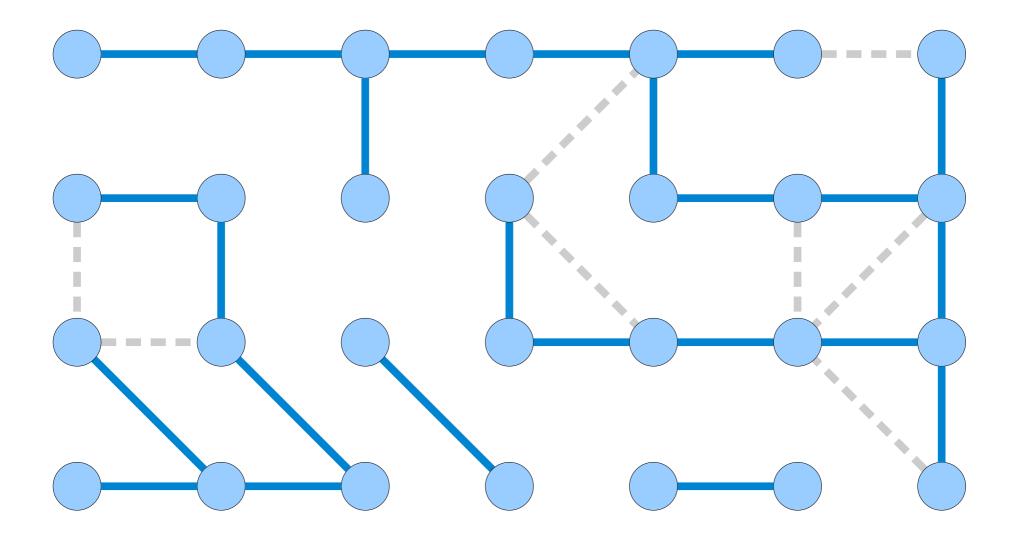


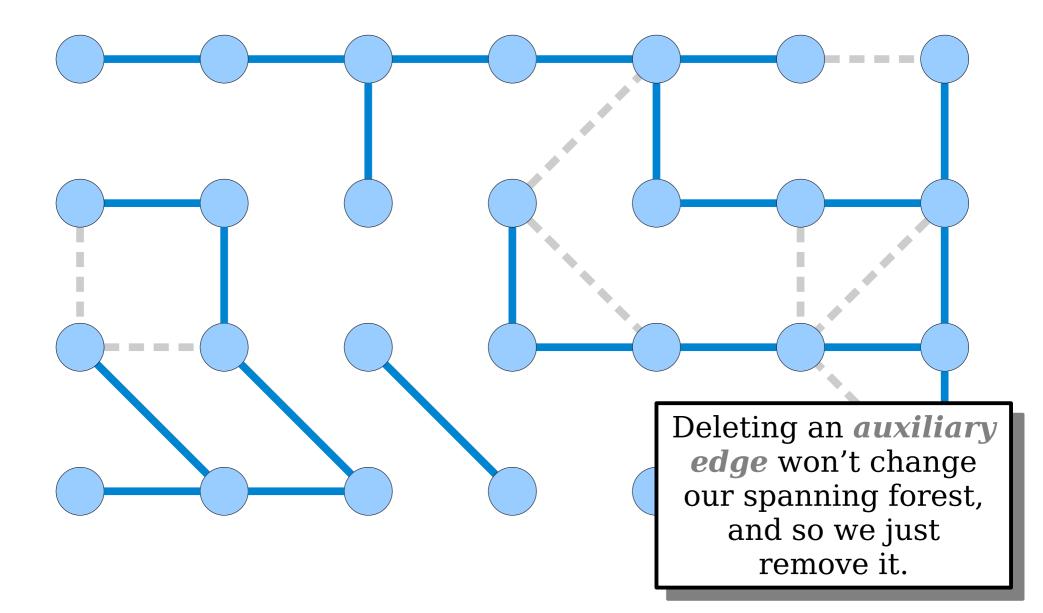


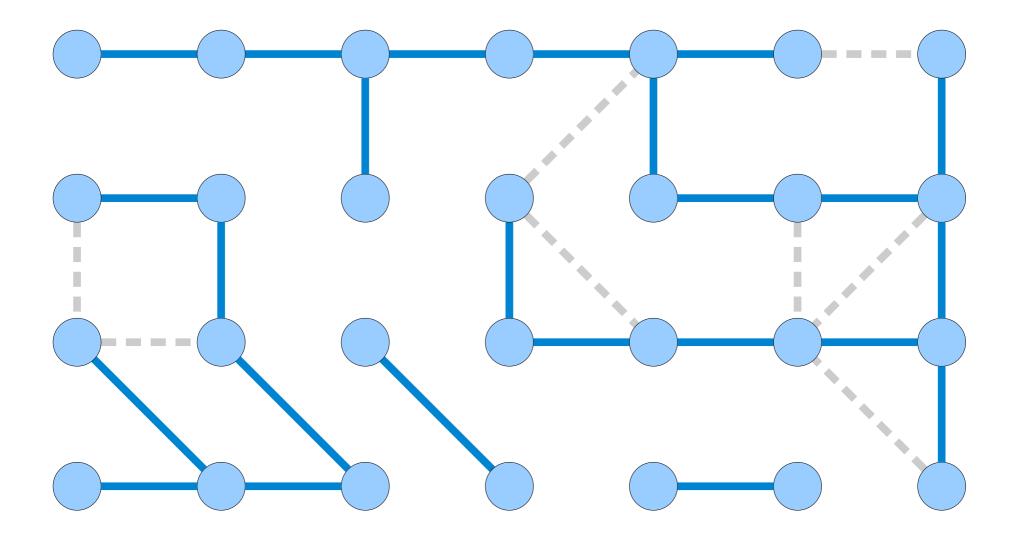


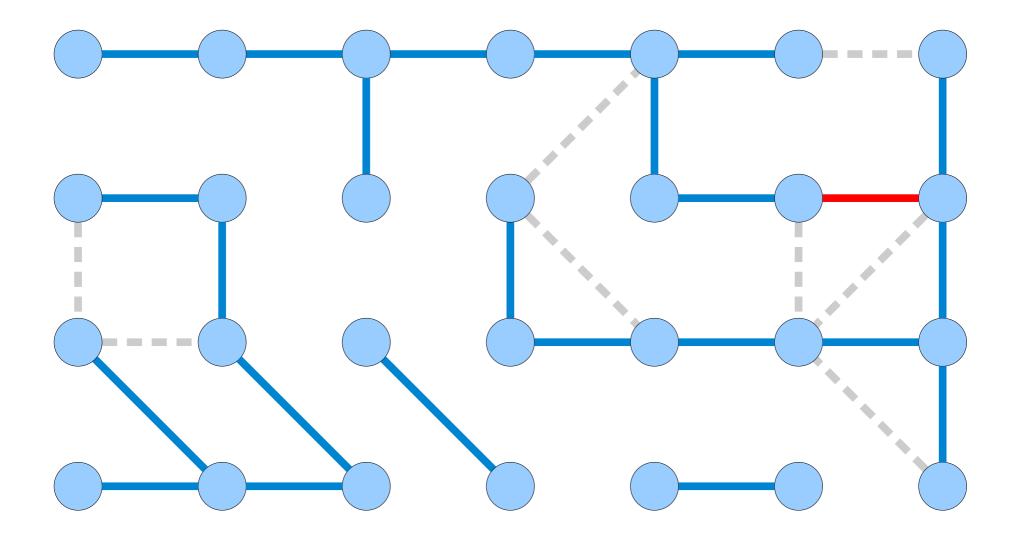


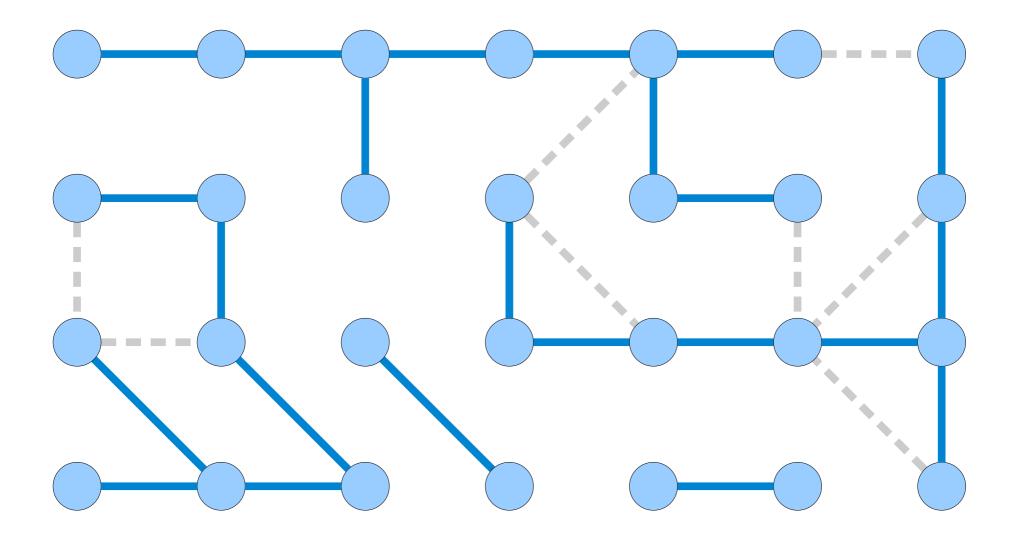


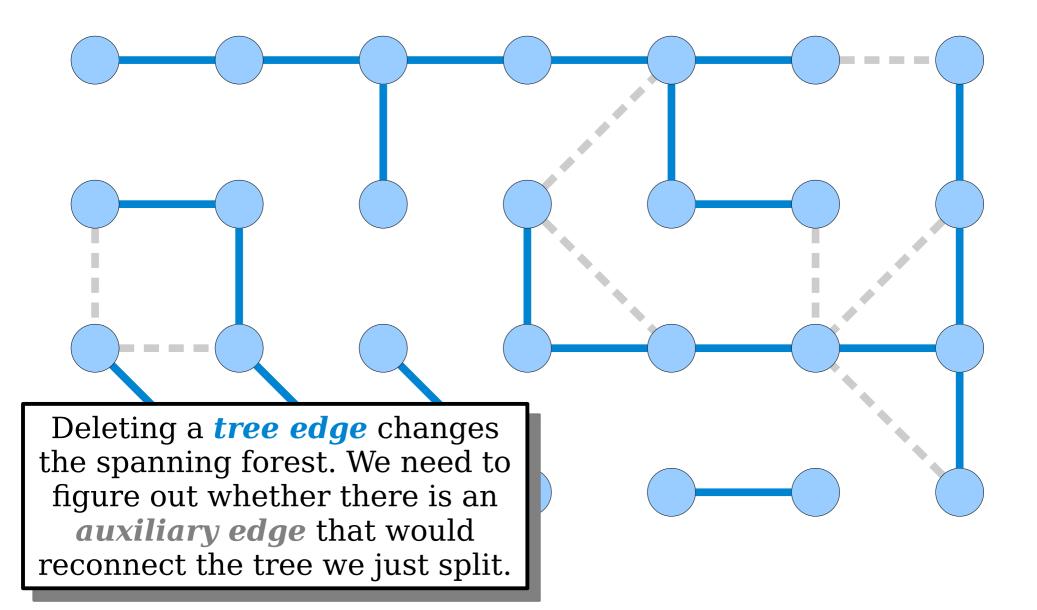


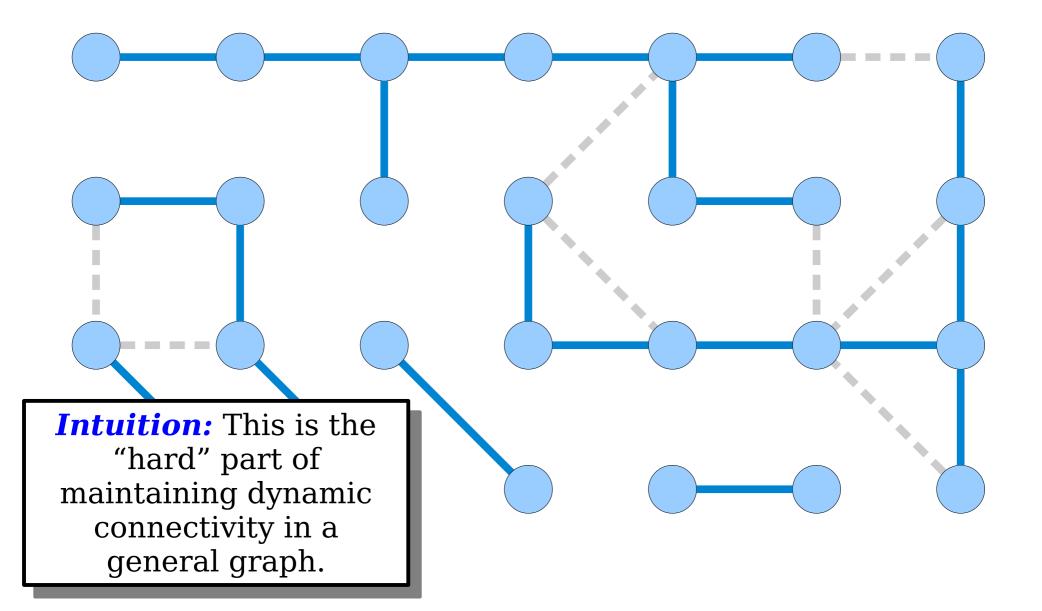


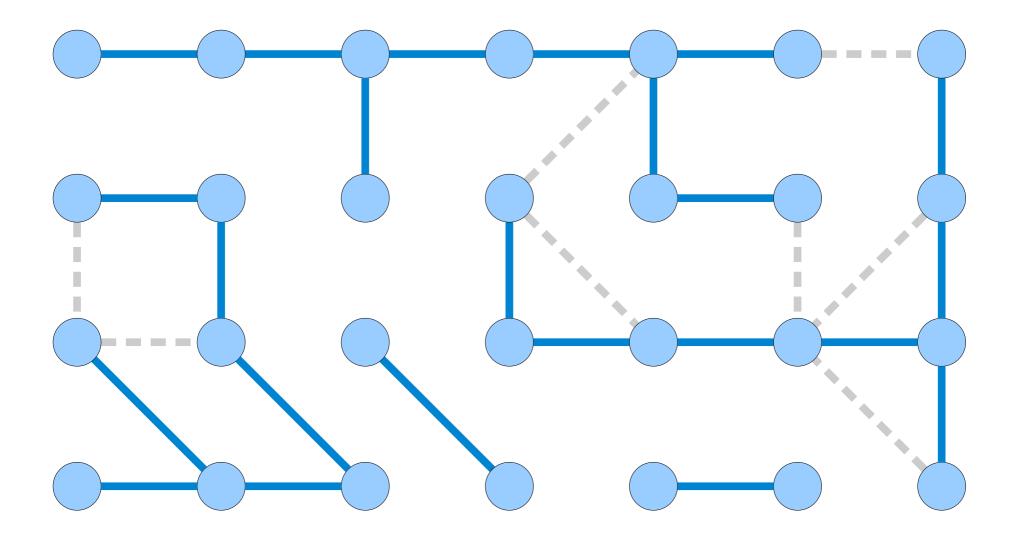


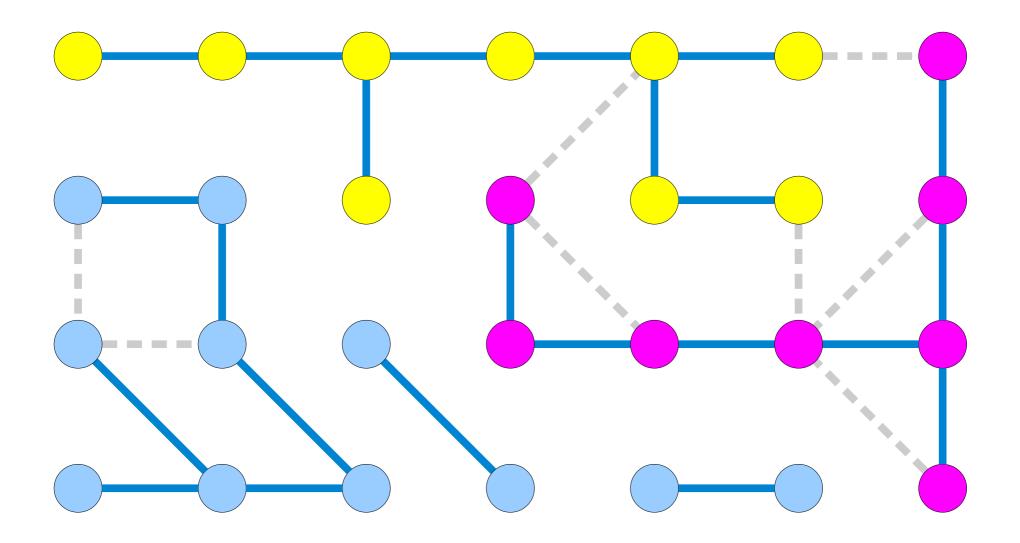


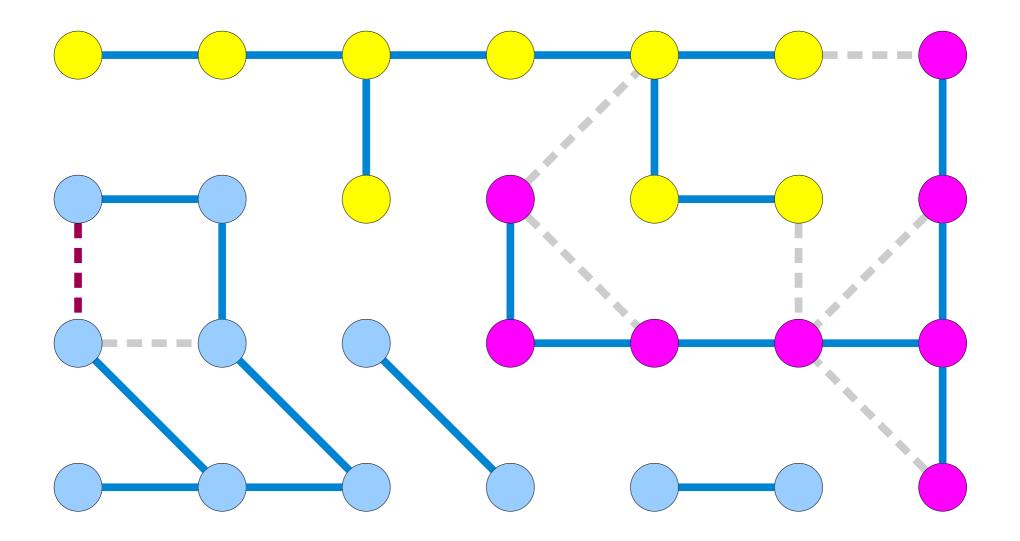


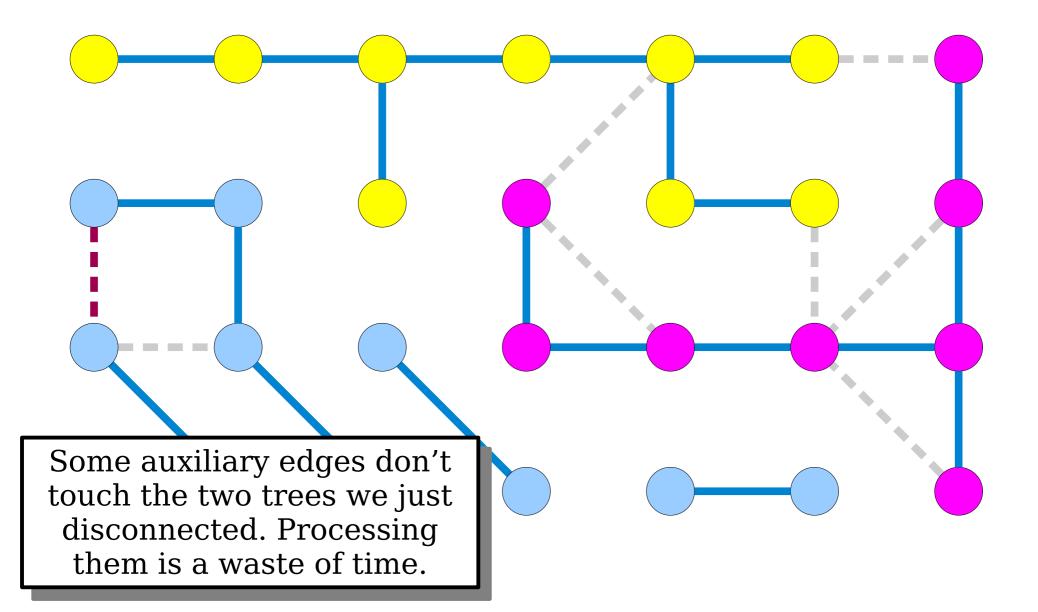


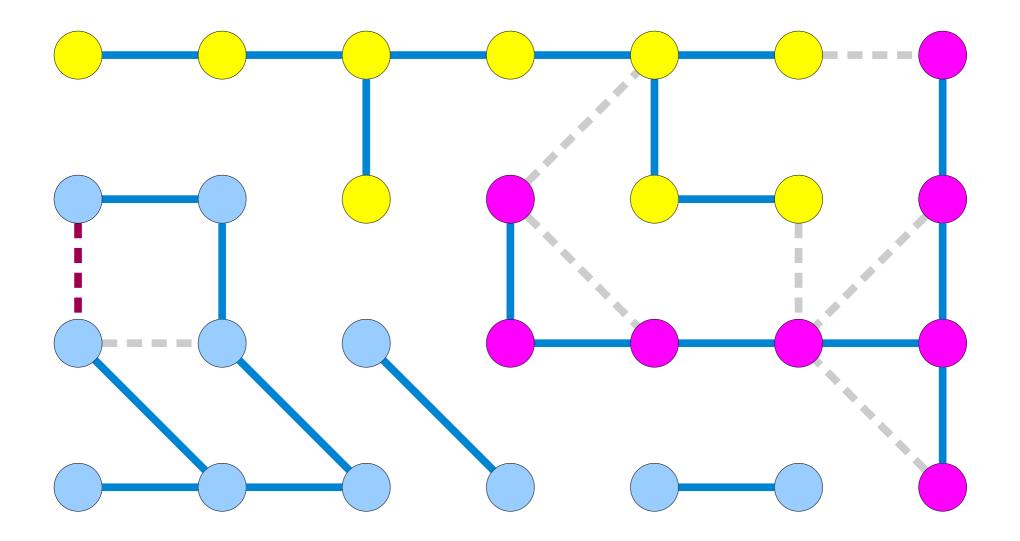


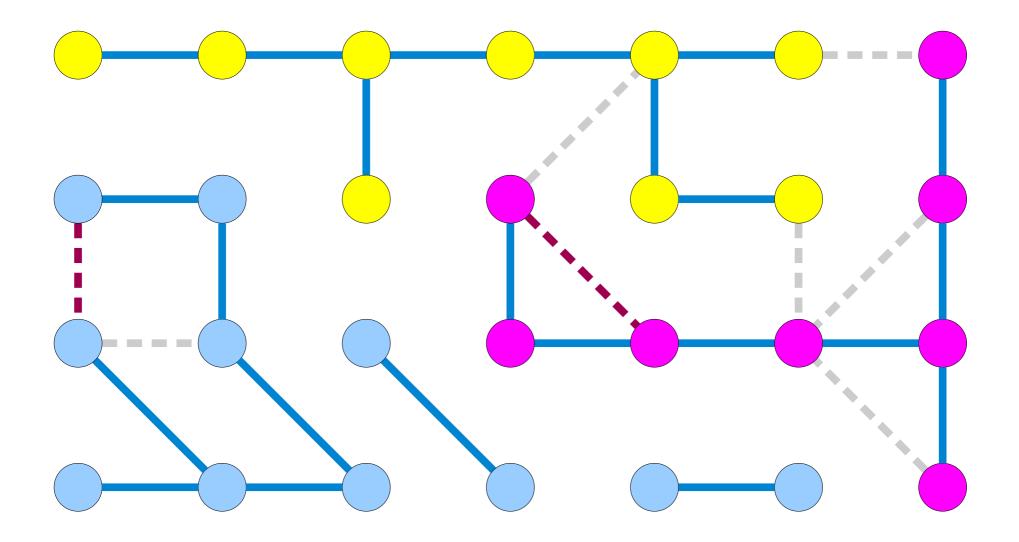




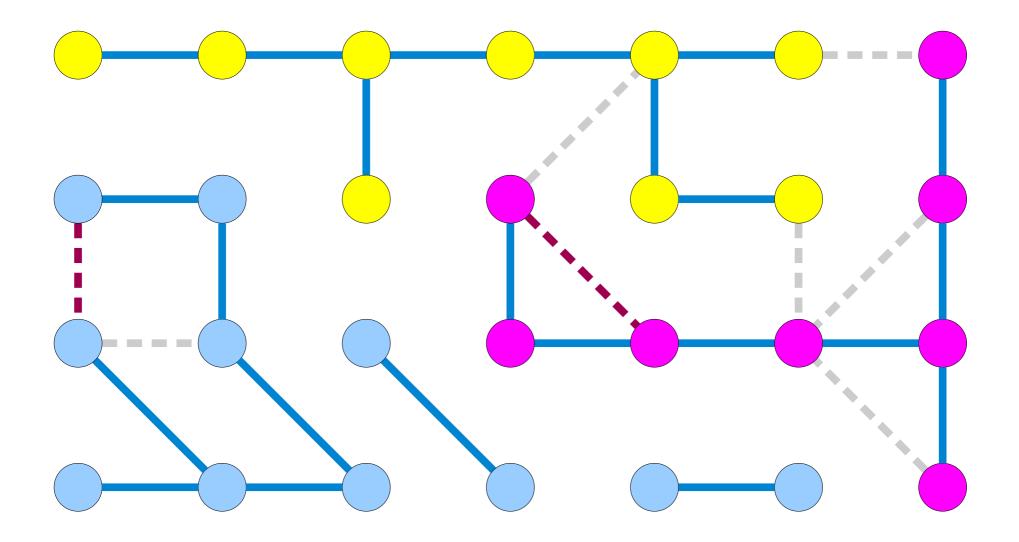


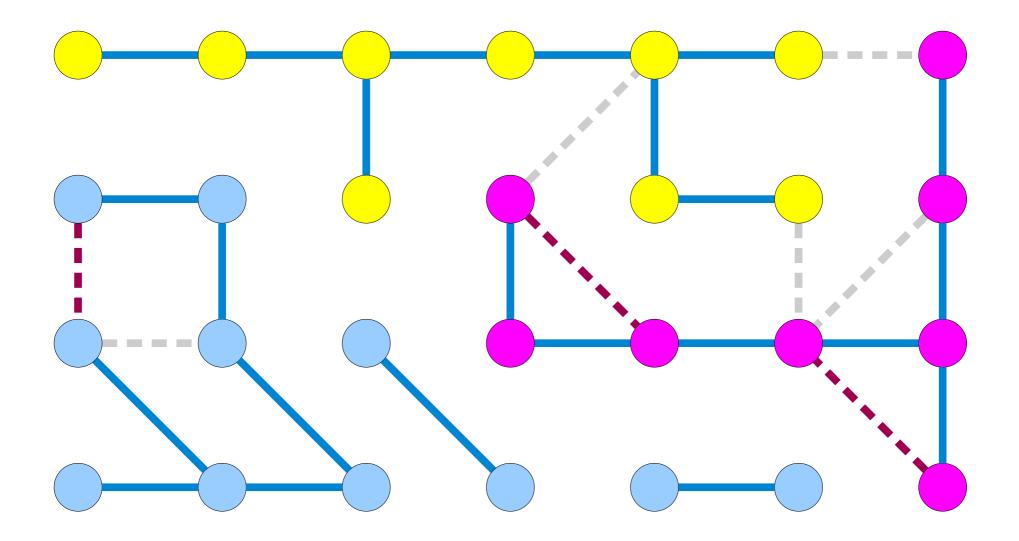


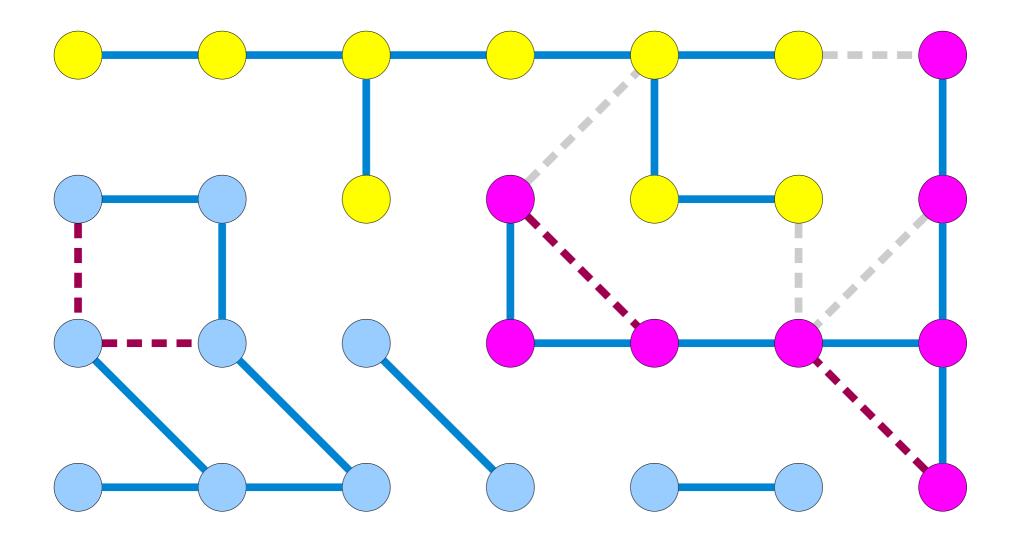


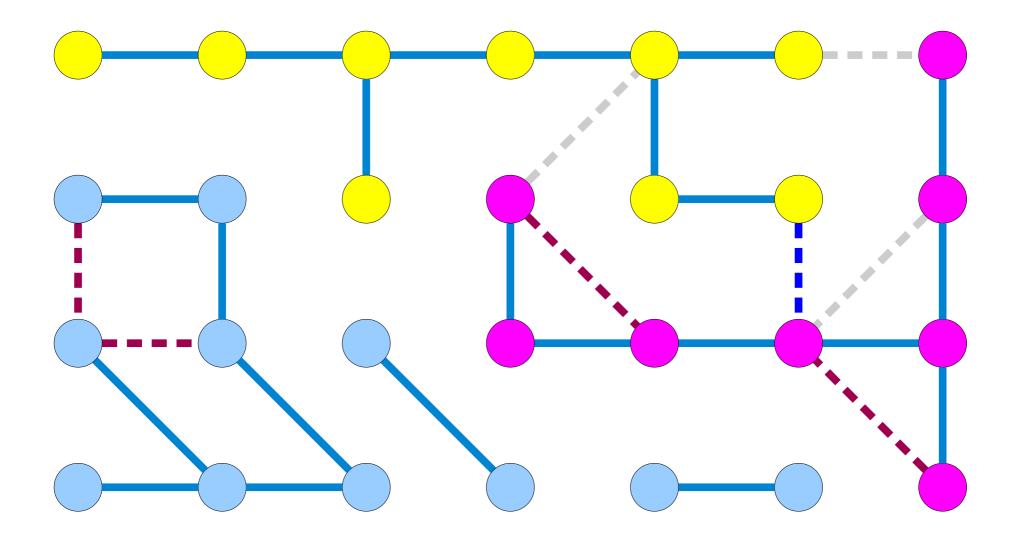


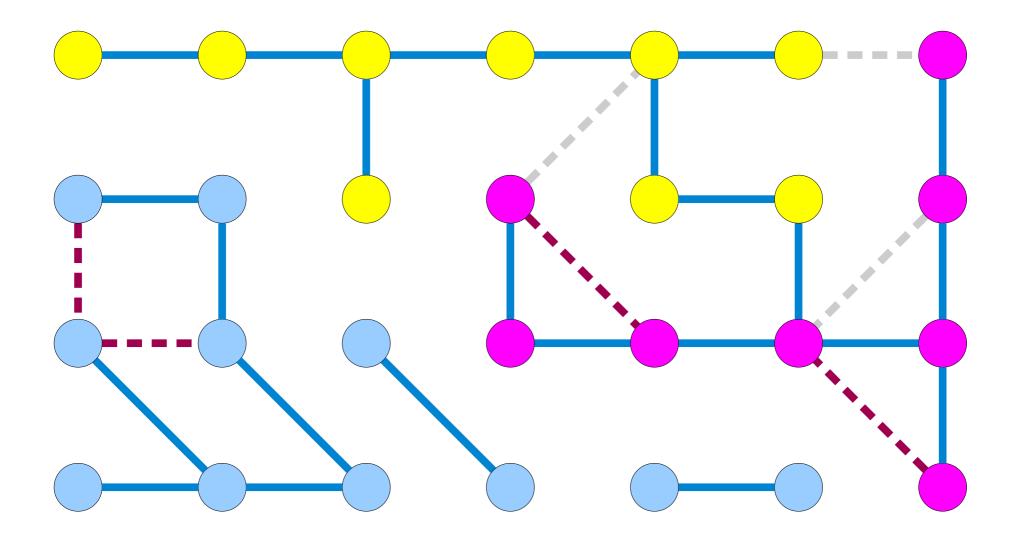
Some auxiliary edges link nodes that are part of the same tree fragment. We want to minimize the time spent processing them.

