## Euler Tour Trees

## Outline for Today

- Dynamic Connectivity
- Figuring out what's connected in a graph as the edges change.
- Euler Tour Representations
- An inspired and clever way to represent trees.
- Euler Tour Trees
- Encoding Euler tours in a creative way.
- Extending ETTs
- Extending our basic structure.


## The Dynamic Connectivity Problem

## The Connectivity Problem

- The graph connectivity problem is the following:

Given an undirected graph $G$, preprocess the graph so we can answer queries of the form "are nodes $u$ and $v$ connected?"

- Using $\Theta(m+n)$ preprocessing, can preprocess the graph to answer queries in time $O(1)$.



## Dynamic Connectivity

- The dynamic connectivity problem is the following:

Maintain an undirected graph $G$ so that edges may be inserted an deleted and connectivity queries may be answered efficiently.

- This is a much harder problem!



## Special Cases

- Last time, we covered the incremental connectivity problem in which edges can only be added and not removed.
- Today, we'll cover dynamic connectivity in forests, a special case in which the graph is known to be a forest.
- Next time, we'll cover fully-dynamic connectivity, in which there are no restrictions on which edges can be added and removed.

Dynamic Connectivity in Forests

## Dynamic Connectivity in Forests

- Consider the following special-case of the dynamic connectivity problem:
Maintain an undirected forest $F$ so that edges may be inserted an deleted and connectivity queries may be answered efficiently.
- Each deleted edge splits a tree in two; each added edge joins two trees and never closes a cycle.



## Dynamic Connectivity in Forests

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Maintain an undirected forest $F$ so that edges may be inserted an deleted and connectivity queries may be answered efficiently.
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## Dynamic Connectivity in Forests

- Goal: Support these three operations:
- link(u,v): Add in edge uv. The assumption is that $u$ and $v$ are in separate trees.
- cut( $u, v$ ): Cut the edge $u v$. The assumption is that the edge exists in the forest.
- are-connected $(u, v)$ : Return whether $u$ and $v$ are connected.
- The data structure we'll develop can perform these operations time $\mathbf{O}(\log n)$ each.


## Euler Tours

## Euler Tours

- An Euler tour is a path through a graph $G$ that visits every edge exactly once.
- It mathematically formalizes the "trace this figure without picking up your pencil or redrawing any lines" puzzles.



## Euler Tours

- An Euler tour is a path through a graph $G$ that visits every edge exactly once.
- It mathematically formalizes the "trace this figure without picking up your pencil or redrawing any lines" puzzles.
- Classic Theorem 1: A graph $G$ has a closed Euler tour if and only if $G$ is connected and every node in $G$ has even degree.
- Classic Theorem 2: A directed graph $G$ has a closed Euler tour if and only if $G$ is strongly connected and every node's indegree equals its outdegree.


## Euler Tours on Trees

- Trees do not have Euler tours.

ac cd db bd dffd dc ce ec ca
- Technique: replace each undirected edge $u v$ with two directed edges $u v$ and $v u$.
- The resulting graph then has an Euler tour.


## Properties of Euler Tours

- Fact: Any cyclic shift of an Euler tour of a tree is also an Euler tour.

ab ba ag gh hi id dc cd de ed di ij ji ih hg gf fg ga


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## Rerooting a Tour

- In some cases, we will need to cyclicly shift a tour to put an edge leaving a particular node $x$ at front.
- We will call this operation reroot(x).

ij ji ih hg gf fg ga ab ba ag gh hi id dc cd de ed di


## Rerooting a Tour

- To perform reroot(x):
- Pick any edge $r x$ leaving our new start node $r$.
- Split the tour into $A$ and $B$, where $A$ consists of everything up to but not including $r x$ and $B$ consists of everything from $r x$ forward.
- Concatenate $B A$.

ij ji ih hg gf fg ga ab ba ag gh hi id dc cd de ed di


## Euler Tours and Dynamic Trees

- Given two trees $T_{1}$ and $T_{2}$, where $u \in T_{1}$ and $v \in T_{2}$, executing link ( $u, v$ ) links the trees together by adding edge $u v$.
- Watch what happens to the Euler tours:

ab bd db bc ce ec cb ba



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## Euler Tours and Dynamic Trees

