Euler Tour Trees

Outline for Today

- **Dynamic Connectivity**
 - Figuring out what's connected in a graph as the edges change.
- Euler Tour Representations
 - An inspired and clever way to represent trees.
- Euler Tour Trees
 - Encoding Euler tours in a creative way.
- Extending ETTs
 - Extending our basic structure.

The Dynamic Connectivity Problem

The Connectivity Problem

• The *graph connectivity problem* is the following:

Given an undirected graph *G*, preprocess the graph so we can answer queries of the form "are nodes *u* and *v* connected?"

• Using $\Theta(m + n)$ preprocessing, can preprocess the graph to answer queries in time O(1).



Dynamic Connectivity

• The *dynamic connectivity problem* is the following:

Maintain an undirected graph G so that edges may be inserted an deleted and connectivity queries may be answered efficiently.

• This is a *much* harder problem!



Special Cases

- Last time, we covered the *incremental connectivity problem* in which edges can only
 be added and not removed.
- Today, we'll cover *dynamic connectivity in forests*, a special case in which the graph is known to be a forest.
- Next time, we'll cover *fully-dynamic connectivity*, in which there are no restrictions on which edges can be added and removed.

• Consider the following special-case of the dynamic connectivity problem:

Maintain an undirected **forest** F so that edges may be inserted an deleted and connectivity queries may be answered efficiently.

• Each deleted edge splits a tree in two; each added edge joins two trees and never closes a cycle.



• Consider the following special-case of the dynamic connectivity problem:

Maintain an undirected **forest** F so that edges may be inserted an deleted and connectivity queries may be answered efficiently.

• Each deleted edge splits a tree in two; each added edge joins two trees and never closes a cycle.



- **Goal**: Support these three operations:
 - **link**(*u*, *v*): Add in edge *uv*. The assumption is that *u* and *v* are in separate trees.
 - *cut*(*u*, *v*): Cut the edge *uv*. The assumption is that the edge exists in the forest.
 - *are-connected*(*u*, *v*): Return whether *u* and *v* are connected.
- The data structure we'll develop can perform these operations time **O(log** *n*) each.

Euler Tours

Euler Tours

- An *Euler tour* is a path through a graph *G* that visits every edge exactly once.
- It mathematically formalizes the "trace this figure without picking up your pencil or redrawing any lines" puzzles.



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- An *Euler tour* is a path through a graph *G* that visits every edge exactly once.
- It mathematically formalizes the "trace this figure without picking up your pencil or redrawing any lines" puzzles.
- Classic Theorem 1: A graph G has a closed Euler tour if and only if G is connected and every node in G has even degree.
- Classic Theorem 2: A directed graph G has a closed Euler tour if and only if G is strongly connected and every node's indegree equals its outdegree.

Euler Tours on Trees

• Trees do not have Euler tours.



ac cd db bd df fd dc ce ec ca

- **Technique:** replace each undirected edge *uv* with two directed edges *uv* and *vu*.
- The resulting graph then has an Euler tour.

Properties of Euler Tours

• **Fact:** Any cyclic shift of an Euler tour of a tree is also an Euler tour.



ab ba ag gh hi id dc cd de ed di ij ji ih hg gf fg ga

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Rerooting a Tour

- In some cases, we will need to cyclicly shift a tour to put an edge leaving a particular node *x* at front.
- We will call this operation *reroot*(*x*).



ij ji ih hg gf fg ga ab ba ag gh hi id dc cd de ed di

Rerooting a Tour

- To perform *reroot*(*x*):
 - Pick any edge *rx* leaving our new start node *r*.
 - Split the tour into *A* and *B*, where *A* consists of everything up to but not including *rx* and *B* consists of everything from *rx* forward.
 - Concatenate BA.



ij ji ih hg gf fg ga ab ba ag gh hi id dc cd de ed di

- Given two trees T_1 and T_2 , where $u \in T_1$ and $v \in T_2$, executing link(u, v) links the trees together by adding edge uv.
- Watch what happens to the Euler tours:



ab bd db bc ce ec cb ba

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- Given two trees T_1 and T_2 , where $u \in T_1$ and $v \in T_2$, executing link(u, v) links the trees together by adding edge uv.
- To *link*(*u*, *v*):
 - Let E_1 and E_2 be Euler tours of T_1 and T_2 , respectively.
 - *reroot*(*u*).
 - *reroot*(v).
 - Concatenate $E_1 uv E_2 vu$.