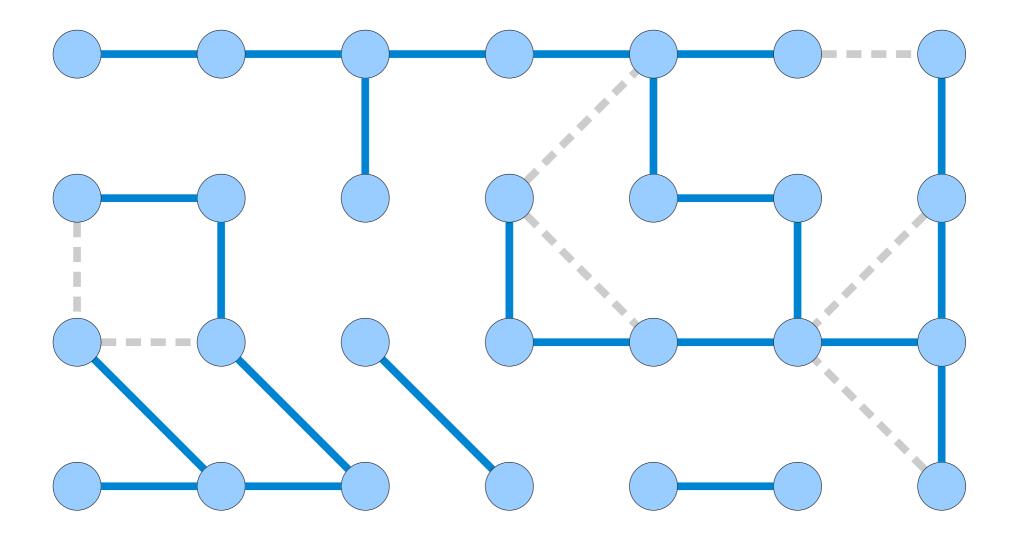


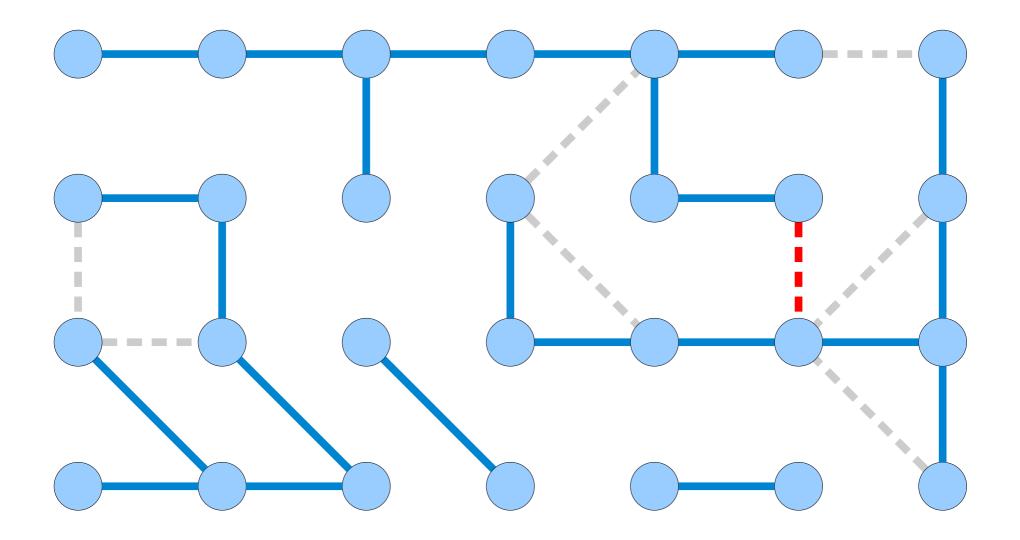


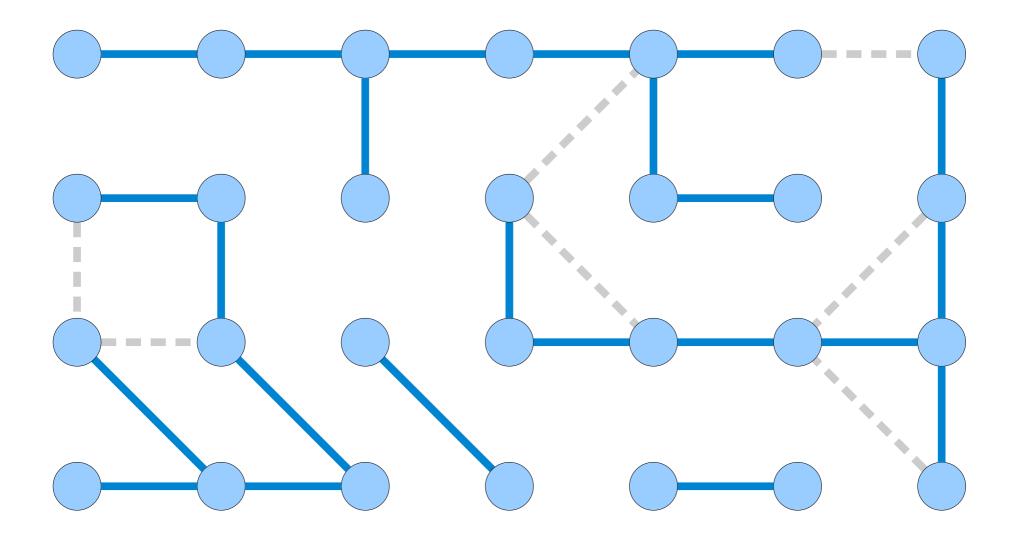


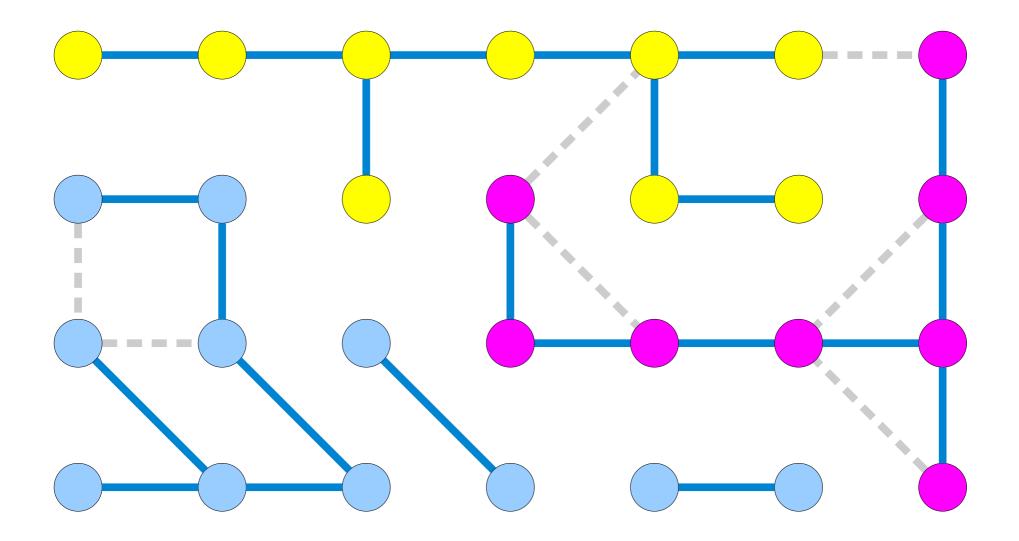


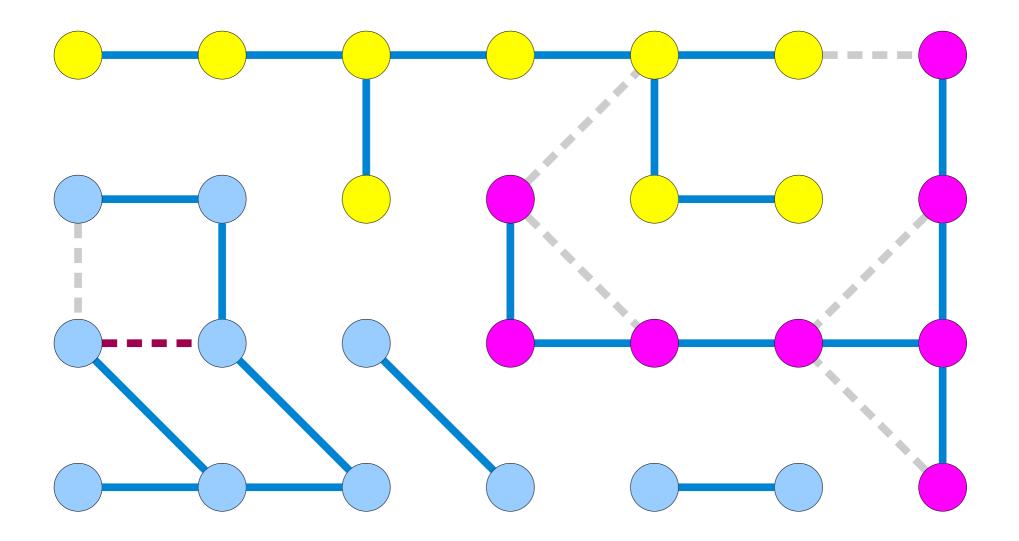


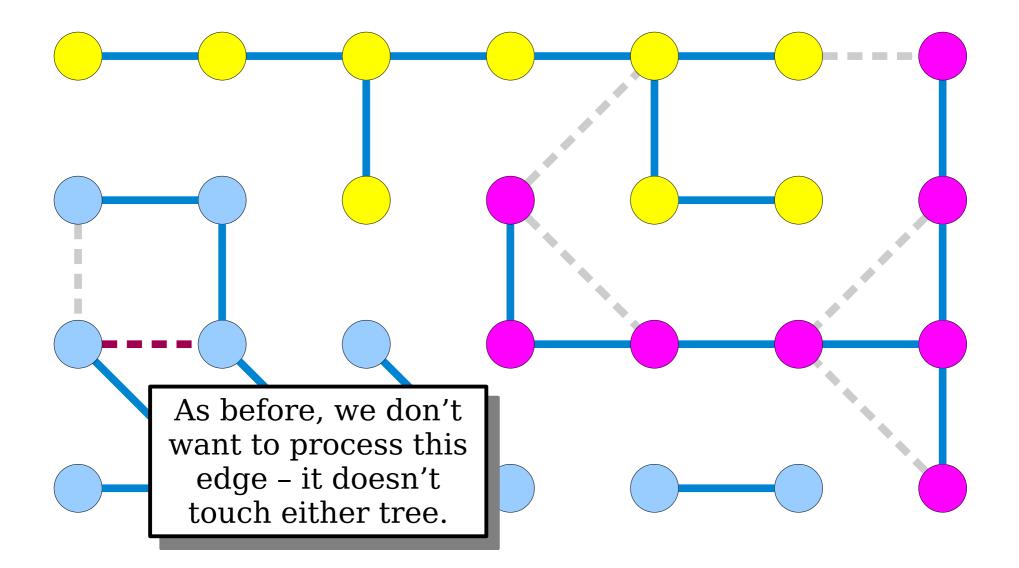


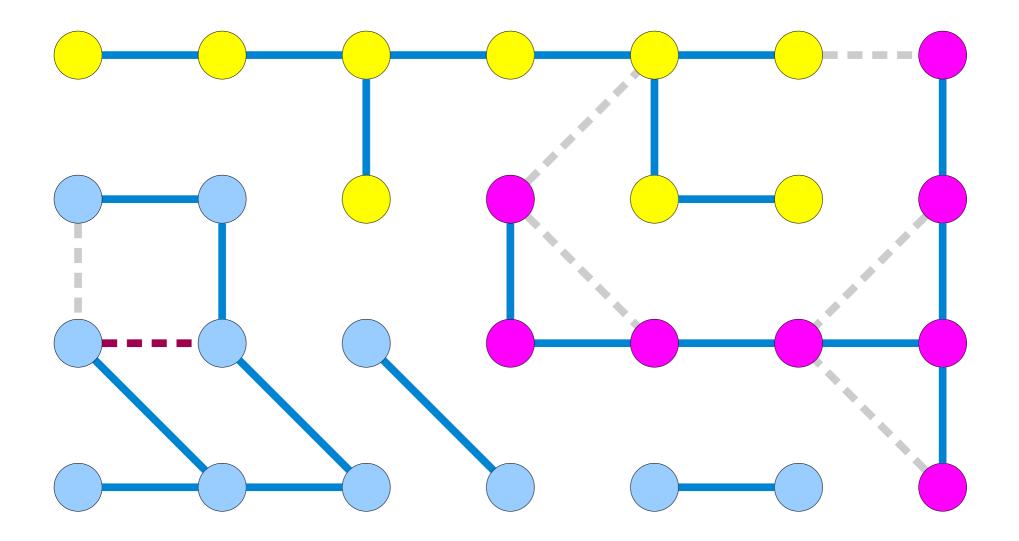


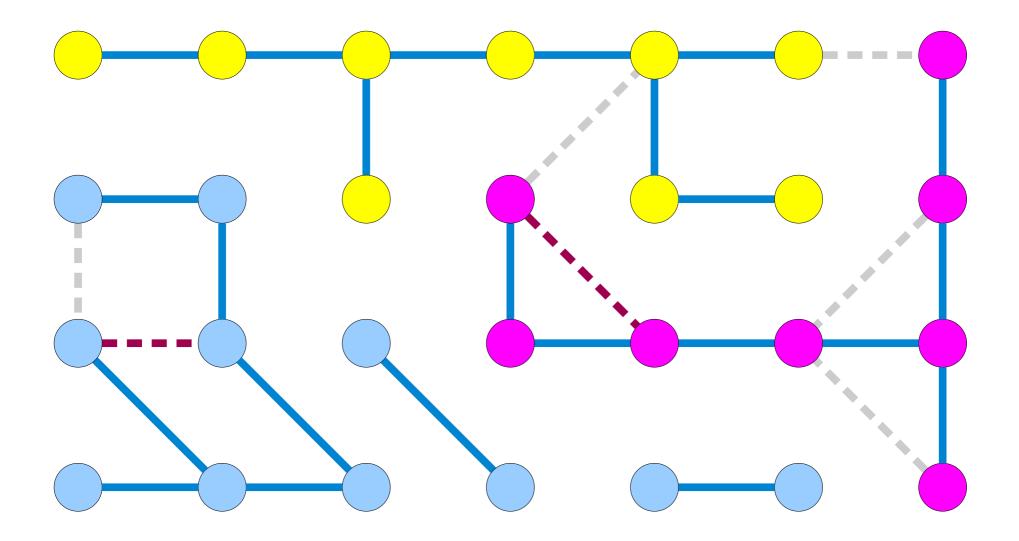




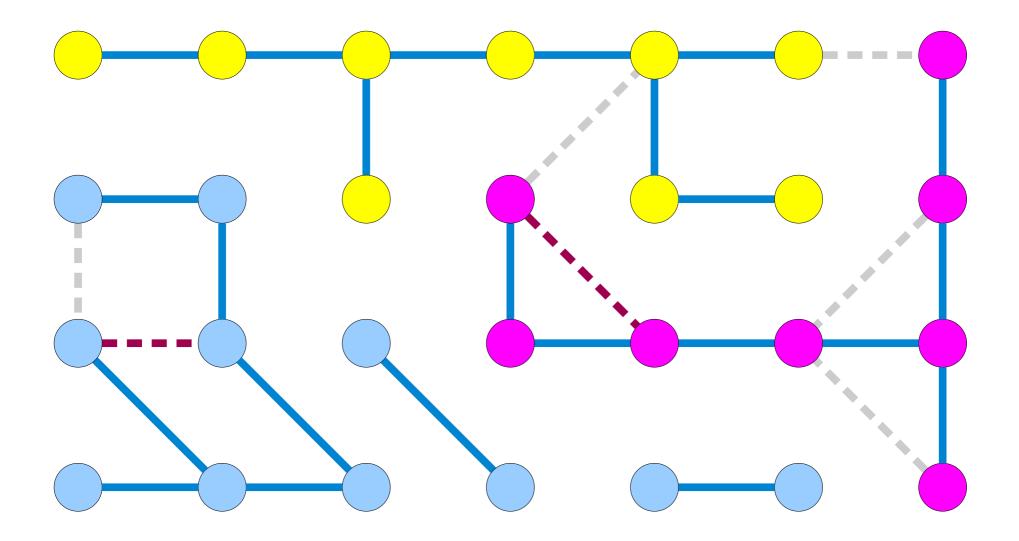


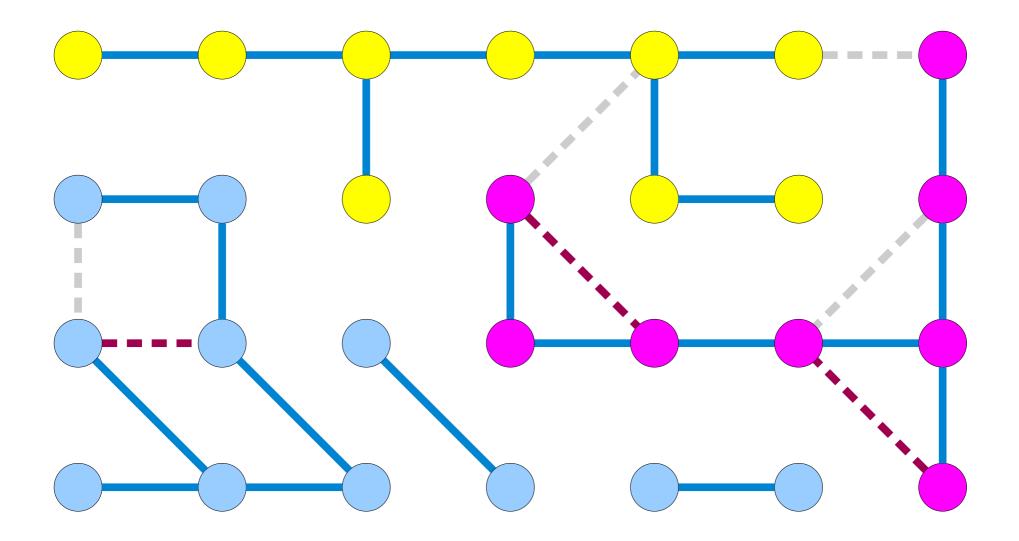


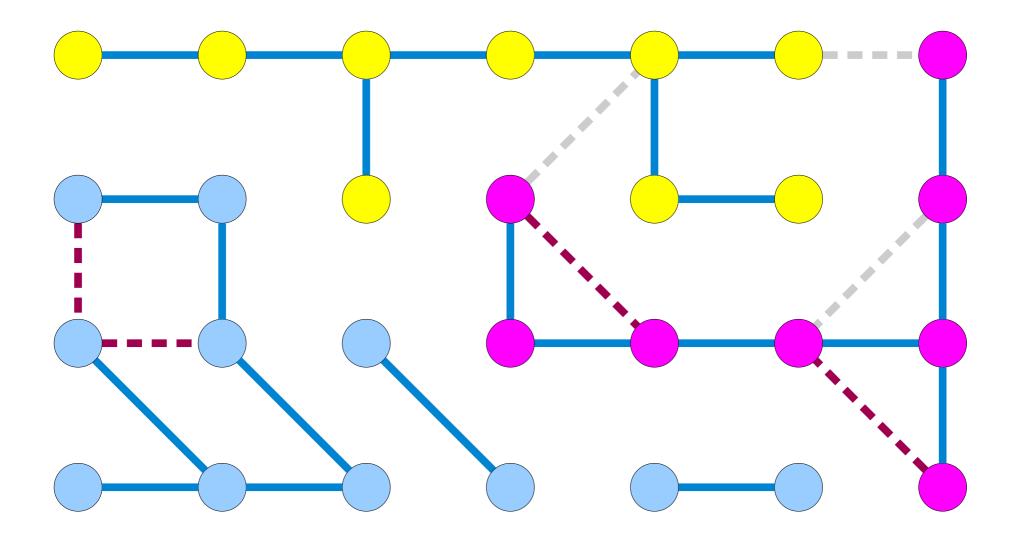


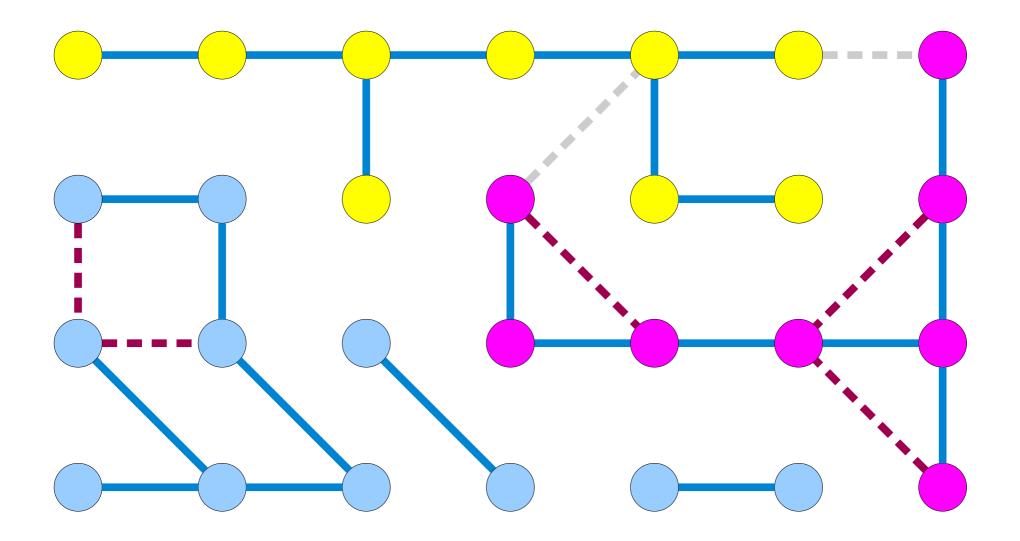


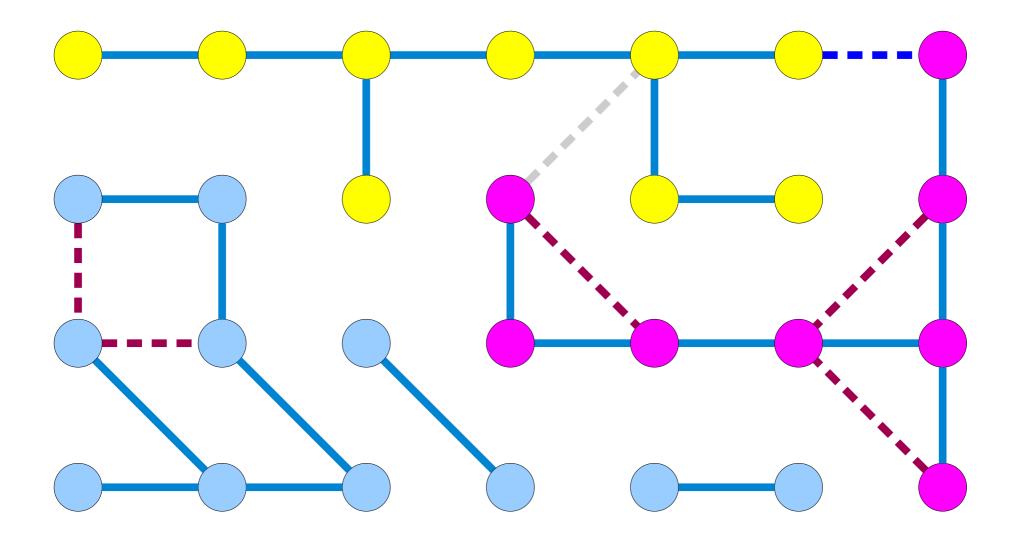
We already know that this edge won't connect these two trees. Is there a way to avoid rescanning it?

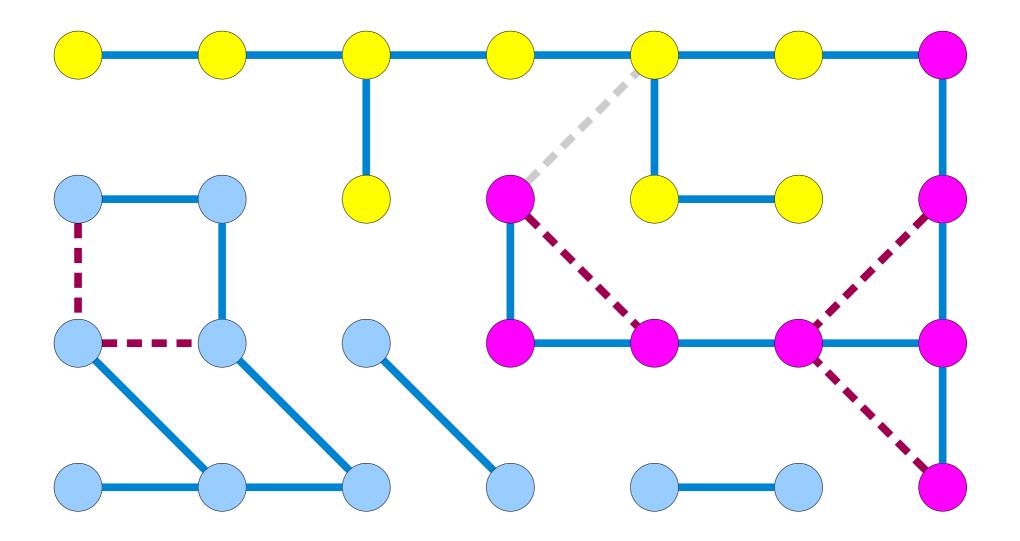


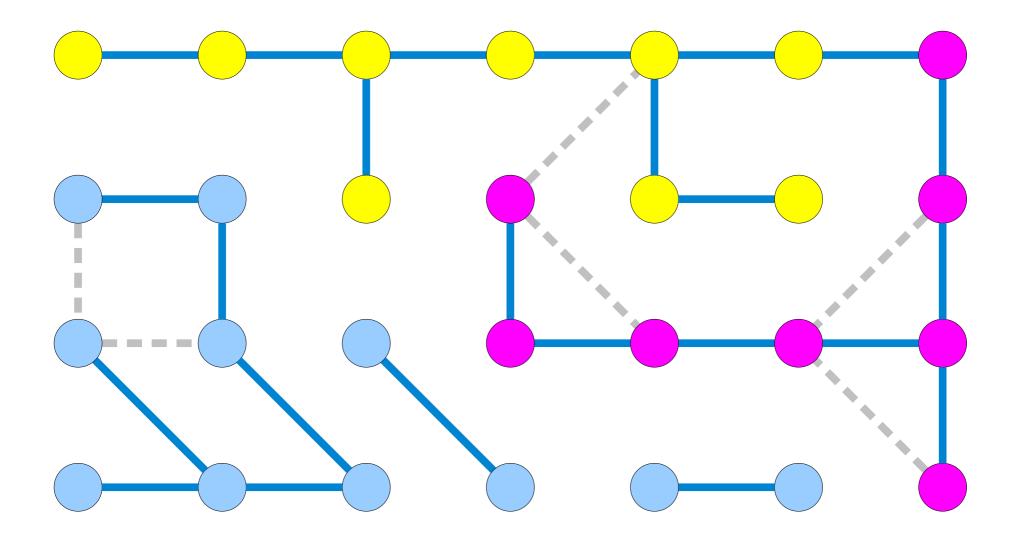


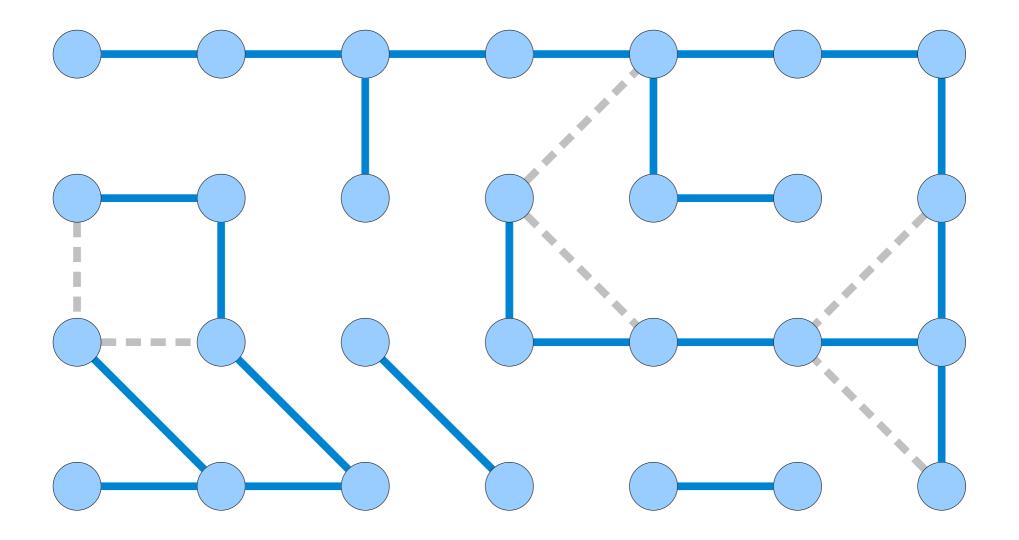












The Challenges

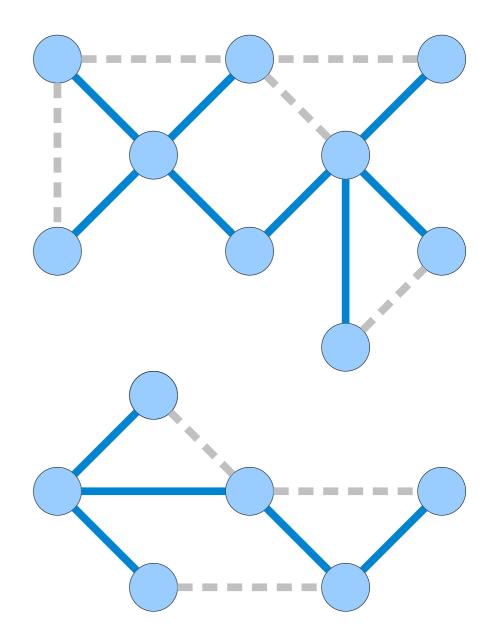
- **Goal:** After disconnecting a tree T into two trees T_1 and T_2 , search for an edge that will reconnect it.
- **Challenge 1:** Avoid scanning edges that don't have endpoints in either T_1 or T_2 .
- **Challenge 2:** Avoid rescanning edges that, based on past cuts, couldn't possibly work.

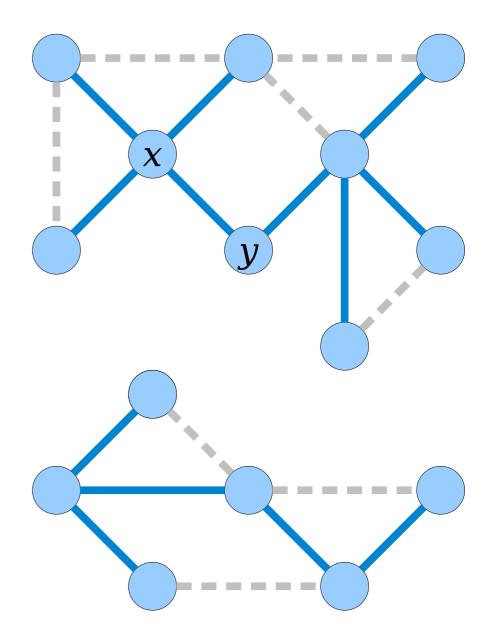
The Challenges

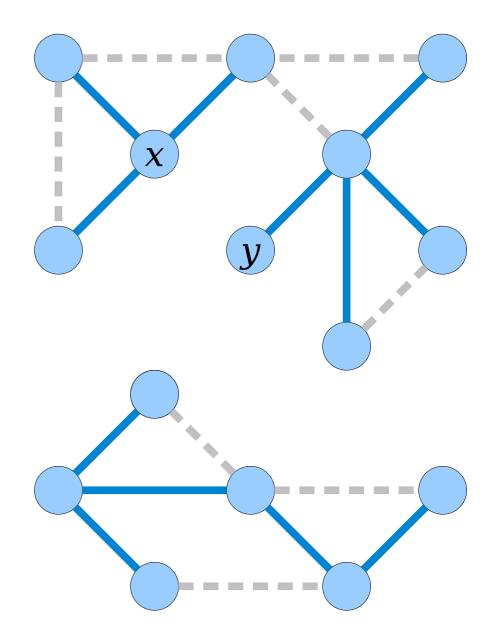
Goal: After disconnecting a tree T into two trees T_1 and T_2 , search for an edge that will reconnect it.

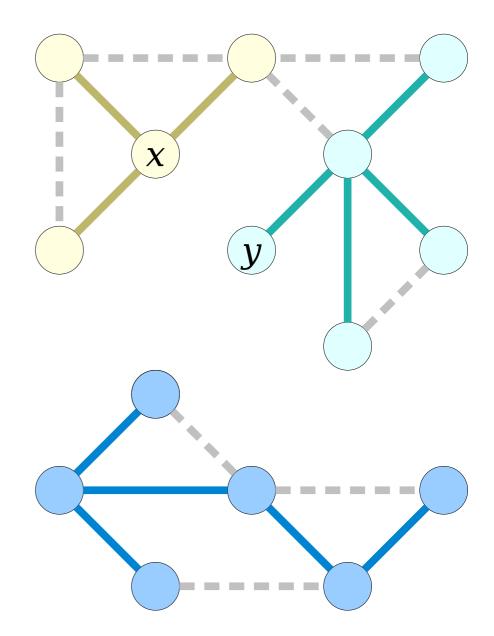
• **Challenge 1:** Avoid scanning edges that don't have endpoints in either T_1 or T_2 .

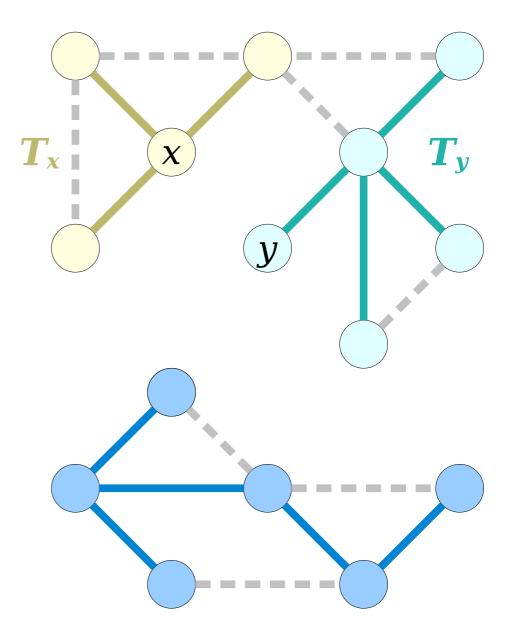
Challenge 2: Avoid rescanning edges that, based on past cuts, couldn't possibly work.



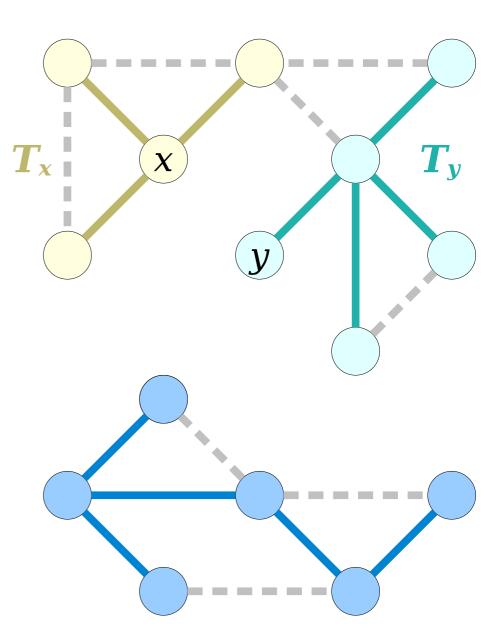




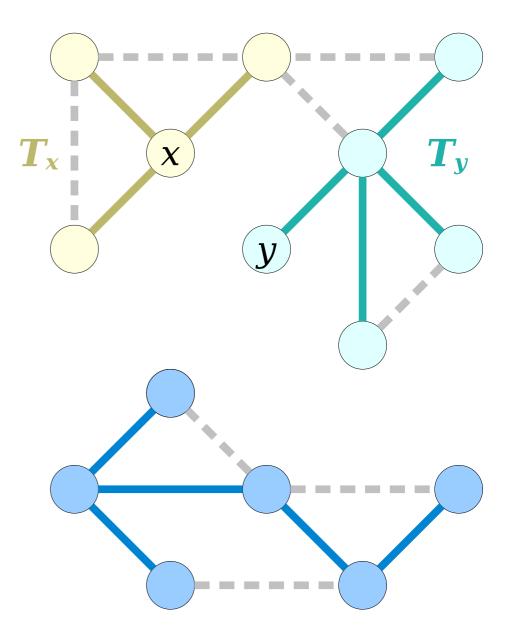




- Suppose we cut the tree edge xy, splitting a tree T into T_x and T_y .
- We need to search for an auxiliary edge that could reconnect T_x and T_y .



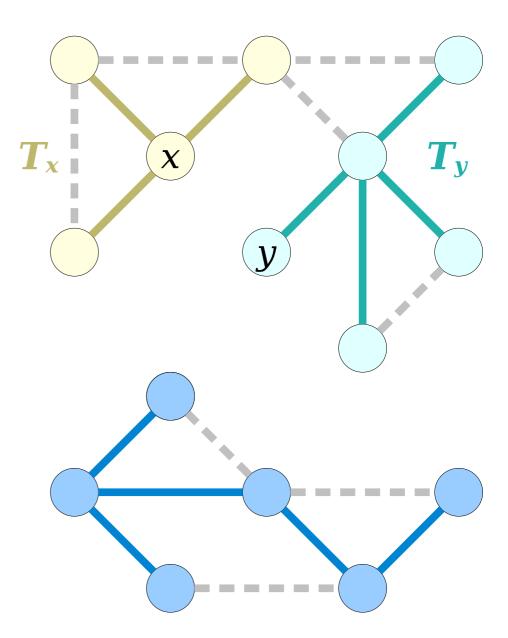
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- We need to search for an auxiliary edge that could reconnect T_x and T_y .
- **Observation:** Auxiliary edges with one endpoint in T_x either run between T_x and itself or between T_x and T_y .



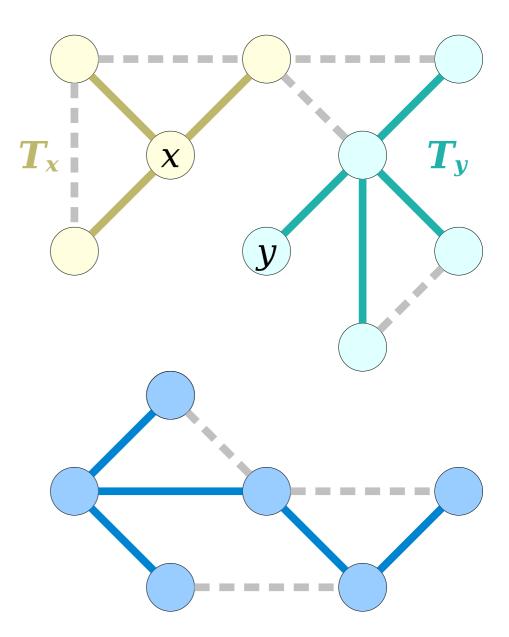
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Why? Answer at

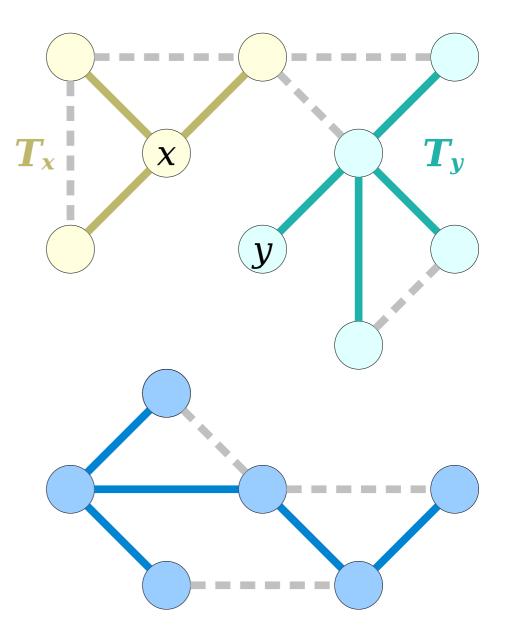
https://pollev.com/cs166spr23



- Suppose we cut the tree edge xy, splitting a tree T into T_x and T_y .
- We need to search for an auxiliary edge that could reconnect T_x and T_y .
- **Observation:** Auxiliary edges with one endpoint in T_x either run between T_x and itself or between T_x and T_y .
- **Goal:** Organize auxiliary edges so we can find just those incident to T_x .



- Fortunately, we've already seen a way to do this!
- **Recall:** Euler tour trees can be augmented so that we can
 - attach packets to nodes, and
 - quickly execute queries of the form "find and remove some packet in this tree."
- Replace "packet" with "auxiliary edge" and we can find an auxiliary edge with one endpoint in T_x in amortized time $O(\log n)$.
- **Intuition:** We can "quickly" find an edge touching T_x . This will not be our bottleneck.



The Challenges

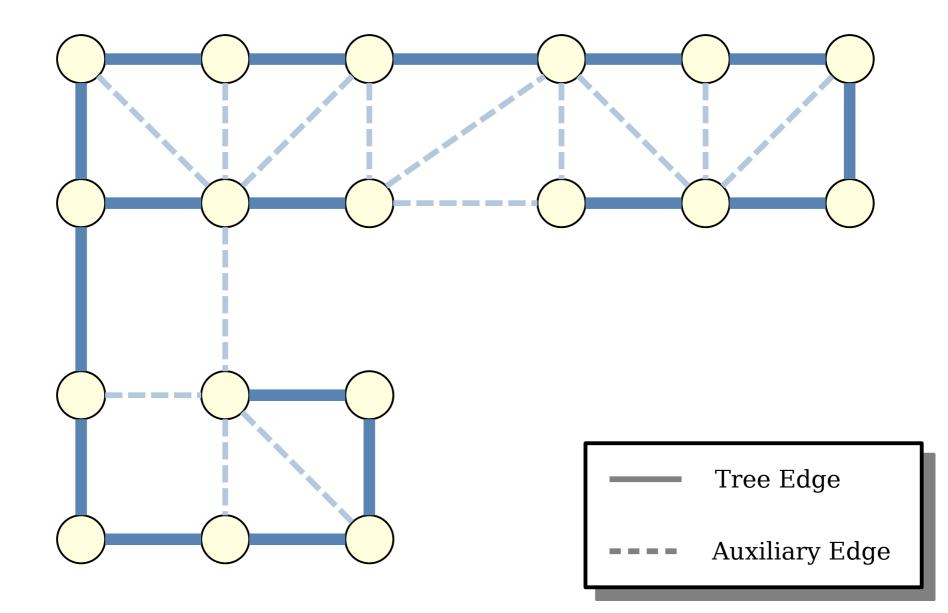
- **Goal:** After disconnecting a tree T into two trees T_1 and T_2 , search for an edge that will reconnect it.
- **Challenge 1:** Avoid scanning edges that don't have endpoints in either T_1 or T_2 .
- **Challenge 2:** Avoid rescanning edges that, based on past cuts, couldn't possibly work.

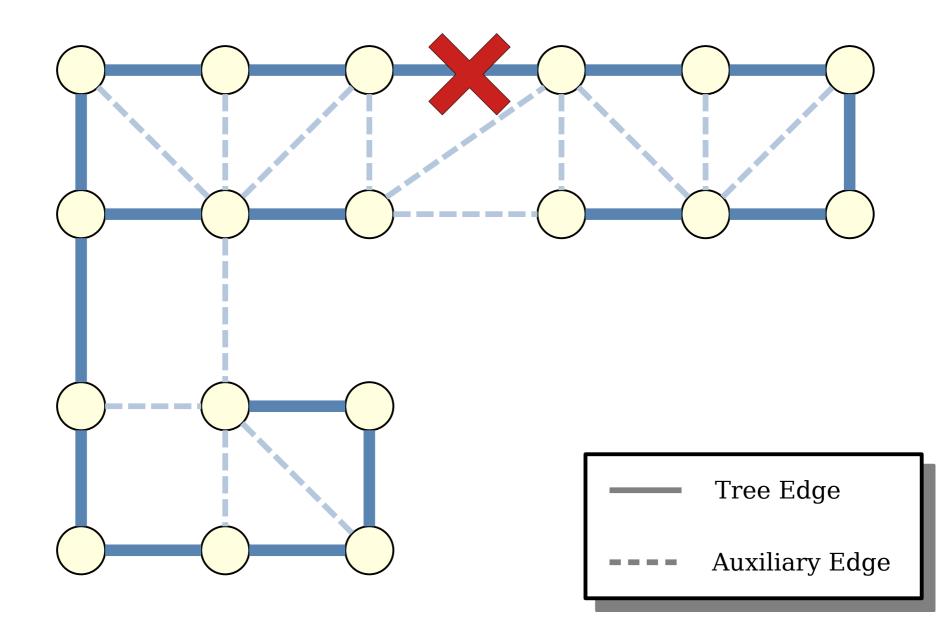
The Challenges

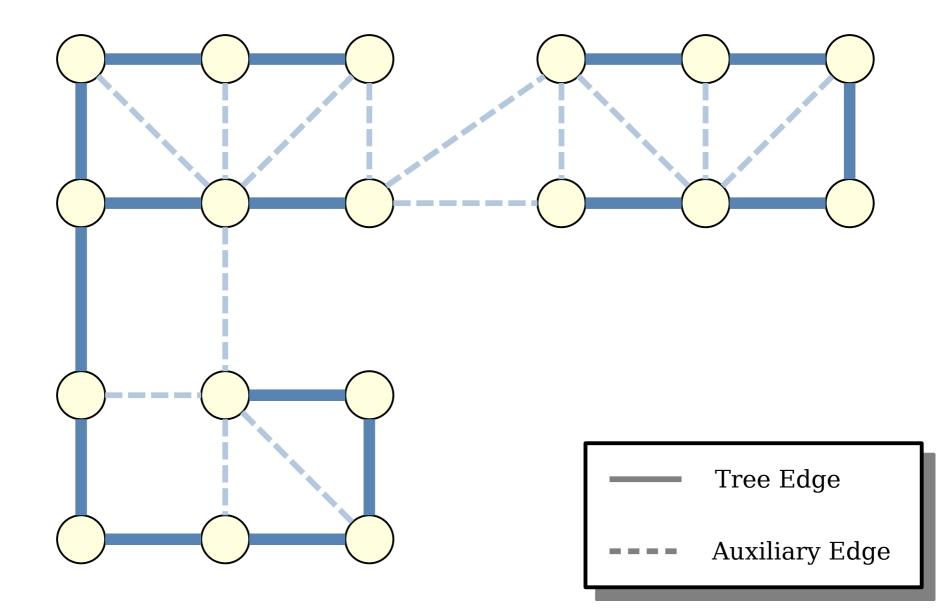
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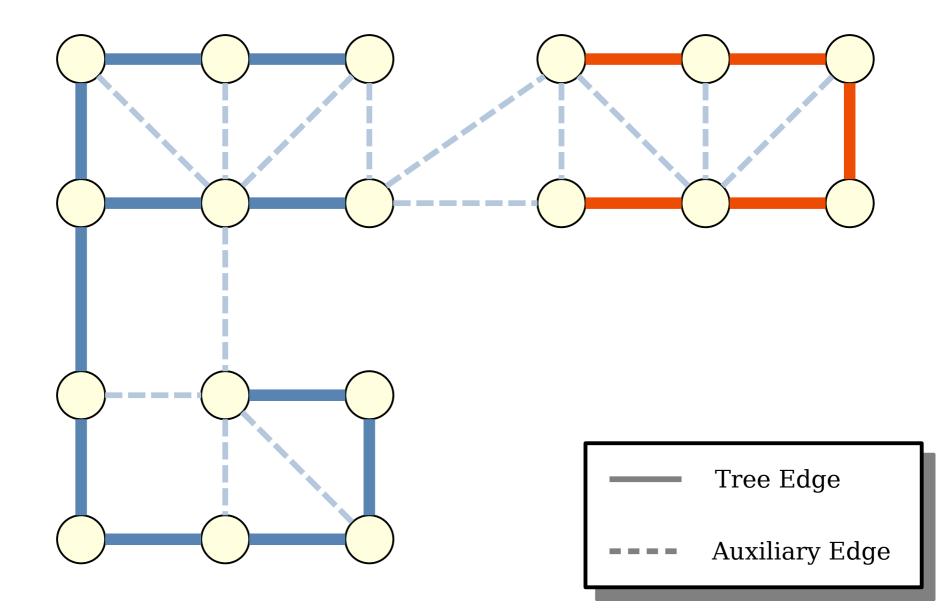
Challenge 1: Avoid scanning edges that don't have endpoints in either T_1 or T_2 .

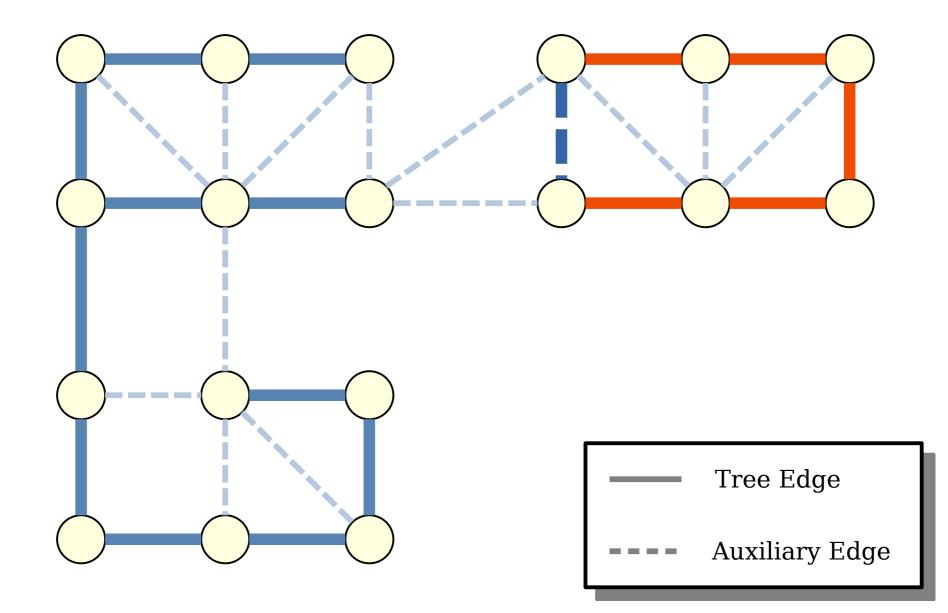
• **Challenge 2:** Avoid rescanning edges that, based on past cuts, couldn't possibly work.

