

Euler Tour Trees

Outline for Today

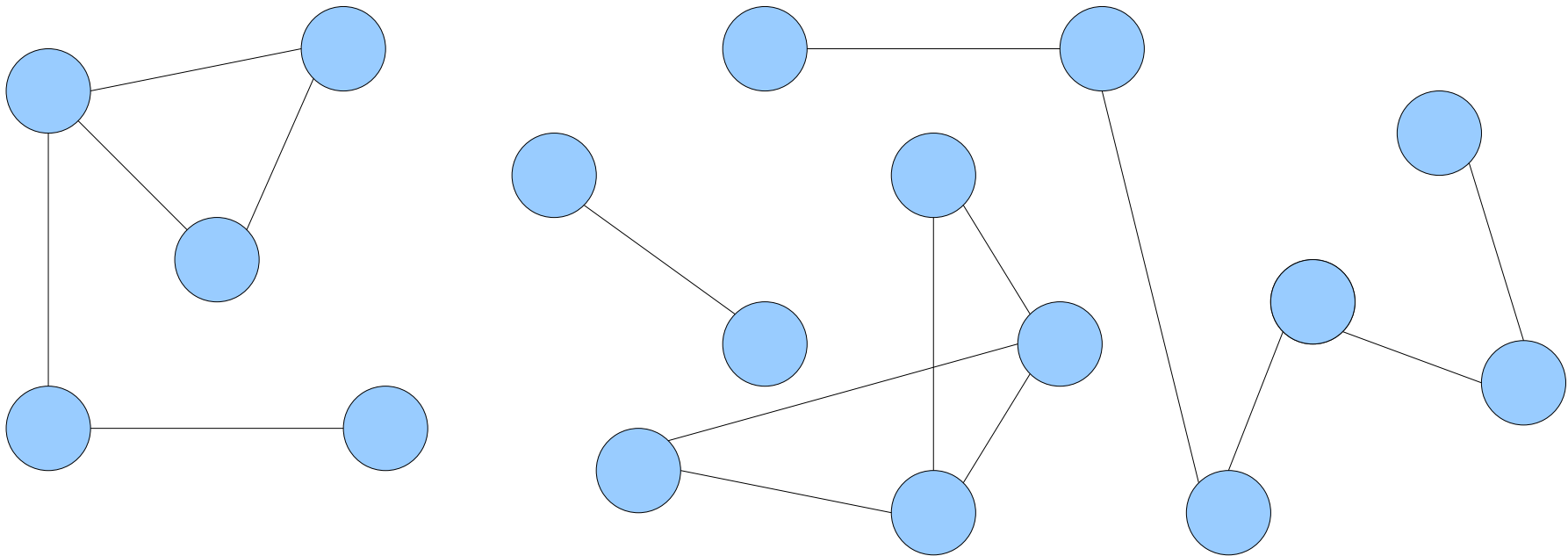
- ***Dynamic Connectivity***
 - Figuring out what's connected in a graph as the edges change.
- ***Euler Tour Representations***
 - An inspired and clever way to represent trees.
- ***Euler Tour Trees***
 - Encoding Euler tours in a creative way.
- ***Extending ETTs***
 - Extending our basic structure.

The Dynamic Connectivity Problem

The Connectivity Problem