- Given a tree *T*, executing *cut*(*u*, *v*) cuts the edge *uv* from the tree (assuming it exists).
- Watch what happens to the Euler tour of *T*:



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ba ab bd db

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- Given a tree *T*, executing *cut*(*u*, *v*) cuts the edge *uv* from the tree (assuming it exists).
- To perform cut(u, v):
 - Let *E* be the Euler tour containing *uv* and *vu*.
 - Remove uv and vu from E to form E_1 , E_2 , and E_3 .
 - Then E_1E_3 and E_2 are Euler tours of the two new trees.

Checking Connectivity

- We also need a way to answer queries of the form *areconnected*(*u*, *v*).
- This query focuses on *nodes*, but our Euler tours store *edges*.
- *Cute Trick:* Introduce a self-loop on each node that represents the node itself. Add that to each tour as a proxy for the node itself.
- Now, we can answer *are-connected*(*x*, *y*) by seeing if *xx* and *yy* are part of the same tour.



ba aa ab bb bd dd db

ce ee ec cg gg gh hh hg gf ff fg gc cc

Checking Connectivity

- This also makes it a lot easier to reroot a tour at a node *x*.
- We simply find *xx*, then rotate that edge to the front of the tour.



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Putting It All Together

- To *link*(*x*, *y*):
 - Rotate xx and yy to the fronts of their tours T_x and T_y .
 - Join the tours together as $T_x xy T_y yx$.
- To *cut*(*x*, *y*):
 - Delete the edges xy and yxfrom the tour T to form tours T_1, T_2, T_3 .
 - Regroup the tours as $T_1 T_3$ and T_2 .
- To answer *are- connected*(x, y):
 - Determine whether *xx* and *yy* are in the same tour.



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aa ab bb ba ac cc ca ad dd de ee ed da



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cc ca ad dd da aa ab bb ba ac ce ee ec



Implementing This Approach

The Story So Far

- We've seen how to implement *reroot*, *link, cut*, and *are-connected* in terms of operations on Euler tours.
- The efficiency of those operations depend on how we choose to encode our sequences.
- *Question:* What data structure should we use to store those sequences?

- We need a representation that lets us perform the following operations:
 - Locate specific edges (*reroot*, *link*, *cut*, *are-connected*).
 - Split a sequence at a point (*reroot*, *cut*).
 - Join two sequences together (*reroot, link*).
 - Remove an edge from a sequence (*cut*).
 - Append an edge to a sequence (*link*).
 - Check if two edges are in the same sequence (*are-connected*).
- What data structures might be appropriate here?



- **Idea 1:** Use doubly-linked lists, plus an auxiliary hash table / BST to locate edges.
 - Assuming we have a hash table telling us where edges are, we can split, join, and rotate tours in time O(1).
- **Problem:** There isn't an easy way to test whether two nodes are in the same tour. Scanning within the linked list make take time $\Theta(n)$.
- Can we do better?



- In incremental connectivity, we selected a representative for each CC.
- We then had elements store parent pointers that formed a path to the representative.
- Could we do something like that here?



- The idea of using trees to store representatives is a good one.
 - If the trees are wide and flat, it won't take too long to find the representative.
 - If we don't have to update "too many" pointers when CC's change, our operations can run quickly.
- The trees we used last time won't (immediately) work here.
 - We have to store the elements of the tour in sequential order. There was no such notion of order in disjoint set forests.
 - In disjoint-set forests, linked items can never be cut, allowing for some clever optimizations.
- What's another tree we can use?



- **Idea 2:** Store our sequences in a balanced BST, sorted by their position within the sequence.
- We'll use the *shape* and *algorithm* of a BST, but won't have the ability to conventionally search the tree top-down.
- We'll rely on the fact that we have external pointers that let us jump to items within the BST.



- We can now answer *are-connected*(x, y) in time O(log n).
 - Find *xx* and *yy* using our auxiliary lookup table.
 - Walk up from *xx* and *yy* to the roots of their trees.
 - See if they're the same root.



- **Challenge:** We need to be able to cut a sequence just before an edge, and we need to be able to join two sequences together efficiently.
- **Answer:** Use splay trees! They support these operations in amortized time O(log *n*).





ae



ae



ae

ba

db

ef

ee

ff

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ea

[°]dd

cb

bc

ab

bb

aa

bd

CC

• **Answer:** Use splay trees! They support these operations in amortized time O(log *n*).

 \boldsymbol{C}

aa ab bb bc cc cb bd dd db ba ae ee ef ff fe ea

e

b

а

ea

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ef

ae



To answer
 are-connected(x, y):



- To answer
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 - Splay *xx*.



- To answer
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- To answer
 are-connected(x, y):
 - Splay *xx*.
 - Splay yy.
 - Return whether *xx* was encountered on the second splay.
- Amortized cost:
 O(log n).