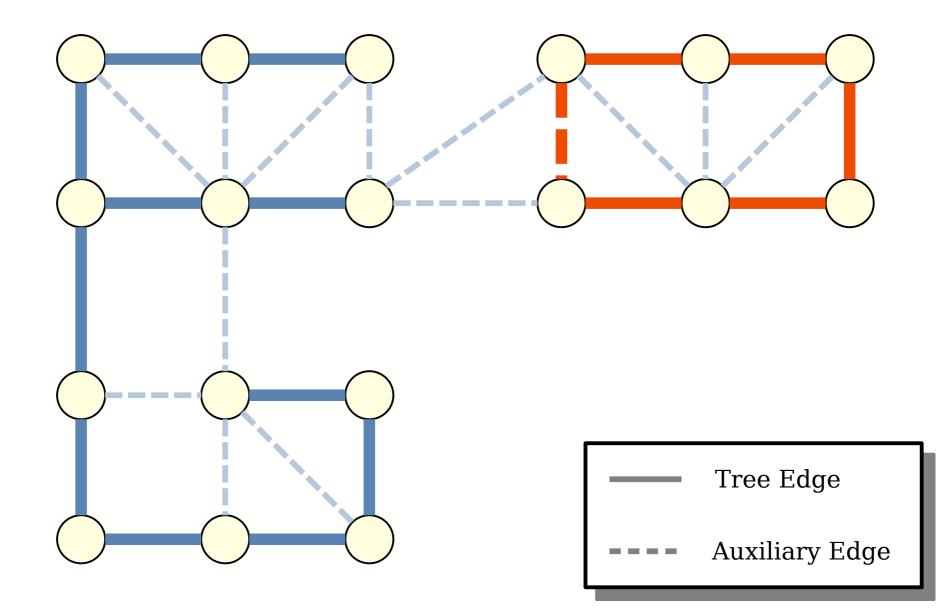


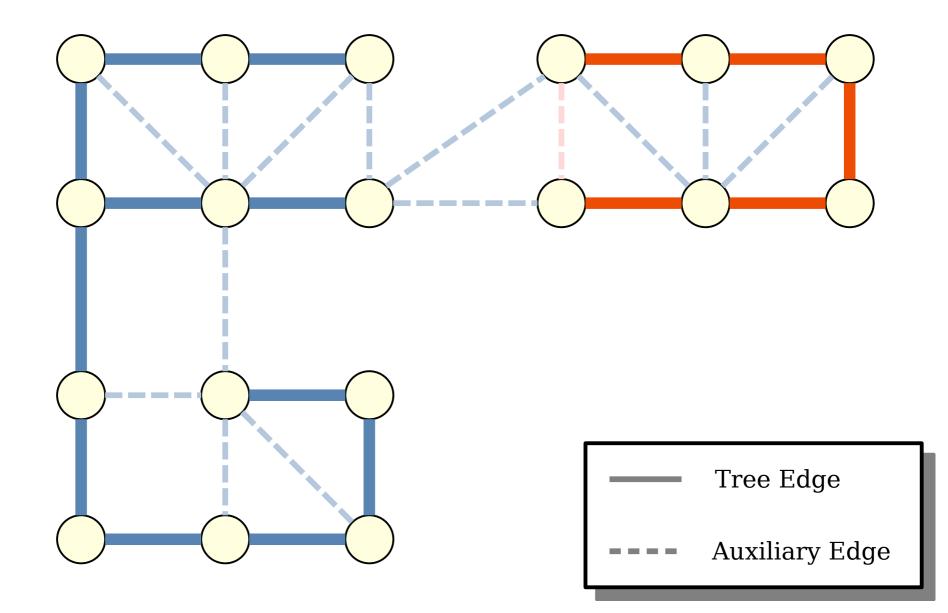


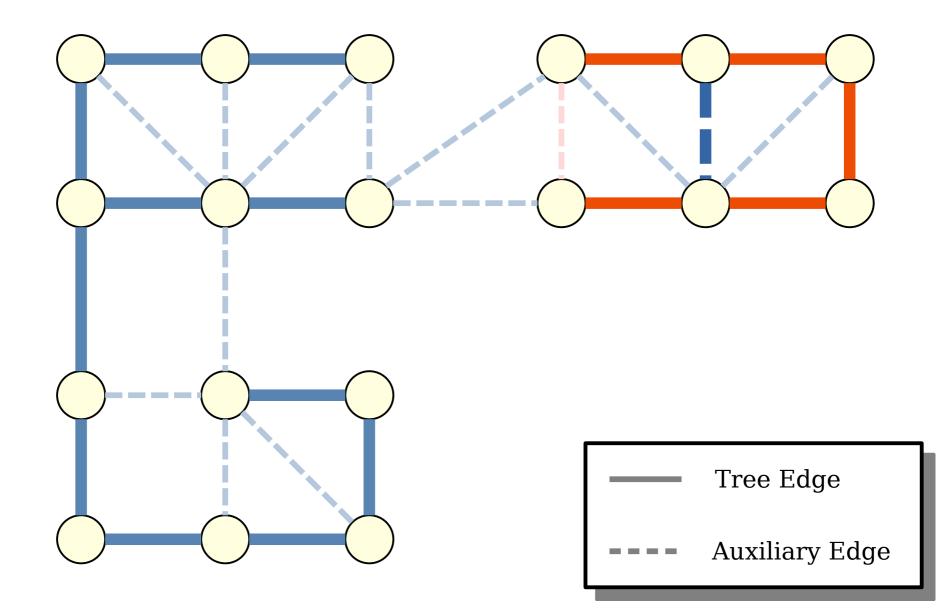


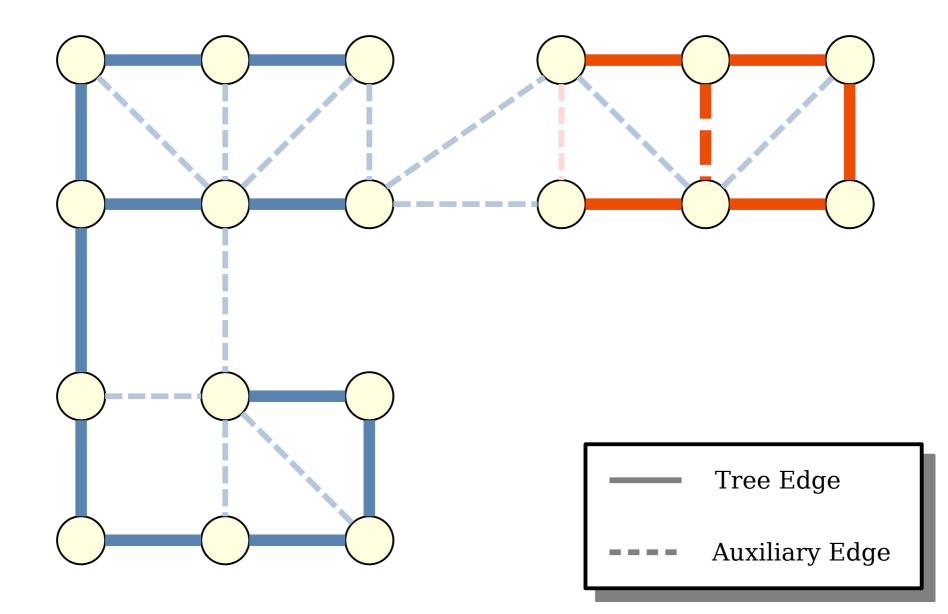


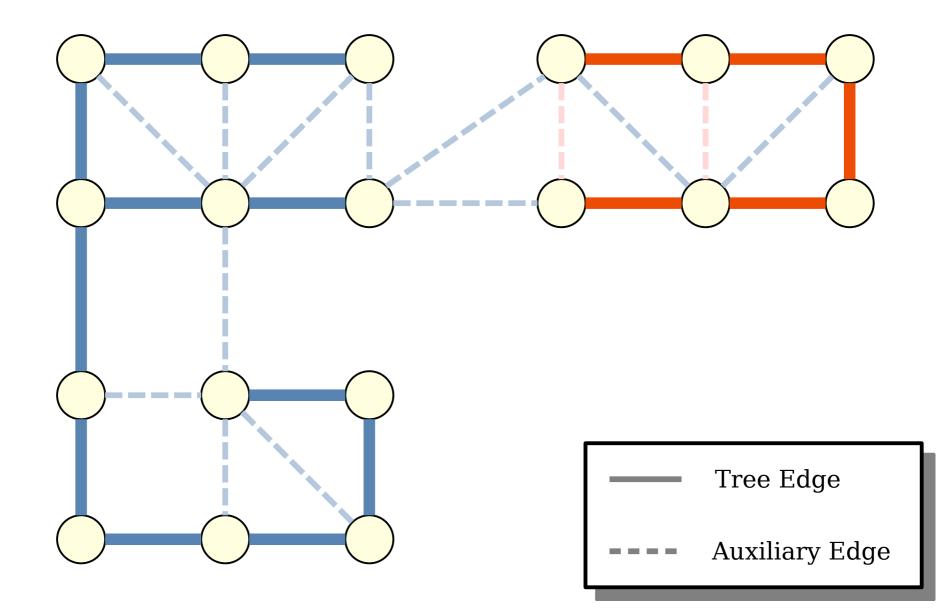


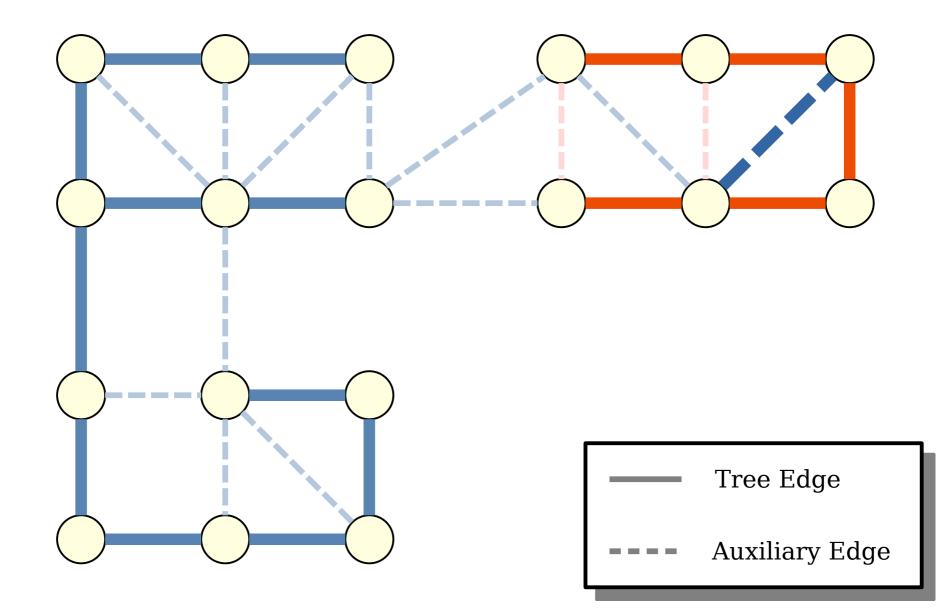


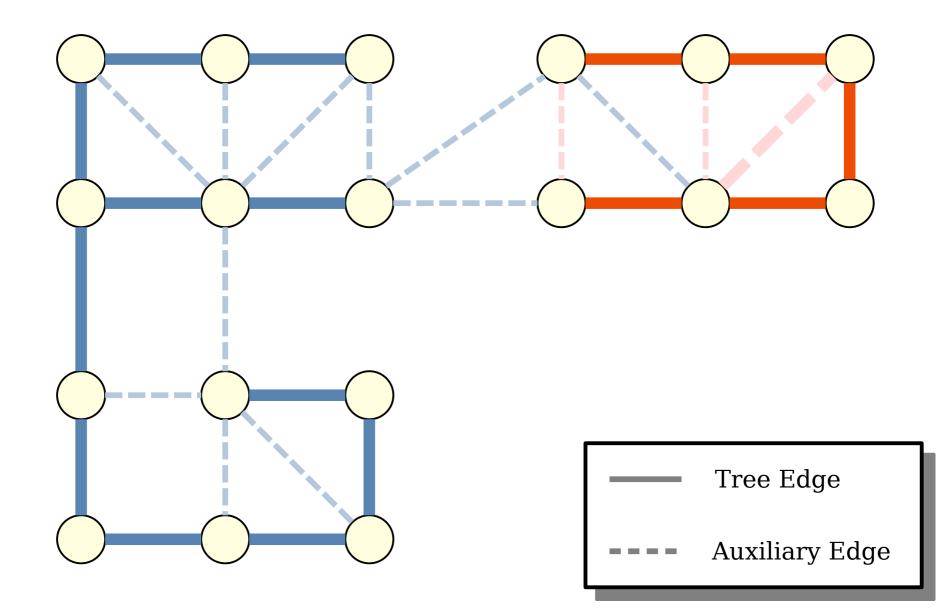


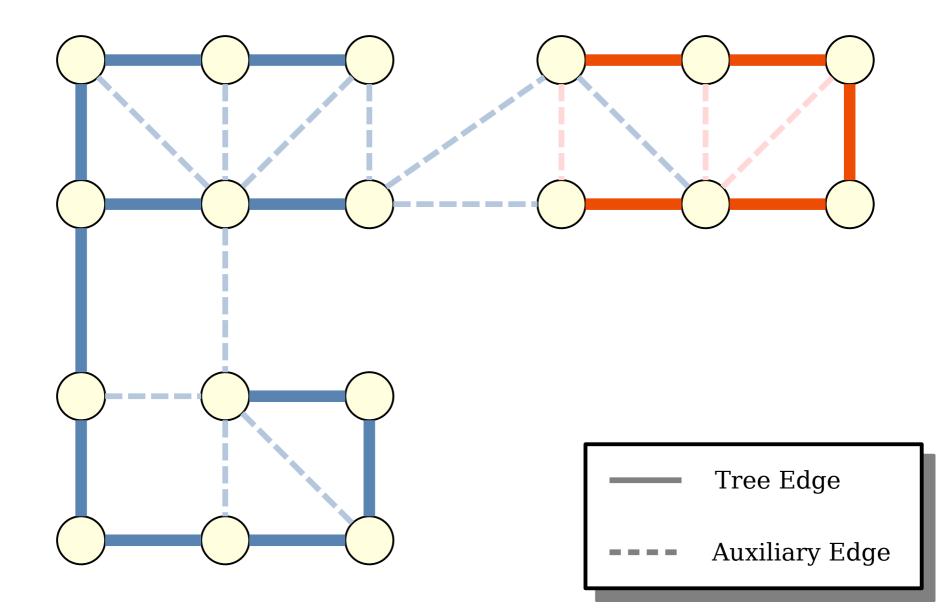


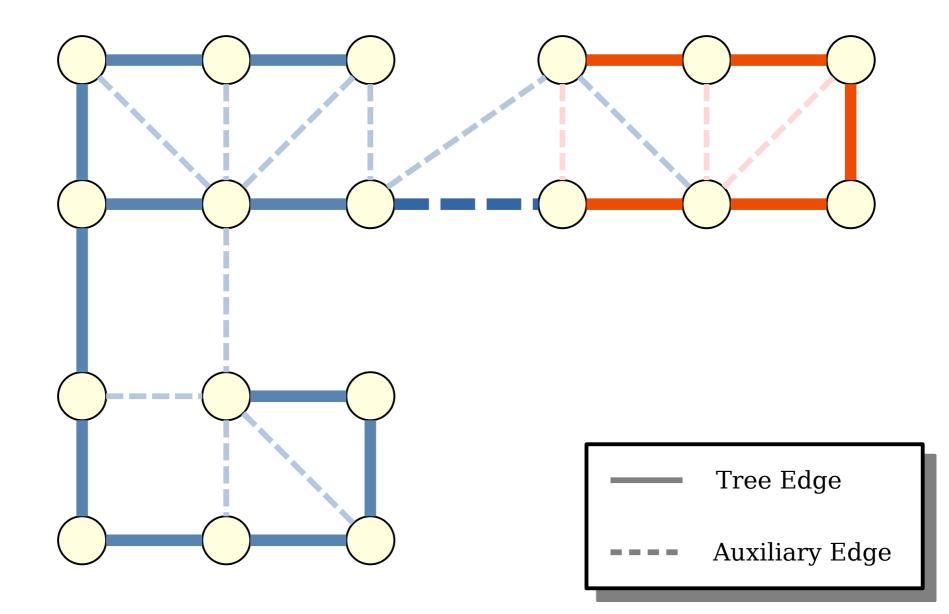


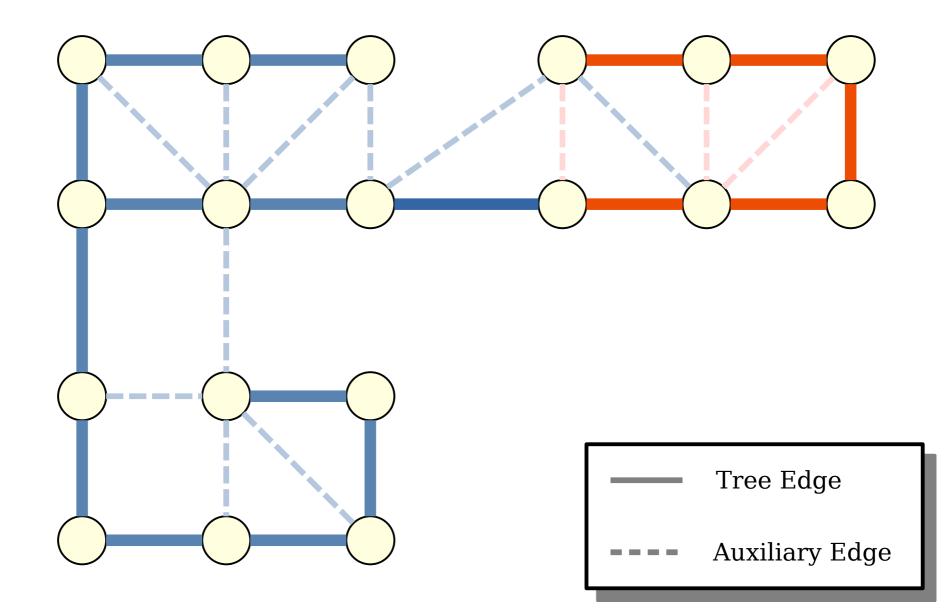


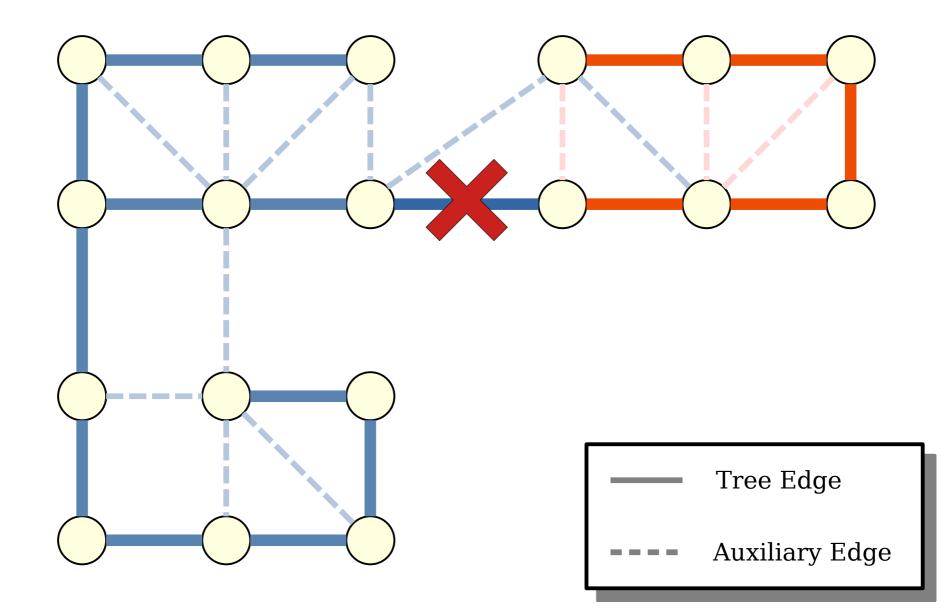


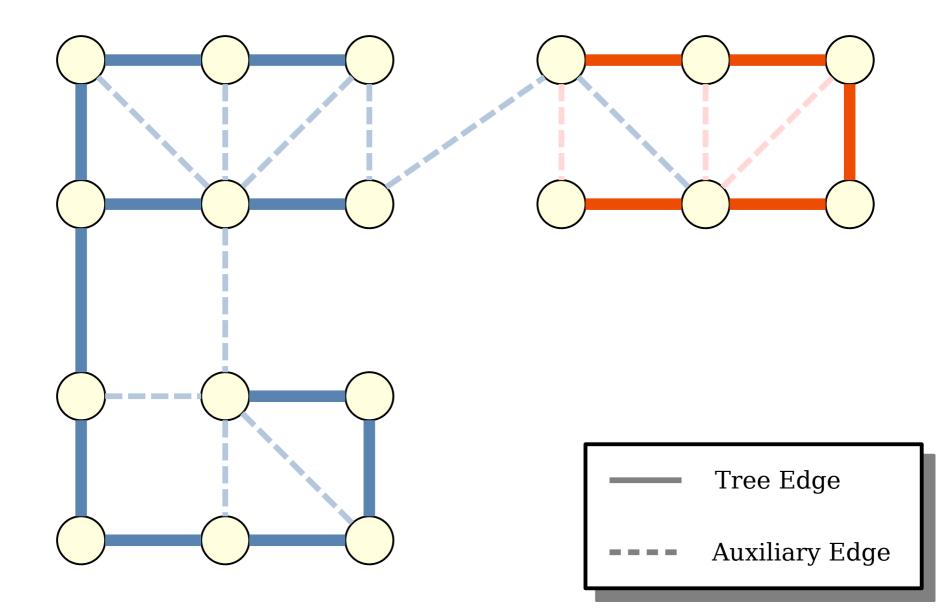


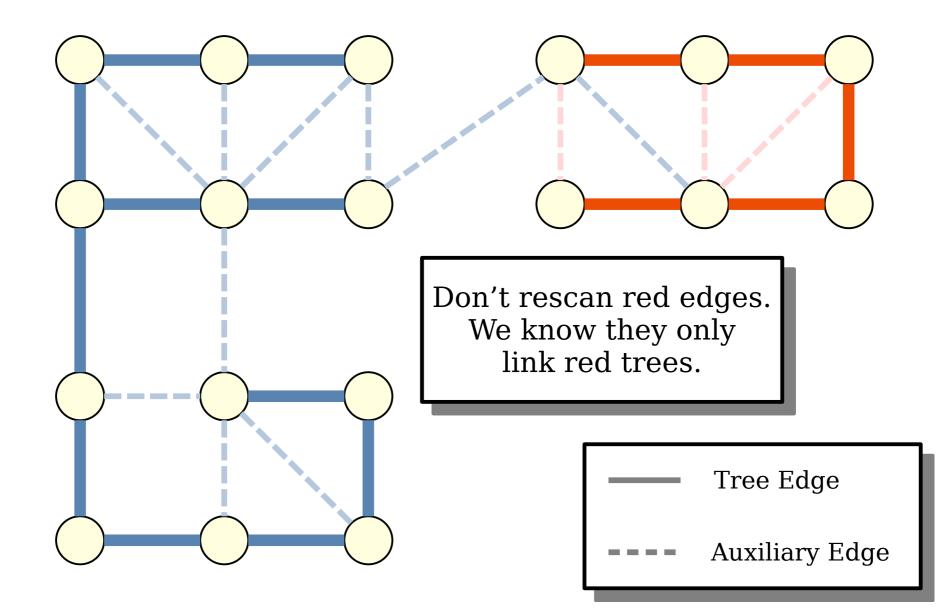


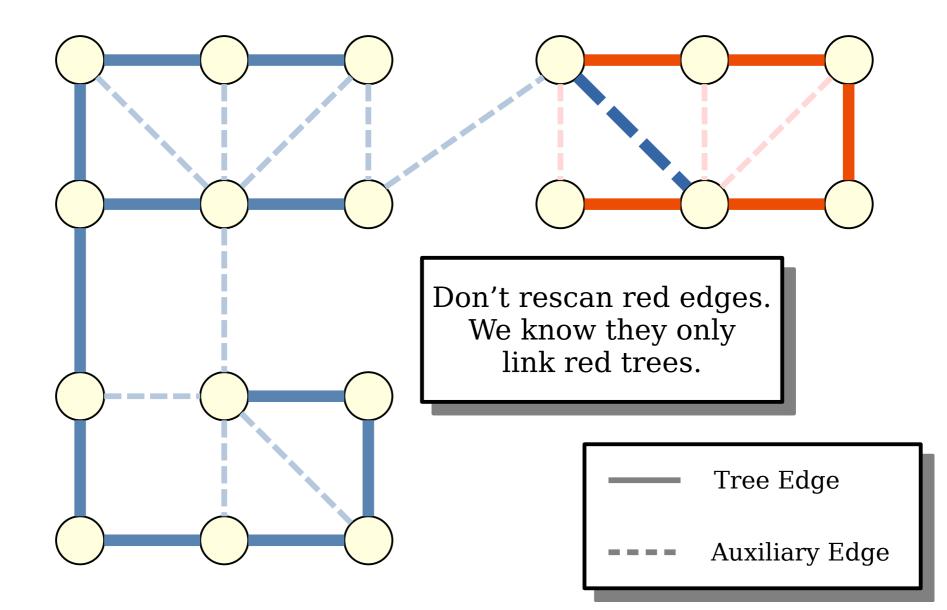


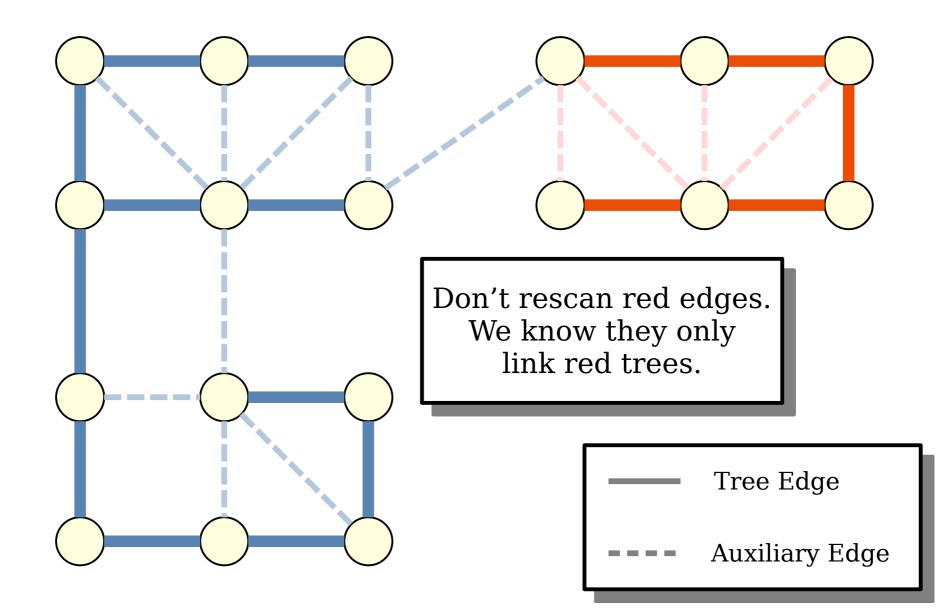


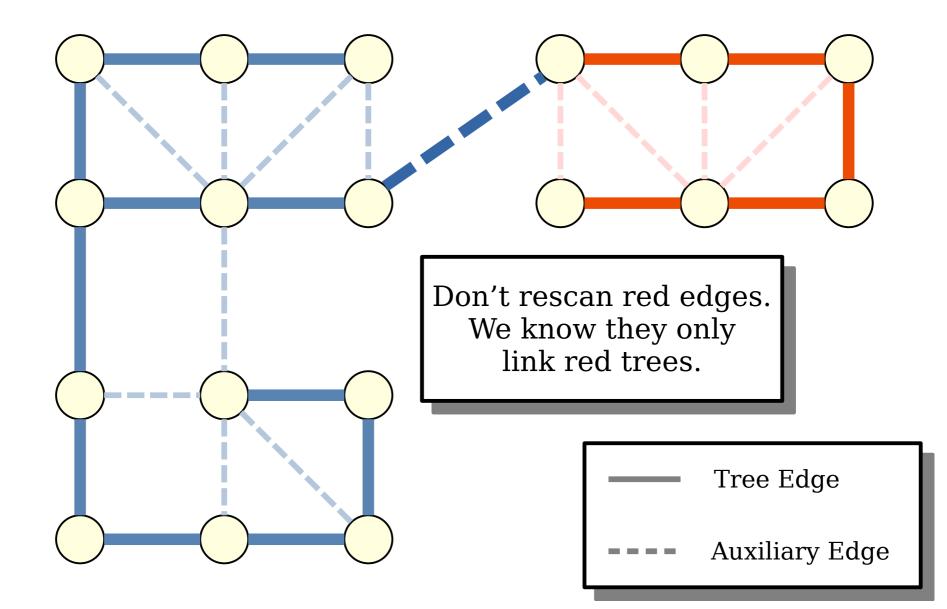


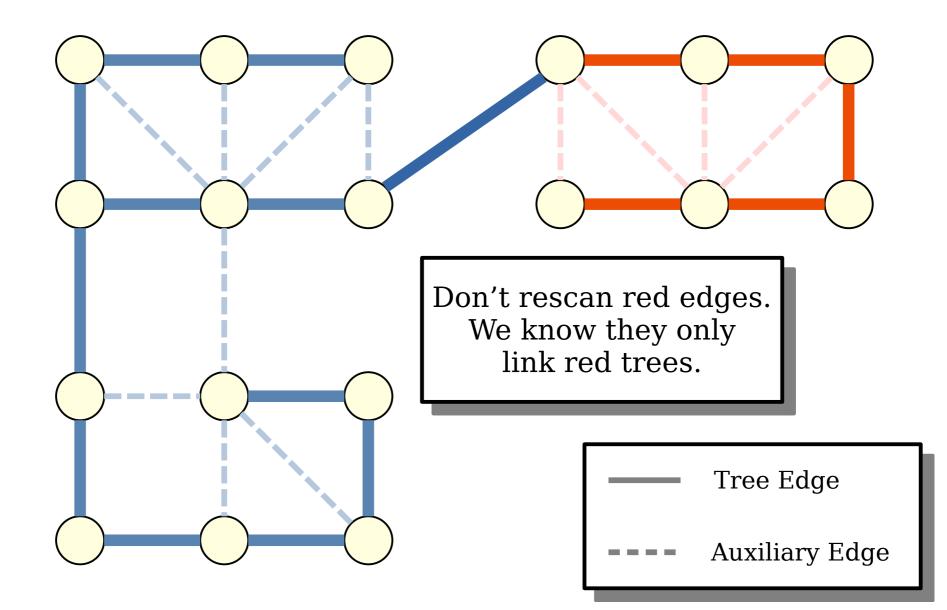


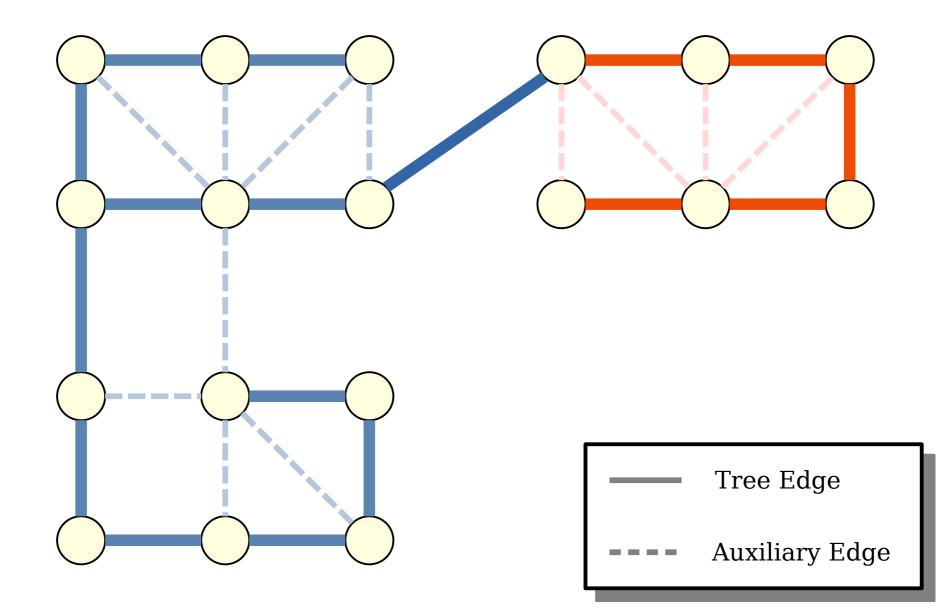


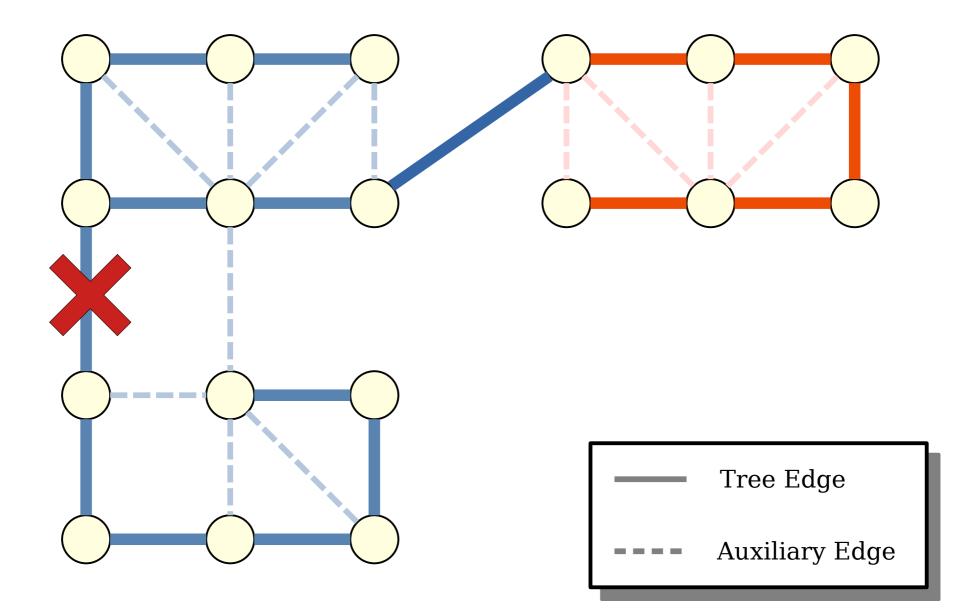


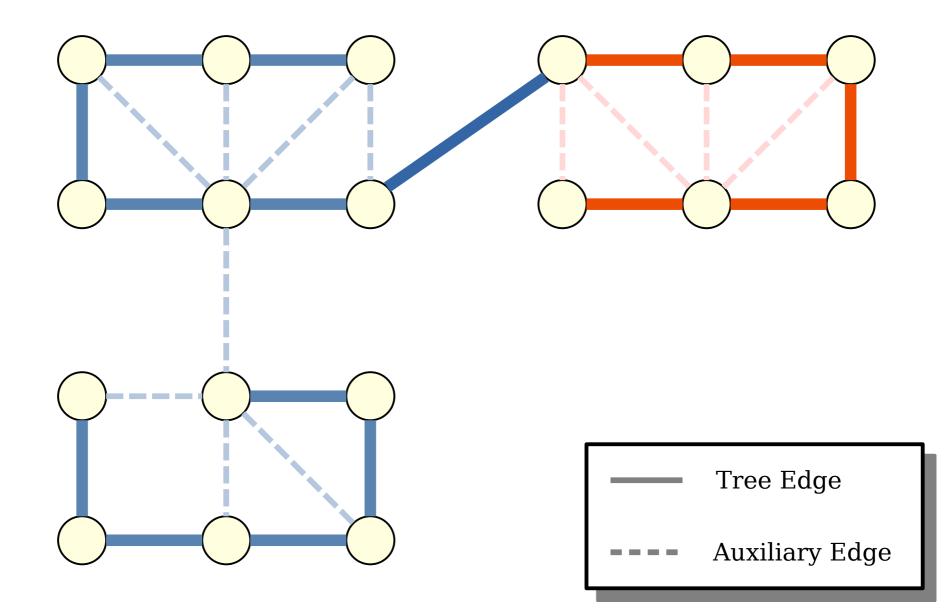


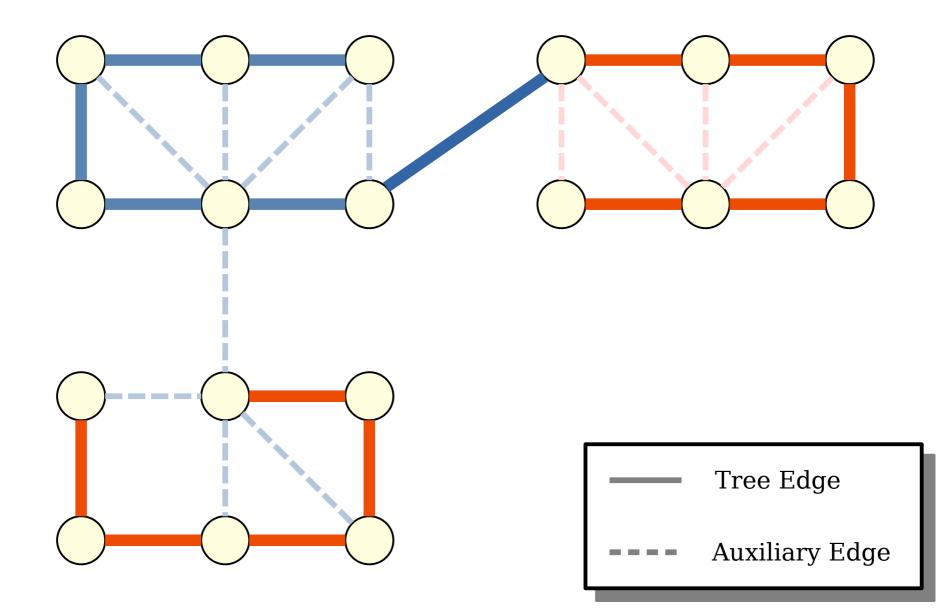


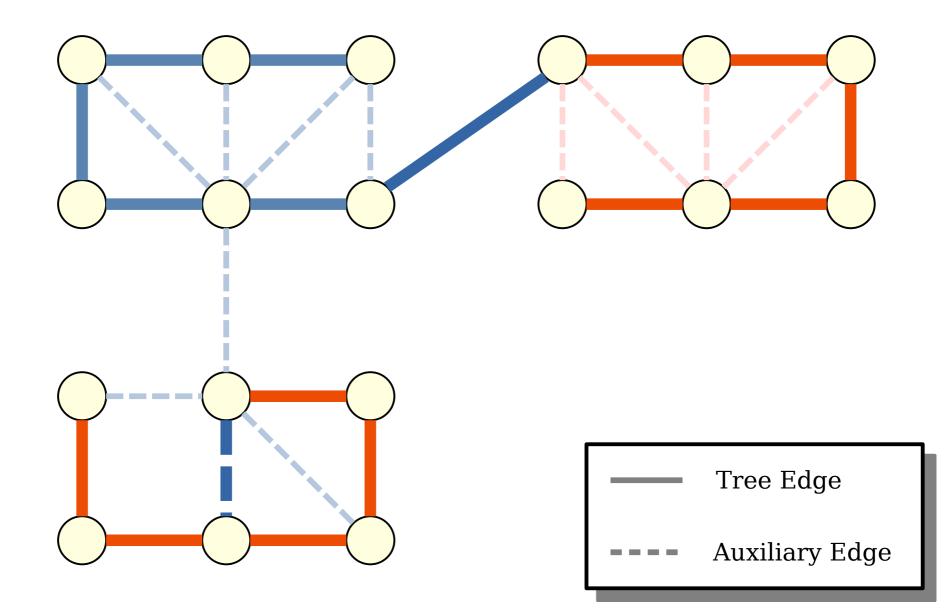


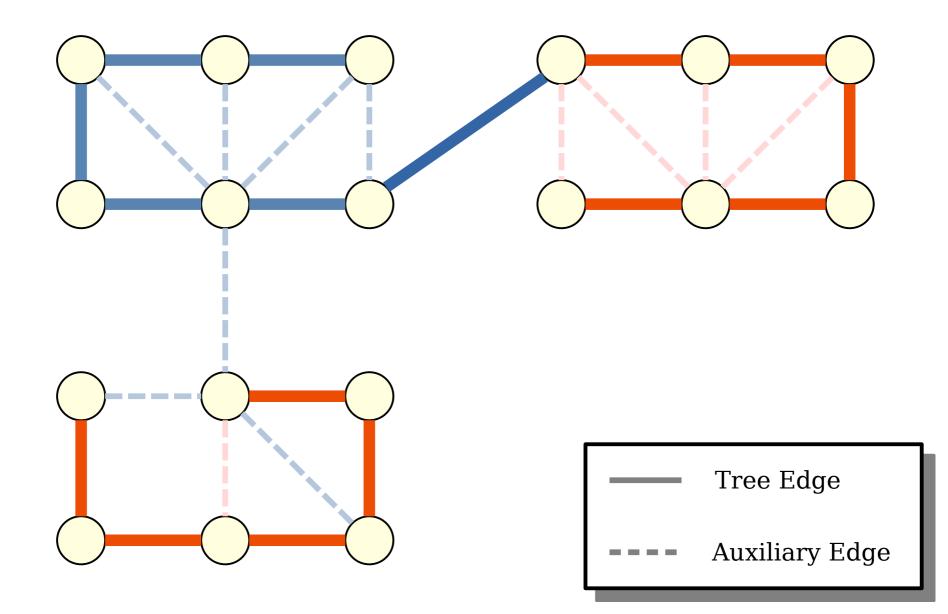


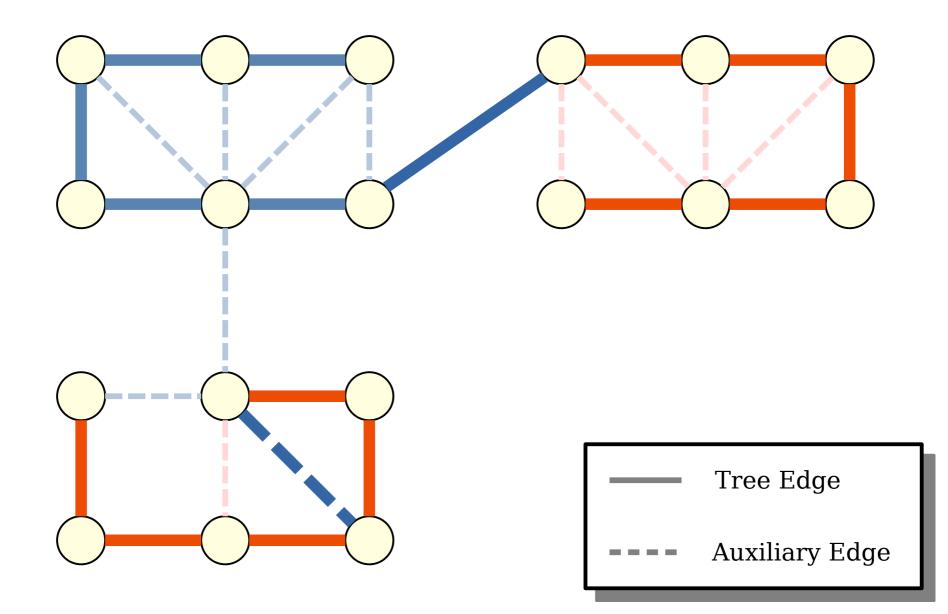


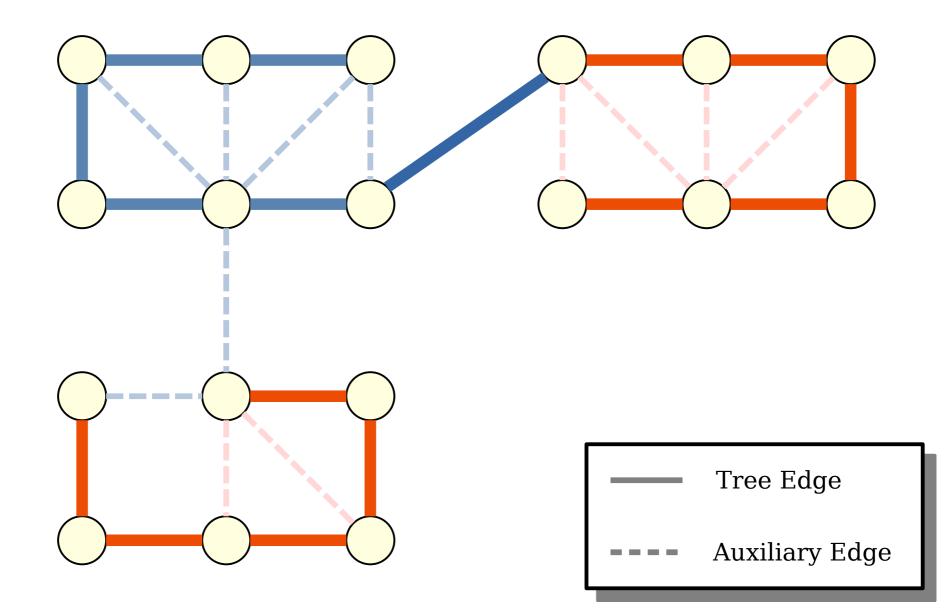


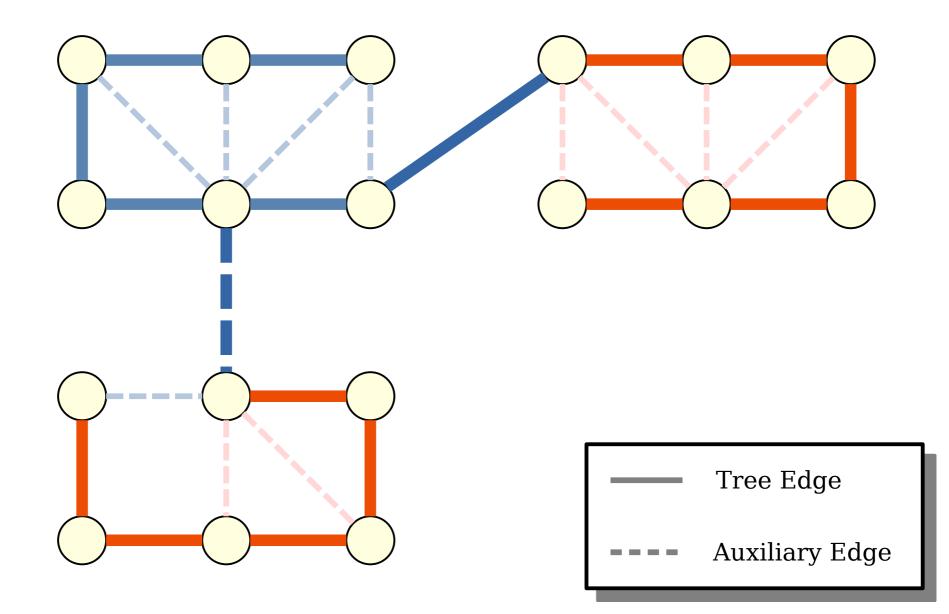


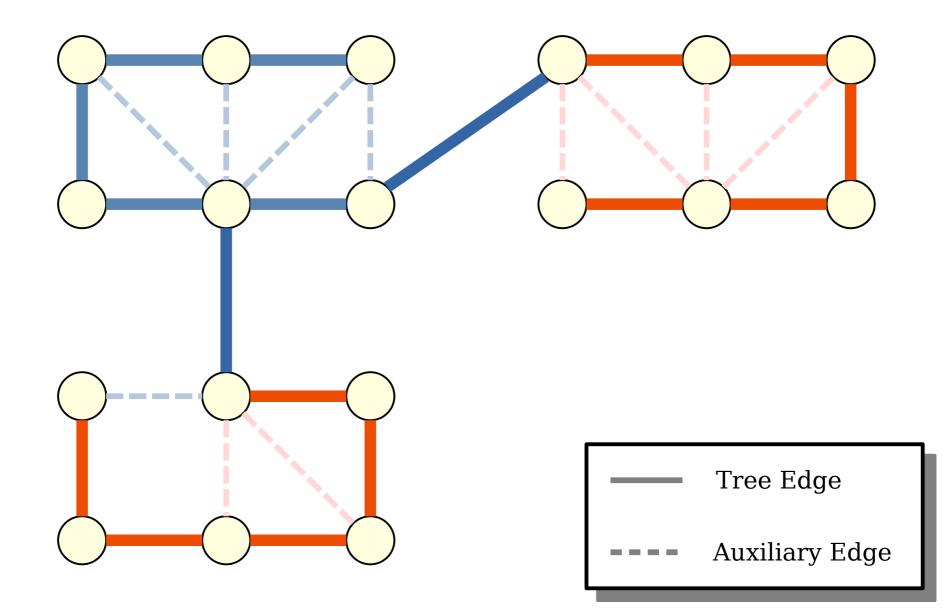


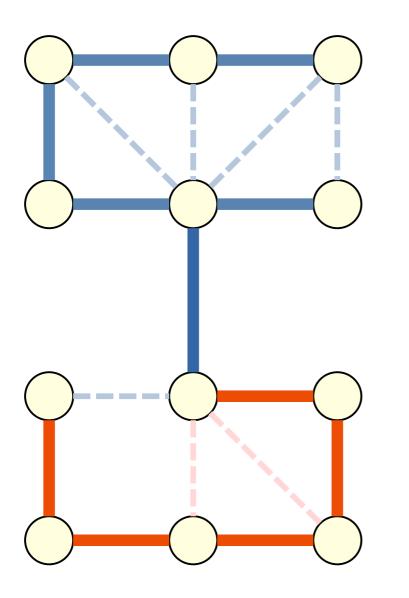


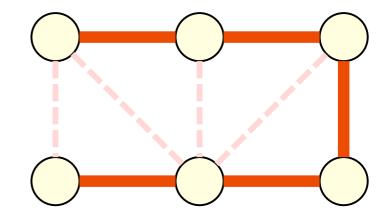


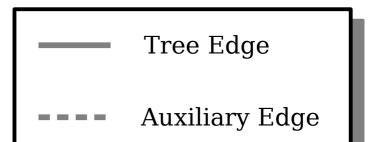


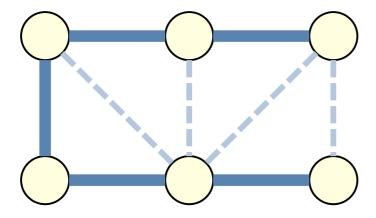


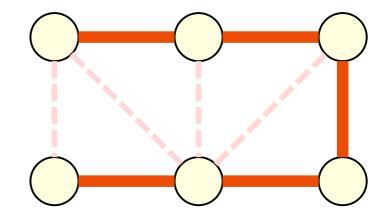


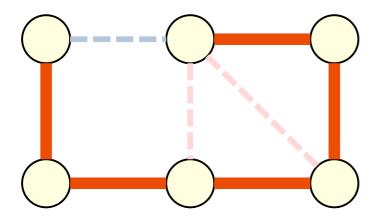


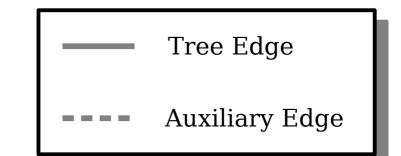


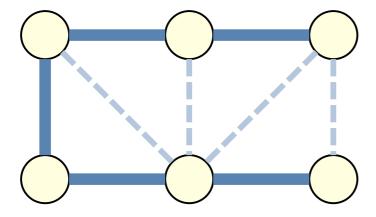


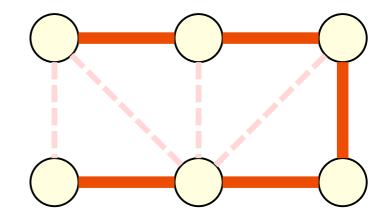


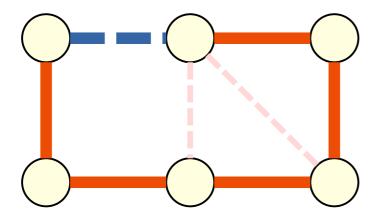


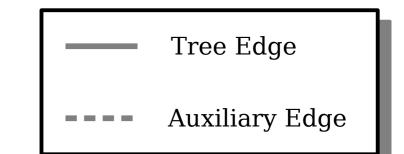


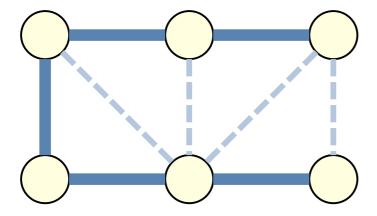


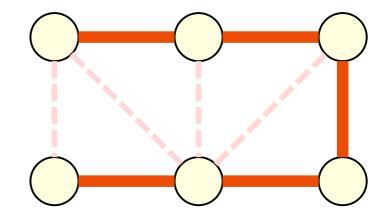


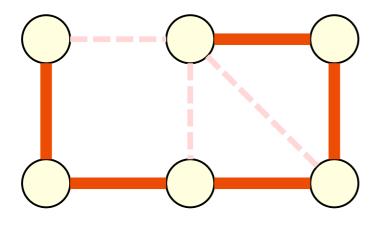


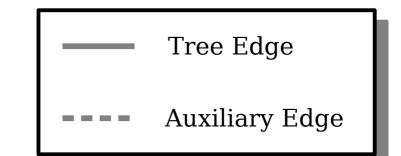


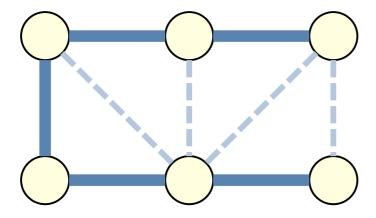


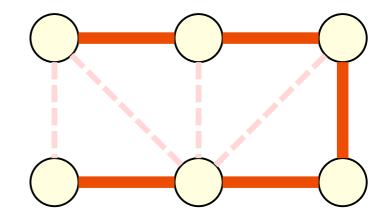


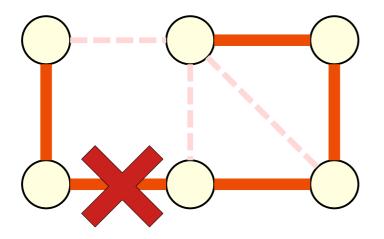


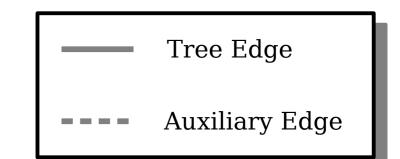


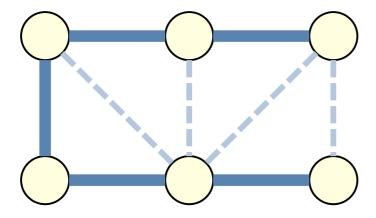


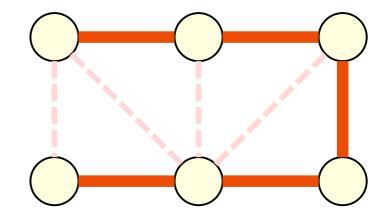


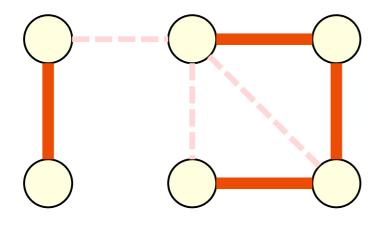


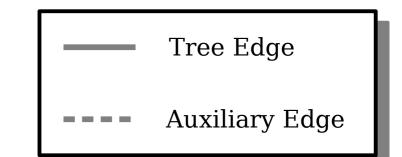


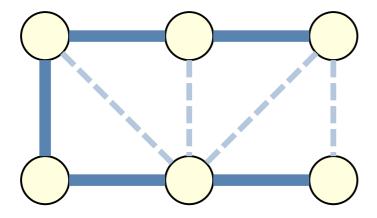


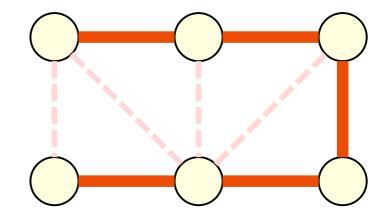


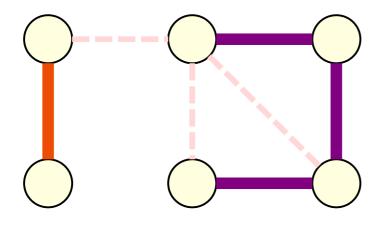


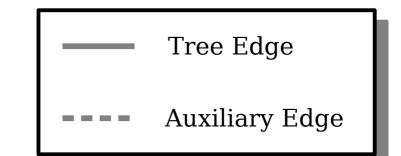


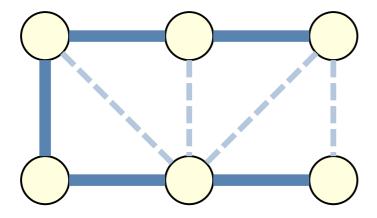