- The **graph connectivity problem** is the following:

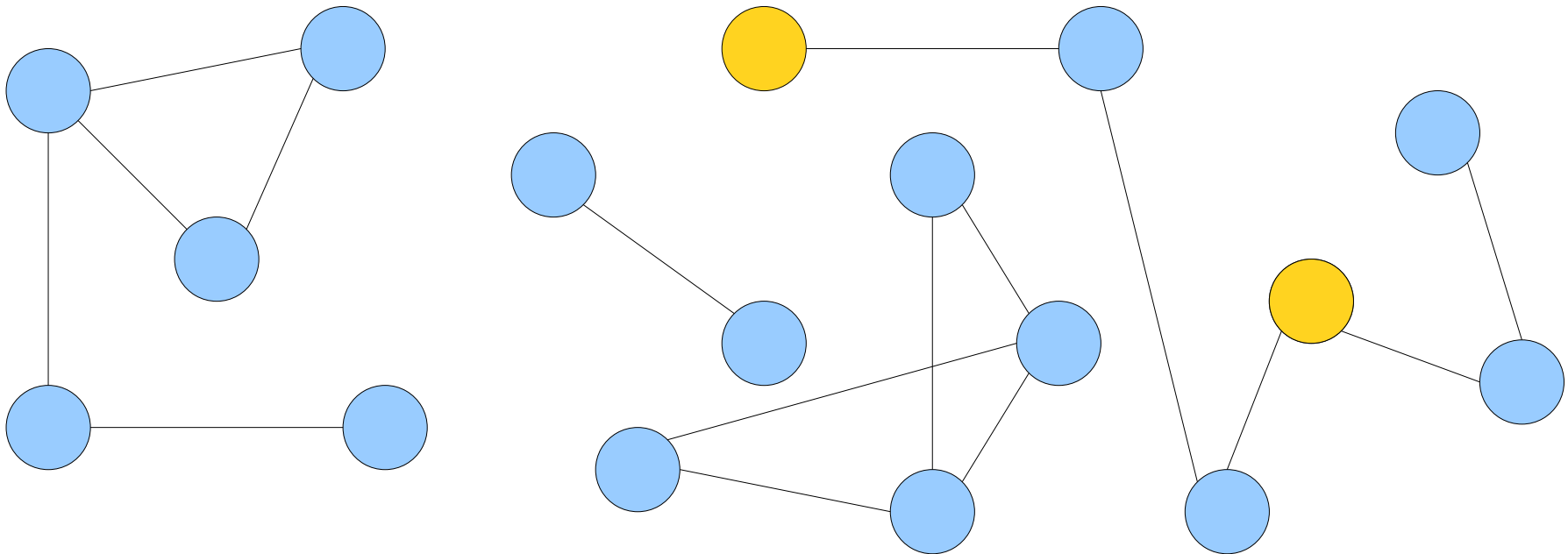
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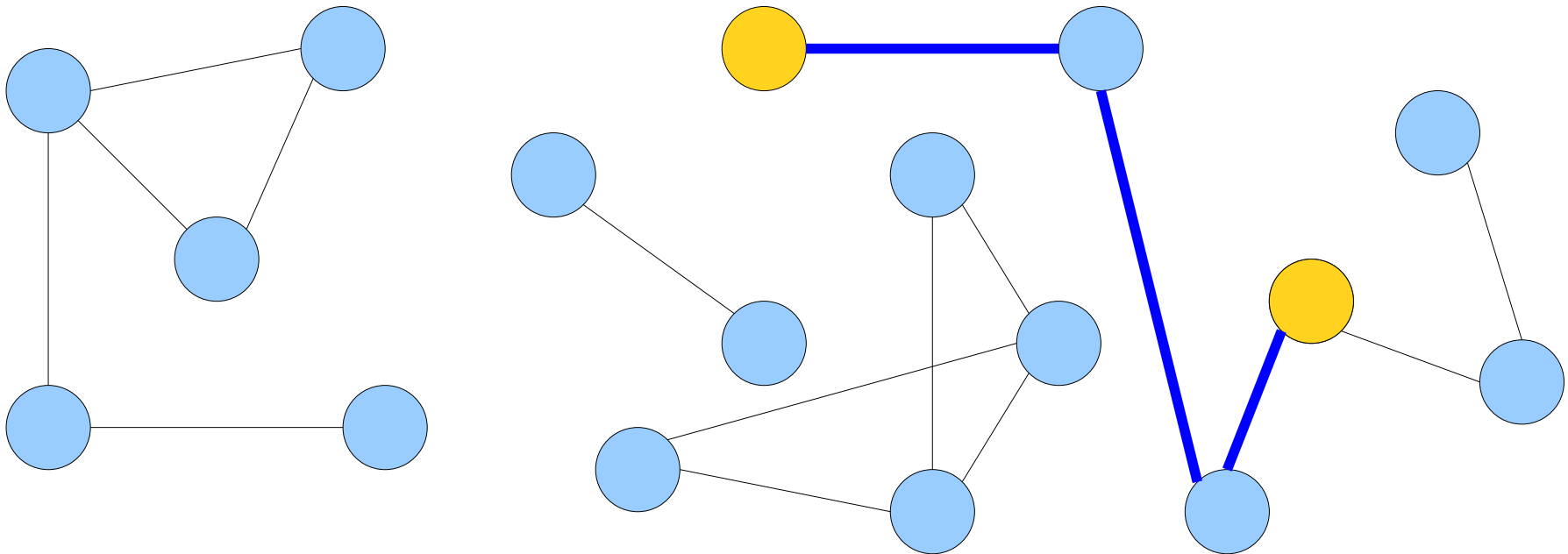
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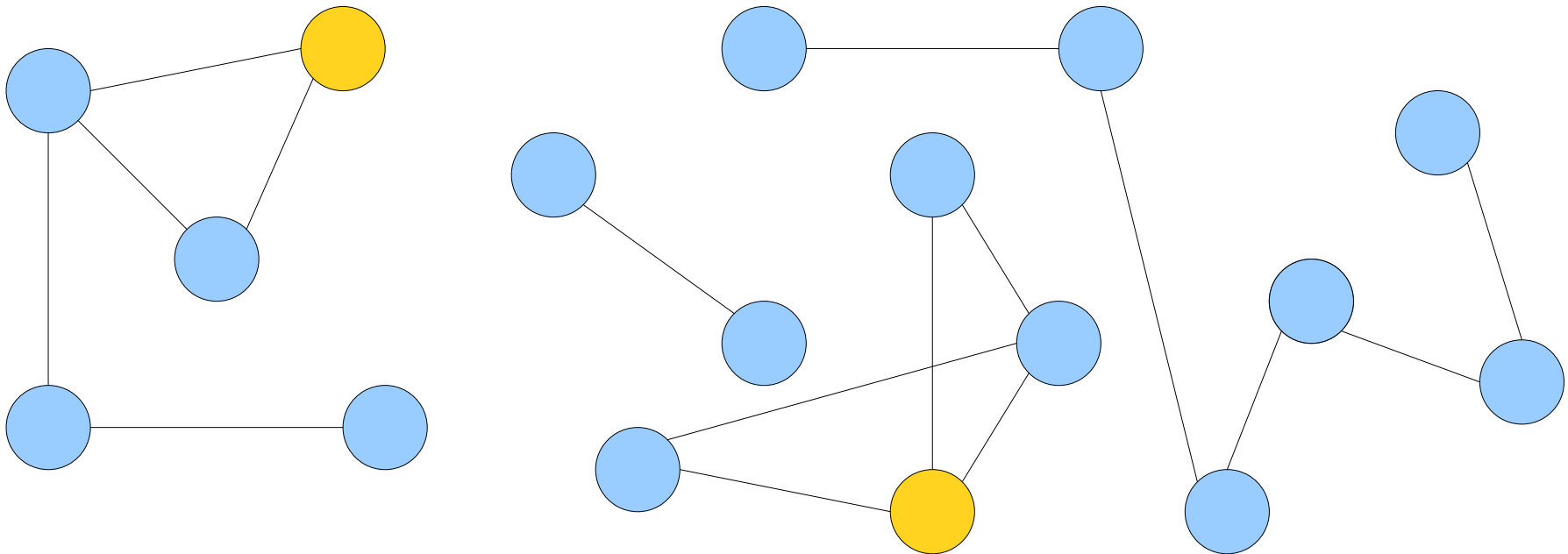
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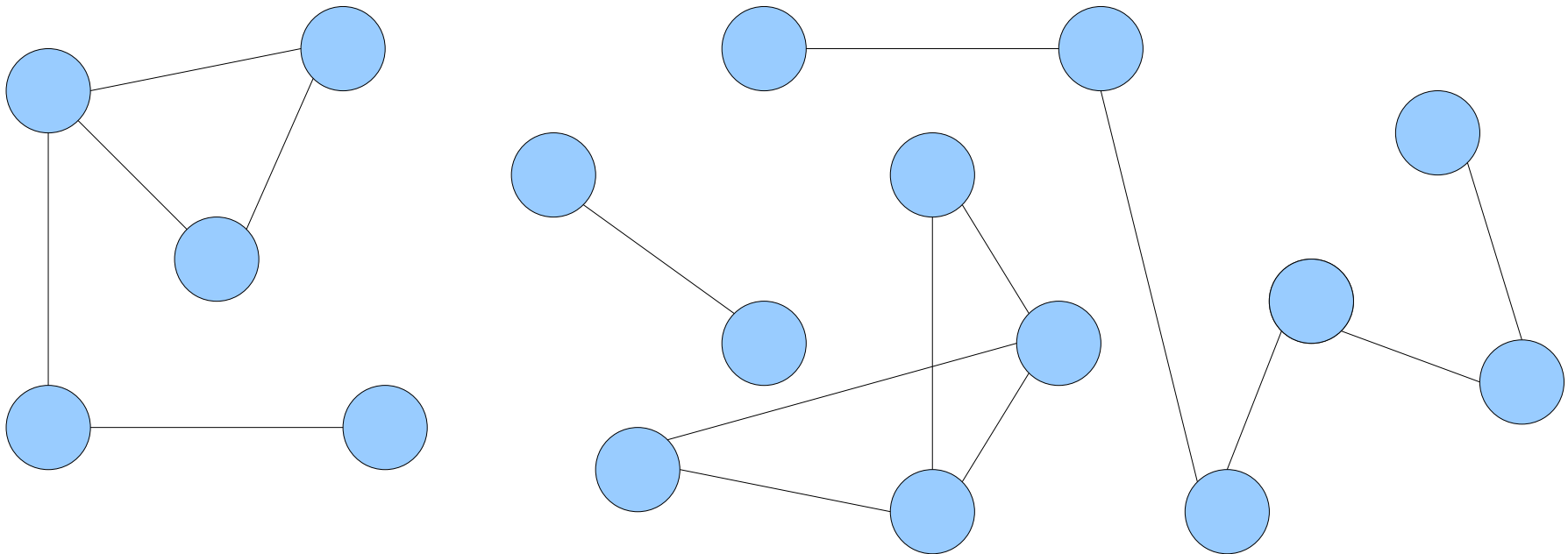
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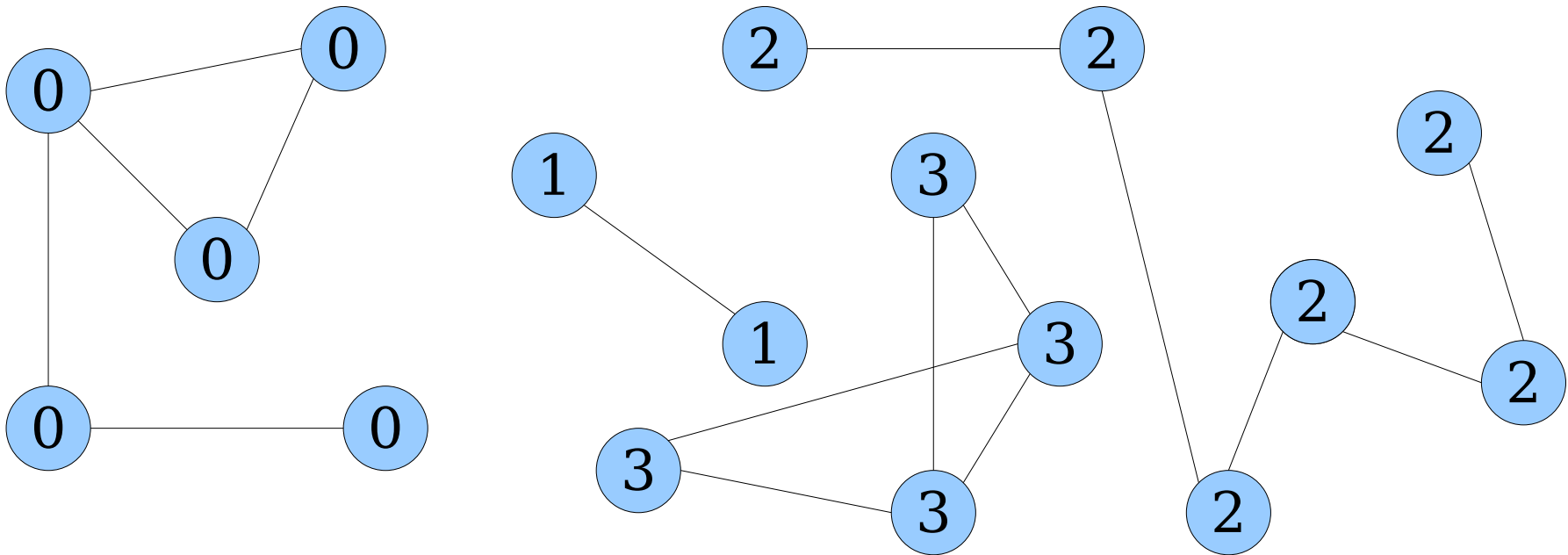