- Given two trees $T_{1}$ and $T_{2}$, where $u \in T_{1}$ and $v \in T_{2}$, executing link( $u, v$ ) links the trees together by adding edge $u v$.
- To link(u, v):
- Let $E_{1}$ and $E_{2}$ be Euler tours of $T_{1}$ and $T_{2}$, respectively.
- reroot(u).
- reroot(v).
- Concatenate $E_{1} u v E_{2} v u$.


## Euler Tours and Dynamic Trees

- Given a tree $T$, executing cut( $u, v$ ) cuts the edge $u v$ from the tree (assuming it exists).
- Watch what happens to the Euler tour of $T$ :

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## Euler Tours and Dynamic Trees

- Given a tree $T$, executing cut( $u, v$ ) cuts the edge $u v$ from the tree (assuming it exists).
- To perform cut(u,v):
- Let $E$ be the Euler tour containing $u v$ and $v u$.
- Remove $u v$ and $v u$ from $E$ to form $E_{1}, E_{2}$, and $E_{3}$.
- Then $E_{1} E_{3}$ and $E_{2}$ are Euler tours of the two new trees.


## Checking Connectivity

- We also need a way to answer queries of the form areconnected ( $u, v$ ).
- This query focuses on nodes, but our Euler tours store edges.
- Cute Trick: Introduce a self-loop on each node that represents the node itself. Add that to each tour as a proxy for the node itself.
- Now, we can answer are-connected $(x, y)$ by seeing if $x x$ and yy are part of the same tour.



## Checking Connectivity

- This also makes it a lot easier to reroot a tour at a node $x$.
- We simply find $x x$, then rotate that edge to the front of the tour.



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## Putting It All Together

- To link(x, y):
- Rotate $x x$ and $y y$ to the fronts
of their tours $T_{x}$ and $T_{y}$.
- Join the tours together as
$a$
aa $T_{x} x y T_{y} y x$.
- To cut( $x, y$ ):
- Delete the edges $x y$ and $y x$ from the tour $T$ to form tours $T_{1}, T_{2}, T_{3}$.
- Regroup the tours as $T_{1} T_{3}$ and $T_{2}$.
- To answer areconnected ( $x, y$ ):
- Determine whether $x x$ and $y y$ are in the same tour.



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aa ab bb ba ac cc ca ad dd de ee ed da



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cc ca ad dd da aa ab bb ba ac ce ee ec



## Implementing This Approach

## The Story So Far

- We've seen how to implement reroot, link, cut, and are-connected in terms of operations on Euler tours.
- The efficiency of those operations depend on how we choose to encode our sequences.
- Question: What data structure should we use to store those sequences?


## Representation Issues

- We need a representation that lets us perform the following operations:
- Locate specific edges (reroot, link, cut, are-connected).
- Split a sequence at a point (reroot, cut).
- Join two sequences together (reroot, link).
- Remove an edge from a sequence (cut).
- Append an edge to a sequence (link).
- Check if two edges are in the same sequence (are-connected).
- What data structures might be appropriate here?

Answer at
https://pollev.com/cs166spr23

## Representation Issues

- Idea 1: Use doubly-linked lists, plus an auxiliary hash table / BST to locate edges.
- Assuming we have a hash table telling us where edges are, we can split, join, and rotate tours in time O(1).
- Problem: There isn't an easy way to test whether two nodes are in the same tour. Scanning within the linked list make take time $\Theta(n)$.
- Can we do better?



## Representation Issues

- In incremental connectivity, we selected a representative for each CC.
- We then had elements store parent pointers that formed a path to the representative.
- Could we do something like that here?



## Representation Issues

- The idea of using trees to store representatives is a good one.
- If the trees are wide and flat, it won't take too long to find the representative.
- If we don't have to update "too many" pointers when CC's change, our operations can run quickly.
- The trees we used last time won't (immediately) work here.
- We have to store the elements of the tour in sequential order. There was no such notion of order in disjoint set forests.
- In disjoint-set forests, linked items can never be cut, allowing for some clever optimizations.
- What's another tree we can use?