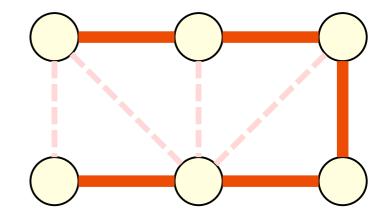


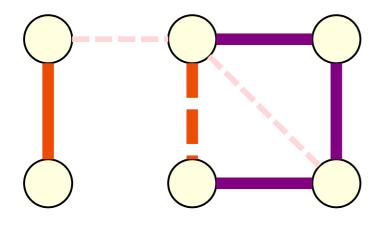


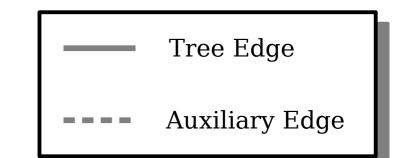


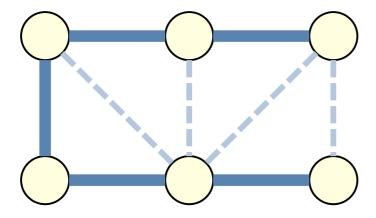


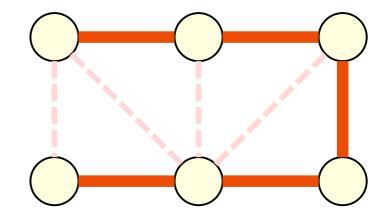


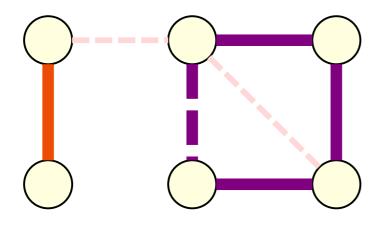


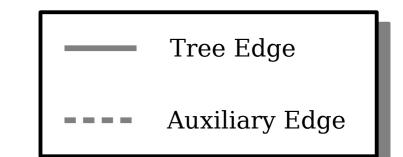


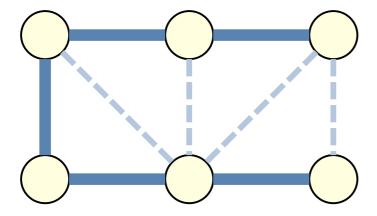


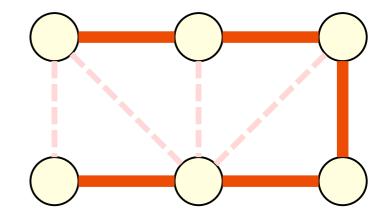


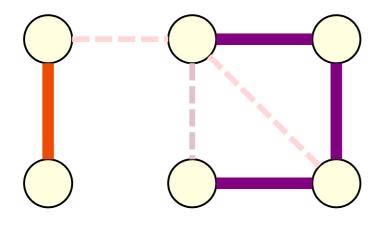


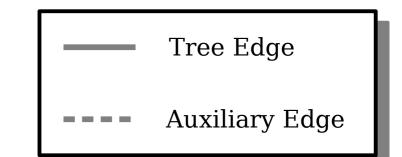


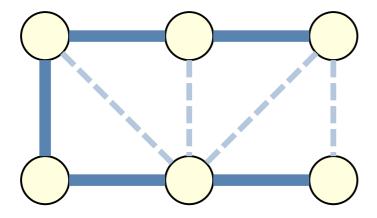


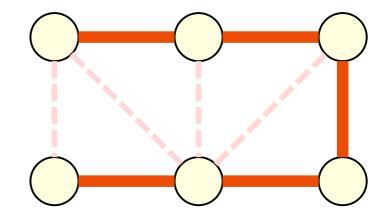


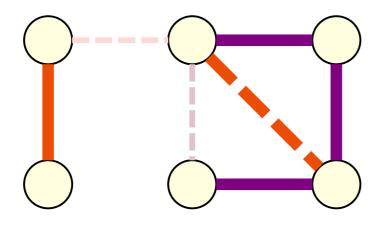


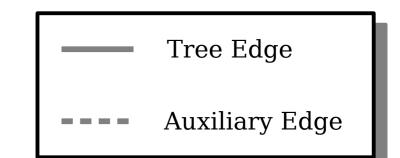


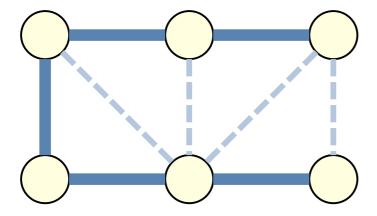


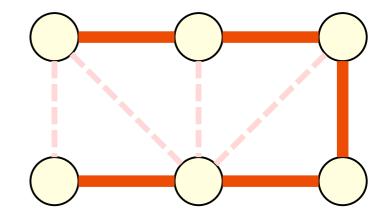


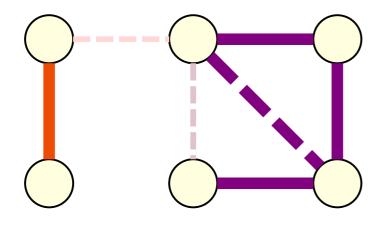


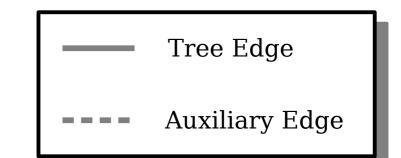


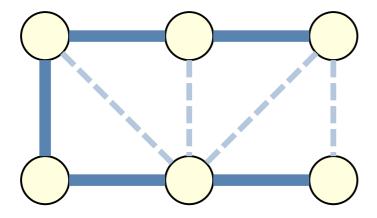


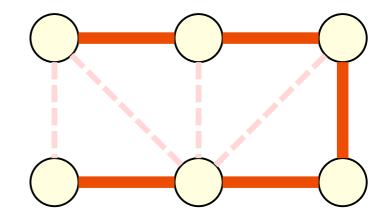


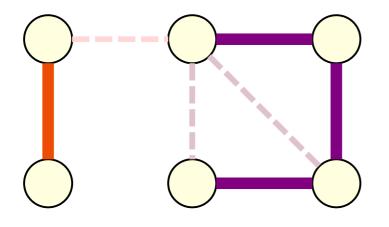


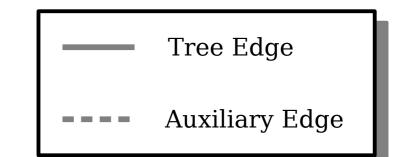


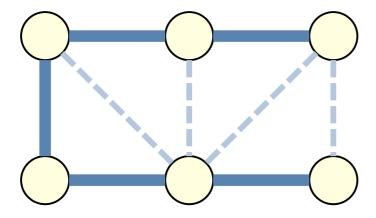


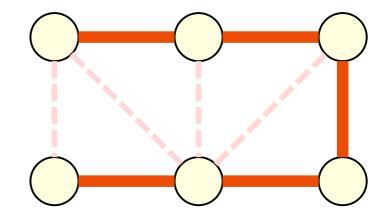


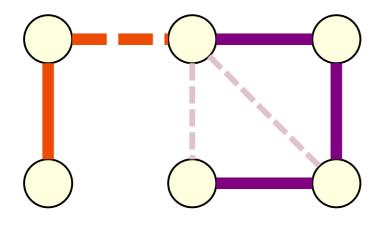


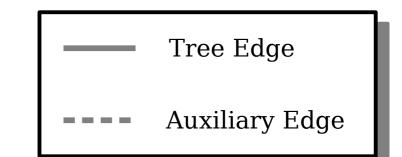


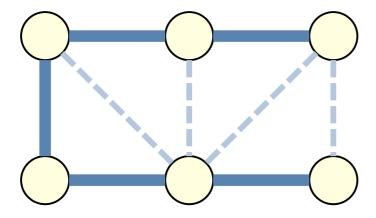


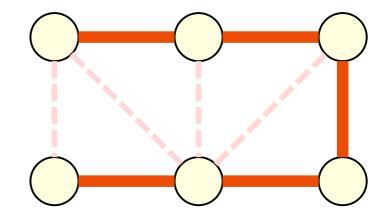


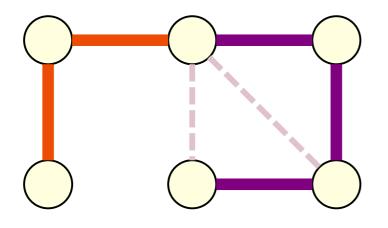


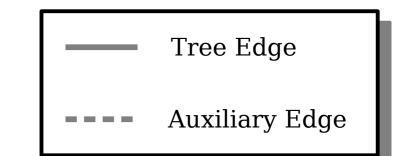








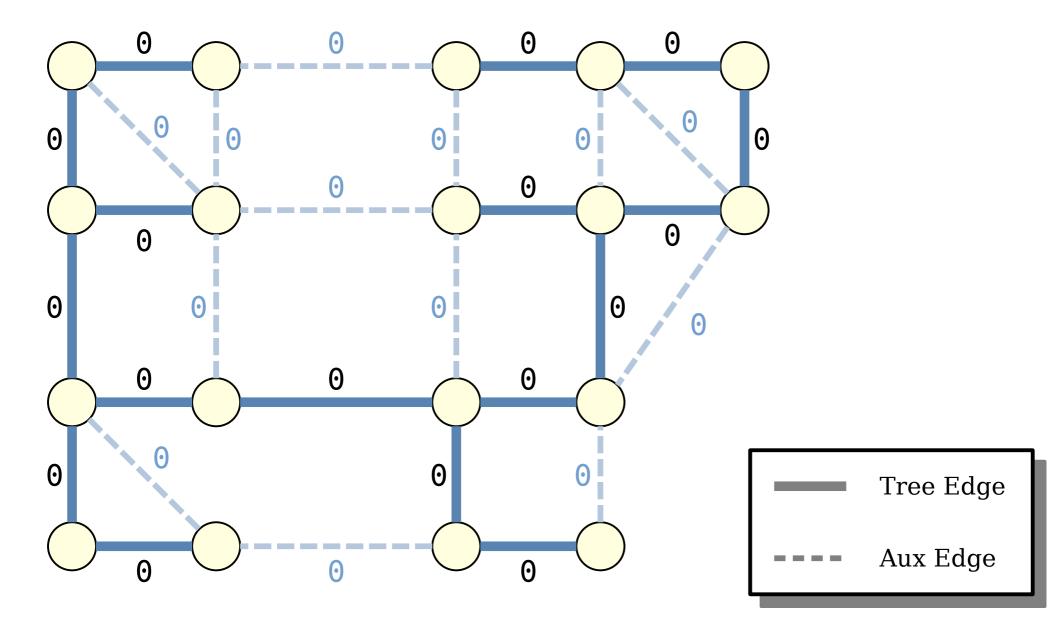


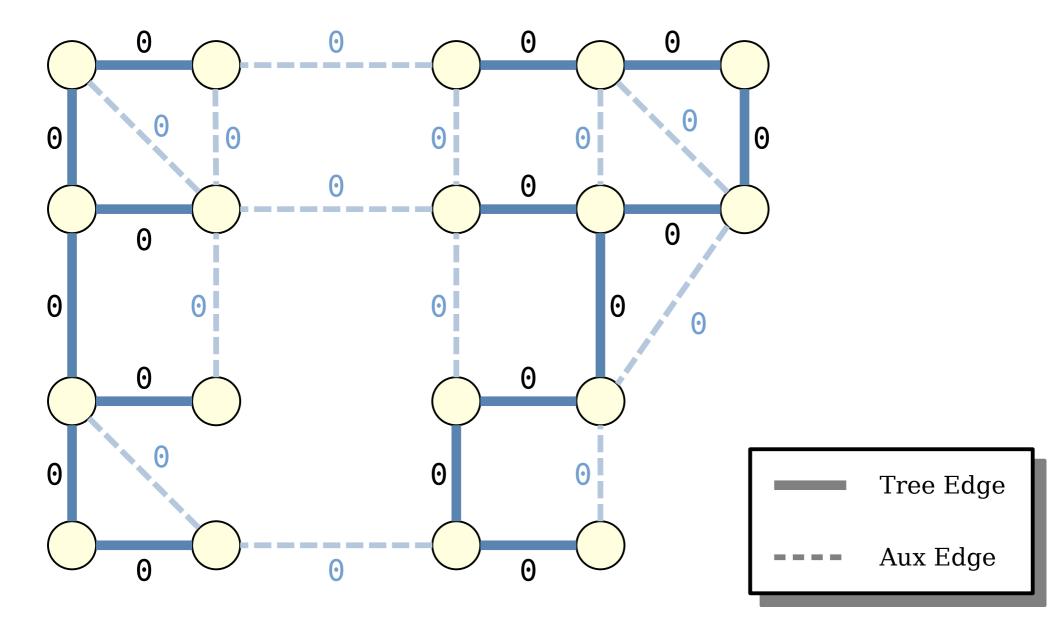


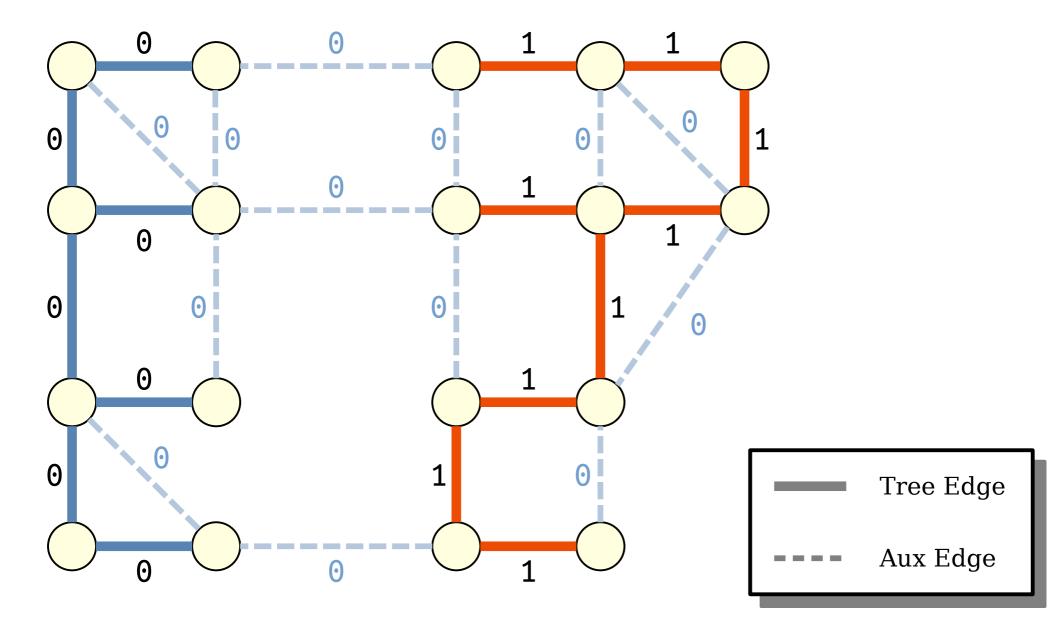
A Germ of an Idea

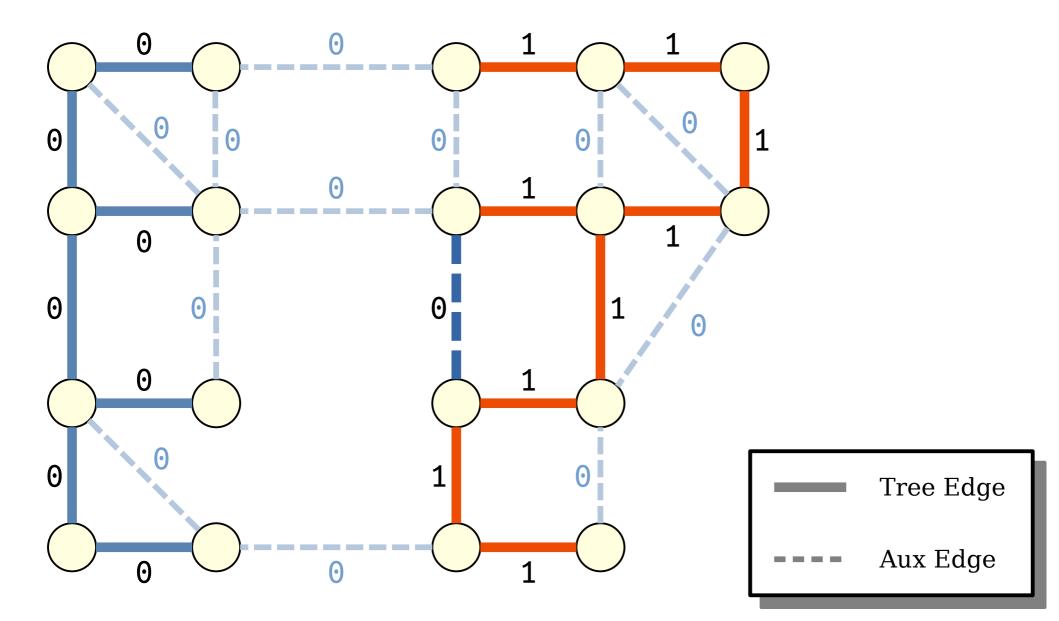
- Begin with all edges having the same color.
- When cutting a tree edge, assign edges in one of the two trees a new color.
- When an edge fails to reconnect a tree, give it the color of the tree it belongs to.
- When looking for a replacement edge, don't use edges that are the same color as the tree itself, since those can't work.

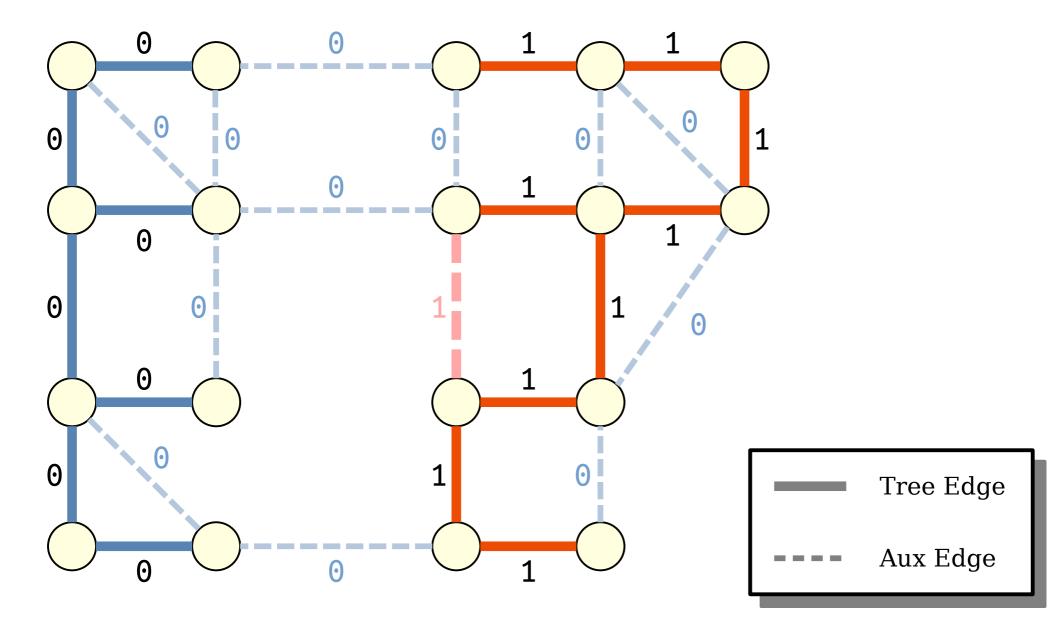
- **Idea:** Assign each edge a **level**, initially 0.
- Initial Proposal:
 - When cutting an edge at level l, pick one of the two resulting trees and raise all its level-l edges to level (l+1).
 - When looking for an edge to reconnect the tree, if an edge at level l fails to reconnect, raise it to level l+1.
- There are a lot of details we still need to work out, but this is a reasonable guess for a starting point.