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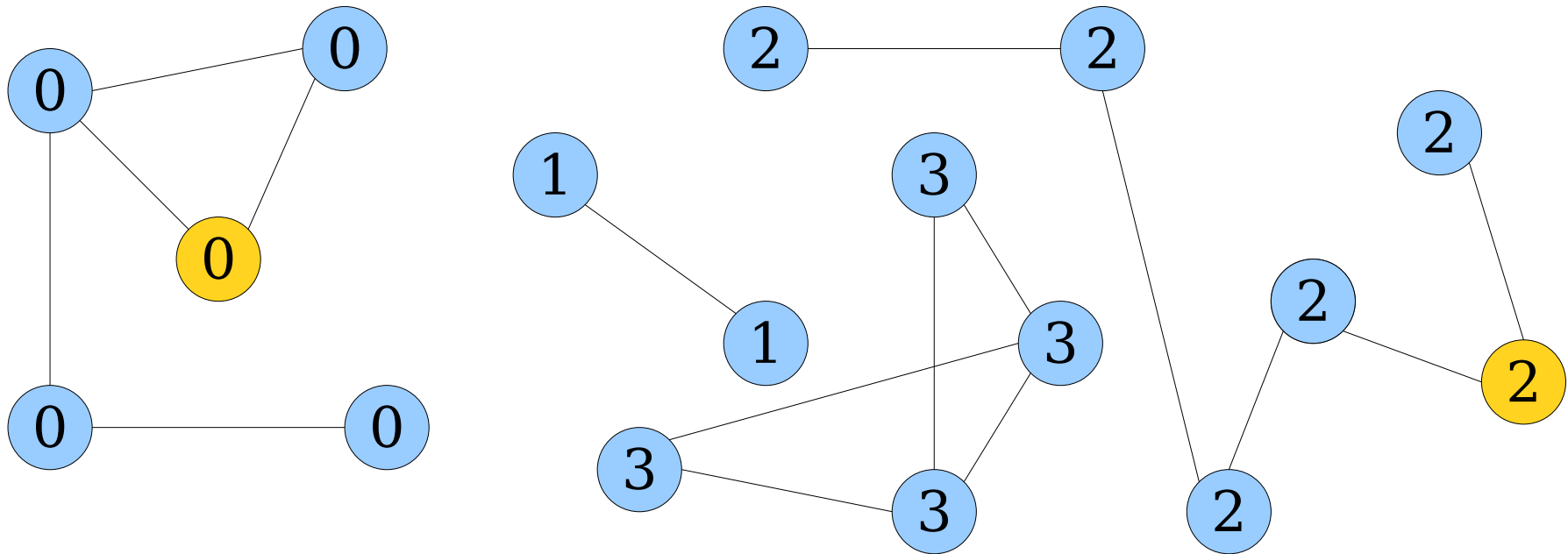
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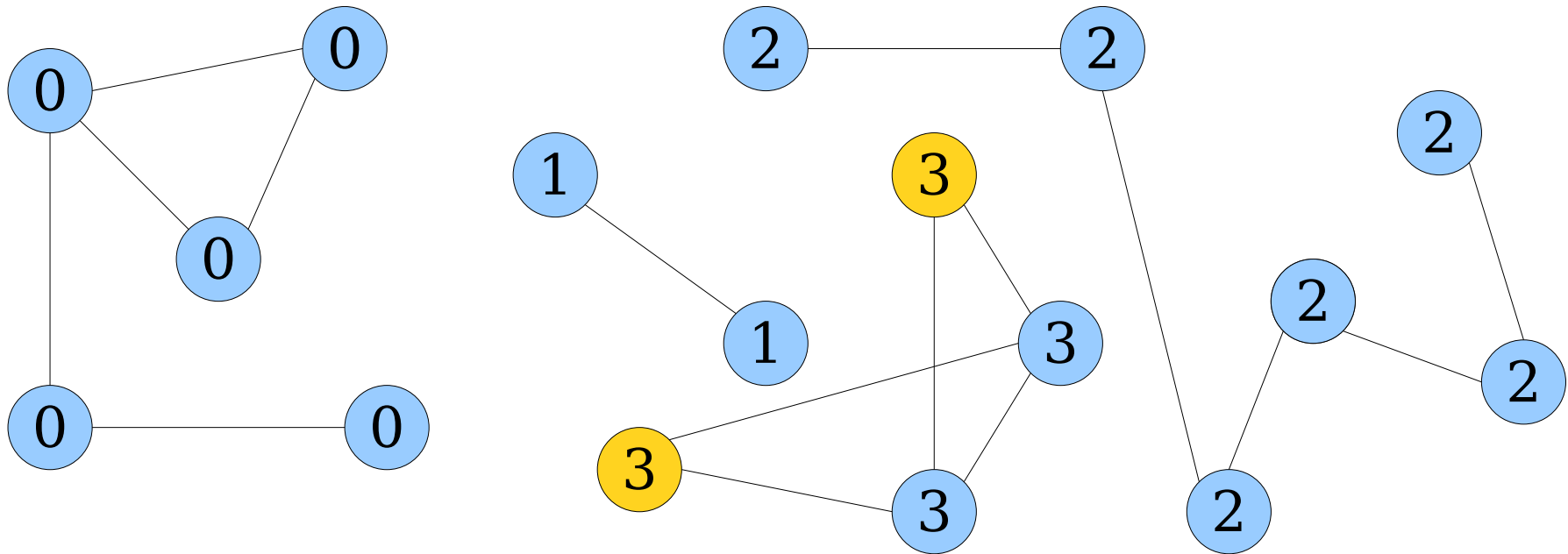
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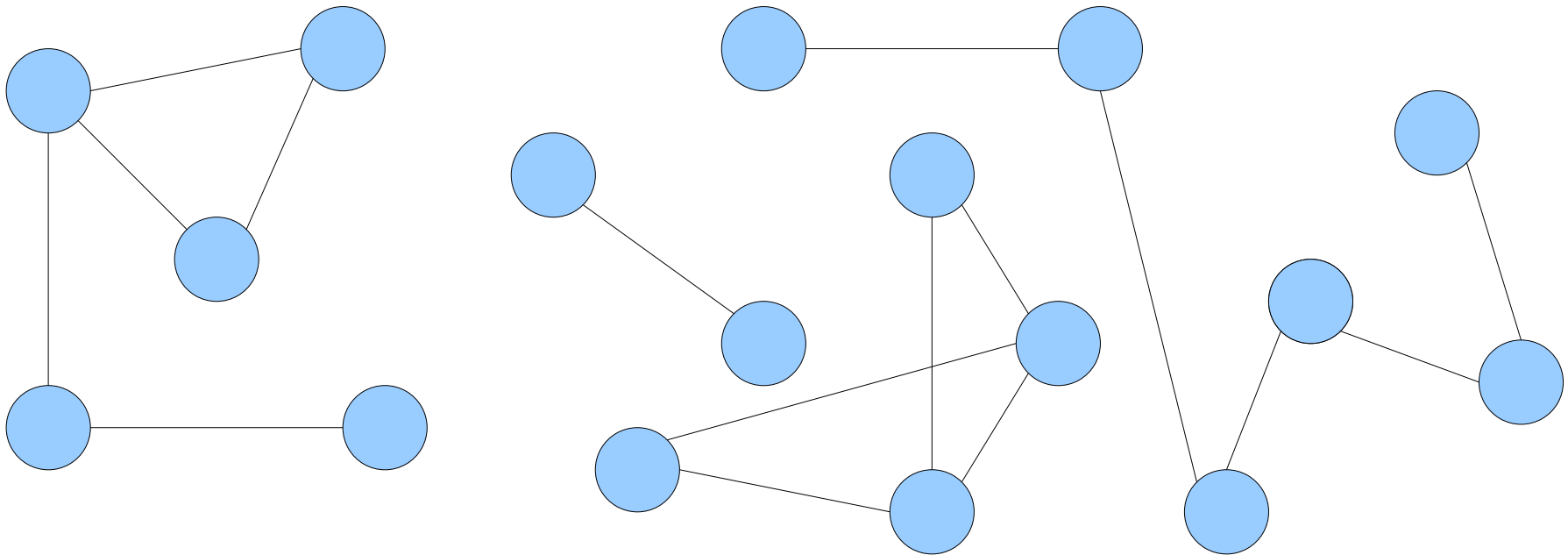
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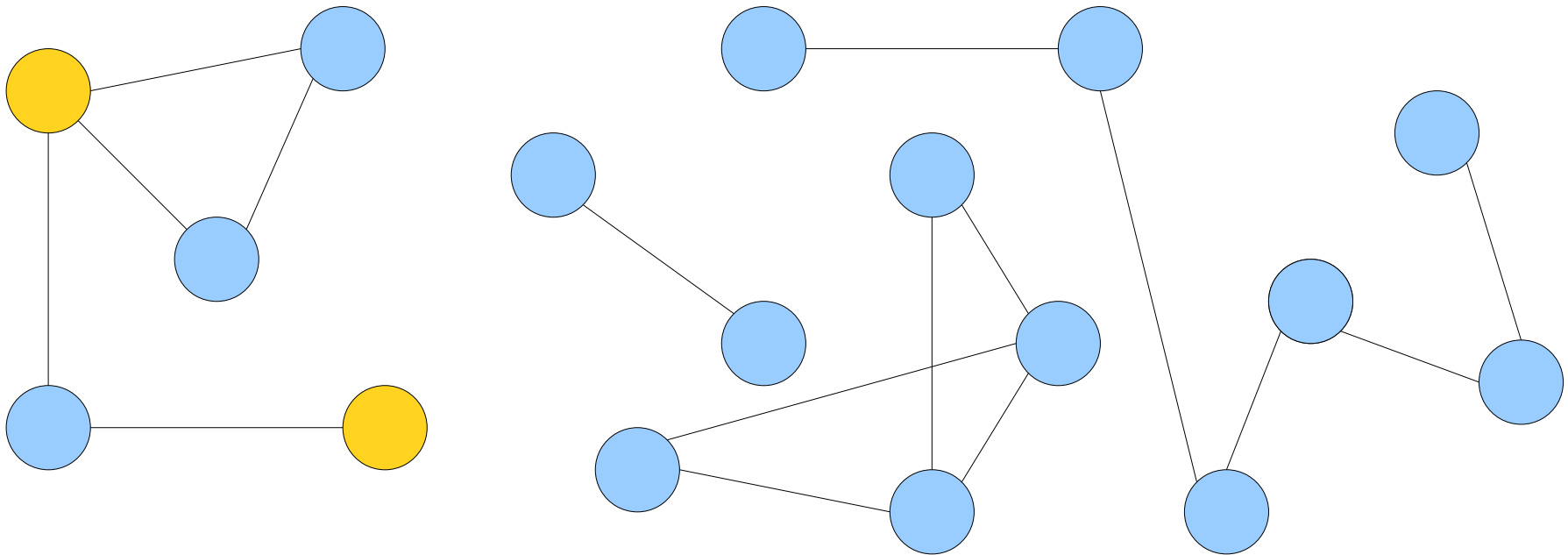
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- This is a *much* harder problem!