## Binary Search(less) Trees

- Idea 2: Store our sequences in a balanced BST, sorted by their position within the sequence.
- We'll use the shape and algorithm of a BST, but won't have the ability to conventionally search the tree top-down.
- We'll rely on the fact that we have external pointers that let us jump to items within the BST.

aa ab bb bc cc cb bd dd db ba

$e e$ ef ff fe


## Binary Search(less) Trees

- We can now answer are-connected $(x, y)$ in time O(log $n$ ).
- Find $x x$ and $y y$ using our auxiliary lookup table.
- Walk up from $x x$ and $y y$ to the roots of their trees.
- See if they're the same root.

aa ab bb bc cc cb bd dd db ba



## Binary Search(less) Trees

- Challenge: We need to be able to cut a sequence just before an edge, and we need to be able to join two sequences together efficiently.
- Answer: Use splay trees! They support these operations in amortized time $O(\log n)$.

aa ab bb bc cc cb bd dd db ba




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## Euler Tour Trees

- To answer are-connected $(x, y)$ :



## Euler Tour Trees

- To answer are-connected (x, y):
- Splay xx.



## Euler Tour Trees

- To answer are-connected $(x, y)$ :
- Splay $x x$.
- Splay yy.



## Euler Tour Trees

- To answer are-connected( $x, y$ ):
- Splay $x x$.
- Splay yy.
- Return whether $x x$ was encountered on the second splay.
- Amortized cost: $\mathbf{O}(\log n)$.



## Euler Tour Trees

## - To reroot( $x$ ):

- Splay $x x$.

aa ab bb bc cc cb bd dd db ba


## Euler Tour Trees

- To reroot(x):
- Splay $x x$.
- Disconnect $x$ x's left child tree $T$.



## Euler Tour Trees

- To reroot( $x$ ):



## Euler Tour Trees

- To reroot( $x$ ):
- Splay $x x$.
- Disconnect $x x^{\prime}$ s left child tree $T$.
- Splay the rightmost node in $x$ 's subtree.
- Make T the right child of the root.
- Amortized cost: $\mathbf{O}(\log n)$.

cc cb bd dd db ba aa ab bb bc


## Euler Tour Trees

- To link $(x, y)$ :

cc cd ... dc
$\boldsymbol{j} \boldsymbol{j} \boldsymbol{j} k . . . j k$


## Euler Tour Trees

- To link $(x, y)$ :
- reroot(x) and reroot(y).



## Euler Tour Trees

- To link $(x, y)$ :
- reroot(x) and reroot(y).
- Add $x y$ as the rightmost node of $x$ 's tree.

$y y y f . . . f y$


## Euler Tour Trees

- To link $(x, y)$ :
- reroot(x) and reroot(y).
- Add $x y$ as the rightmost node of $x$ 's tree.
- Splay xy.



## Euler Tour Trees

- To link( $x, y$ ):
- reroot( $x$ ) and reroot(y).
- Add $x y$ as the rightmost node of $x$ 's tree.
- Splay $x y$.
- Set $y y^{\prime}$ s tree as $x y^{\prime}$ s right child.



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- Set $y y^{\prime}$ s tree as $x y$ 's right child.
- Add $y x$ as the rightmost node of the tree.

xx xa ... ax xy yy yf ... fy yx


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- Amortized cost: O(log $n$ ).


## Euler Tour Trees

- To cut $(x, y)$ :


## Euler Tour Trees

- To cut $(x, y)$ :
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## Euler Tour Trees

- To cut $(x, y)$ :
- Splay xy.
- Delete xy.



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## Euler Tour Trees

- To cut $(x, y)$ :
- Splay xy.
- Delete xy.
- Splay yx.
- Delete yx.
- Let $T_{1}$ and $T_{2}$ be the trees on the left and right.