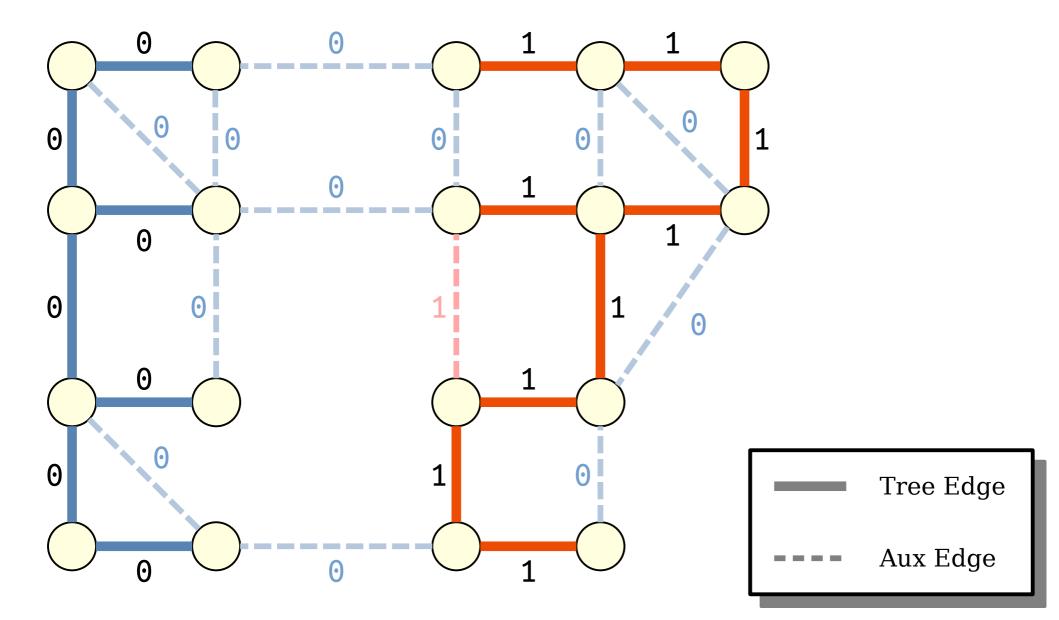


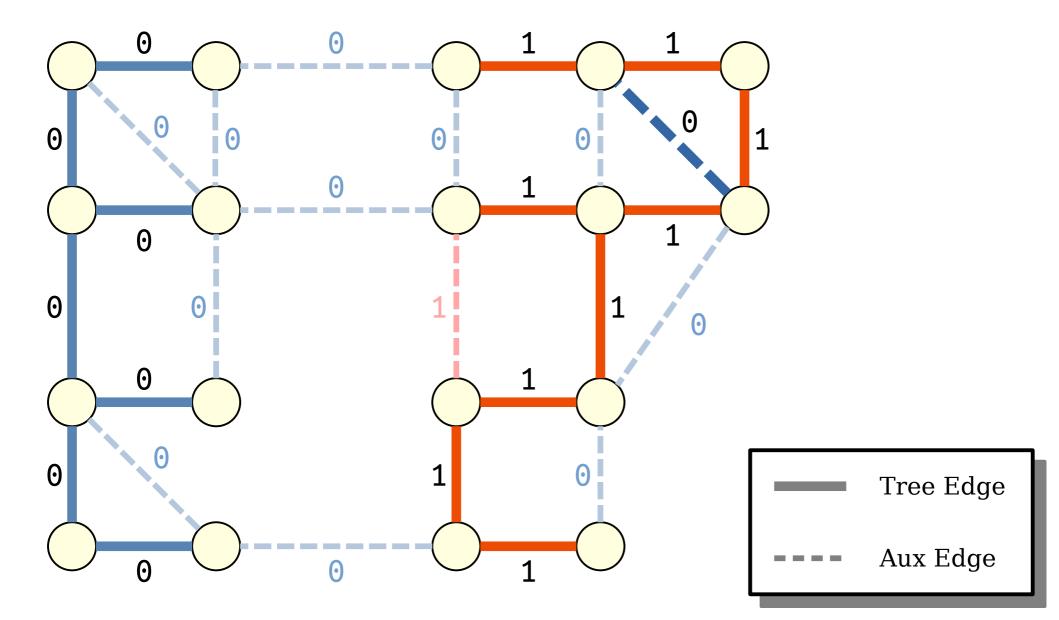


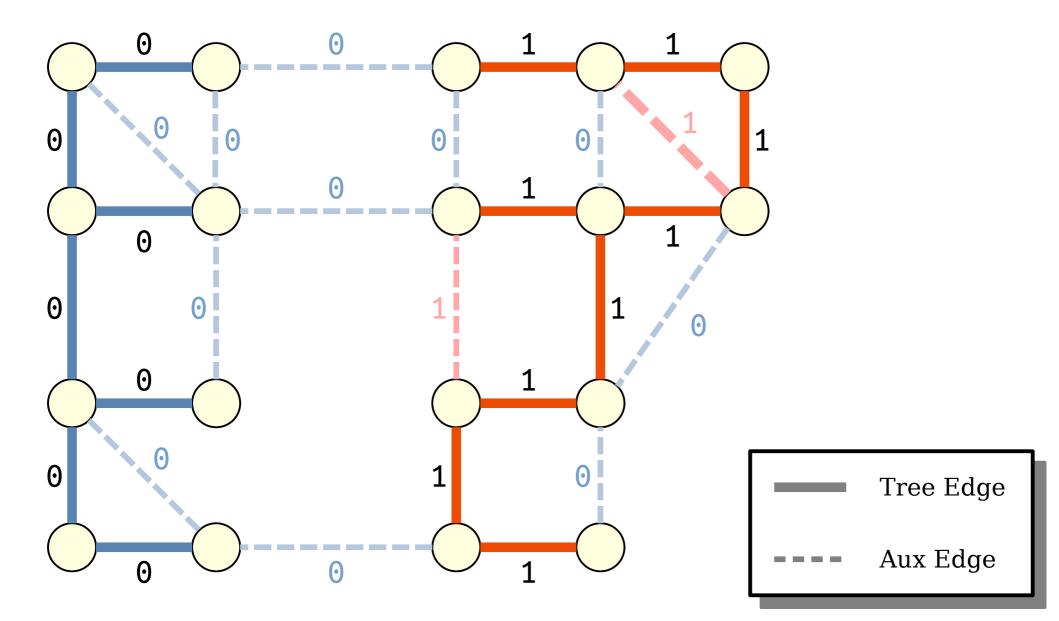


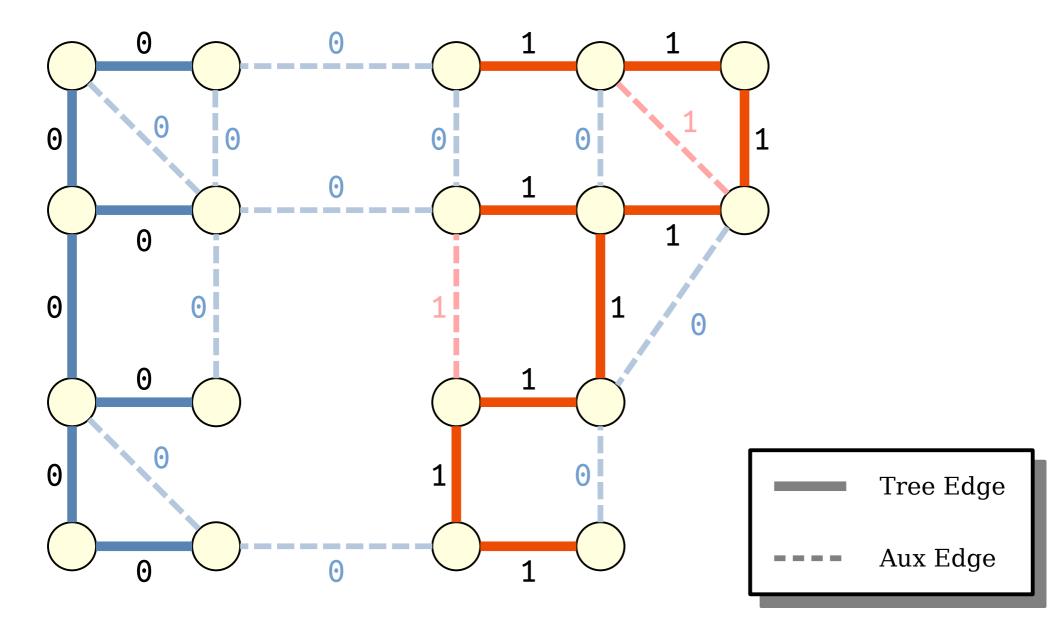


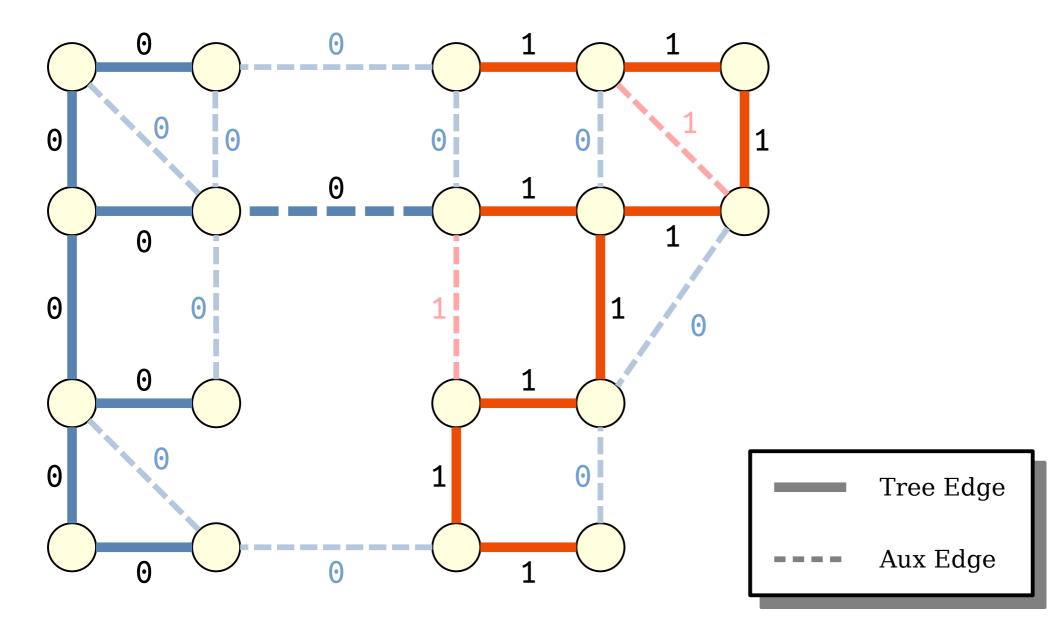


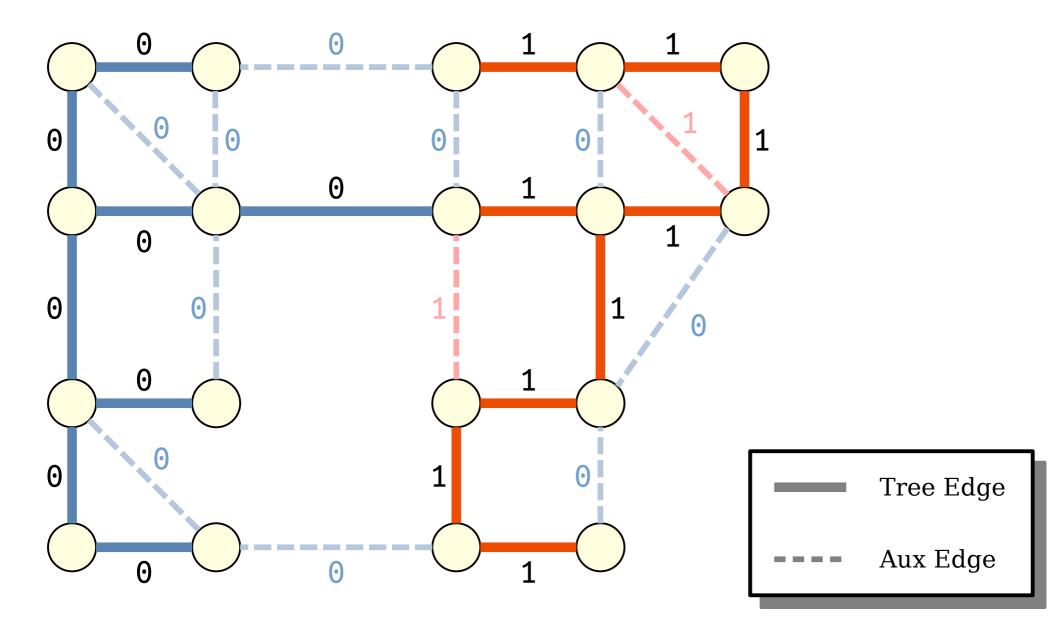


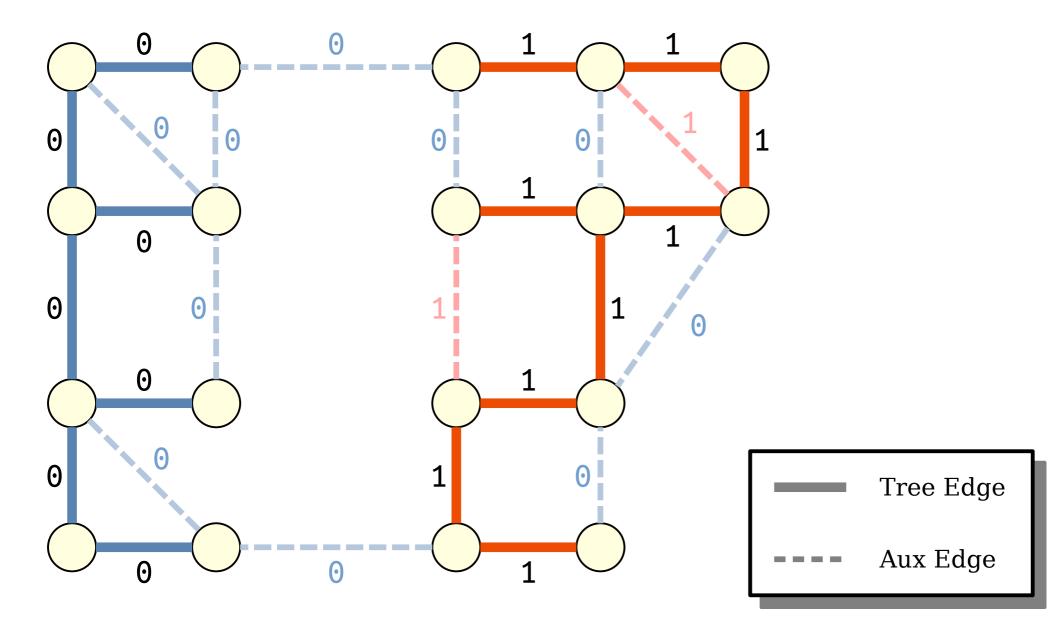


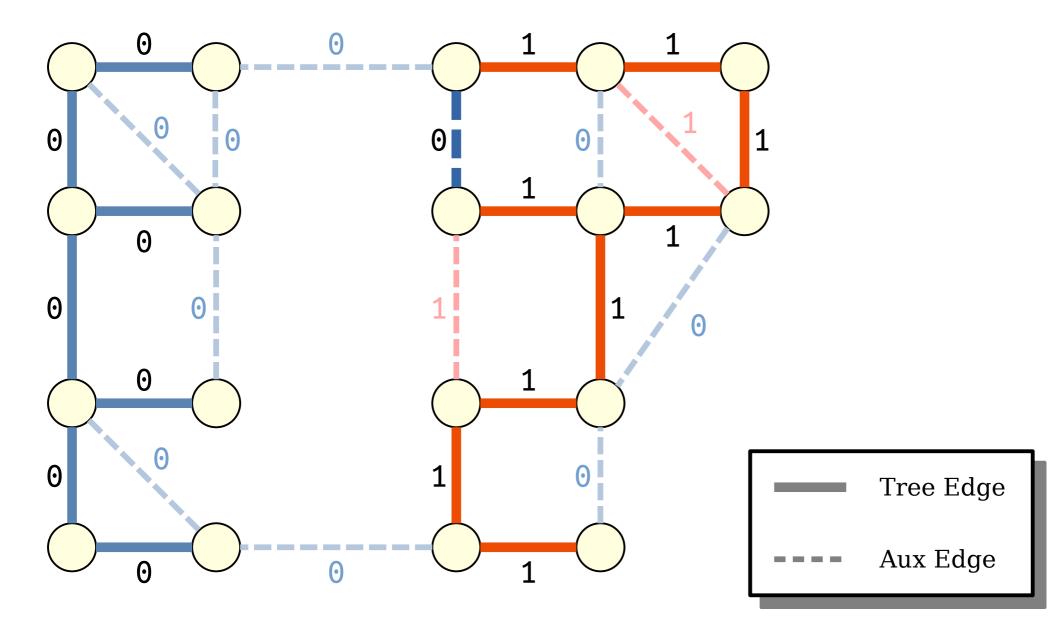


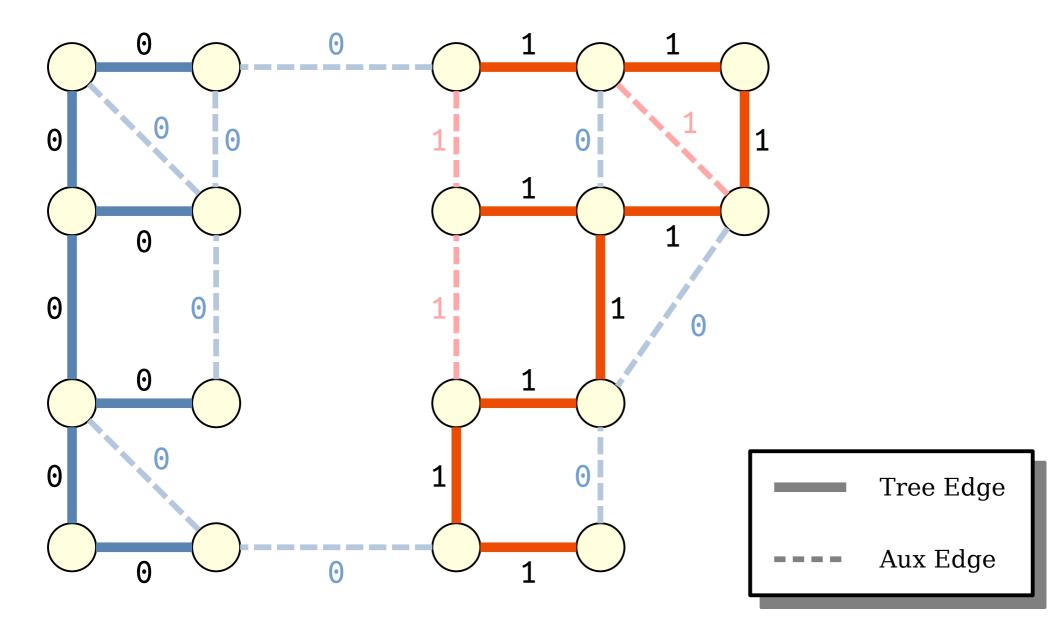


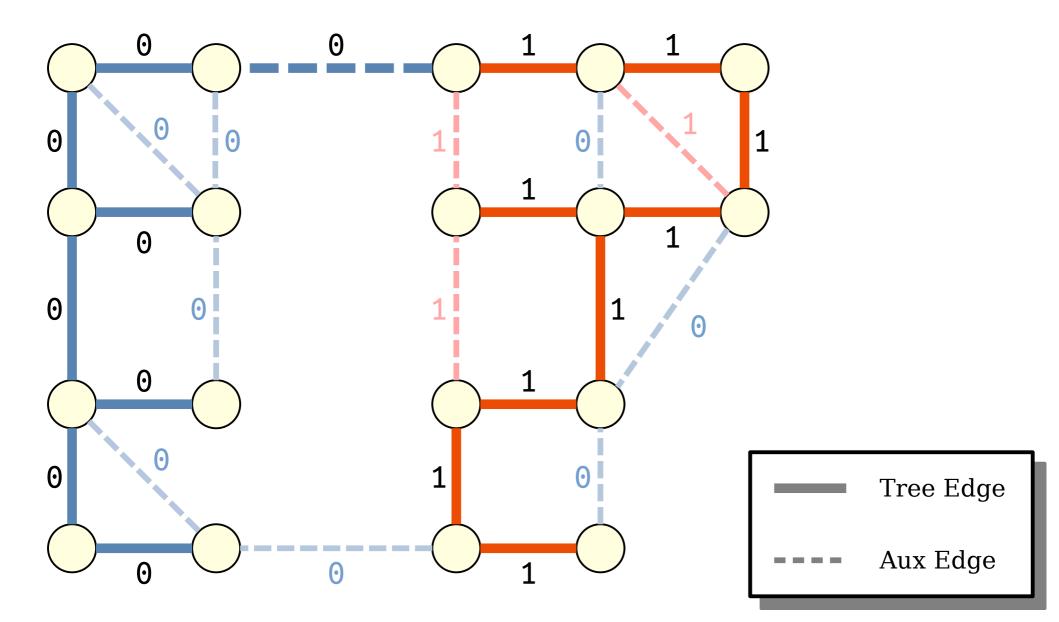


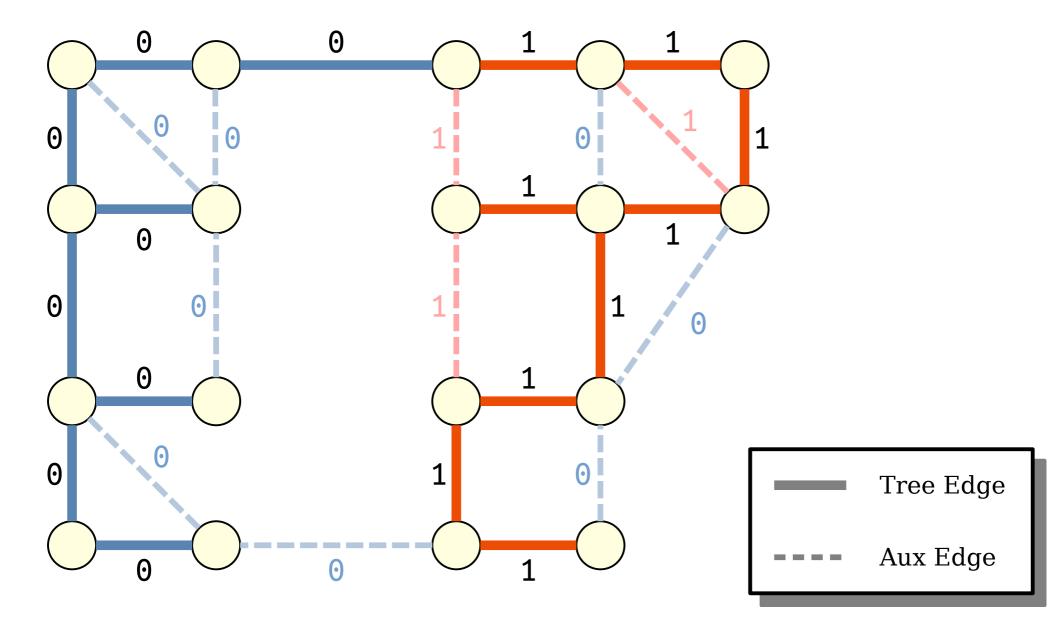


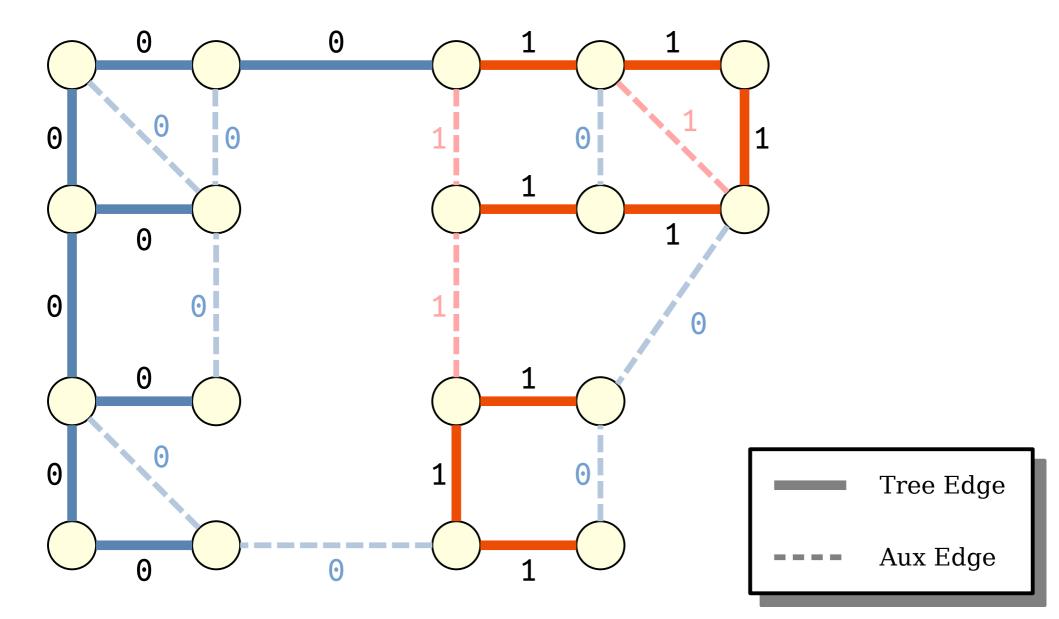


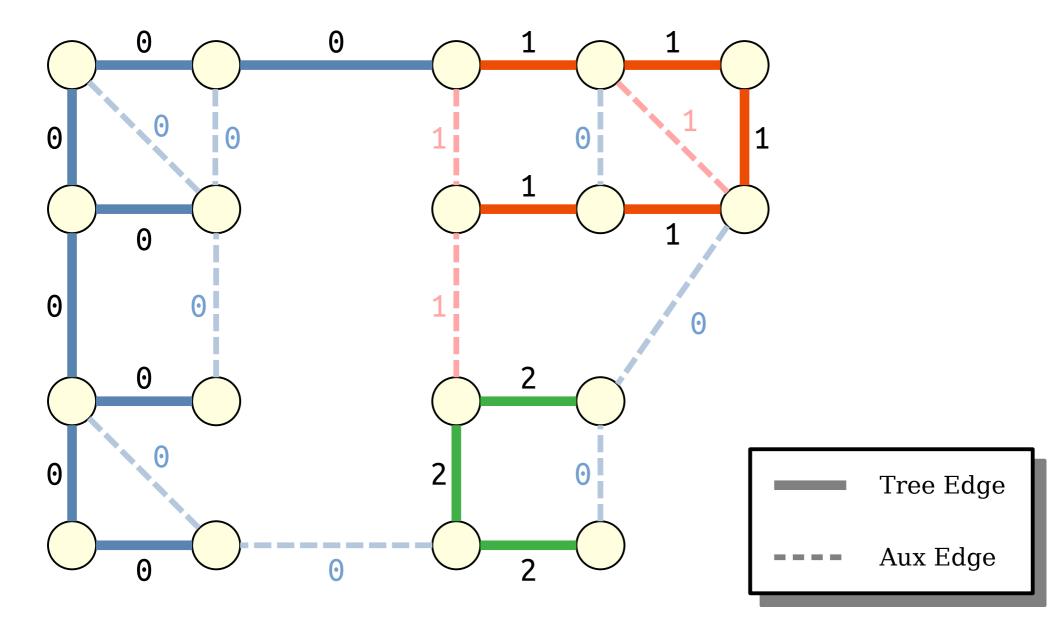


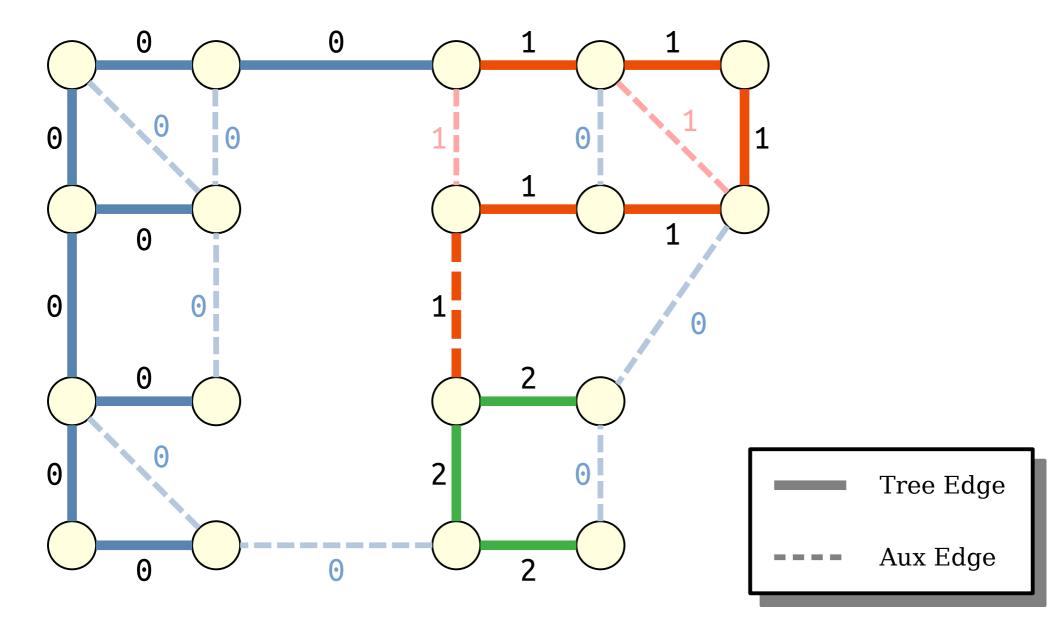


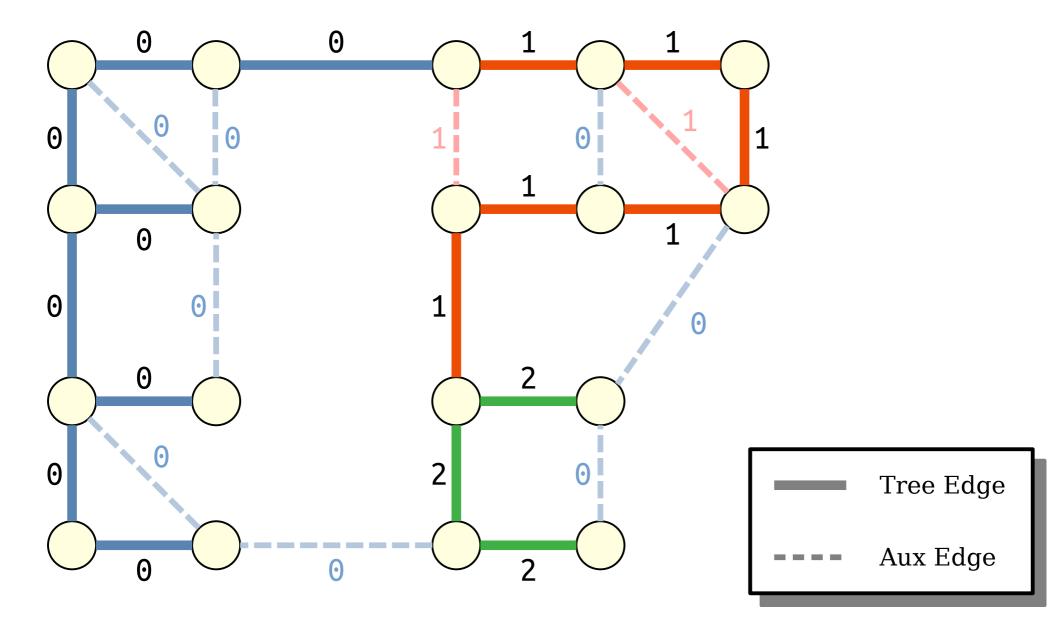


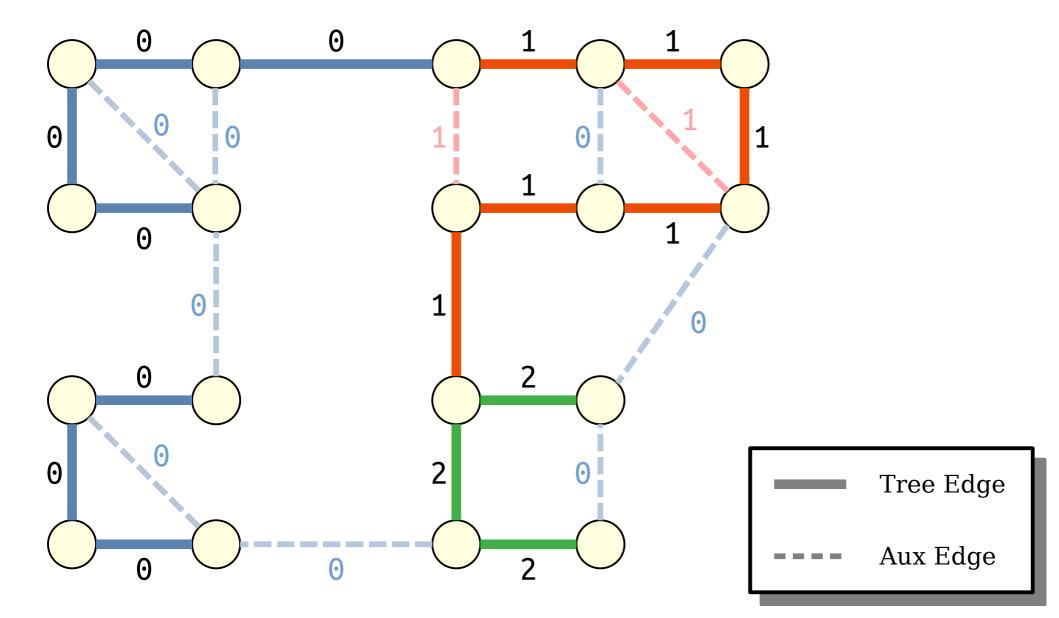


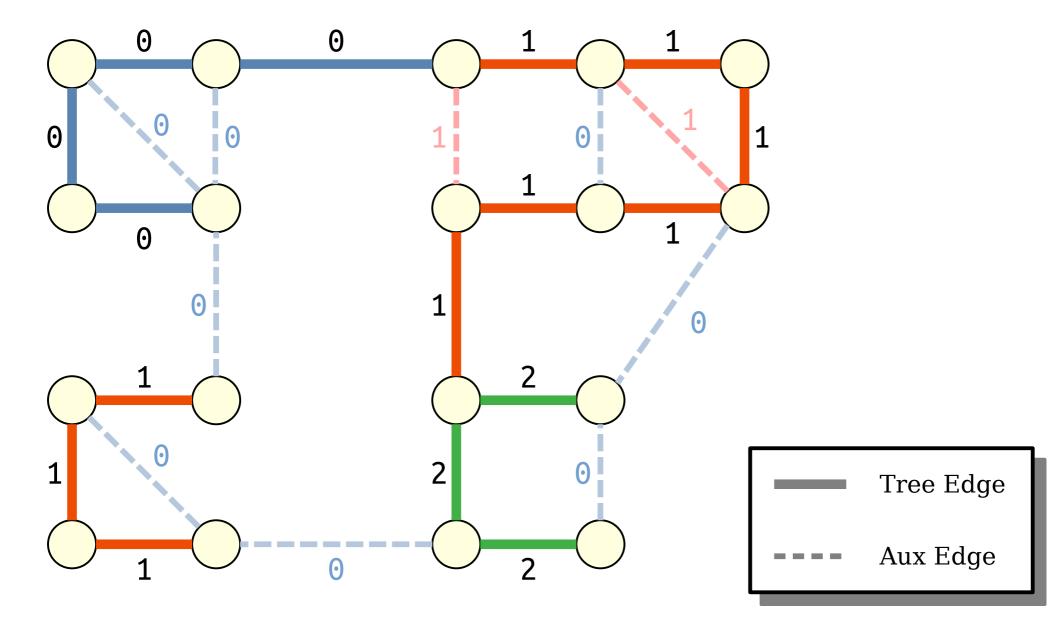


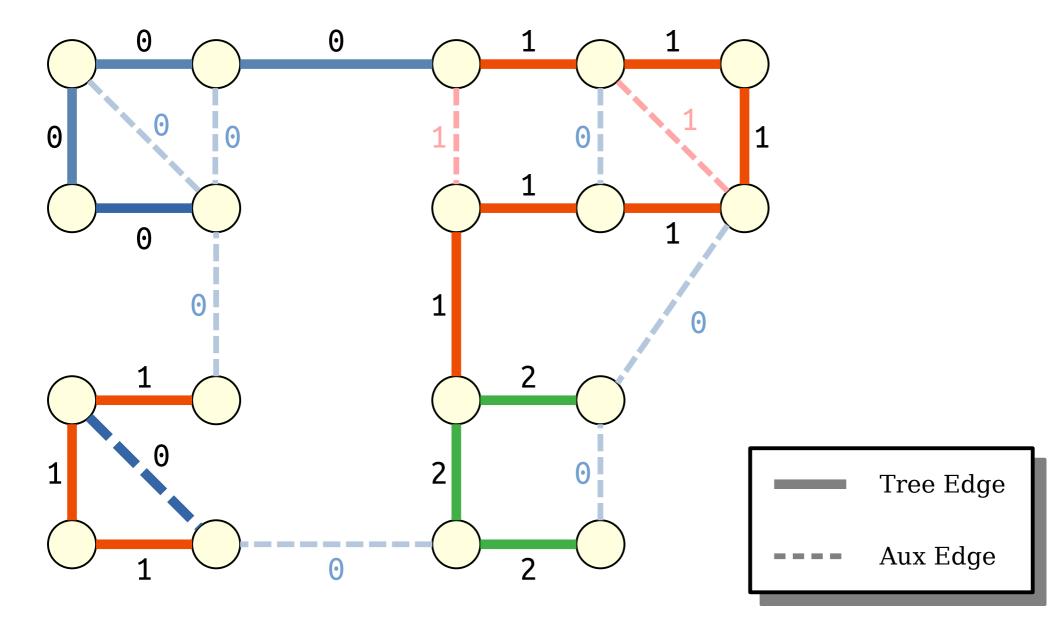


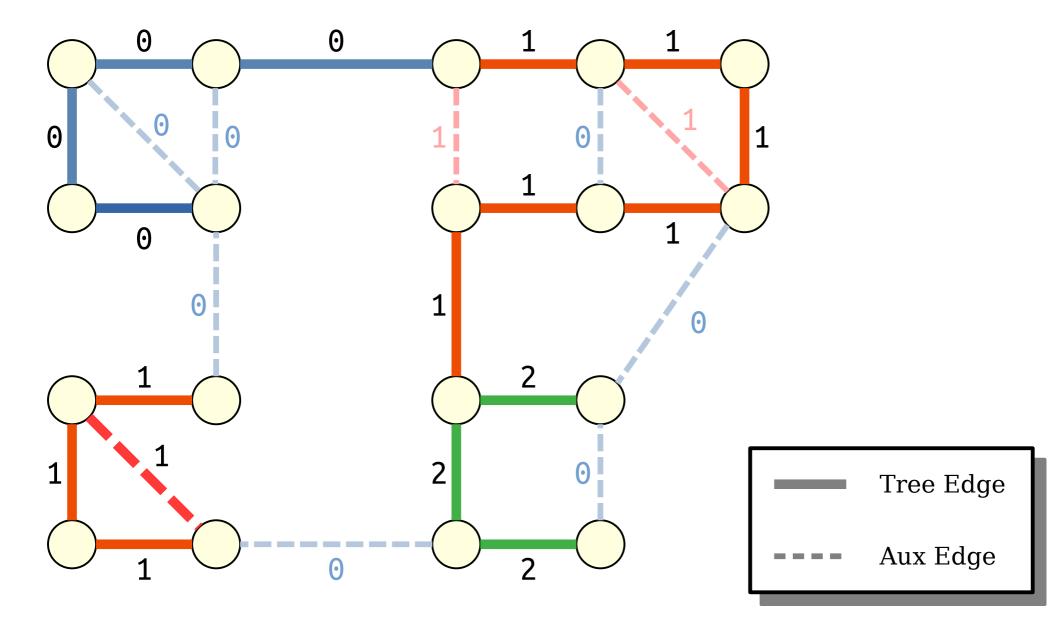


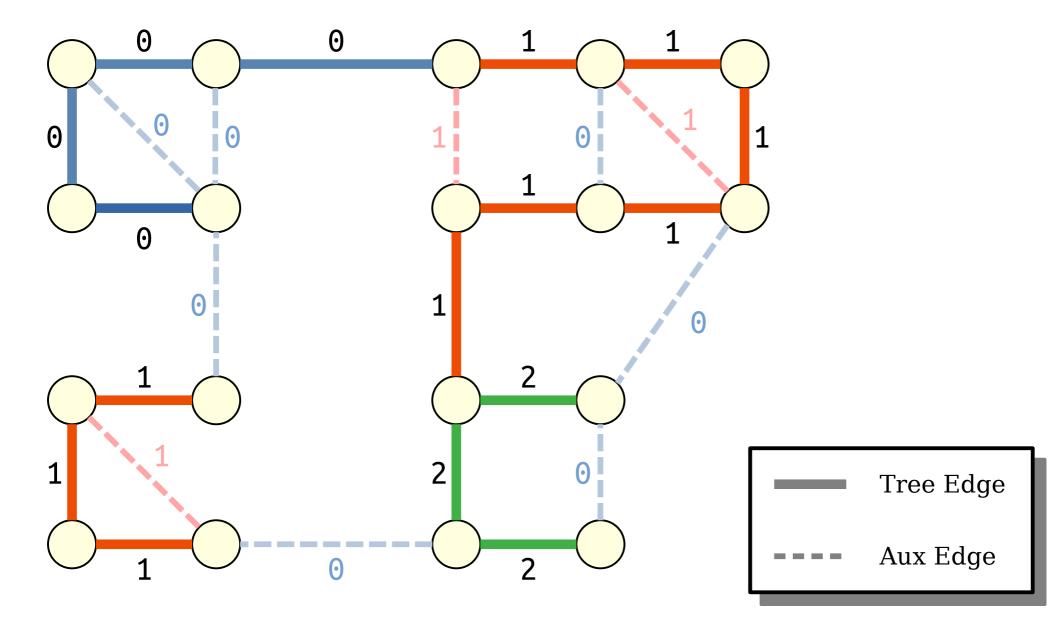


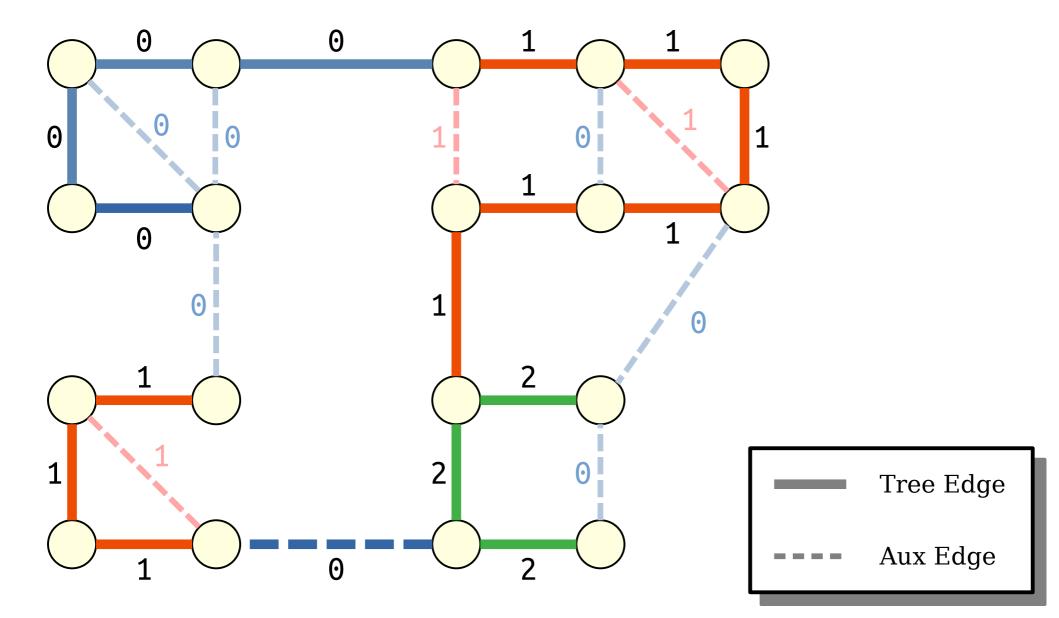


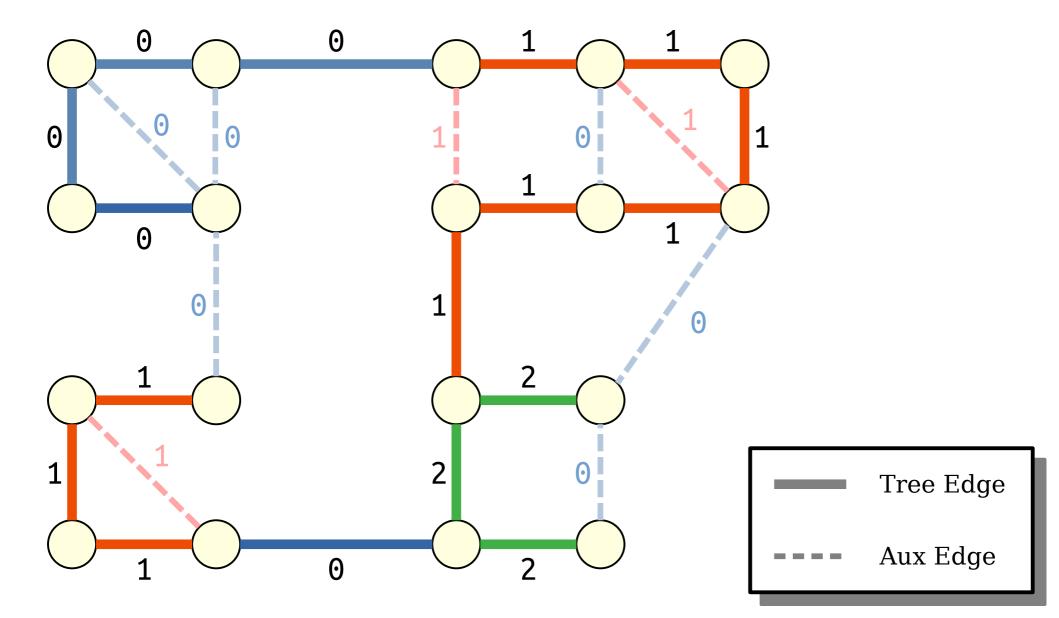


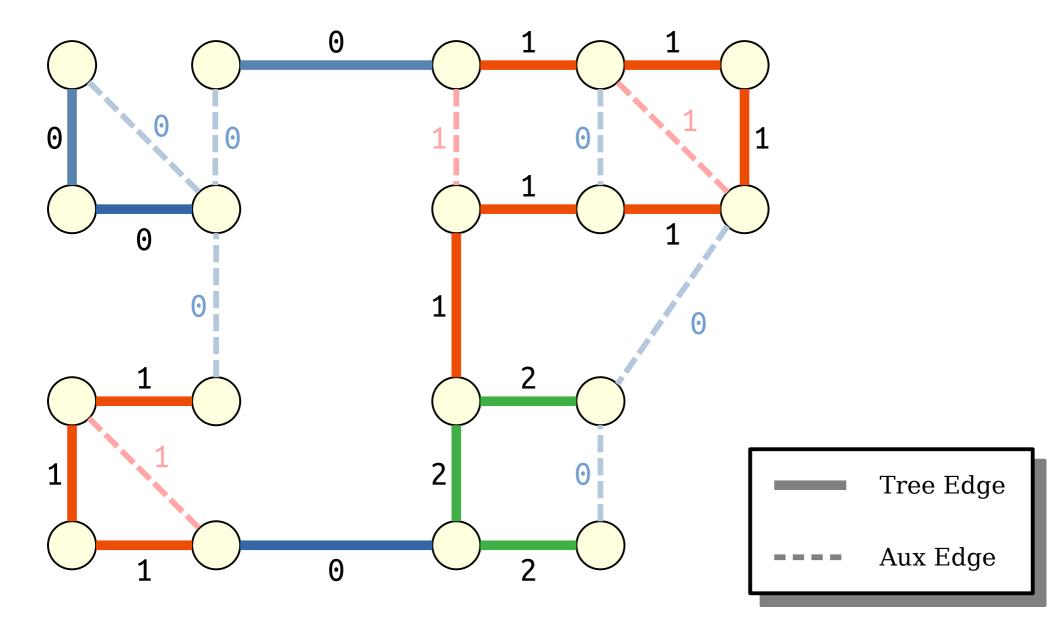


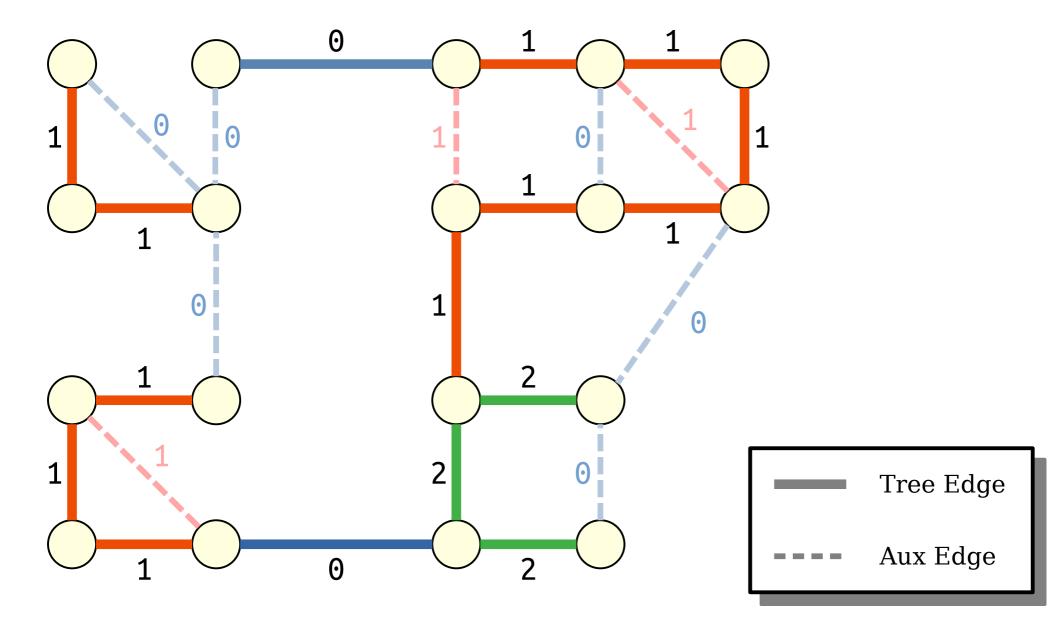


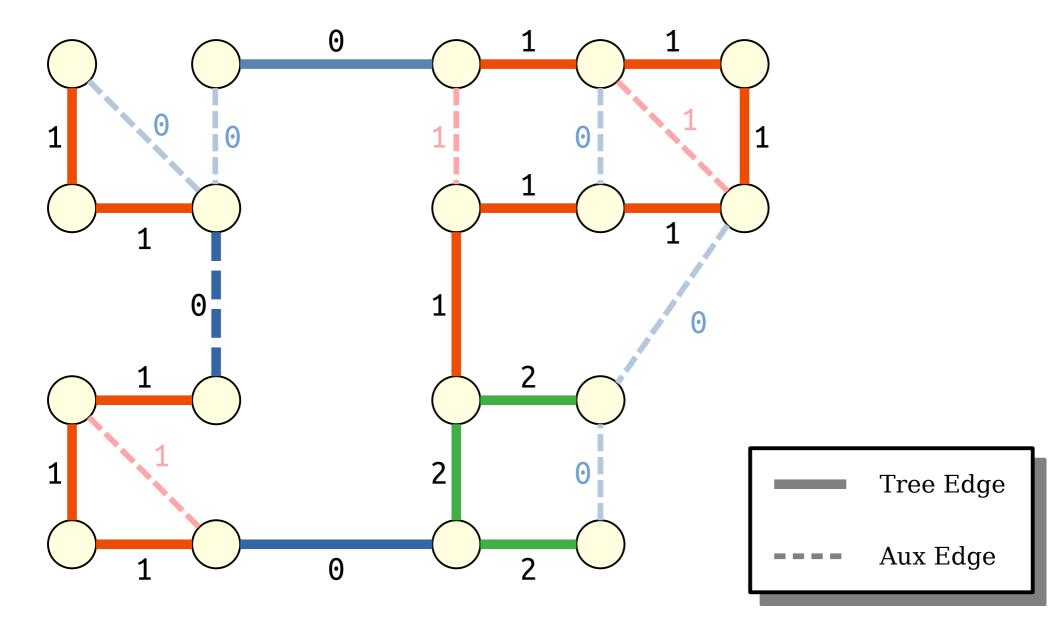


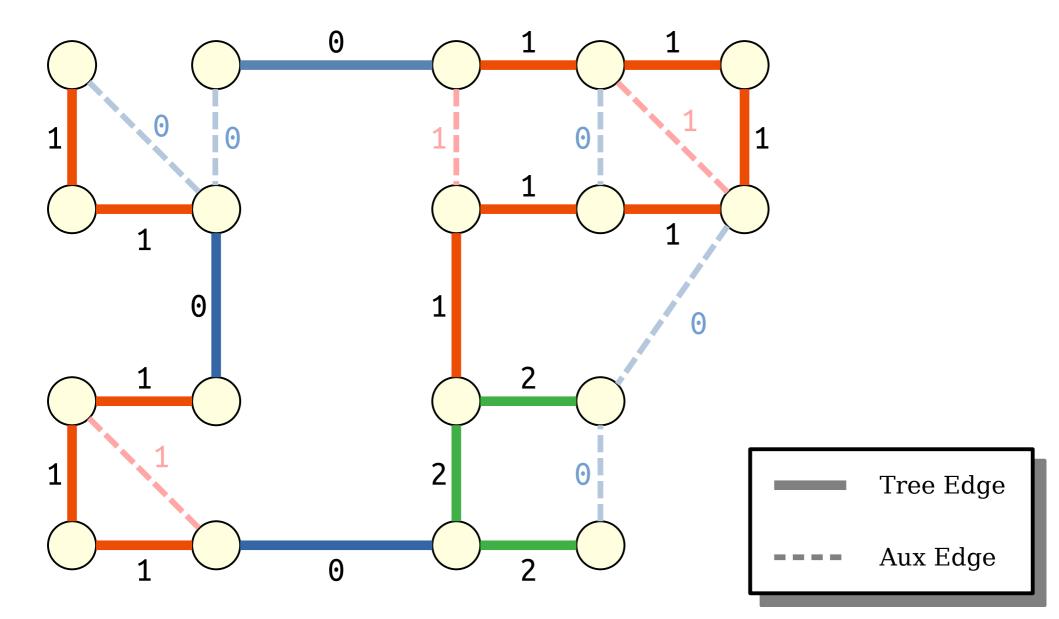


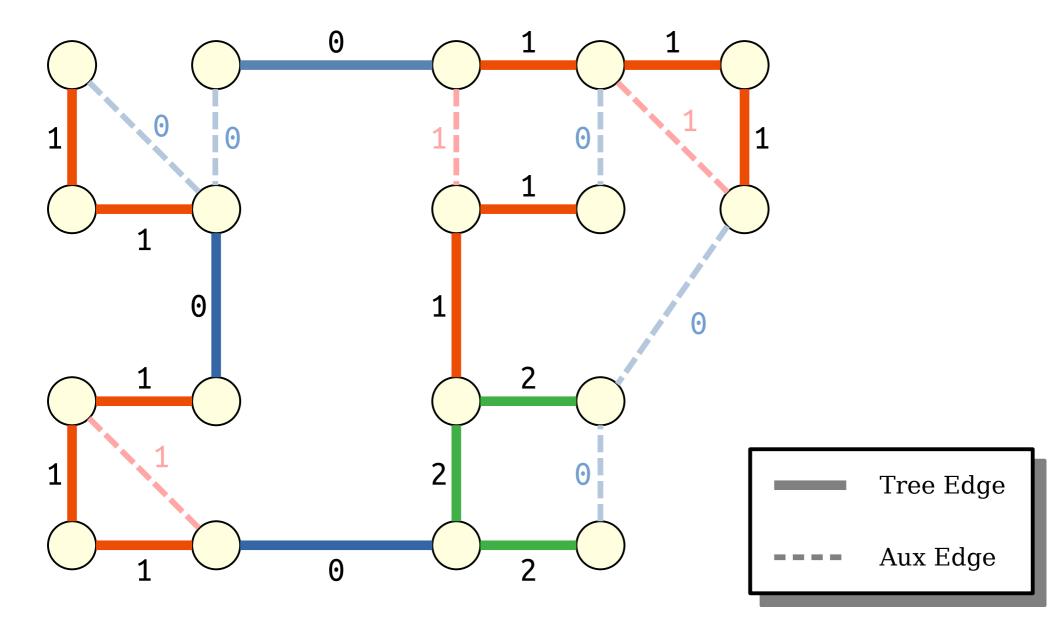


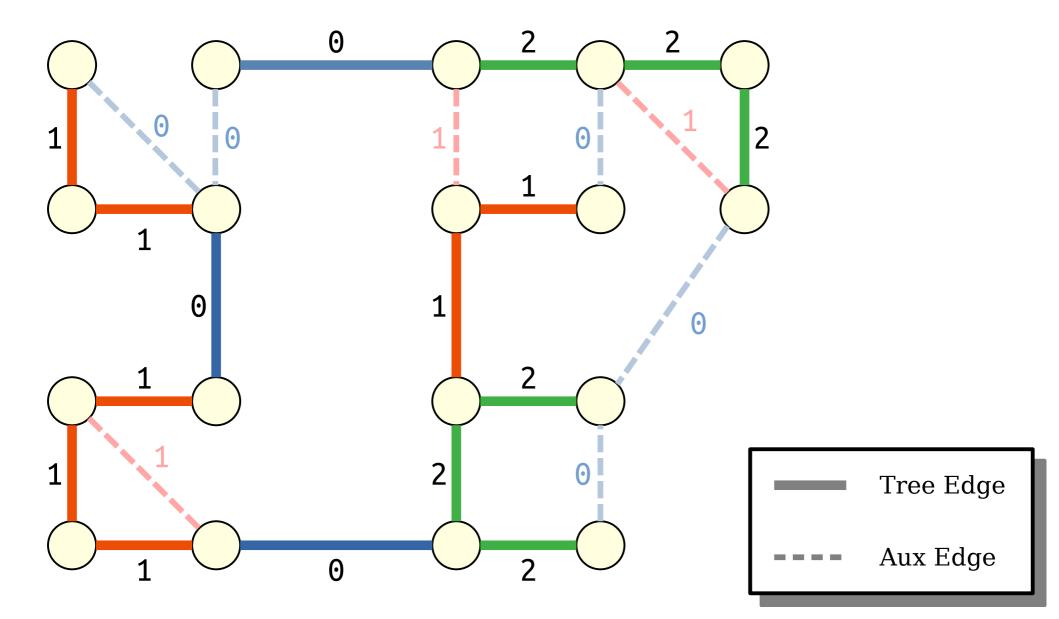


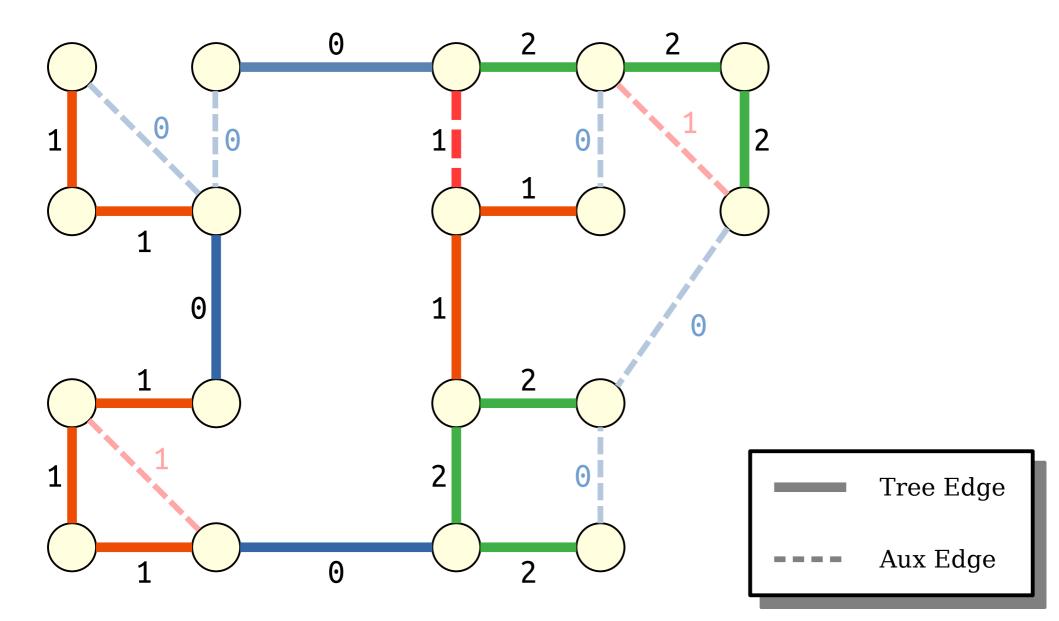


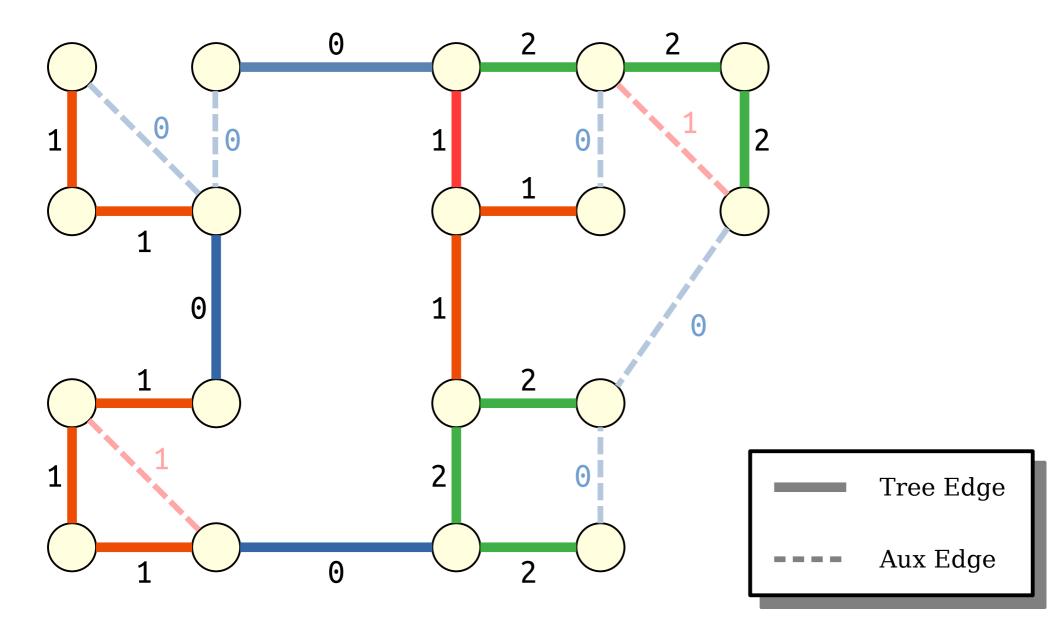


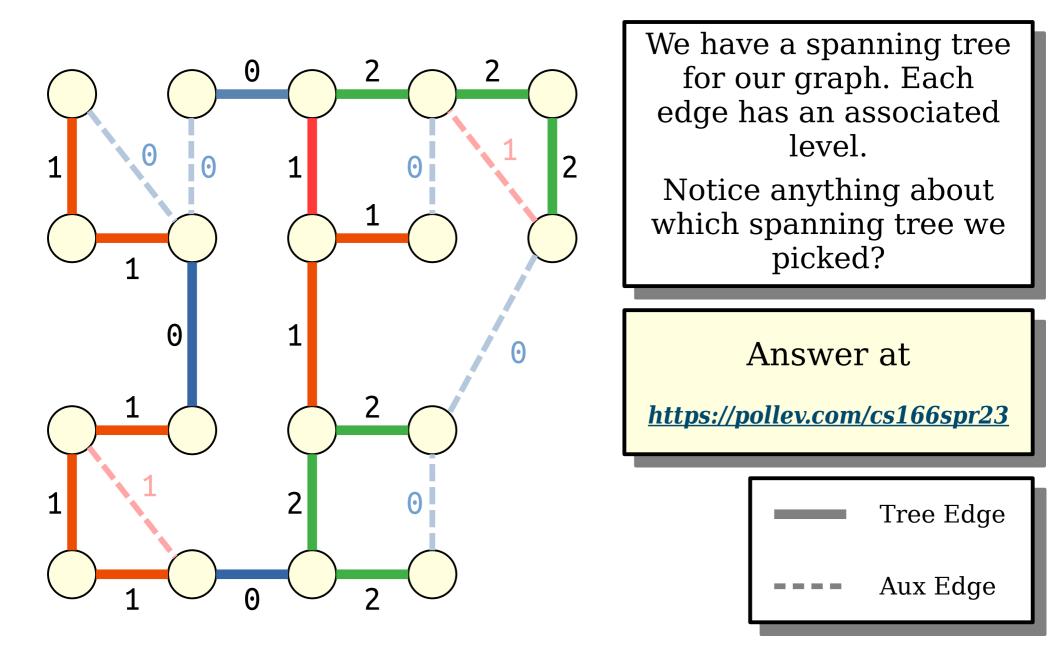












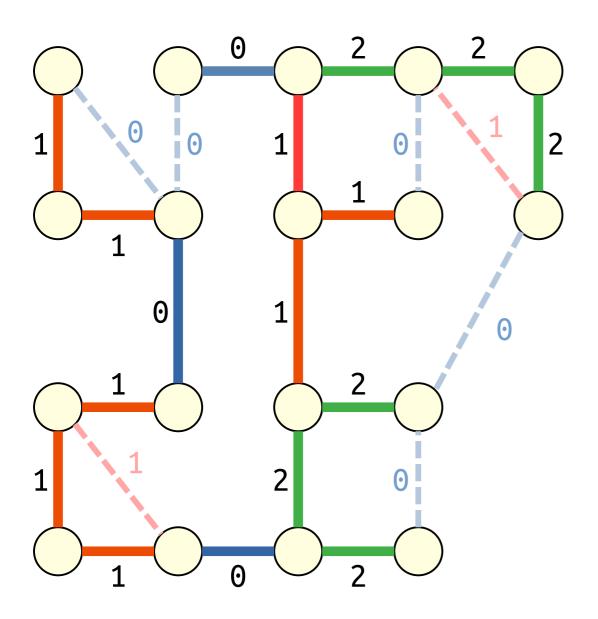
Maximum Spanning Forests

• **Key Idea:** Maintain the following invariant throughout all operations:

The forest F is a maximum spanning forest with respect to levels.

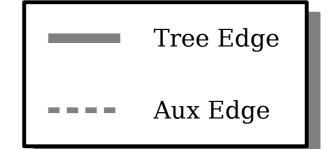
- We'll use this both to formalize the details of all the operations and to ensure correctness.
- Plus, this will help us in some tricky corner cases!

MSF Implications

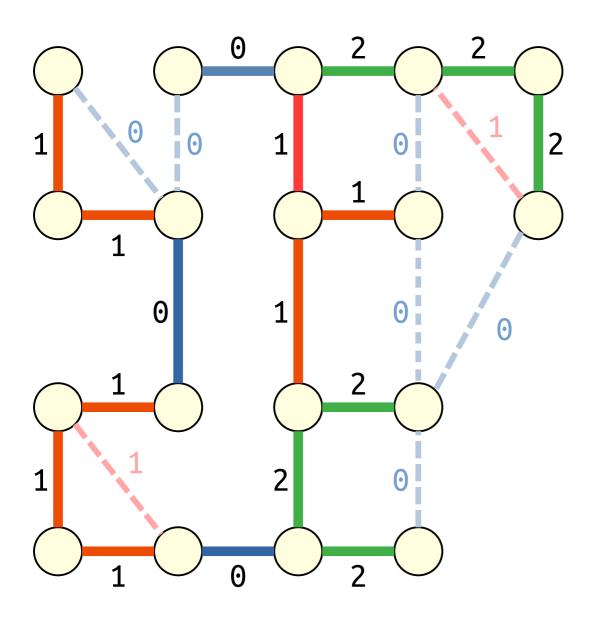


Suppose we add a new edge into the graph. What level should it get?

Answer: Give it level 0, which ensures we still have a MSF.

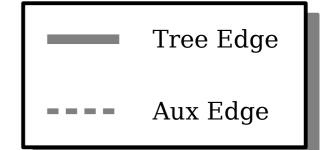


MSF Implications

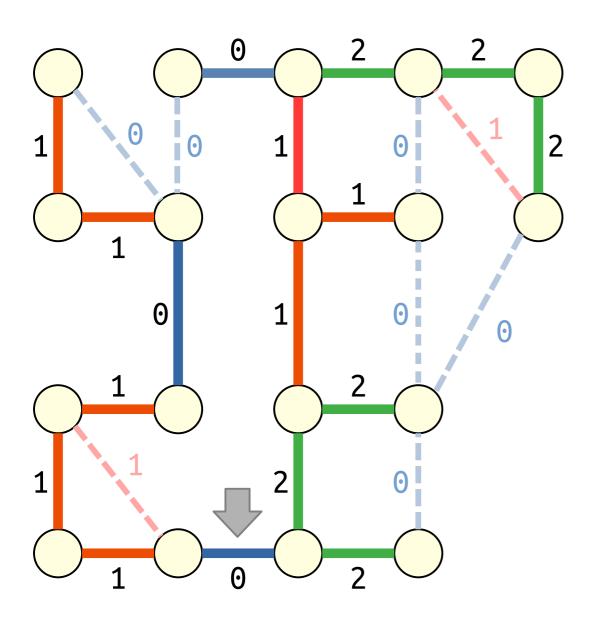


Suppose we add a new edge into the graph. What level should it get?

Answer: Give it level 0, which ensures we still have a MSF.



MSF Implications



Suppose we delete this edge of level 0.

Claim: No auxiliary edge of level 1 or higher can reconnect the tree.

Proof Idea: If such an edge existed, we would have used it in the MSF.

_	Tree Edge
	Aux Edge

An Initial Idea

Invariant: F is a maximum spanning forest.

To check *are-connected*(*x*, *y*):

Return whether x and y are connected in \mathcal{F} .

To *link*(*x*, *y*):