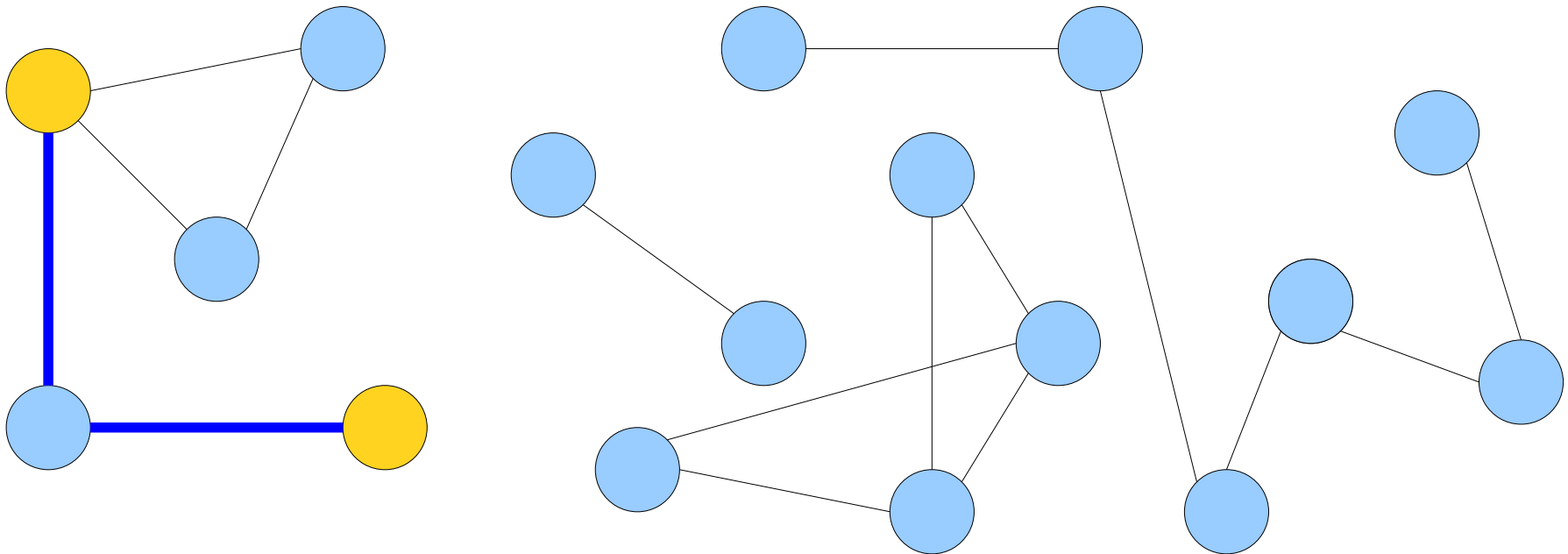
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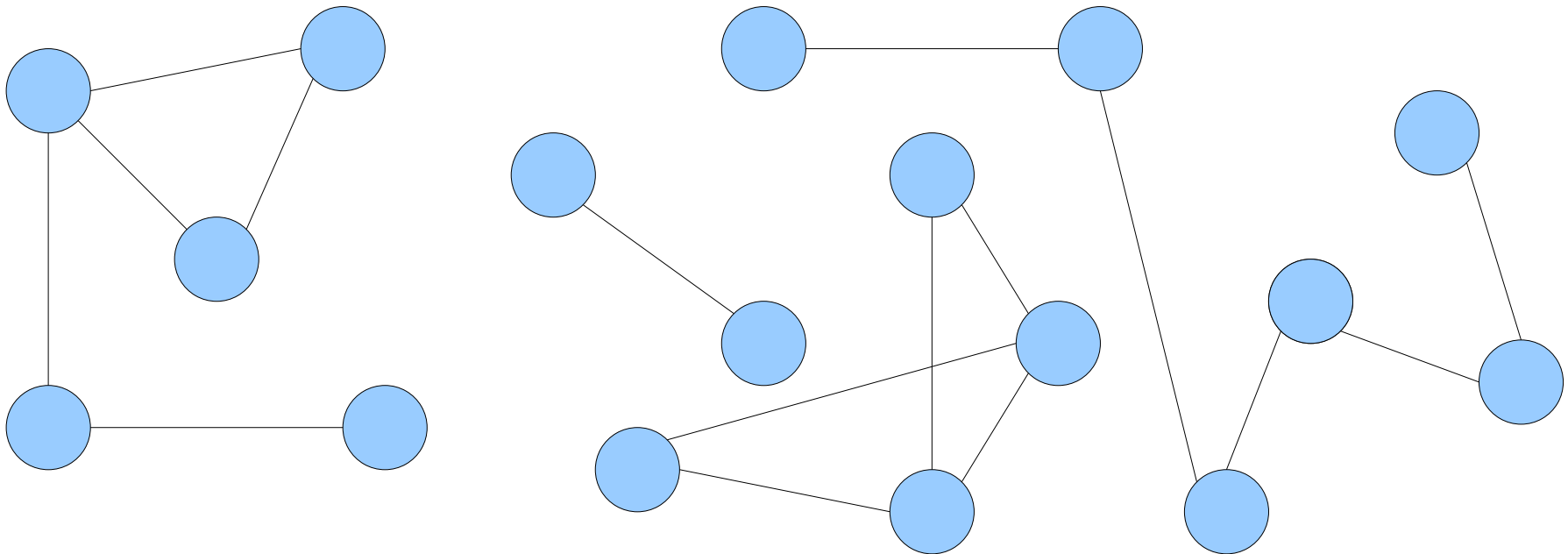
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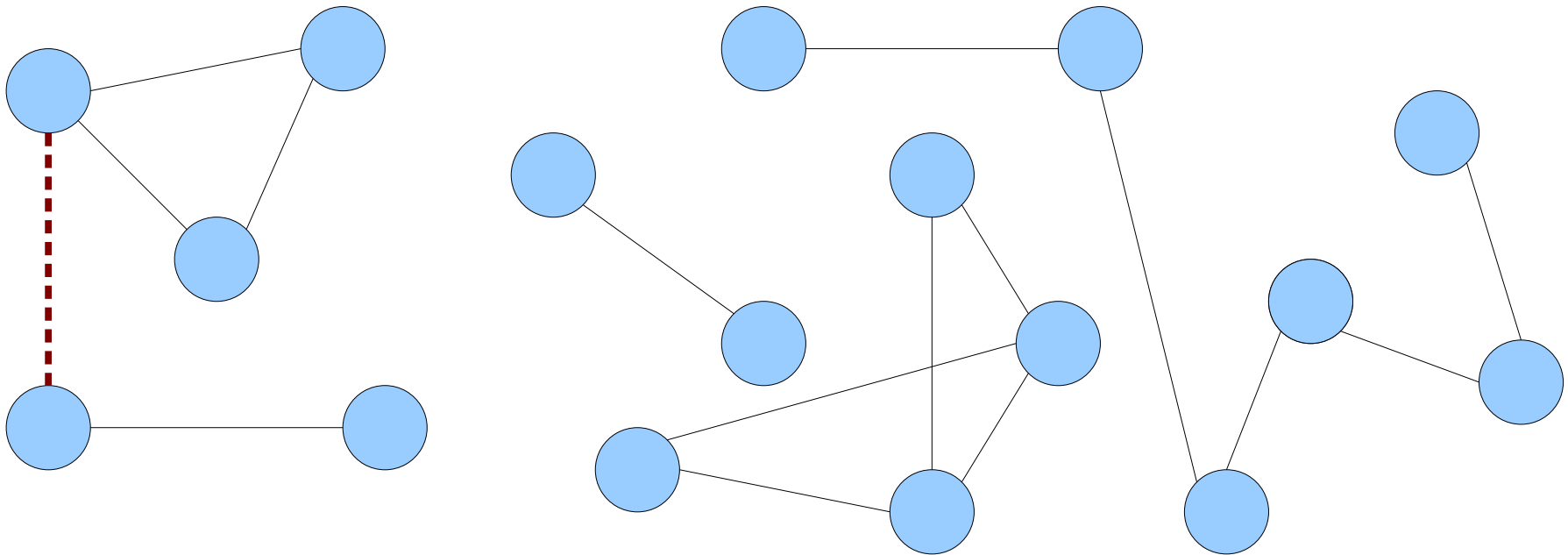
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