- To *reroot*(*x*):
 - Splay *xx*.



aa ab bb bc cc cb bd dd db ba

- To *reroot*(*x*):
 - Splay *xx*.
 - Disconnect *xx*'s left child tree *T*.



cc cb bd dd db ba

- To *reroot*(*x*):
 - Splay *xx*.
 - Disconnect *xx*'s left child tree *T*.
 - Splay the rightmost node in *xx*'s subtree.



aa ab bb bc

cc cb bd dd db ba

- To *reroot*(*x*):
 - Splay *xx*.
 - Disconnect *xx*'s left child tree *T*.
 - Splay the rightmost node in *xx*'s subtree.
 - Make *T* the right child of the root.
- Amortized cost:
 O(log n).



cc cb bd dd db ba aa ab bb bc

• To *link*(*x*, *y*):



cc cd ... dc jj jk ... jk

- To *link*(*x*, *y*):
 - *reroot*(x) and
 reroot(y).



xx xa ... ax yy yf ... fy

- To *link*(*x*, *y*):
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 - Set *yy*'s tree as *xy*'s right child.



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xx xa ... ax xy yy yf ... fy yx

• To *cut*(*x*, *y*):



aa ab ... cx xy yy yf ... fy yx xt ... ba

- To *cut*(*x*, *y*):
 - Splay *xy*.



aa ab ... cx xy yy yf ... fy yx xt ... ba
- To *cut*(*x*, *y*):
 - Splay *xy*.
 - Delete *xy*.



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aa ab ... cx xt ... ba yy yf ... fy

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- Amortized cost: O(log n).



aa ab ... cx xt ... ba yy yf ... fy

- With all things said and done, we get the following amortized runtimes for each operation:
 - *are-connected*: O(log *n*)
 - *link*: O(log *n*)
 - *cut*: O(log *n*)
- These bounds can be made worst-case efficient using different types of balanced BSTs instead of splay trees, but splaying is probably the fastest way to do this.

- We now have a (relatively) simple and fast data structure for solving dynamic connectivity in forests.
- What else can we do with them?

- Suppose we want to add an operation
 size(x) that returns the number of nodes in the tree containing x.
- How might we accomplish this?



- We can determine size(x) as follows:
 - Figure out which Euler tour *xx* is in.
 - Count how many nodes of the form *zz* it contains.
- A naive implementation of this algorithm might take time $\Theta(n)$ if all nodes are in the same tree. Can we do better?



aa ab bb bc cc cb bd dd db ba



ee ef ff fe

- We're storing our Euler tours in balanced BSTs.
- We want to be able to answer the following question about a given BST:

How many nodes of the form xx are in this BST?

• This can be done in time O(log *n*). How?



- *Idea:* Augment the BSTs holding our Euler tours.
- Specifically, each node stores the number of self-loops at or below it in the tree.
- This information can be maintained through rotations and after each splay tree operation.





To determine
 size(x):

- To determine
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 - Splay *xx*.



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- To determine size(x):
 - Splay *xx*.
 - Return the augmented value in the node for *xx*.
- Amortized cost: **O(log n)**.



- Suppose that each node represents a network router.
- We want to add these two operations:
 - *add-packet*(*x*, *p*), which attaches packet *p* to node *x*; and
 - **remove-packet**(*x*), which removes and returns some packet reachable from *x*, chosen arbitrarily from all the options.
- How might we do this?



• Given the Euler tour representation of our trees, this essentially boils down to the following:

Augment a BST containing nodes and edges so that we can quickly identify a node with a packet.

• How might we do this?

- Augment each node xx with a list of the packets it stores.
- Augment each tree node with a bit indicating whether there's a packet in its subtree.
- We can use this latter information to quickly find nodes holding packets.



• To find and remove a packet:



- To find and remove a packet:
 - Walk from the root to any node containing a packet, using the augmentation to guide the search.



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 - Remove a packet from it, updating the root's augmentation.



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 - Splay that node to the root.
 - Remove a packet from it, updating the root's augmentation.
- Amortized cost:
 O(log n).



Generalizing This Idea

- More generally, Euler tour trees play well with augmentations that care about global properties of individual trees.
- There's another way to use splay trees to encode dynamic trees (*st-trees*, also called *link/cut trees*, though the later name is ambiguous) that works well for augmenting over *paths* in trees rather than trees as a whole.
- (Check out the Sleator/Tarjan paper for more details.)

Next Time

- Fully-Dynamic Connectivity
 - Solving connectivity in general graphs, not just forests.
- "Blame It On The Little Guy"
 - A surprisingly versatile algorithmic strategy.
- Holm's Structure
 - An elegant way to solve dynamic connectivity by harnessing augmented ETTs.