Does this work? How fast is it?

If *are-connected*(x, y), add xy as an auxiliary edge to \mathscr{F} . Otherwise add xy as a tree edge to \mathscr{F} .

To *cut*(x, y), where xy is a tree edge of level l: Delete xy from \mathcal{F} .

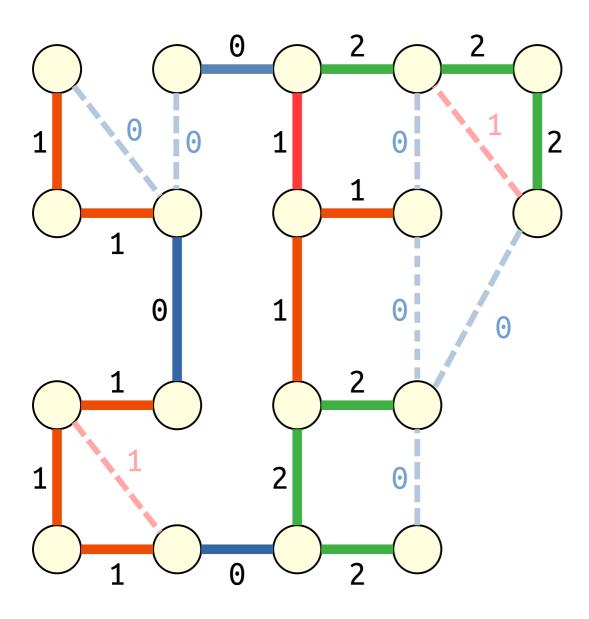
Let T_x and T_y be the trees in \mathscr{F} containing x and y.

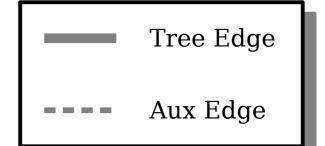
Select one of T_x and T_y arbitrarily; WLOG assume it's T_x .

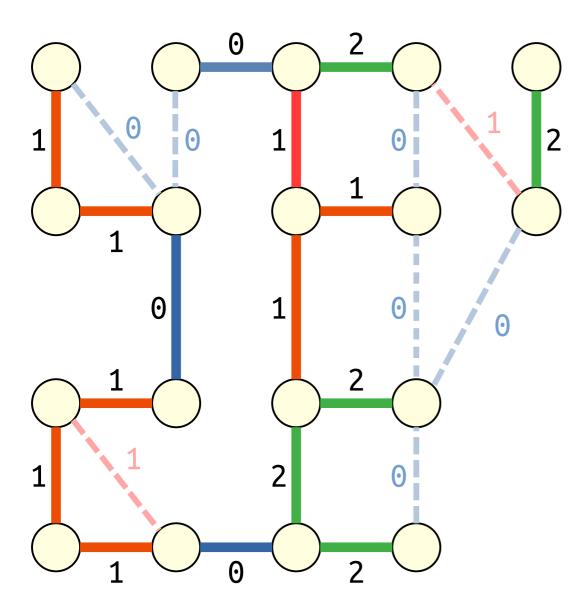
Increment the level of each tree edge of level l in T_x .

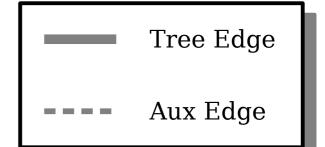
For each auxiliary edge uv in \mathcal{F} touching T_x :

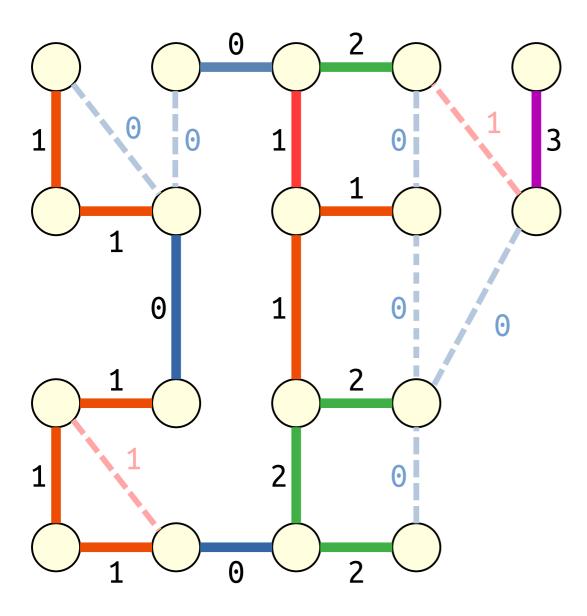
If uv connects T_x and T_y , add uv as a tree edge to \mathscr{F} . Stop. Else increment its level.

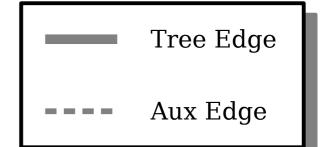


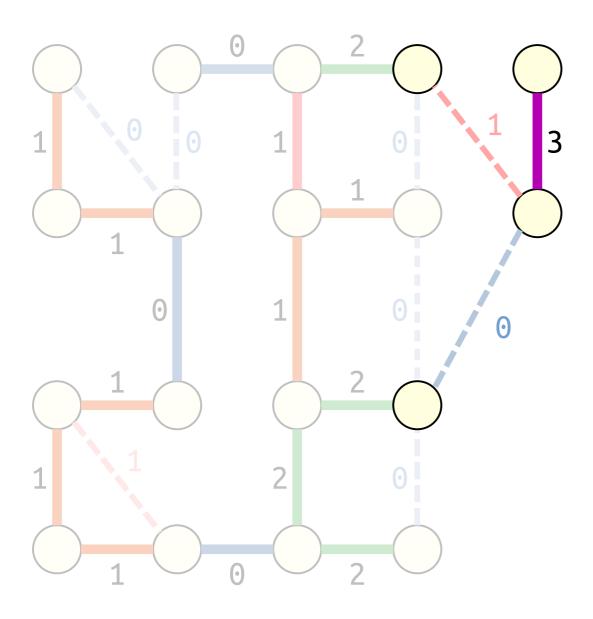




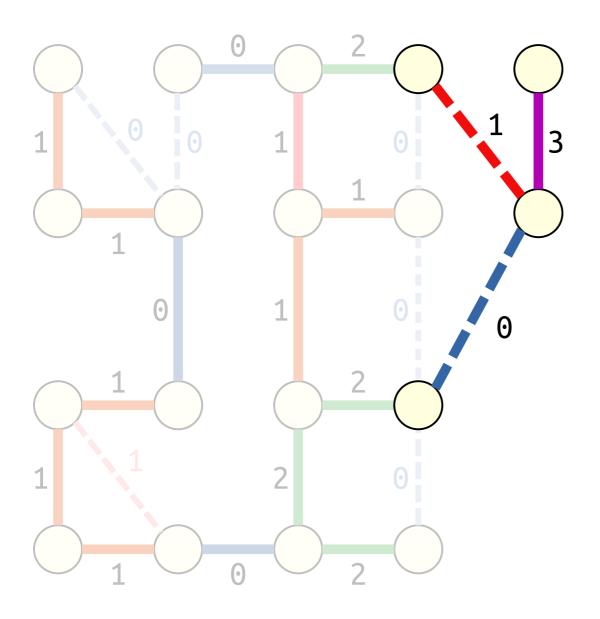


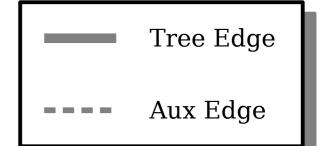


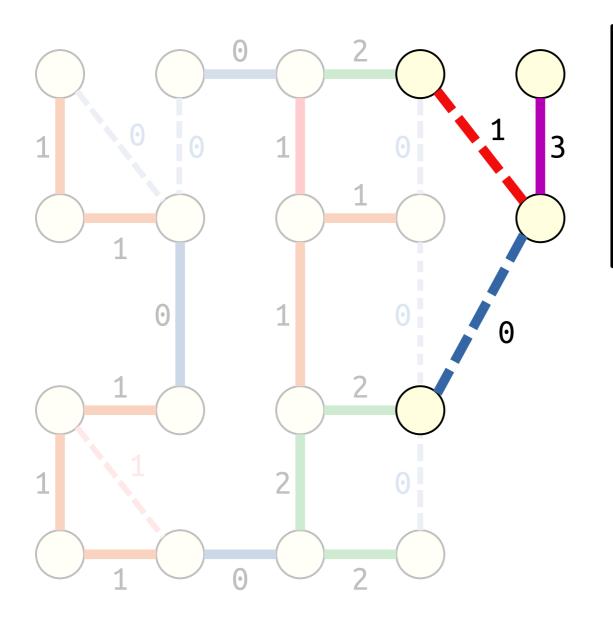




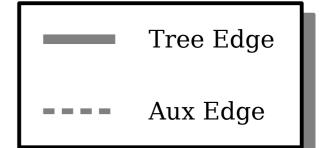
 Tree Edge
 Aux Edge

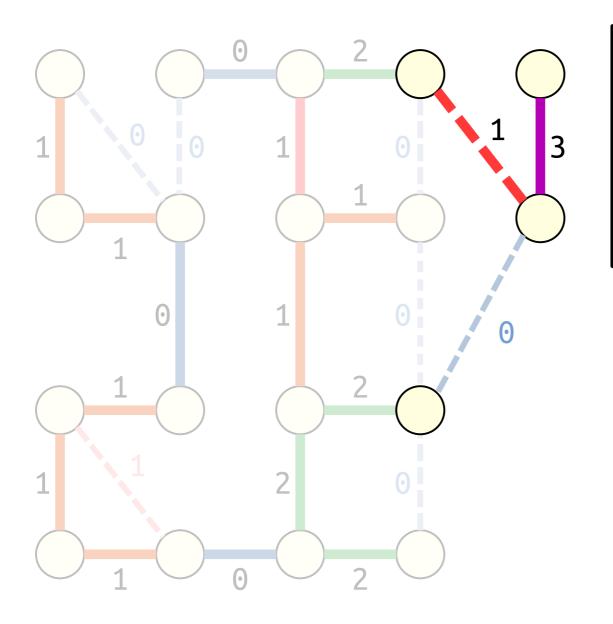




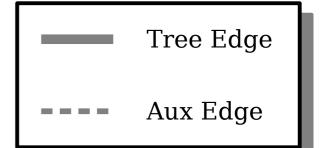


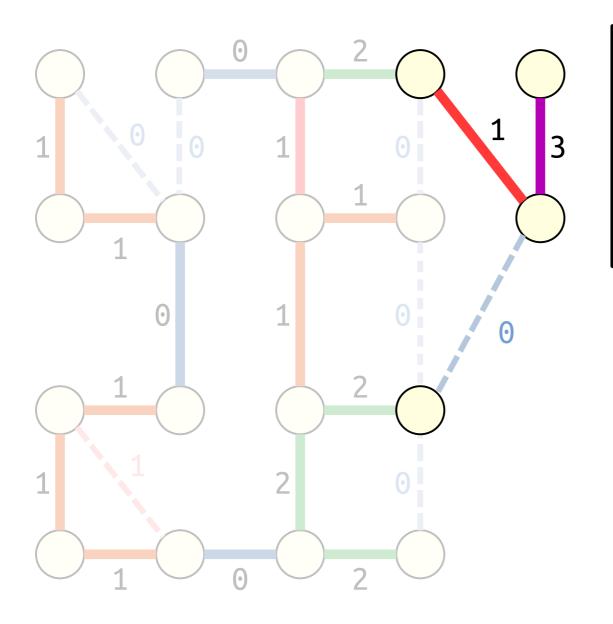
Both of these edges would reconnect. Which should we pick?



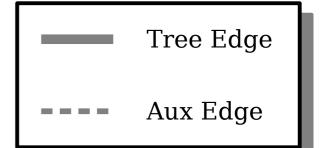


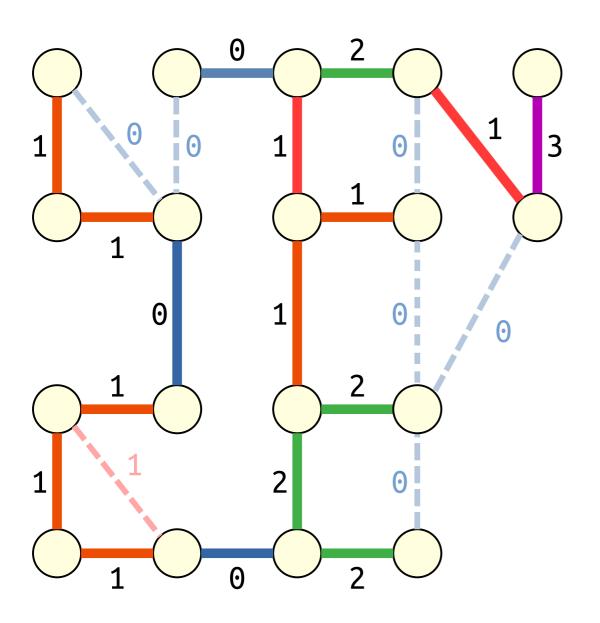
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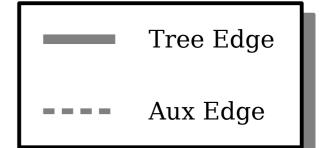


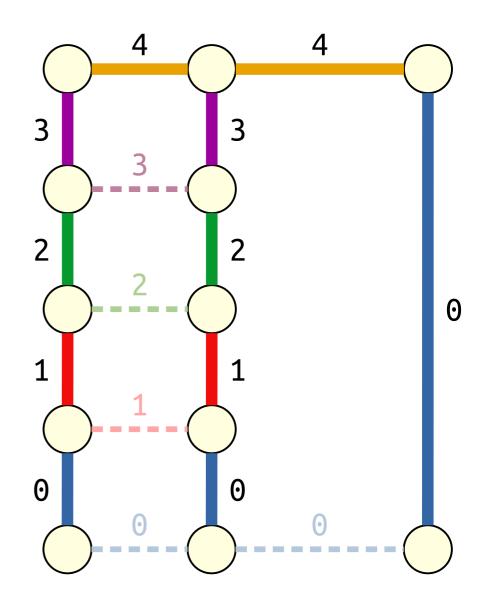
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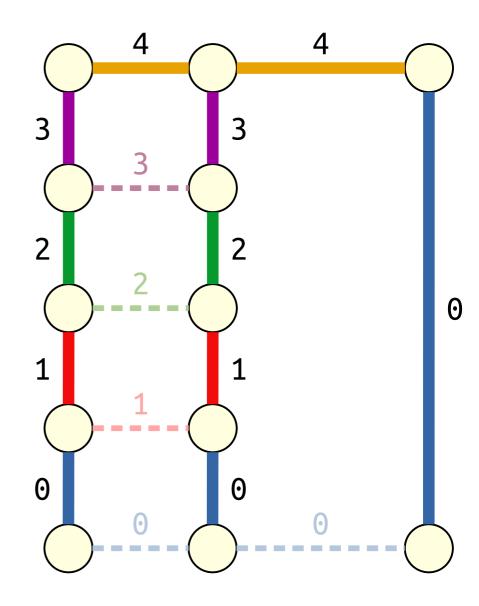


Both of these edges would reconnect. Which should we pick?

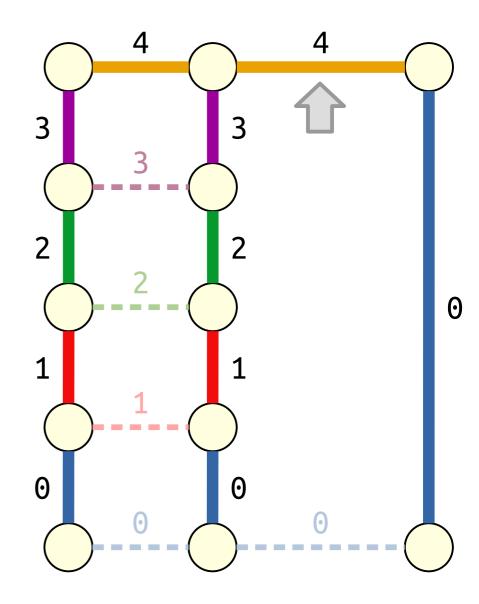




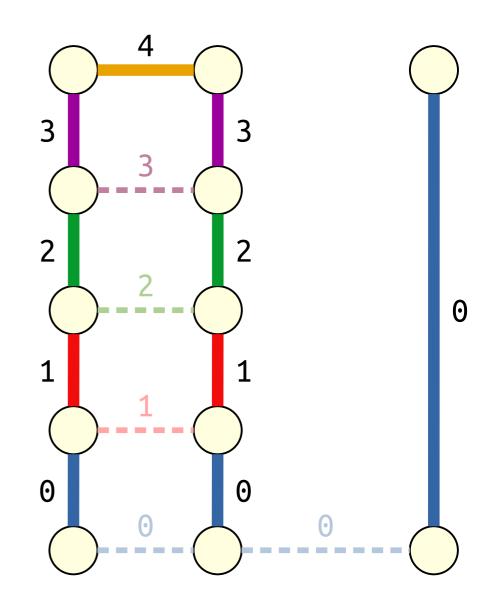
• Suppose we remove the indicated edge.



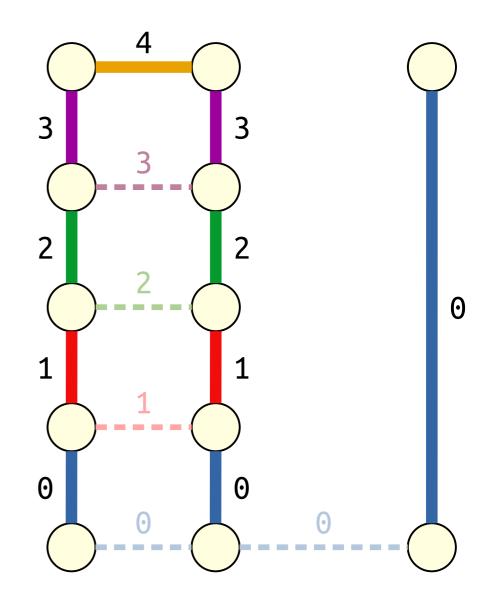
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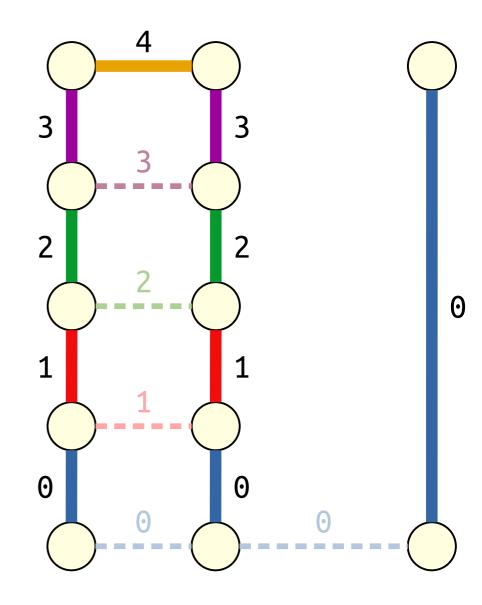
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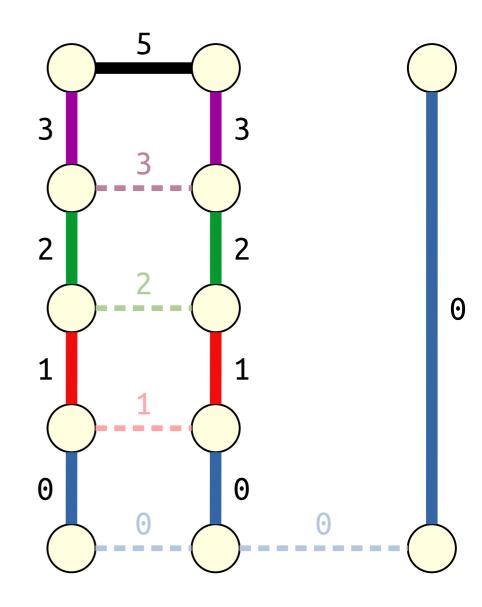
- Suppose we remove the indicated edge.
- Let's follow our standard procedure:



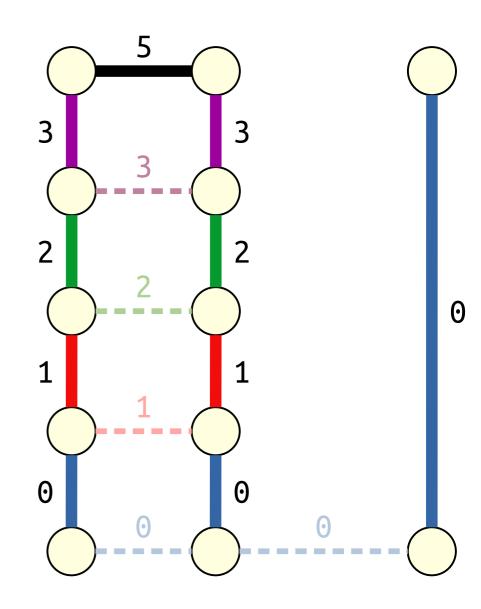
- Suppose we remove the indicated edge.
- Let's follow our standard procedure:
 - Increment all edges of level 4 in the left subtree.



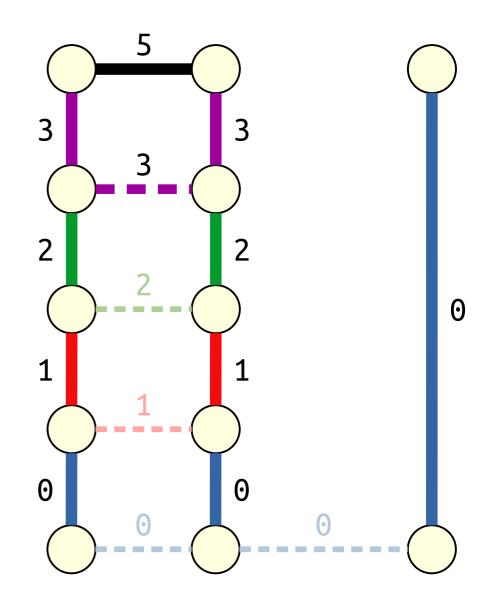
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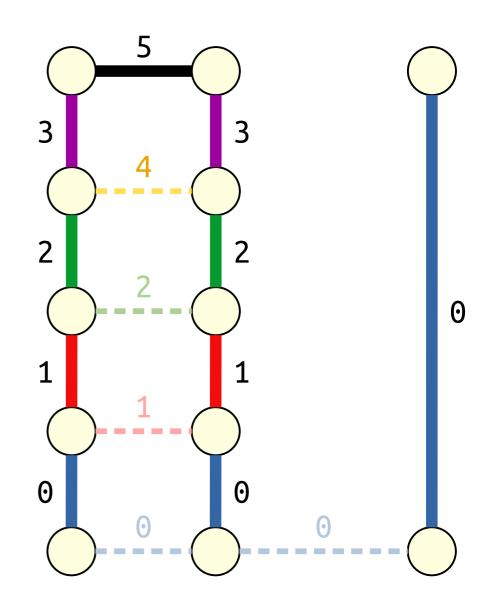
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- Let's follow our standard procedure:
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 - Try reconnecting using auxiliary edges in decreasing level order.