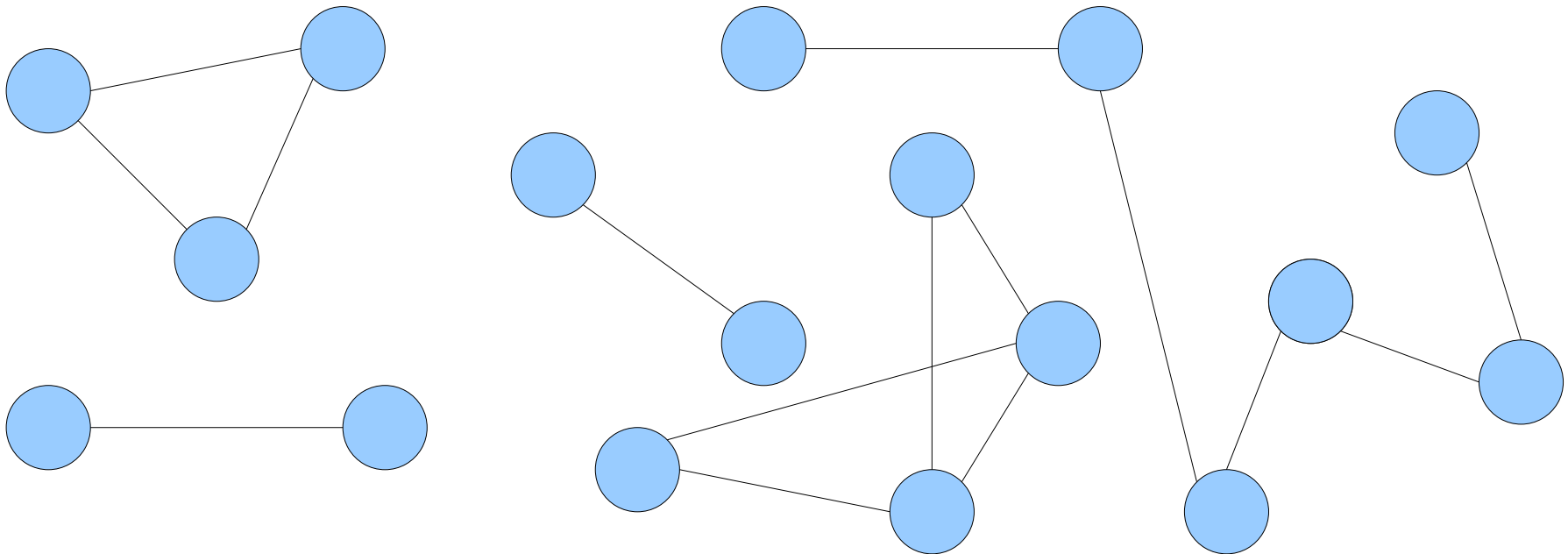
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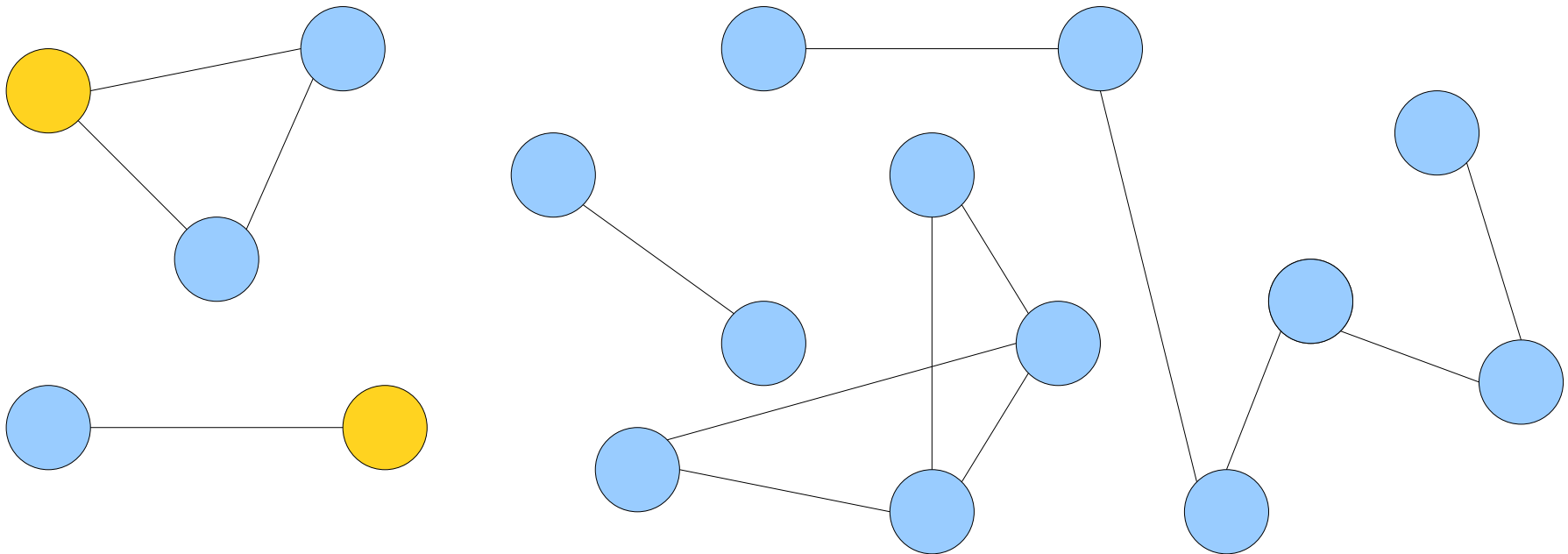
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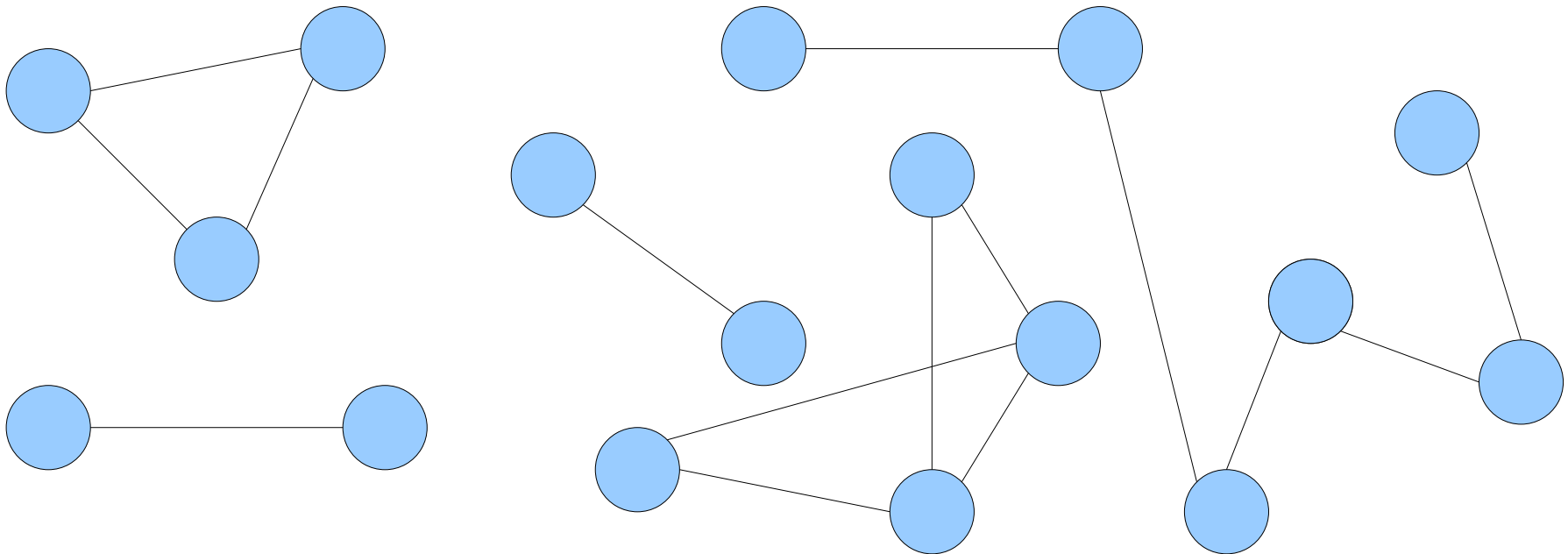
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