## Euler Tour Trees

- To cut $(x, y)$ :
- Splay xy.
- Delete xy.
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- Let $T_{1}$ and $T_{2}$ be the trees on the left and right.
- Splay the rightmost node of $T_{1}$.



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- Splay the rightmost node of $T_{1}$.
- Attach $T_{2}$ as the right child of that node.



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- Let $T_{1}$ and $T_{2}$ be the trees on the left and right.
- Splay the rightmost node of $T_{1}$.
- Attach $T_{2}$ as the right child of that node.
- Amortized cost: $\mathbf{O}(\log \boldsymbol{n})$.


## Euler Tour Trees

- With all things said and done, we get the following amortized runtimes for each operation:
- are-connected: O(log $n$ )
- link: O(log $n$ )
- cut: O(log n)
- These bounds can be made worst-case efficient using different types of balanced BSTs instead of splay trees, but splaying is probably the fastest way to do this.


## Extending Euler Tour Trees

## Extending Euler Tour Trees

- We now have a (relatively) simple and fast data structure for solving dynamic connectivity in forests.
- What else can we do with them?


## Extending Euler Tour Trees

- Suppose we want to add an operation size(x) that returns the number of nodes in the tree containing $x$.
- How might we accomplish this?



## Tree Sizes

- We can determine size( $x$ ) as follows:
- Figure out which Euler tour $x x$ is in.
- Count how many nodes of the form $z z$ it contains.
- A naive implementation of this algorithm might take time $\Theta(n)$ if all nodes are in the same tree. Can we do better?

aa ab bb bc cc cb bd dd db ba



## Tree Sizes

- We're storing our Euler tours in balanced BSTs.
- We want to be able to answer the following question about a given BST:

How many nodes of the form xx are in this BST?

- This can be done in time $\mathrm{O}(\log n)$. How?



## Tree Sizes

- Idea: Augment the BSTs holding our Euler tours.
- Specifically, each node stores the number of self-loops at or below it in the tree.
- This information can be maintained through rotations and after each splay tree operation.



## Tree Sizes

- To determine size(x):


## Tree Sizes

- To determine size(x):
- Splay $x x$.


## Tree Sizes

- To determine size(x):



## Tree Sizes

- To determine size(x):
- Splay $x x$.
- Return the augmented value in the node for $x \chi$.
- Amortized cost: $\mathbf{O}(\log \boldsymbol{n})$.



## Extending Euler Tour Trees

- Suppose that each node represents a network router.
- We want to add these two operations:
- add-packet( $x, p$ ), which attaches packet $p$ to node $x$; and
- remove-packet(x), which removes and returns some packet reachable from $x$, chosen arbitrarily from all the options.
- How might we do this?



## Packet Finding

- Given the Euler tour representation of our trees, this essentially boils down to the following:
Augment a BST containing nodes and edges so that we can quickly identify a node with a packet.
- How might we do this?


## Packet Finding

- Augment each node $x x$ with a list of the packets it stores.
- Augment each tree node with a bit indicating whether there's a packet in its subtree.
- We can use this
latter information to quickly find nodes holding packets.



## Packet Finding

- To find and remove a packet:


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- To find and remove a packet:
- Walk from the root to any node containing a packet, using the augmentation to guide the search.



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- Remove a packet from it, updating the root's augmentation.



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- Splay that node to the root.
- Remove a packet from it, updating the root's augmentation.
- Amortized cost: $O(\log n)$.


## Generalizing This Idea

- More generally, Euler tour trees play well with augmentations that care about global properties of individual trees.
- There's another way to use splay trees to encode dynamic trees (st-trees, also called link/cut trees, though the later name is ambiguous) that works well for augmenting over paths in trees rather than trees as a whole.
- (Check out the Sleator/Tarjan paper for more details.)


## Next Time

- Fully-Dynamic Connectivity
- Solving connectivity in general graphs, not just forests.
- "Blame It On The Little Guy"
- A surprisingly versatile algorithmic strategy.
- Holm's Structure
- An elegant way to solve dynamic connectivity by harnessing augmented ETTs.