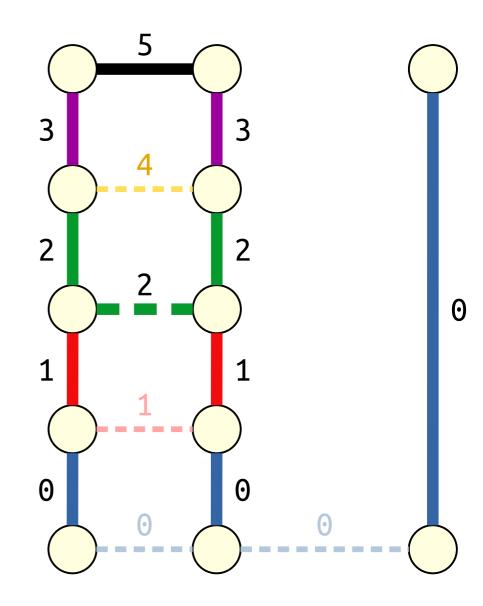
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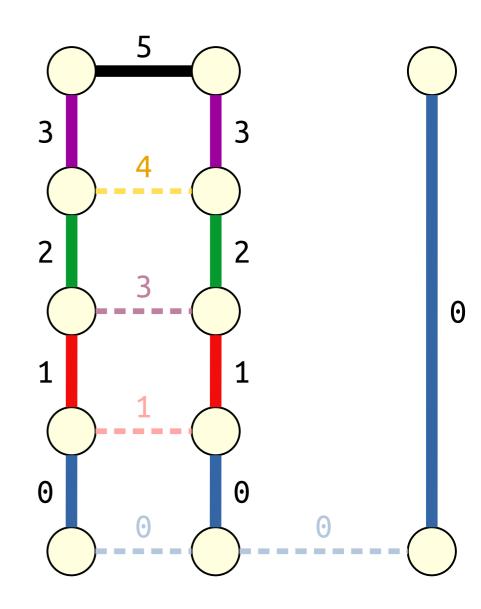
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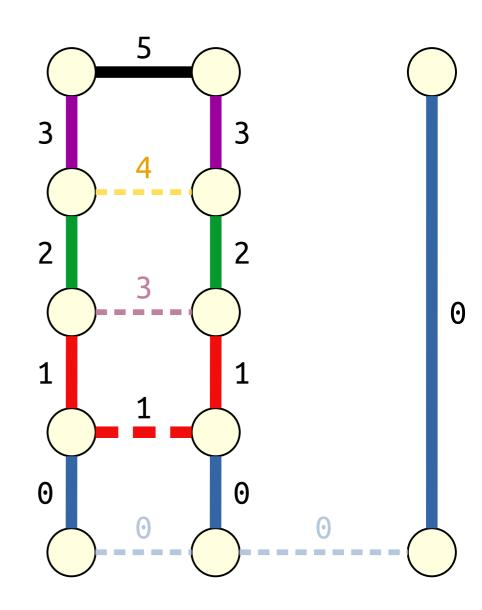
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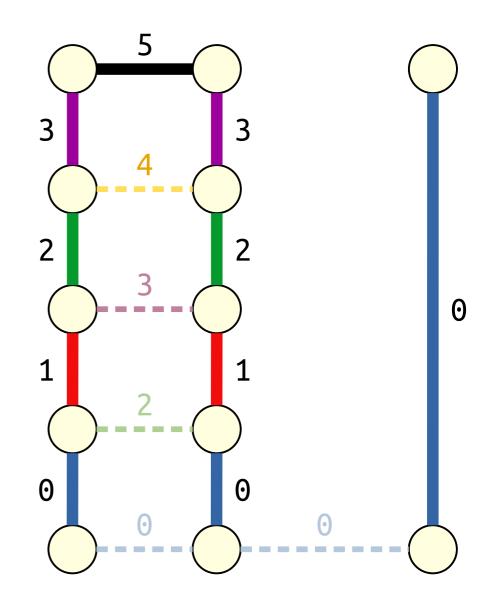
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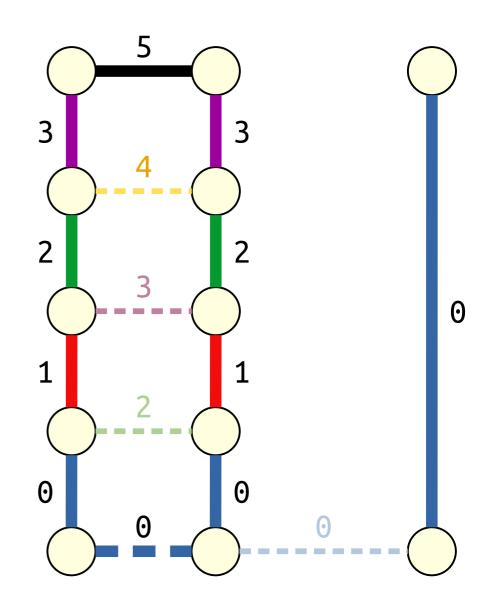
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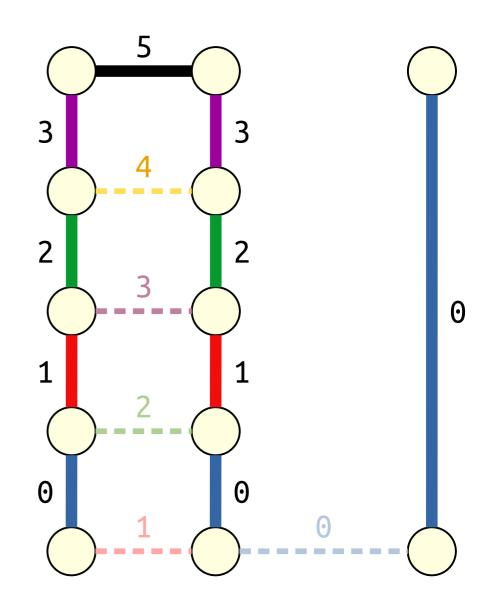
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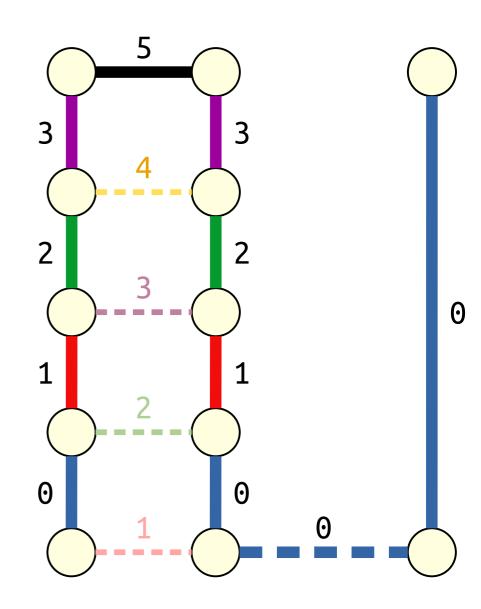
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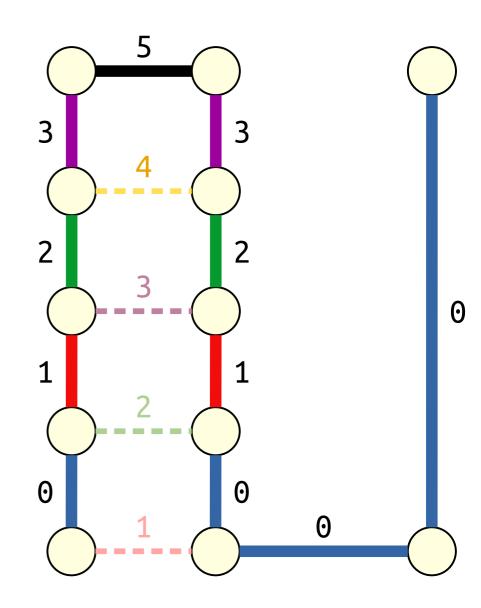
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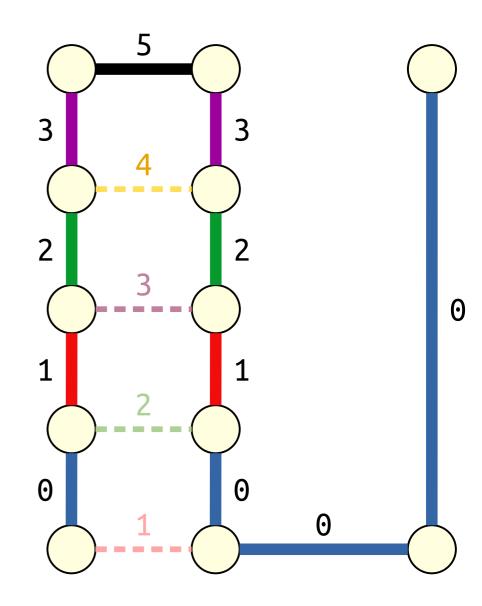
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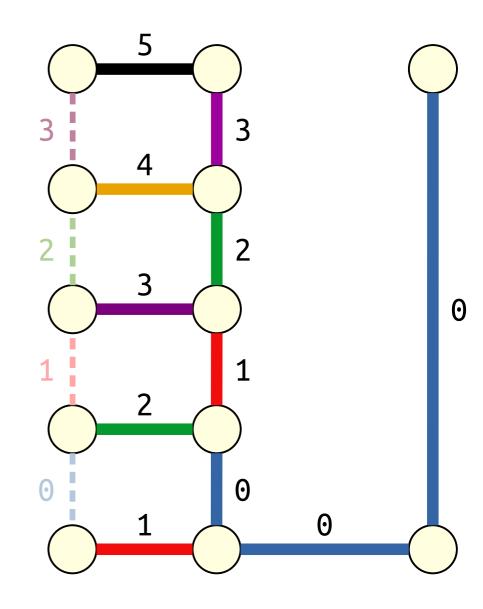
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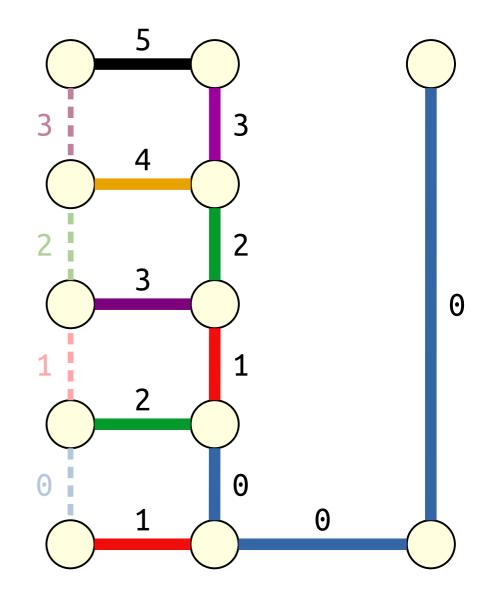
- Suppose we remove the indicated edge.
- Let's follow our standard procedure:
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 - Try reconnecting using auxiliary edges in decreasing level order.
- **Problem:** The resulting tree is not a maximum spanning forest.

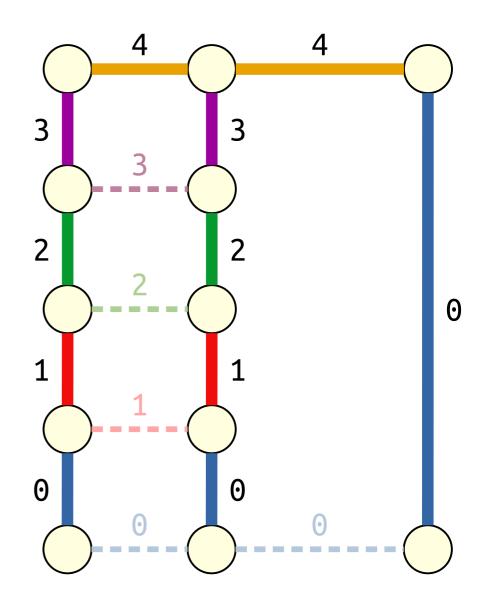


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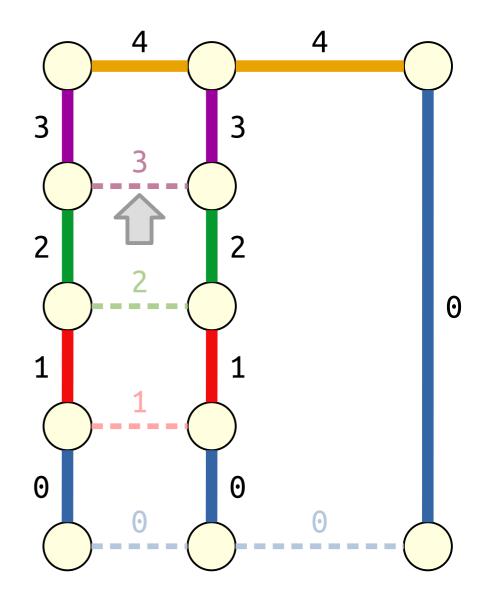


- Suppose we remove the indicated edge.
- Let's follow our standard procedure:
 - Increment all edges of level 4 in the left subtree.
 - Try reconnecting using auxiliary edges in decreasing level order.
- **Problem:** The resulting tree is not a maximum spanning forest.
- What went wrong?

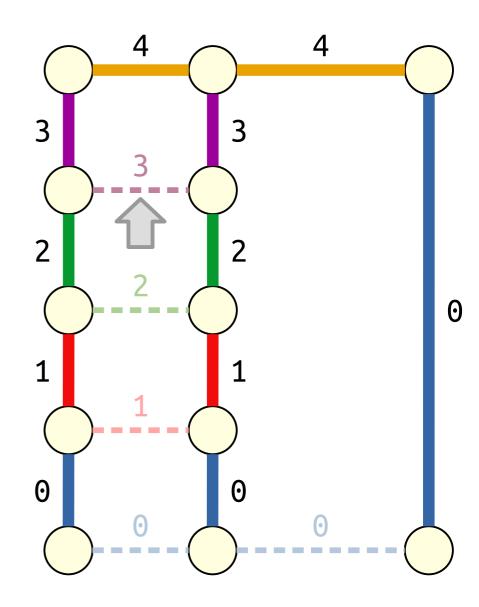




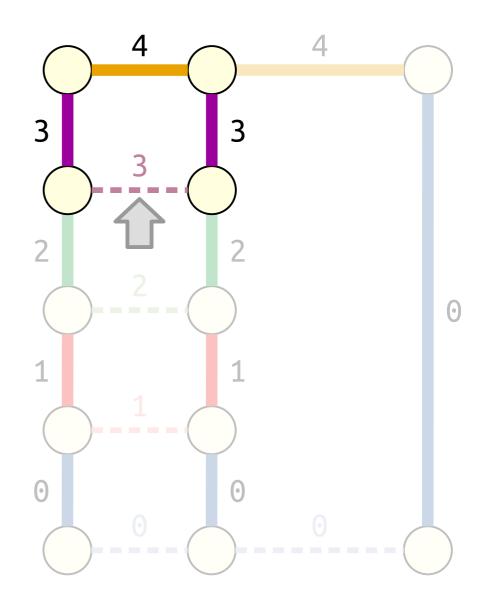
• Pick an auxiliary edge of level *l*. Why wasn't it in the MSF?



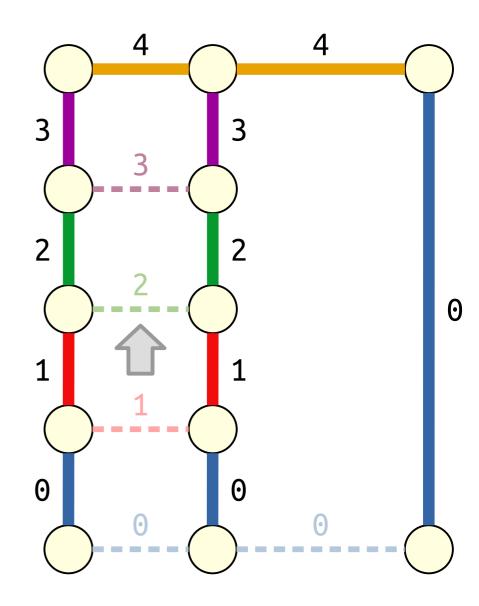
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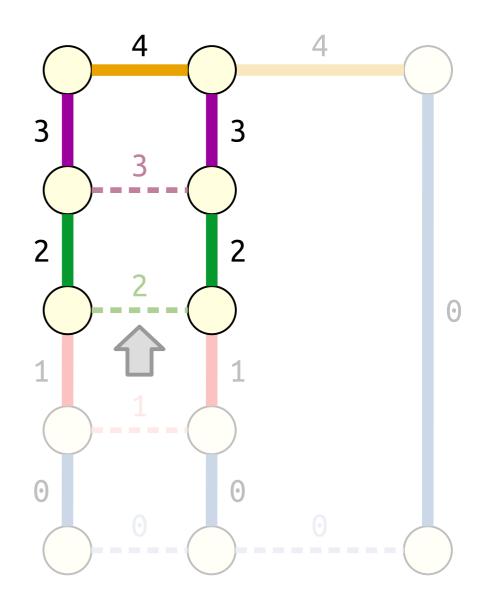
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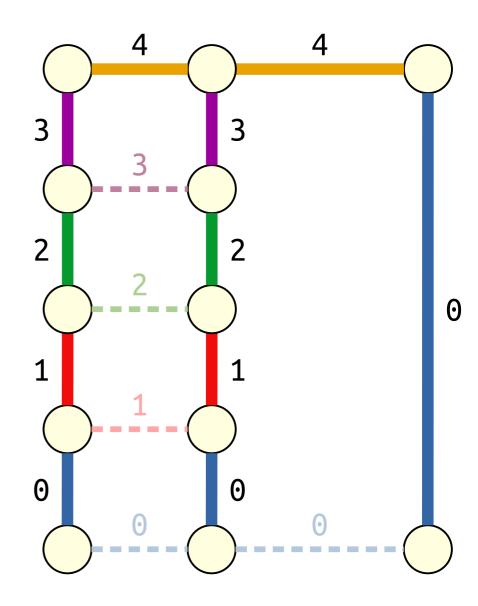
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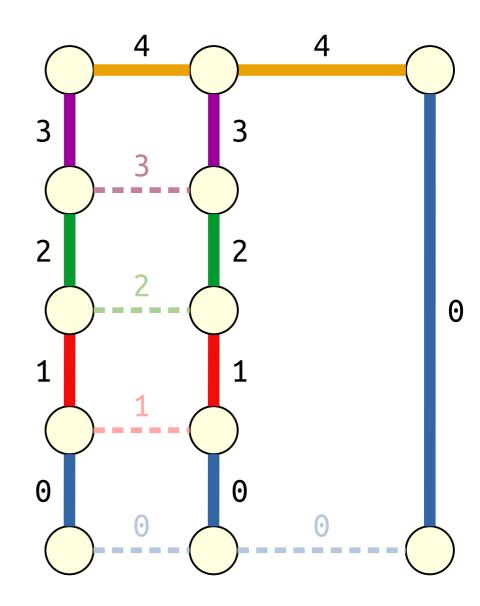
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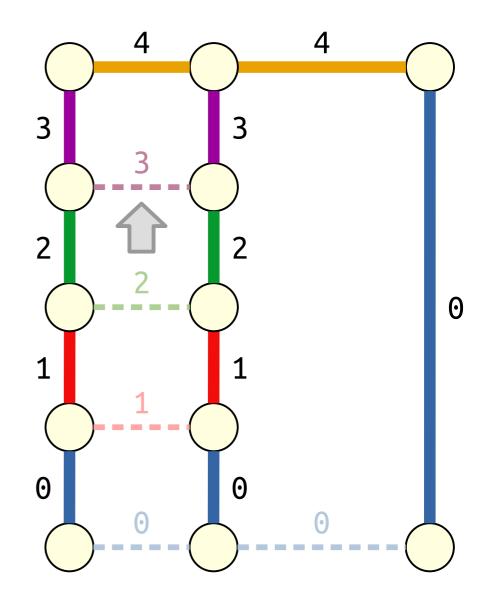
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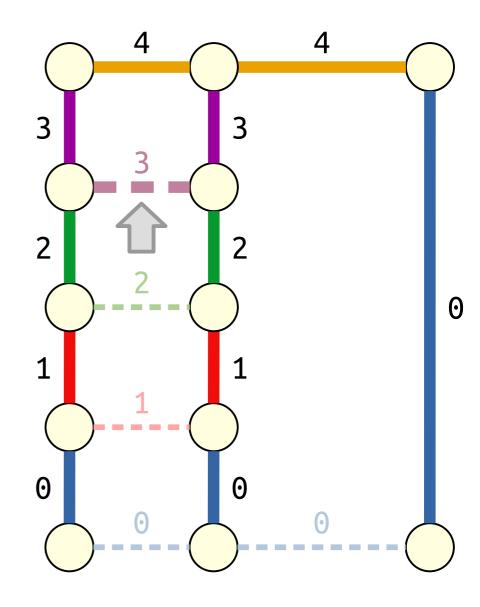
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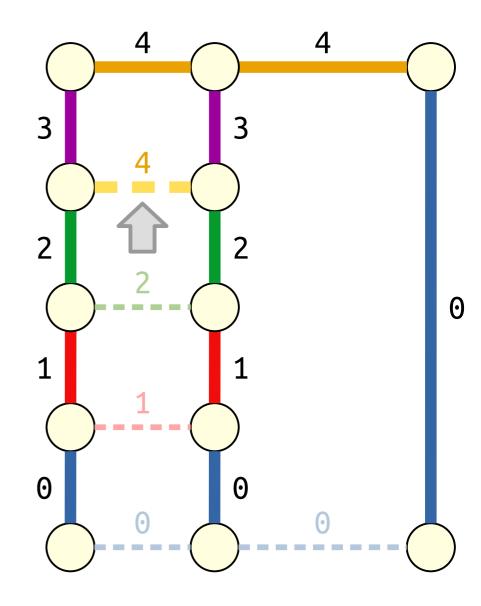
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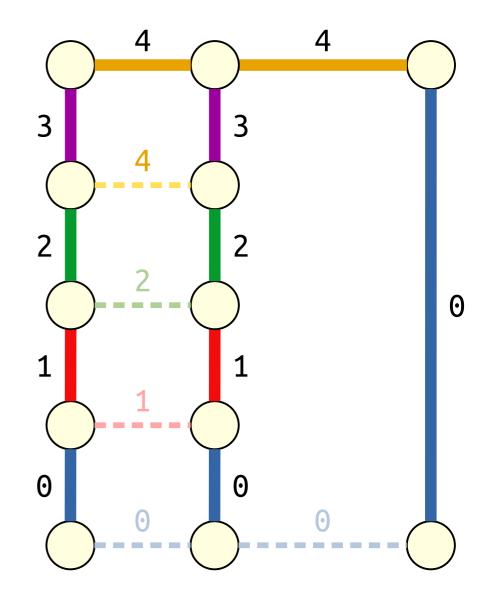
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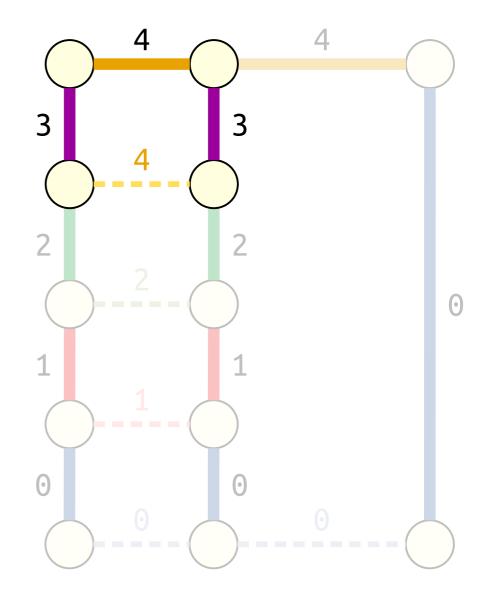
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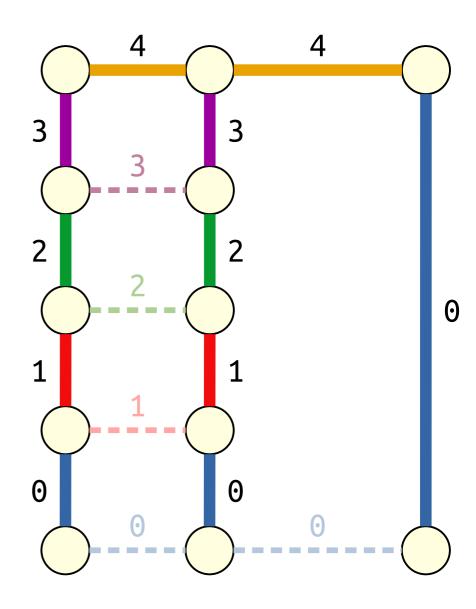


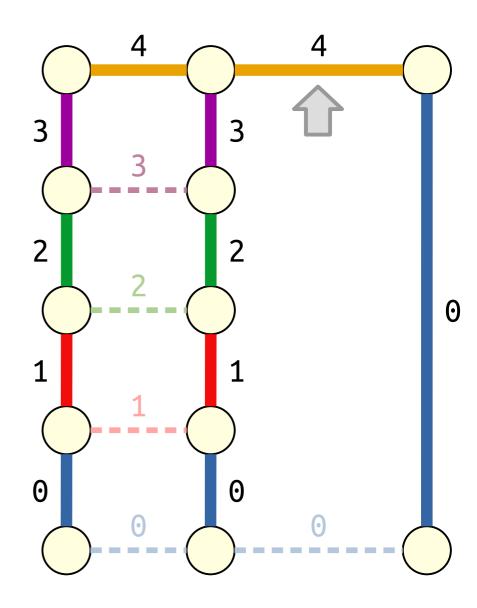
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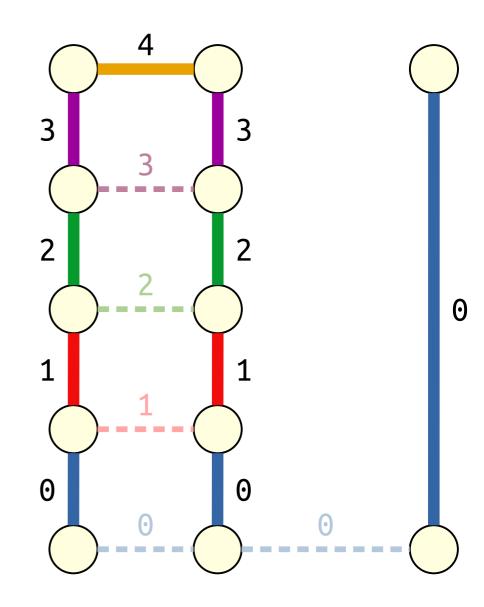


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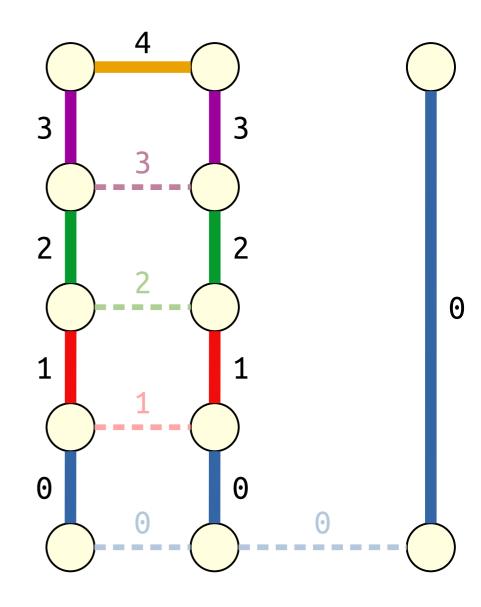




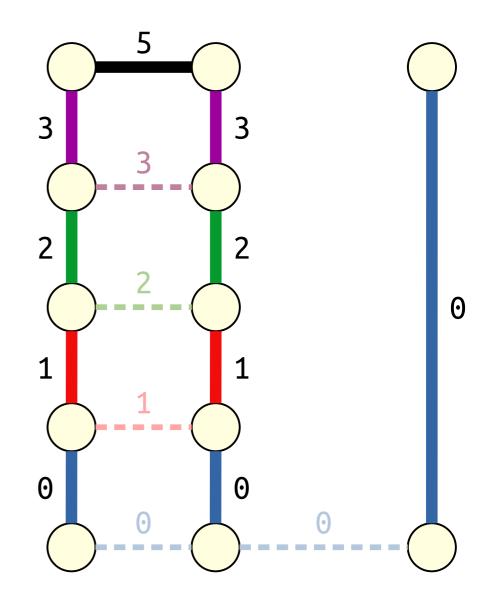




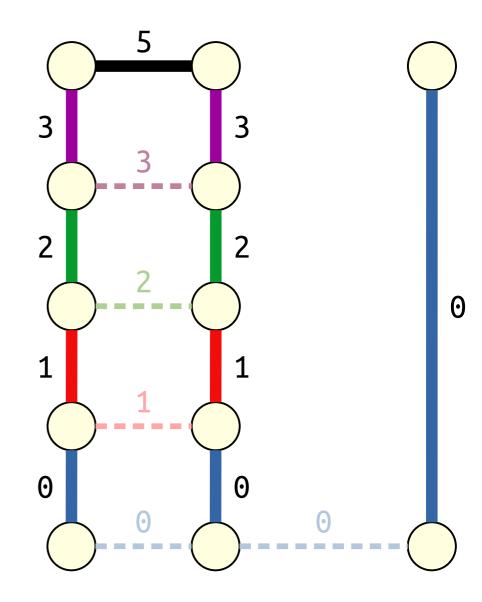
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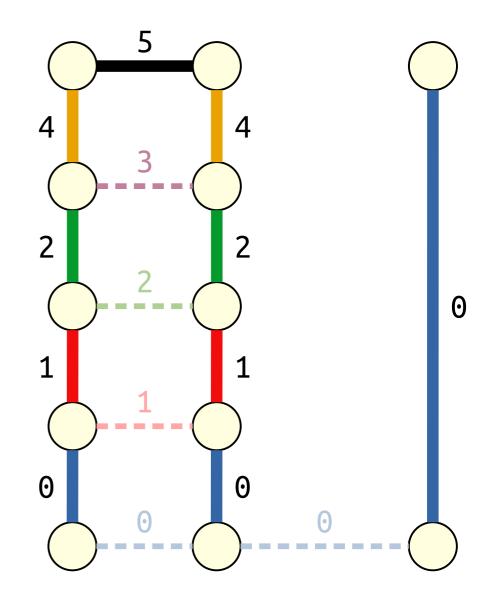
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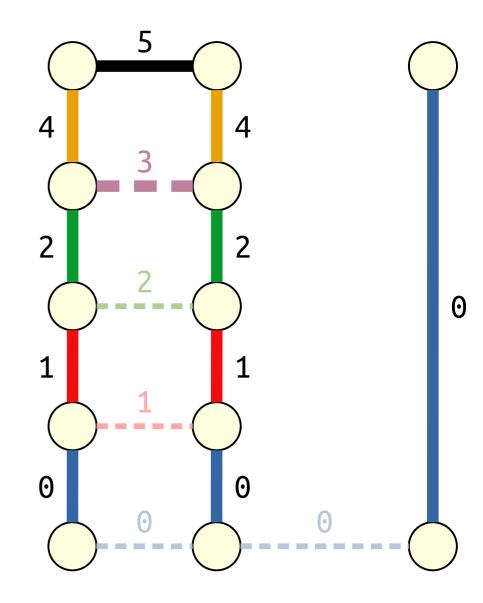
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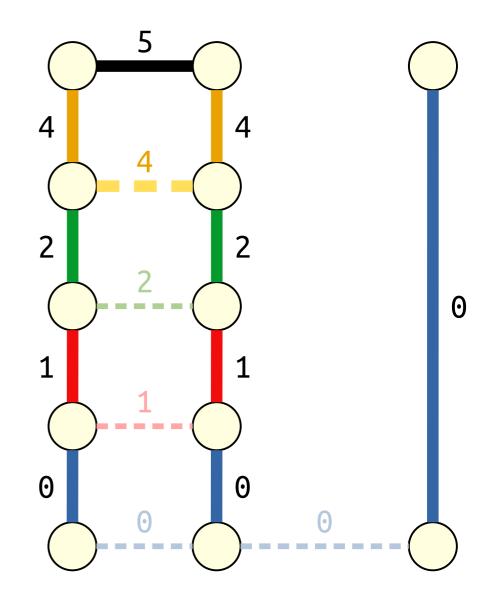
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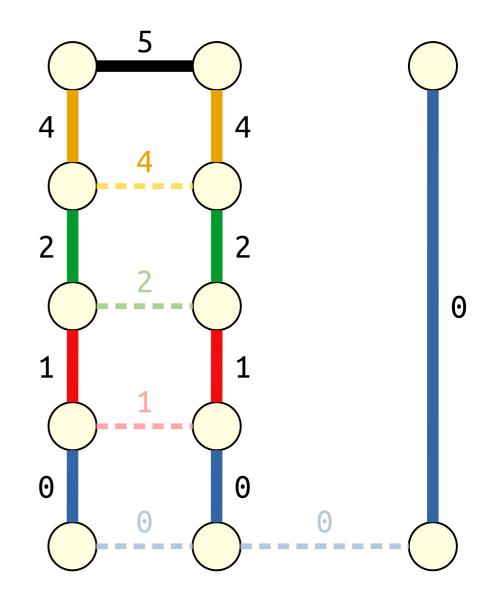
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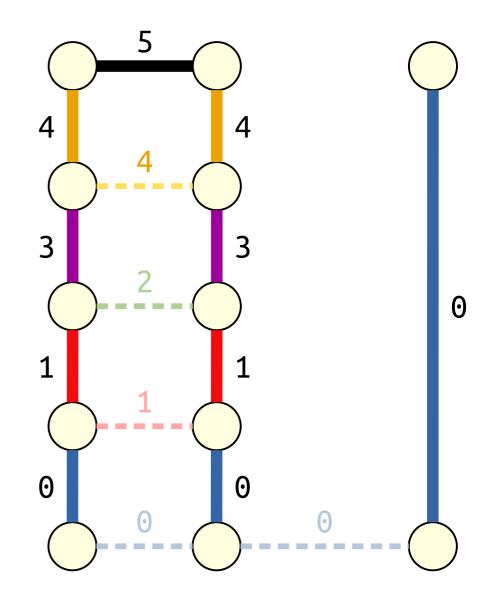
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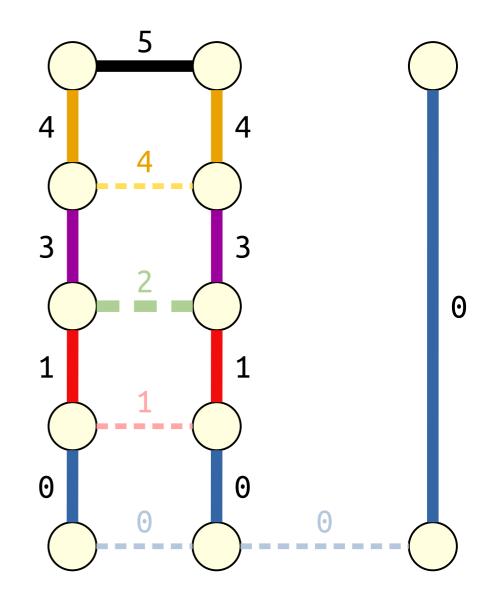
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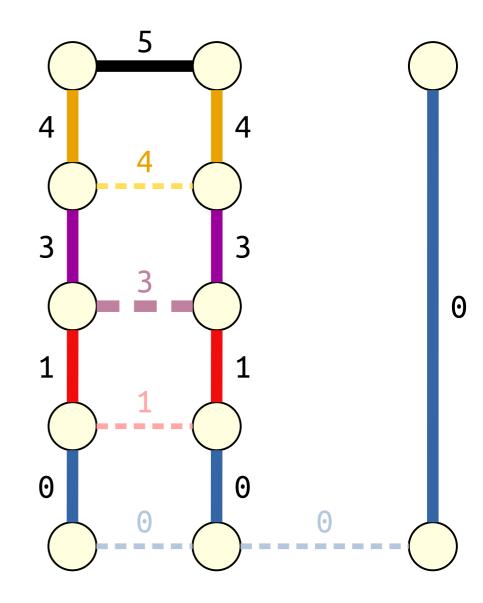
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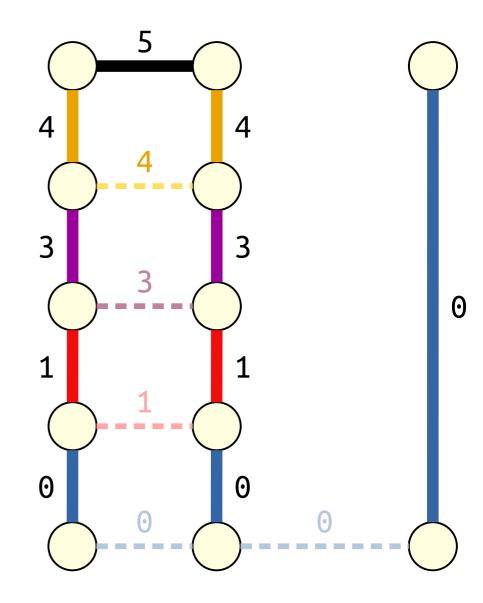
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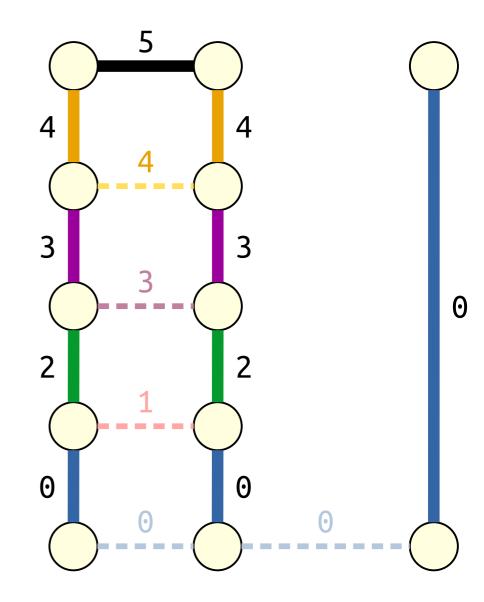
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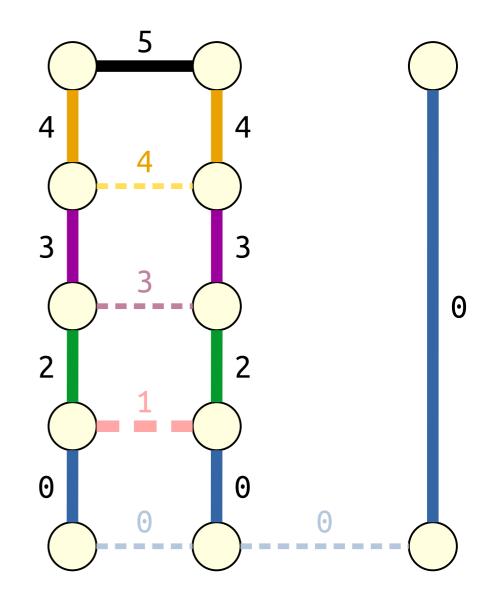
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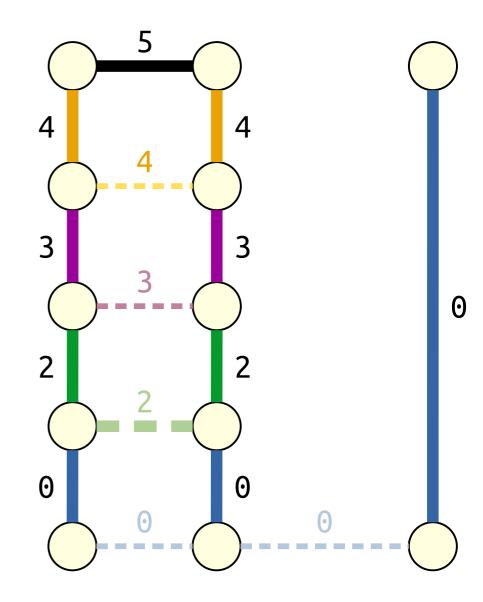
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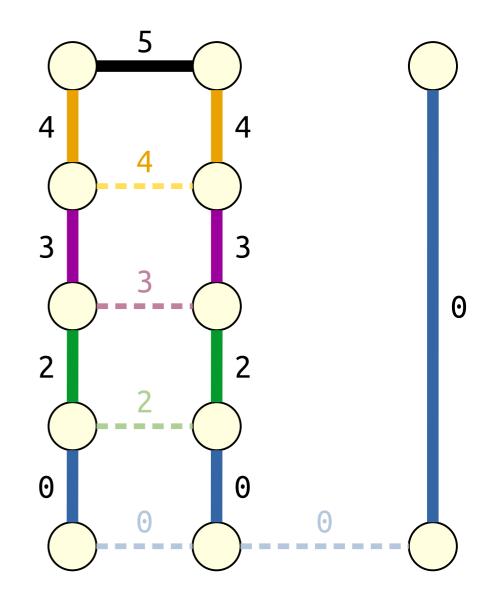
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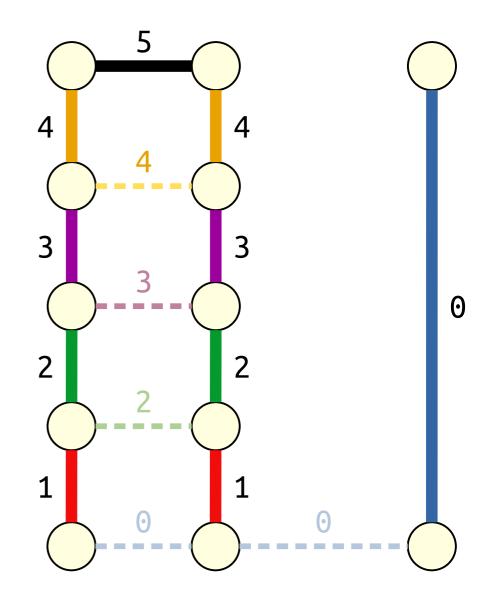
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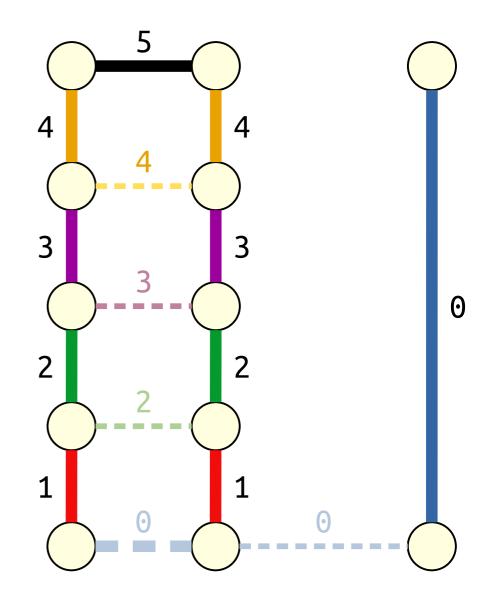
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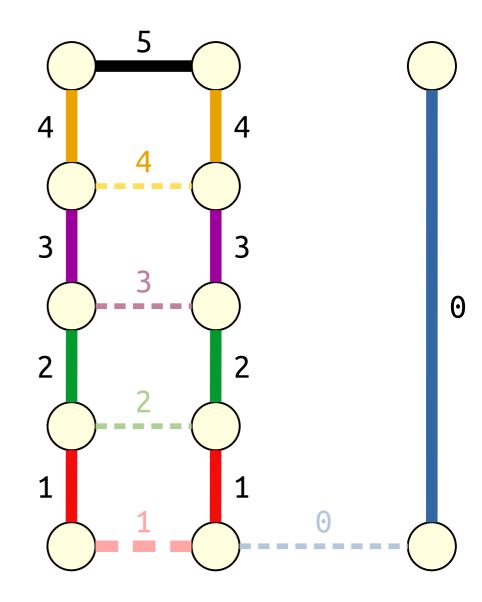
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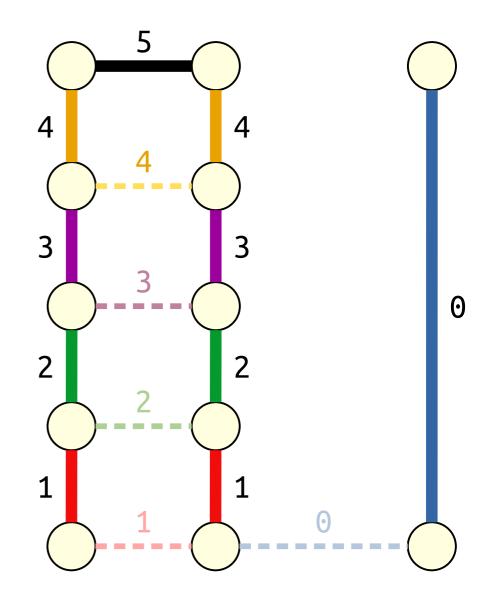
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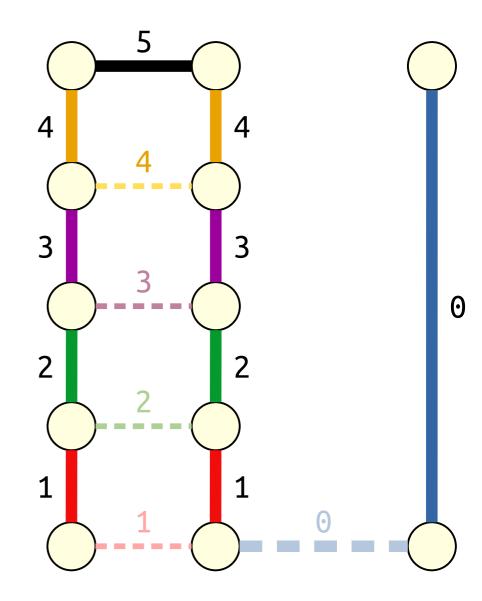
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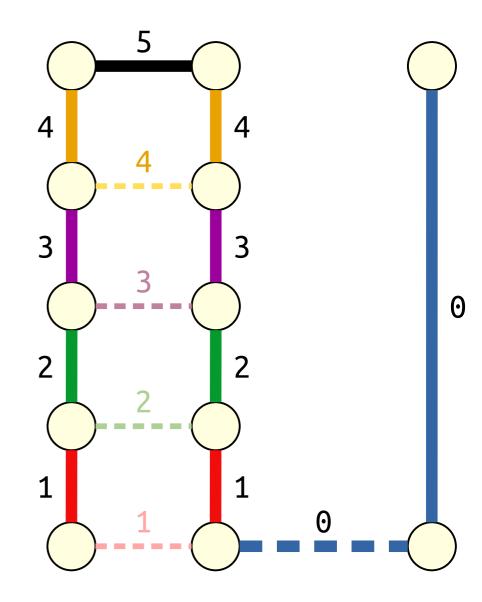
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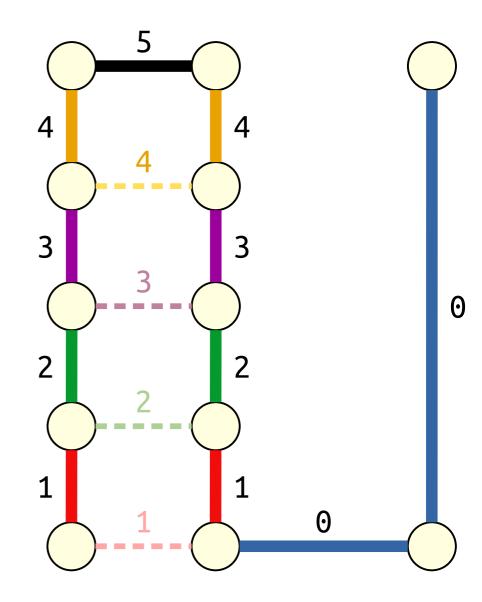
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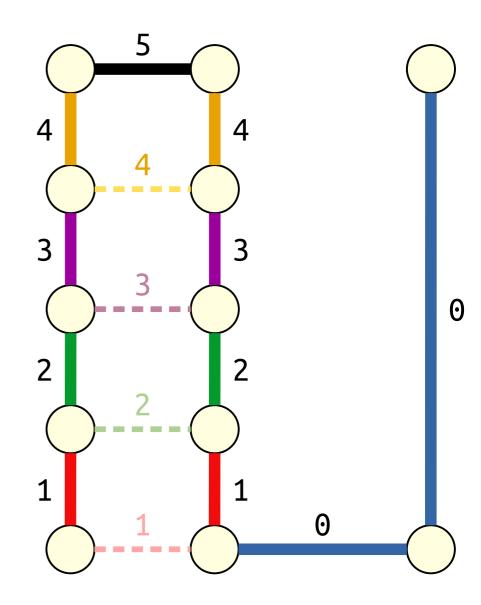
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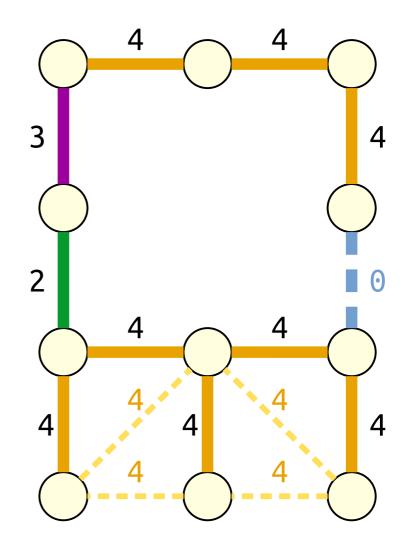