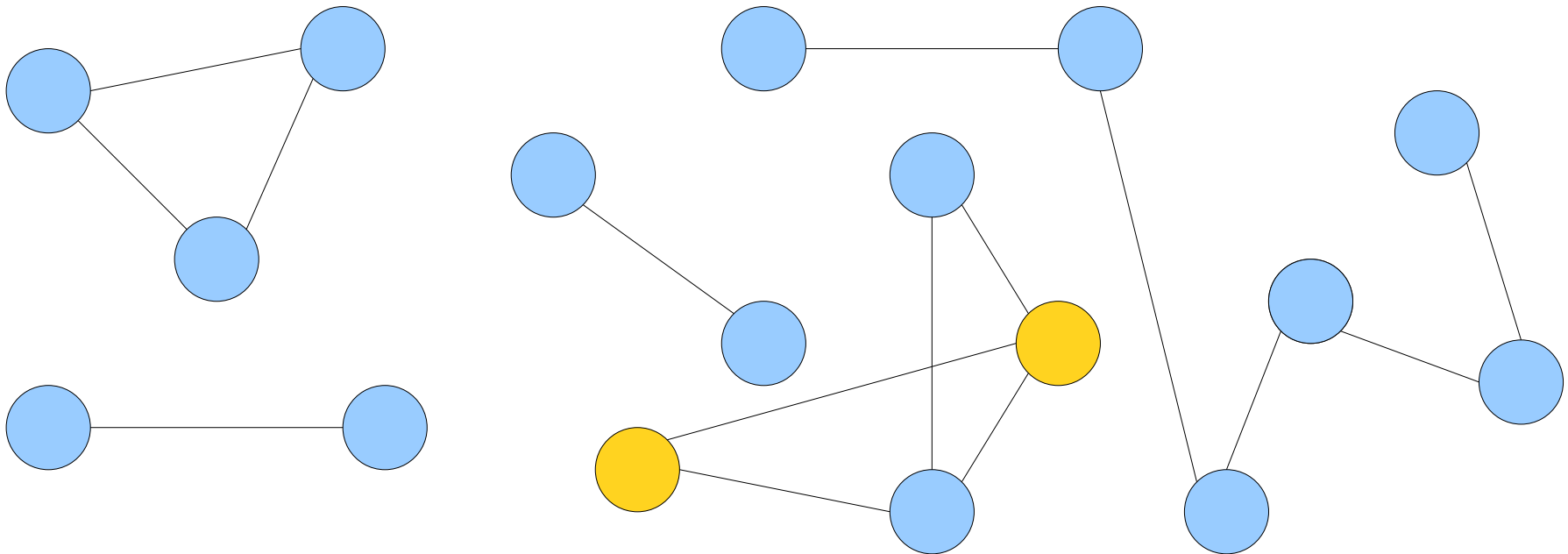
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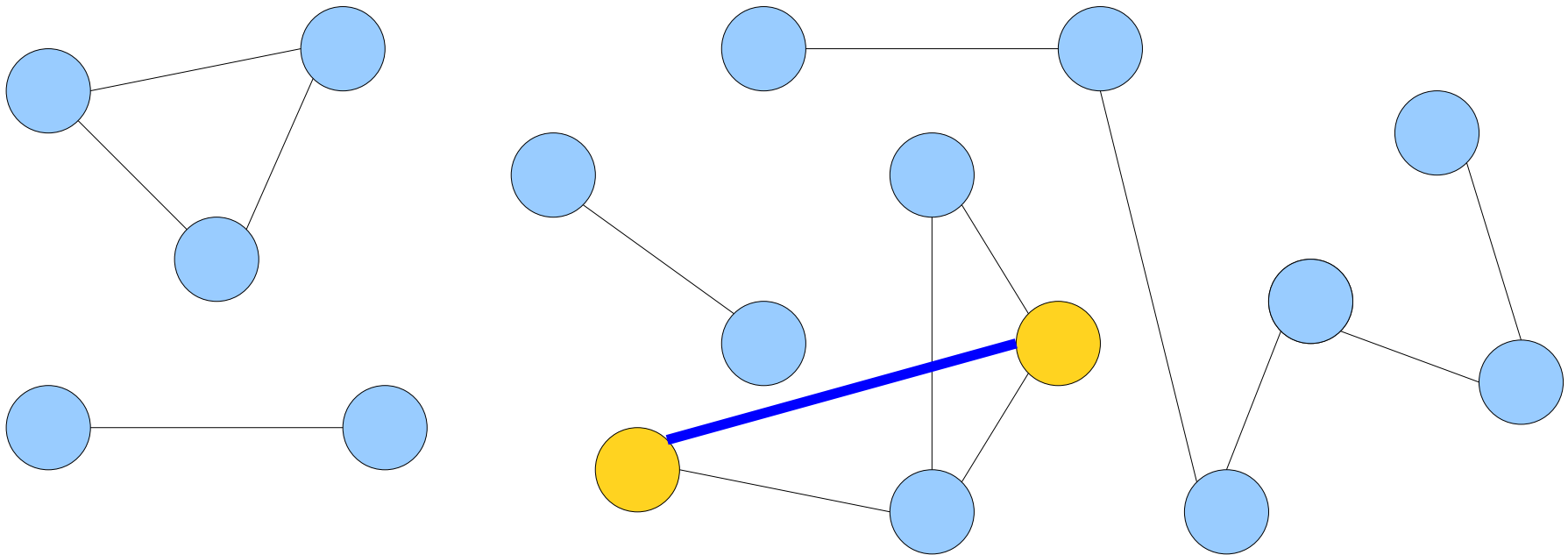
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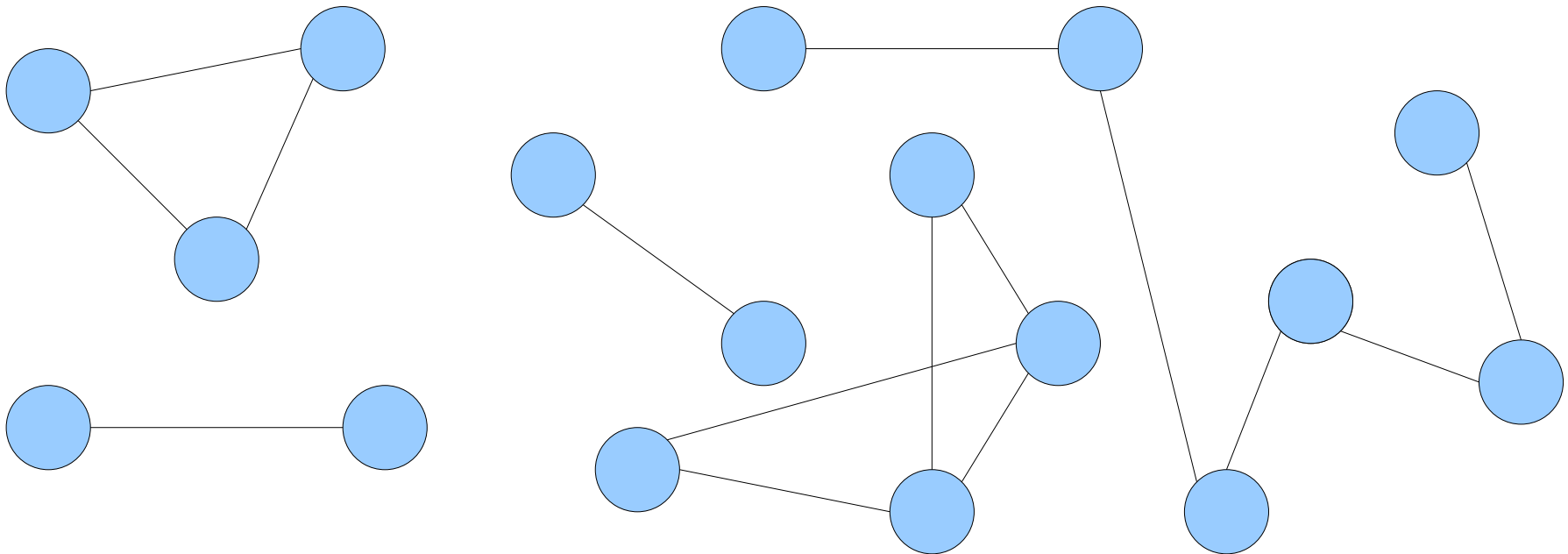
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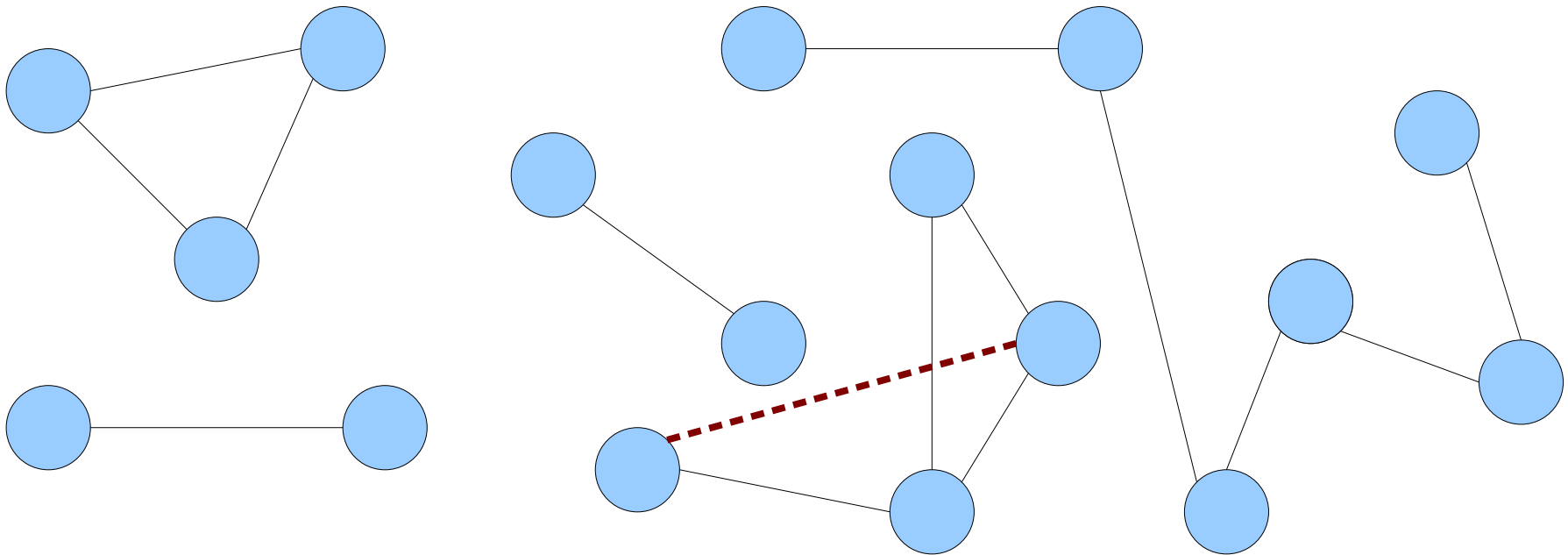
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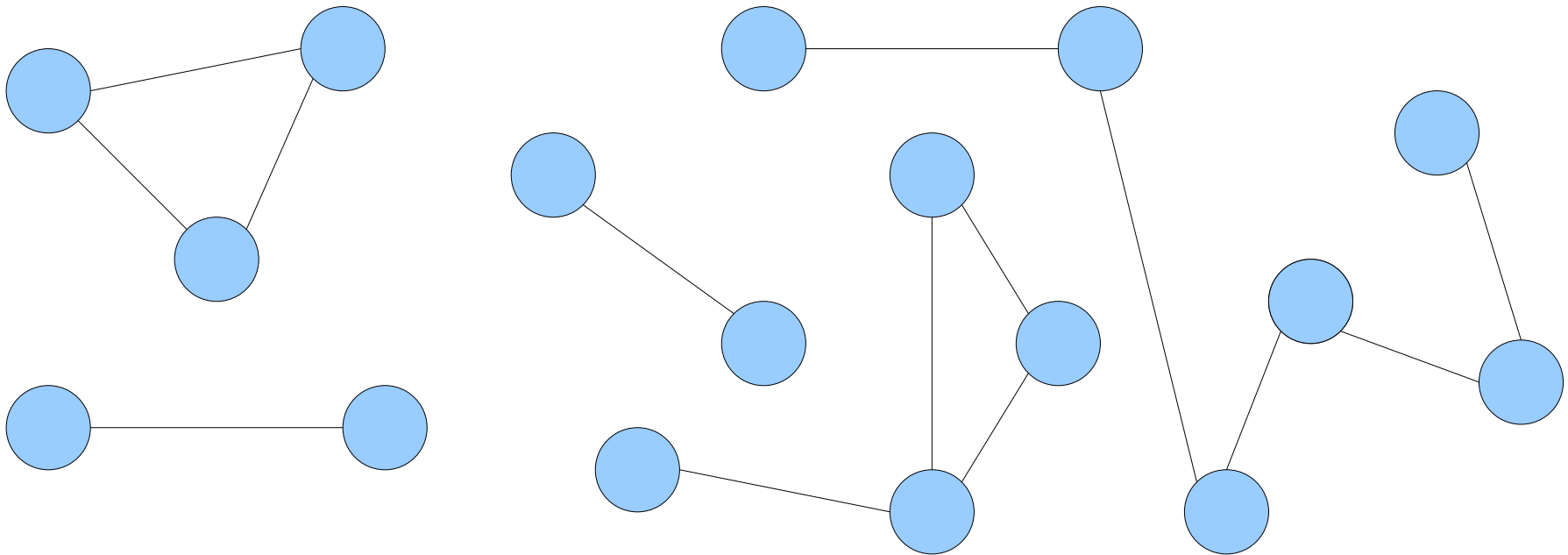
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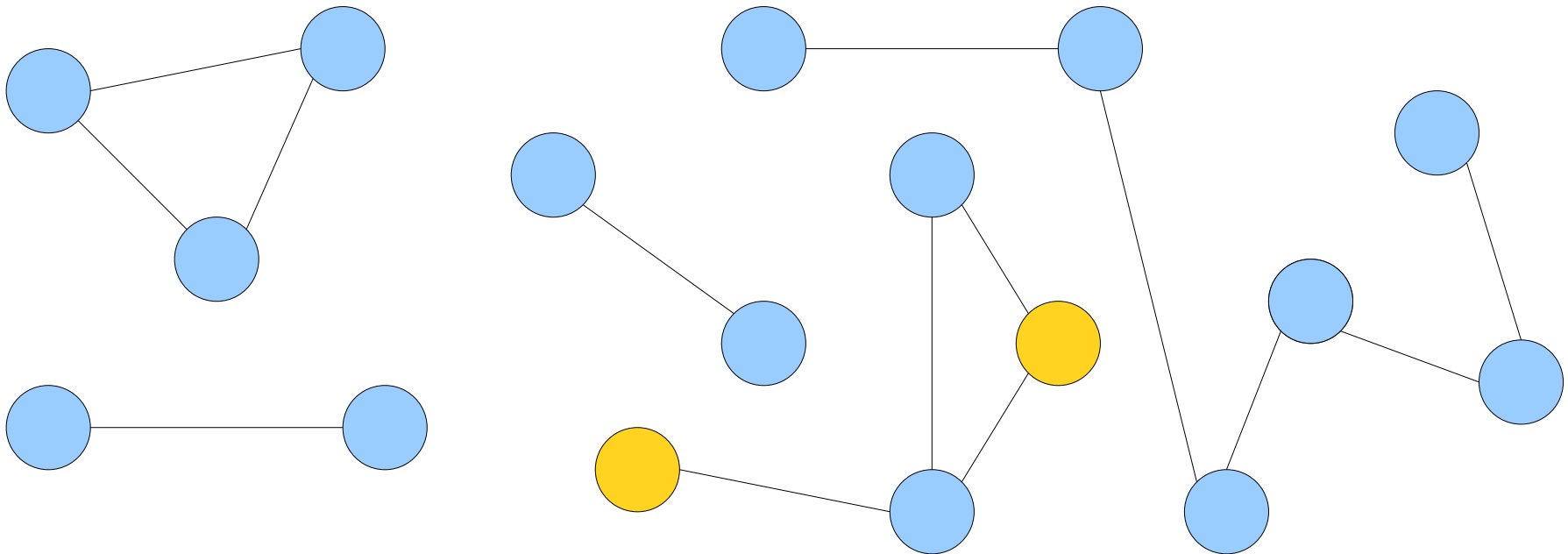
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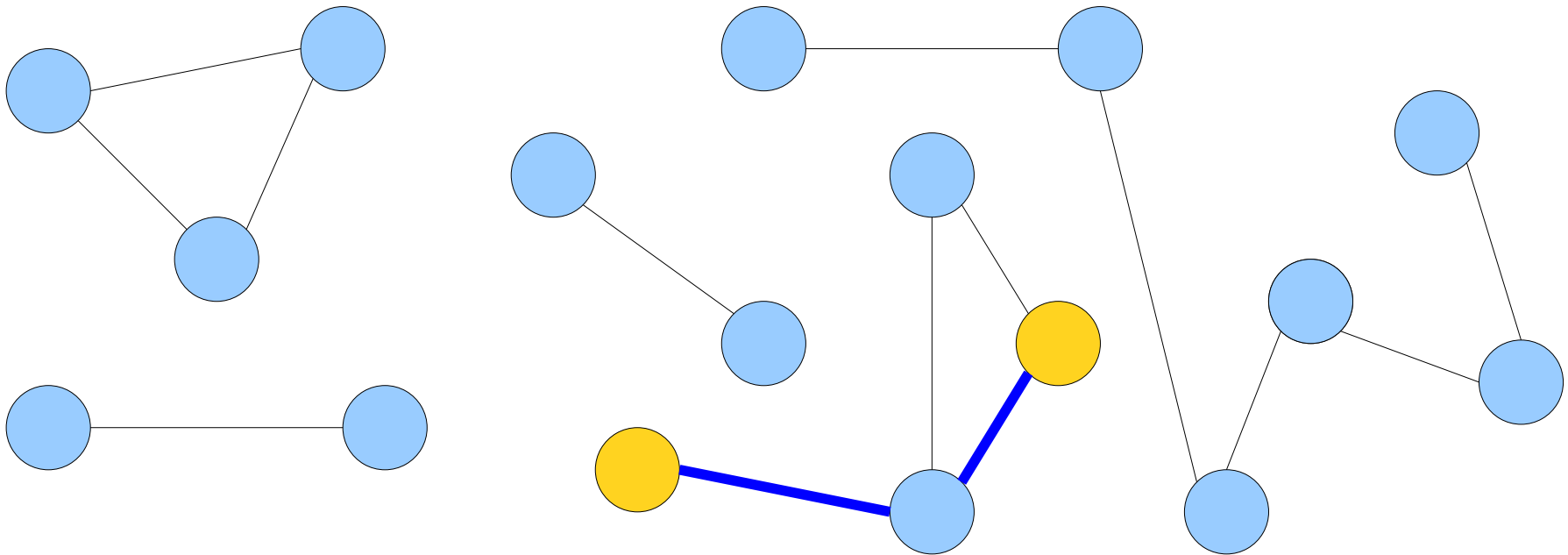