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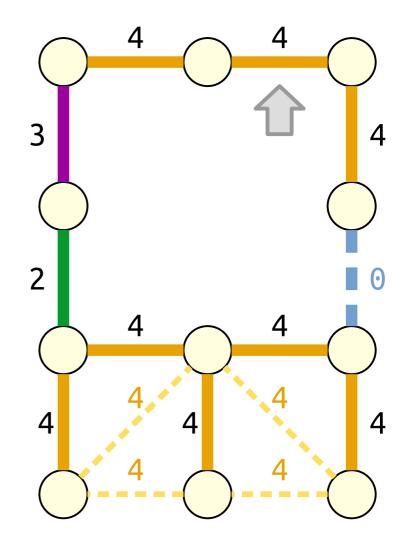


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 - This preserves the MSF property. (*Why?*)
 - This ensures that auxiliary edges, when incremented, preserve the MSF property.

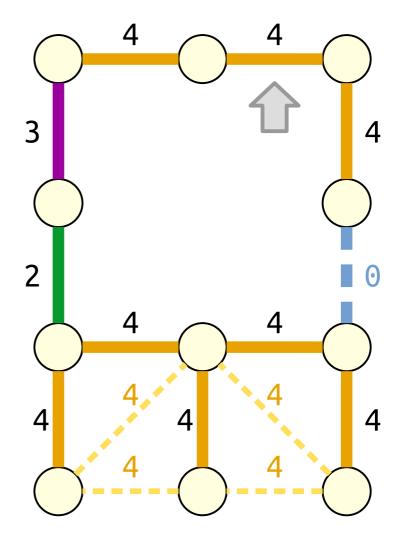




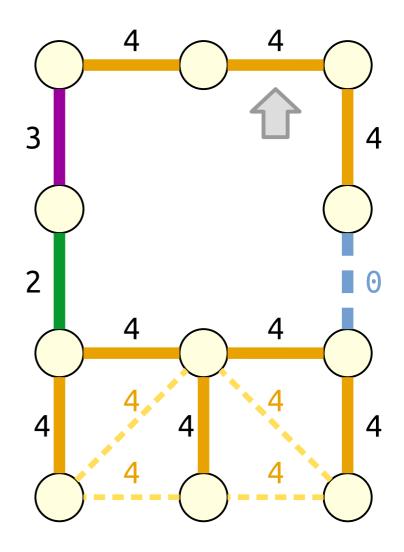
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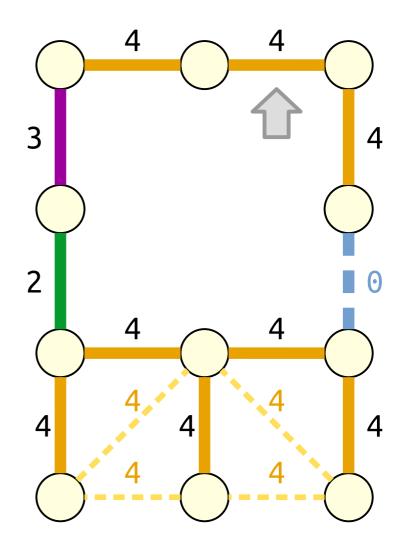
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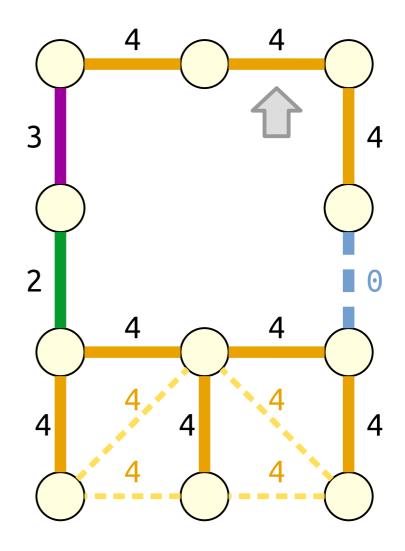
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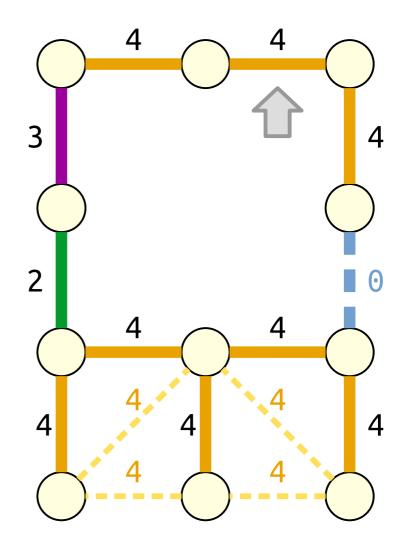
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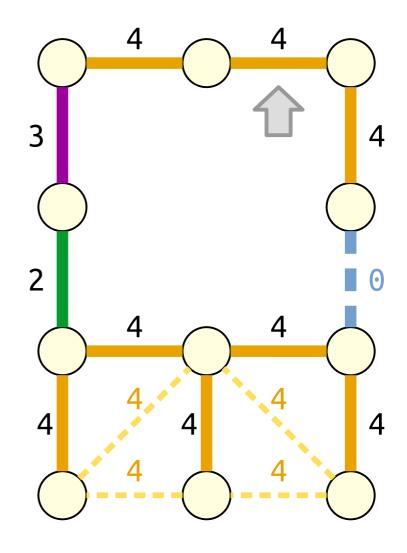
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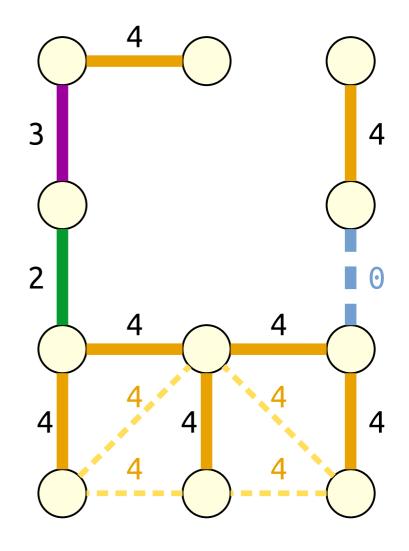
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- What can we do with this insight?



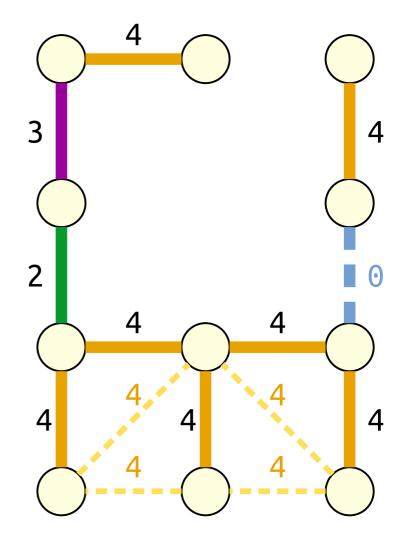
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 Instead just look at subtrees using edges of levels *l* and above.
- Use the same algorithms as before, except restricted to those trees.



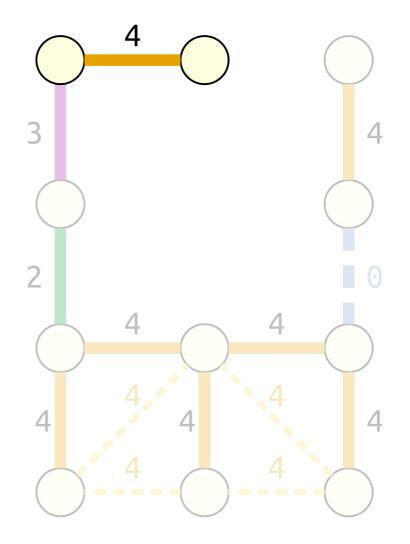
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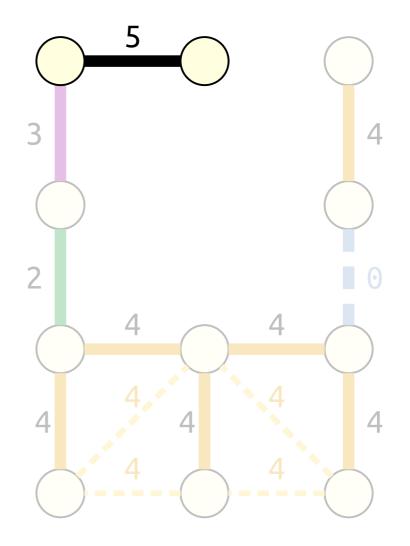
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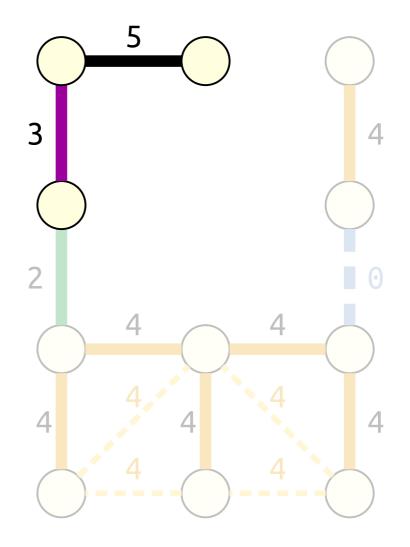
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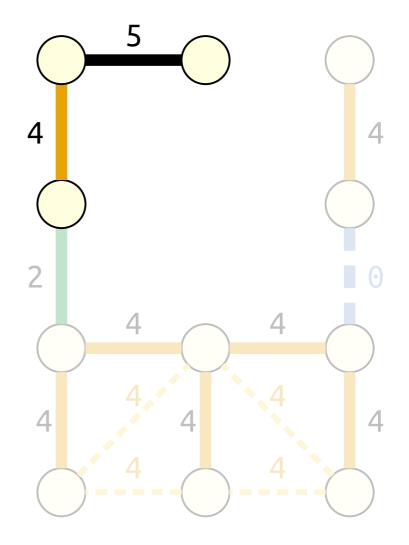
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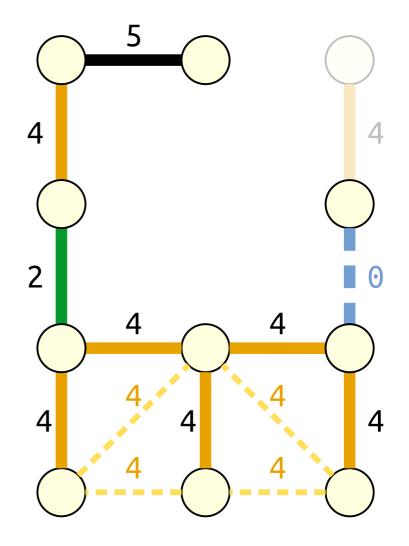
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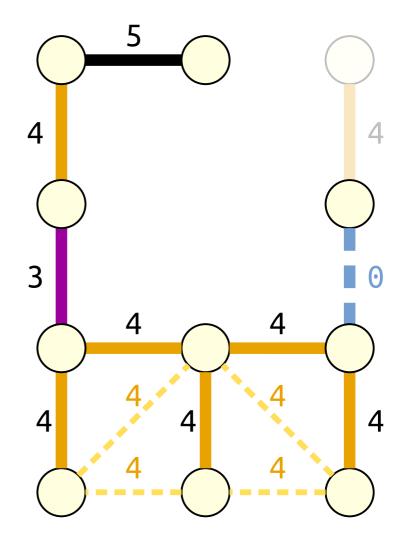
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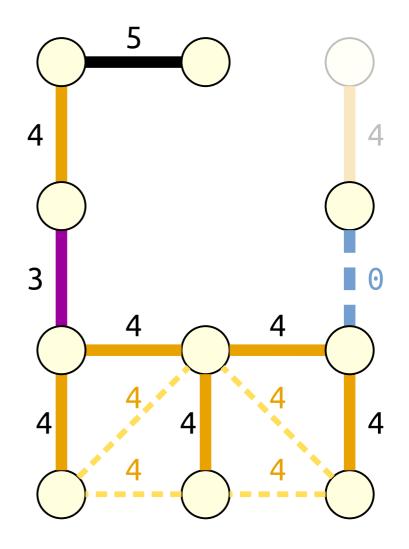
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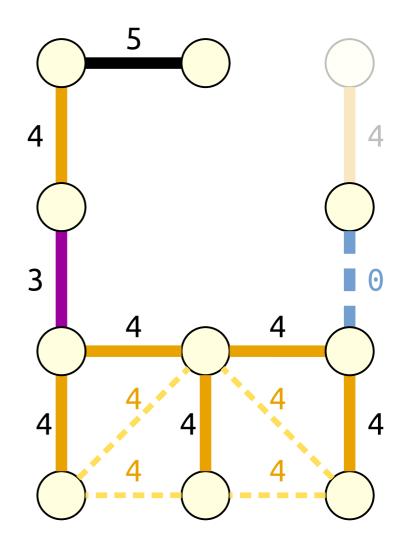
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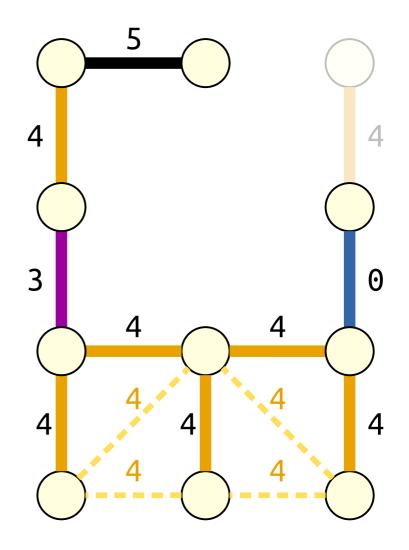
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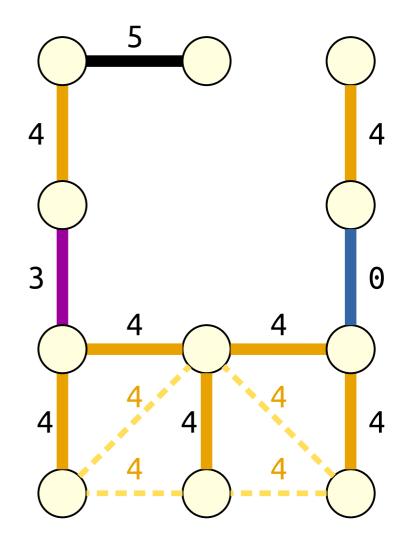
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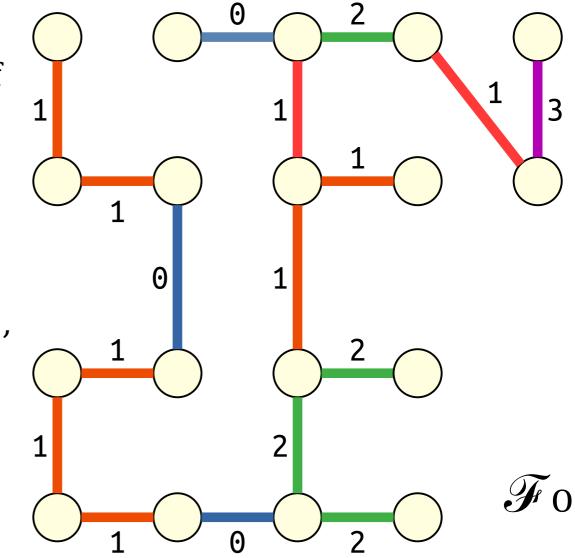
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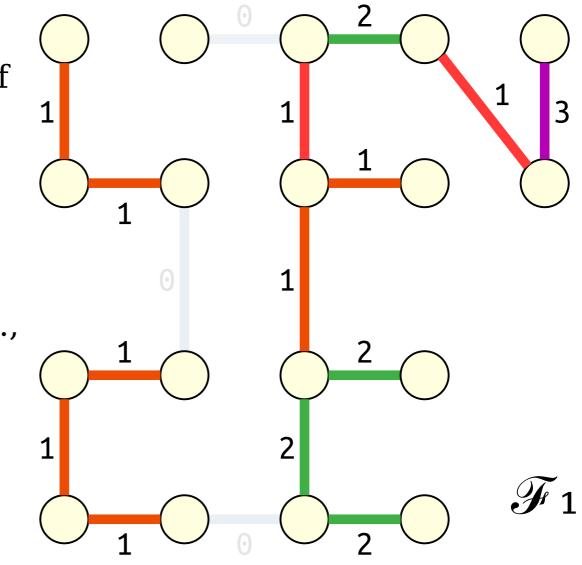
To Recap

- To maintain our MSF, we need to do the following:
 - If we cut an edge at level *l*, we need to search for auxiliary edges first at level *l*, then *l* – 1, then *l* – 2, etc. Otherwise the edge we add might not result in an MSF.
 - When searching for auxiliary edges, we only need to search the part of the tree reachable by edges of level *i* or higher. Any other auxiliary edges in the tree can't possibly be part of the MSF.
 - For each level *i*, before we search for auxiliary edges, we need to increase the level of all tree edges at level *i* to level *i*+1. Otherwise when an edge fails to reconnect and we boost its level, we might not get an MSF.
- Putting this all together:
 - We need a mechanism to quickly find all auxiliary edges of a given level, in a subtree reachable using only edges of a given level or higher, while being able to find all tree edges of a given level quickly.

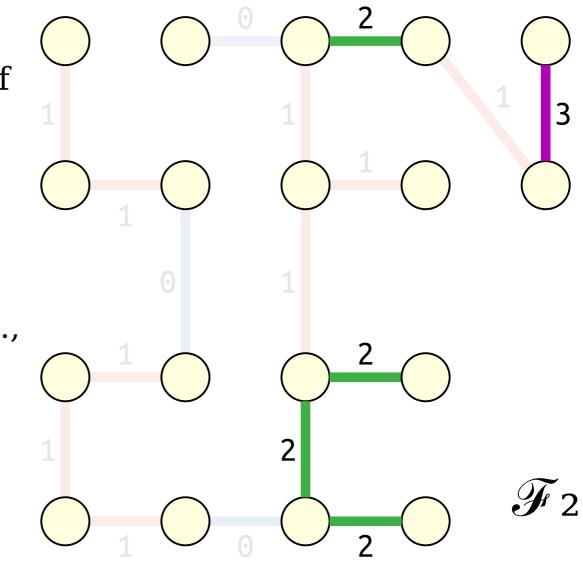
- *Idea:* Store multiple versions of the forest, each focusing on edges of some level or above.
- Let *F*₁ to be the forest of all edges of level *l* or higher.
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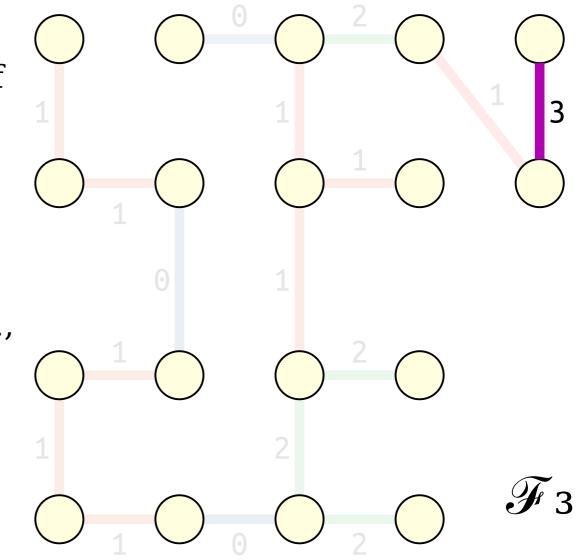
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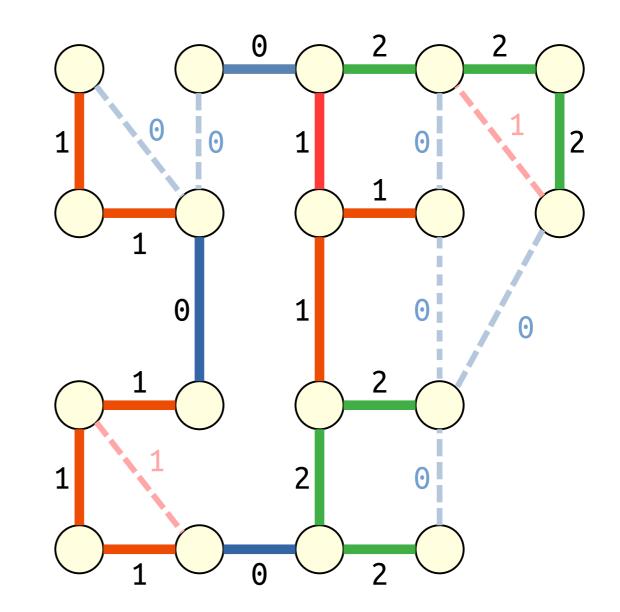
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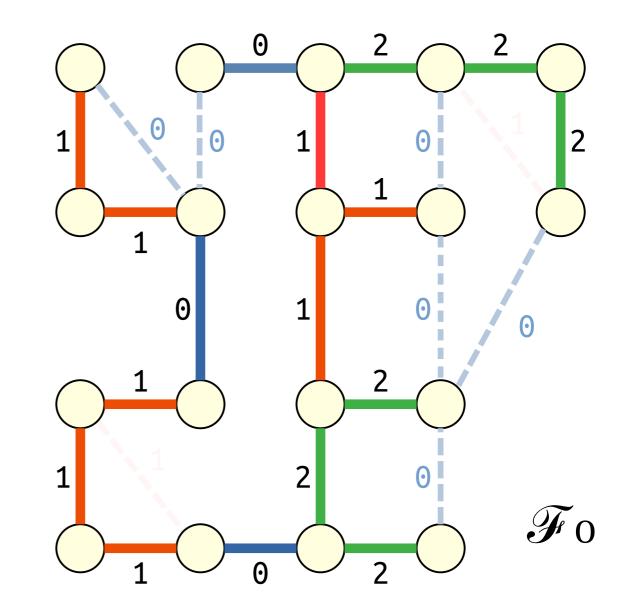


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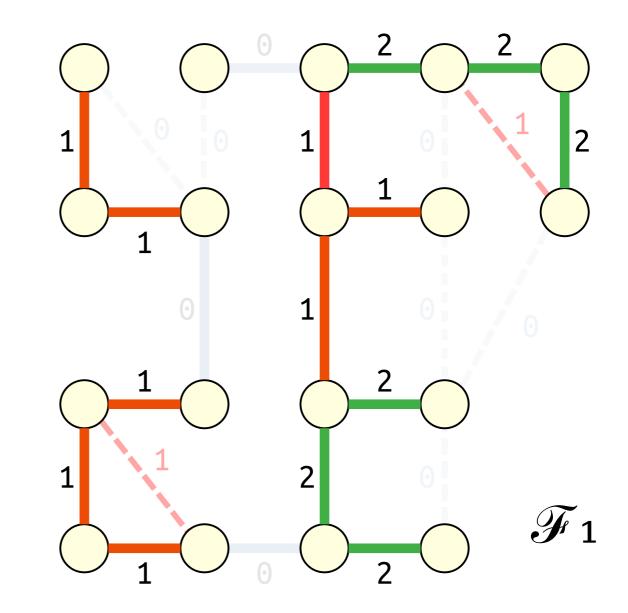
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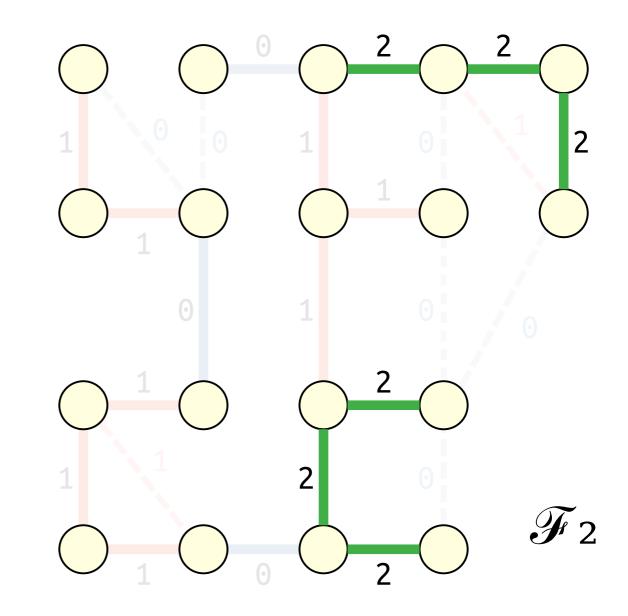
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Otherwise add xy as a tree edge to \mathcal{F}_0 .

To cut(x, y), where xy is a tree edge of level *l*:

Delete xy from \mathcal{F}_0 , \mathcal{F}_1 , ..., and \mathcal{F}_l .

For each level *i* from *l* down to 0:

Let T_x and T_y be the trees in \mathscr{F}_i containing x and y.

Select one of T_x and T_y arbitrarily; WLOG assume it's T_x .

Increment the level of each tree edge of level *i* in T_x , adding each as tree edges to \mathcal{F}_{i+1} .

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How fast is this?

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This is an *are-connected* query in *F*₀. It takes amortized time **O(log n)**.

Let T_x and T_y be the trees in \mathscr{F}_i containing x and y.

Select one of T_x and T_y arbitrarily; WLOG assume it's T_x .

Increment the level of each tree edge of level *i* in T_x , adding each as tree edges to \mathcal{F}_{i+1} .

For each auxiliary edge uv in \mathcal{F}_i touching T_x :

If uv connects T_x and T_y , add uv as a tree edge to \mathcal{F}_r for $r \leq i$. Stop. Else remove uv as an aux edge from \mathcal{F}_i , increment its level, and add it as an aux edge to \mathcal{F}_{i+1} .

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*Invariant 1: F*⁰ is a maximum spanning forest. **Invariant 2:** $\mathcal{F}_0 \supseteq \mathcal{F}_1 \supseteq \mathcal{F}_2 \supseteq \dots$

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adding each as tree e

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Delete xy from $\mathcal{F}_0, \mathcal{F}_1, \dots$ This is an *are-connected* query For each level *i* from $l \operatorname{dot}$ in \mathscr{F}_0 , plus either a *link* in \mathscr{F}_0 or an augmentation update to \mathcal{F}_0 to add xy as a tree edge.

Cost: amortized **O(log** *n*).

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Otherwise add xy as a tree edge to \mathcal{F}_0 .

To cut(x, y), where xy is a tree edge of level l:

Delete xy from \mathcal{F}_0 , \mathcal{F}_1 , ..., and \mathcal{F}_l .

For each level *i* from *l* down to 0:

Let T_x and T_y be the trees in \mathscr{F}_i Select one of T_x and T_y arbitrari Increment the level of each tree adding each as tree edges to \mathscr{F} For each auxiliary edge uv in \mathscr{F}

> If uv connects T_x and T_y , add Else remove uv as an aux ed

This is a *cut* operation across all the levels.

How fast

is this?

Suppose there are *L* levels in the forest. Then this takes (amortized) time **O(L log n)**.

Else remove uv as an aux edge from \mathcal{F}_i , increment its level, and add it as an aux edge to \mathcal{F}_{i+1} .

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This is a *link* operation across all the levels. It takes (amortized) time O(L log n).

For each auxiliary edge uv in \mathcal{F}_i touching $\mathbf{I}_{\mathbf{x}}$

If *uv* connects T_x and T_y , add *uv* as a tree edge to \mathscr{F}_r for $r \leq i$. Stop.

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10 IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	
If are-conne	These steps might take a long time if there are a
Otherwise ad	lot of edges to move.
To <i>cut</i> (x, y), whe	However, <i>each individual edge's level can</i>
Delete xy from	only be incremented L times.
For each leve	Idea: Amortize away this cost by "blaming" it
Let T_x and	on the cost of adding the edge.
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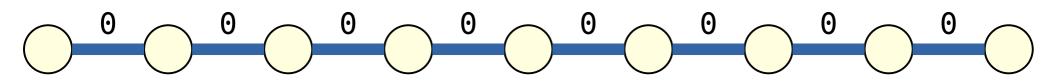
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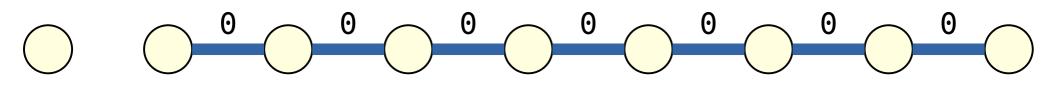
The Amortized Analysis

- Suppose the forest has a maximum of L levels.
- Raising the level of an individual edge takes time O(log n), so across all *cut* operations, we spend at most O(L log n) work on any one edge.
- With the right choice of Φ , we can get these amortized costs on the operations:
 - *link*: **O(L log n)**, paying the full cost of raising the edge's level up front.
 - *cut*: **O(L log n)**, accounting for the costs of all operations not attributable to edge raising.
- **Question:** How big can L get?

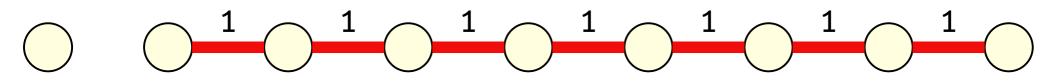
- **Problem:** Without further restrictions, the maximum level in a forest of n nodes is L = n 2.
- How can that happen? How can we prevent it?



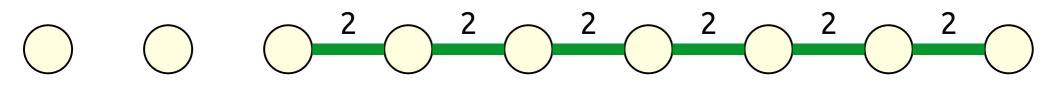
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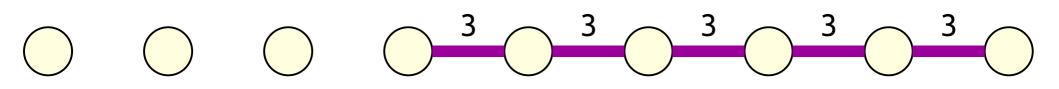
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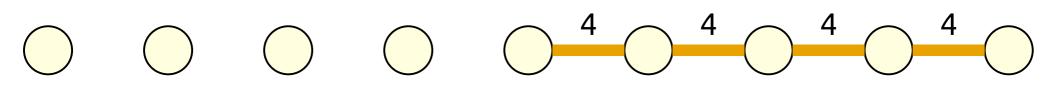
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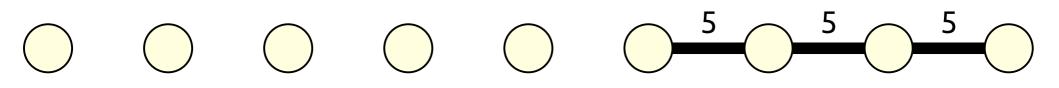
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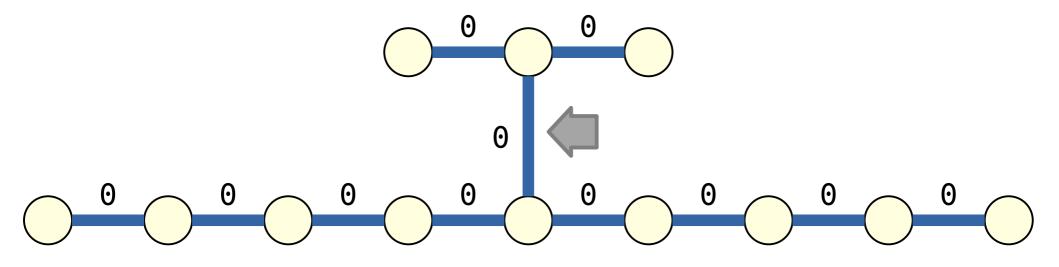
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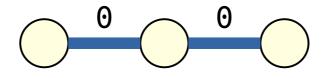
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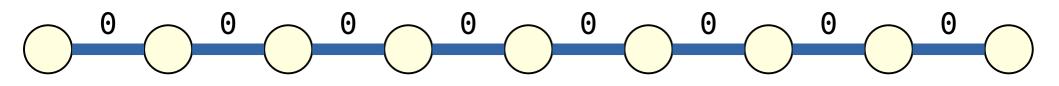
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• Suppose we cut the indicated edge.

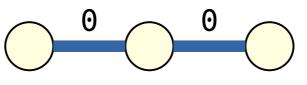


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- Suppose we cut the indicated edge.
- We need to pick one tree and raise all its edges of level 0 to level 1. Which one makes the most sense to select?
- **Answer:** The top one, since it has fewer total edges.



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Blame It On The Little Guy

- **Claim:** If we always pick the smaller tree when boosting levels, the maximum level will be $L = O(\log n)$.
- Why?



https://pollev.com/cs166spr23

Blame It On The Little Guy

- **Claim:** If we always pick the smaller tree when boosting levels, the maximum level will be $L = O(\log n)$.
- Why?
 - The maximum tree size in \mathcal{F}_0 is *n* nodes.
 - The maximum tree size in \mathcal{F}_1 is n/2 nodes.
 - The maximum tree size in \mathcal{F}_2 is n/4 nodes.
 - ...
 - The maximum tree size in $\mathscr{F}_{\lg n}$ is 1 node.
- *General Technique:* "Blame it on the little guy" by repeatedly updating the smaller of two quantities, or accounting for work done on the smaller of two quantities, etc. This often converts linear bounds to logarithmic ones.

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For each level *i* from *l* down to 0:

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The Final Scorecard

- This final data structure is called the *Holm forest* or *layered forest*. It maintains an MSF using our earlier approach while ensuring that $L = O(\log n)$.
- It supports
 - link(u, v) in amortized time $O(\log^2 n)$,
 - cut(u, v) in amortized time $O(\log^2 n)$, and
 - *are-connected*(u, v) in amortized time O(log n).
- These bounds are *substantially* better than the naive approach isn't that amazing?

The Final-er Scorecard

- There is one further improvement we can make to the structure, and it's clever.
 - All connectivity queries are done in \mathcal{F}_0 .
 - Instead of representing the Euler tour tree for \mathcal{F}_0 using splay trees, represent them with B-trees of order log n.
 - This makes *are-connected* take worst-case time $O(\frac{\log n}{\log \log n})$.
 - Updating \mathcal{F}_0 now takes time $O(\frac{\log^2 n}{\log \log n})$, but we don't notice this because the amortized cost of *link* and *cut* is still $O(\log^2 n)$.
- This structure then supports
 - *link*(u, v) in amortized time O(log² n),
 - cut(u, v) in amortized time $O(\log^2 n)$, and
 - **are-connected**(u, v) in worst-case time $O(\frac{\log n}{\log \log n})$.

Going Forward

- Here's some other amazing work folks have done in this space:
 - In 2000, Thorup introduced randomization into the Holm forest to get expected amortized O(log n (log log n)³) costs for *link* and *cut*, with O(log n / log log log n) for *are-connected* queries.
 - In 2013, Kapron et al used randomization without amortization to get O(log⁵ n) worst-case costs per link or cut and O(log n / log log n) are-connected query times, with a high chance of success.
- Every data structure for dynamic connectivity must have *link* and *cut* run in Ω(log *n*) or *are-connected* run in time Ω(log *n* / log log *n*). Is there still a ways to go, or are these lower bounds too loose? *We don't know!*

More Dynamic Problems

- Many other dynamic graph problems exist:
 - Maintaining an MST; can do in $O(\log^4 n)$ time per insertion or deletion.
 - Maintaining single-source or all-pairs shortest paths.
 - Maintaining reachability in a *directed* graph.
- All of these problems were solved in the static case 50+ years ago.
- We have somewhat decent solutions to the dynamic cases.
- This is an active area of research!

Next Time

- Word-Level Parallelism
 - Harnessing a degree of parallelism we've overlooked thus far.
- Sardine Trees
 - Outperforming BSTs for small integers.
- **MSB in O(1)**
 - A seemingly impossible bitwise operation.