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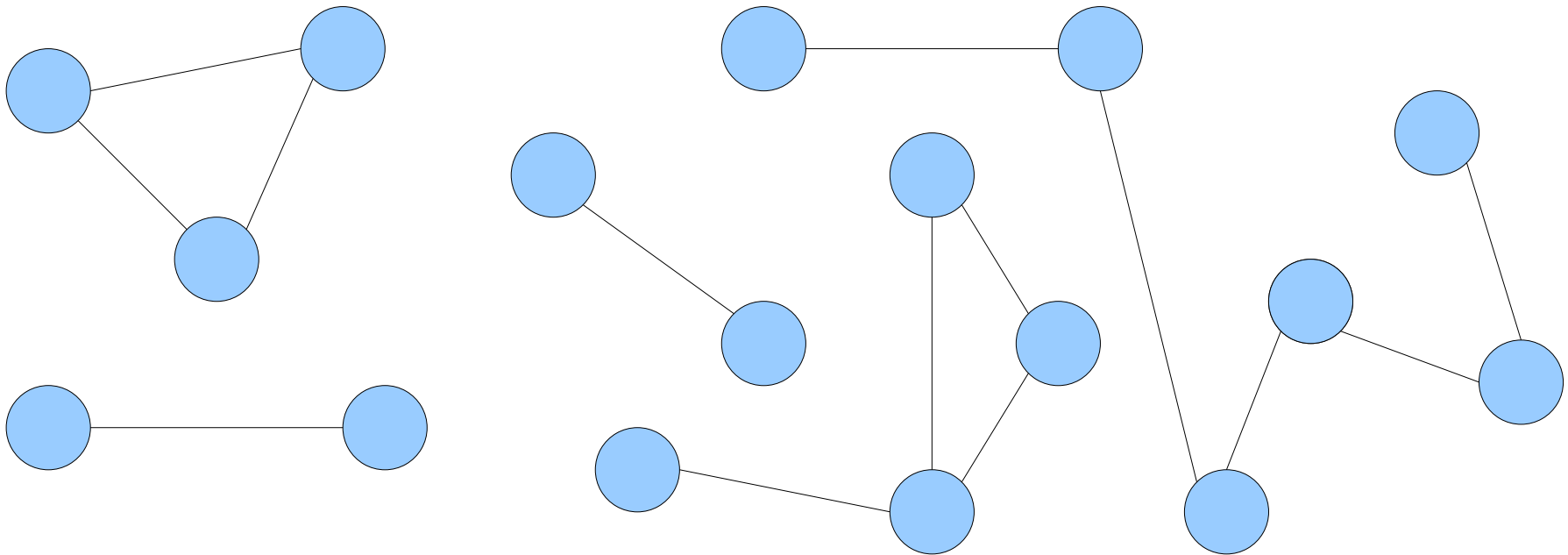
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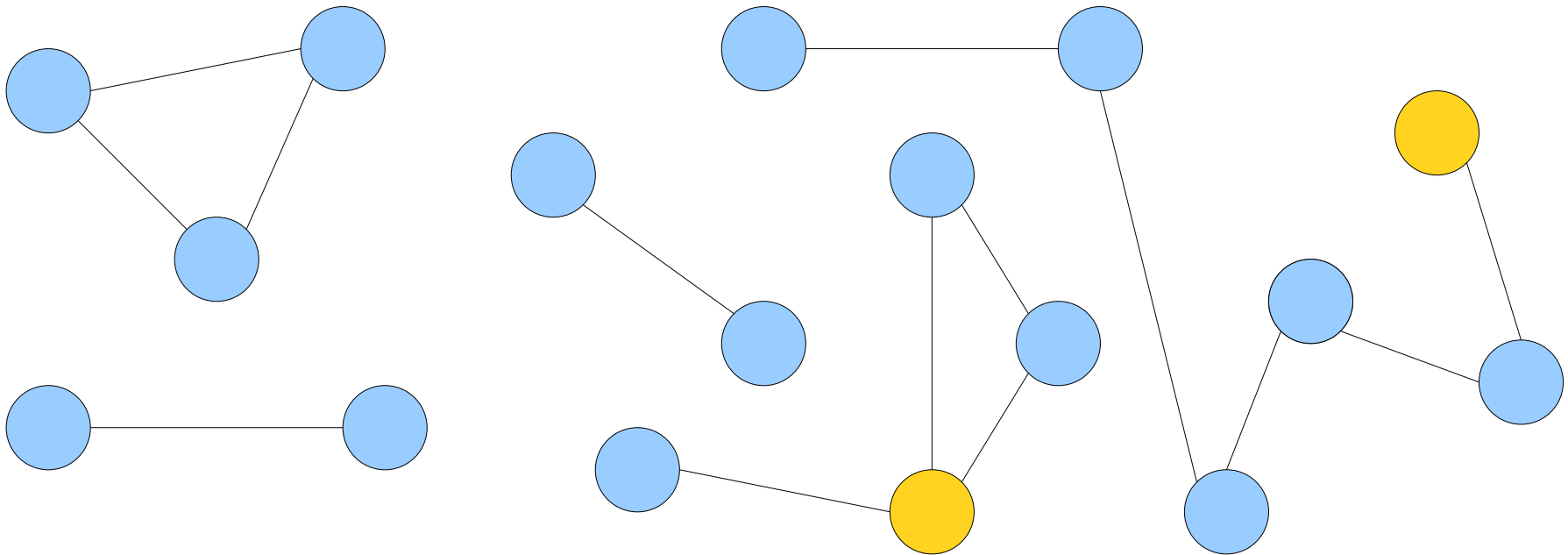
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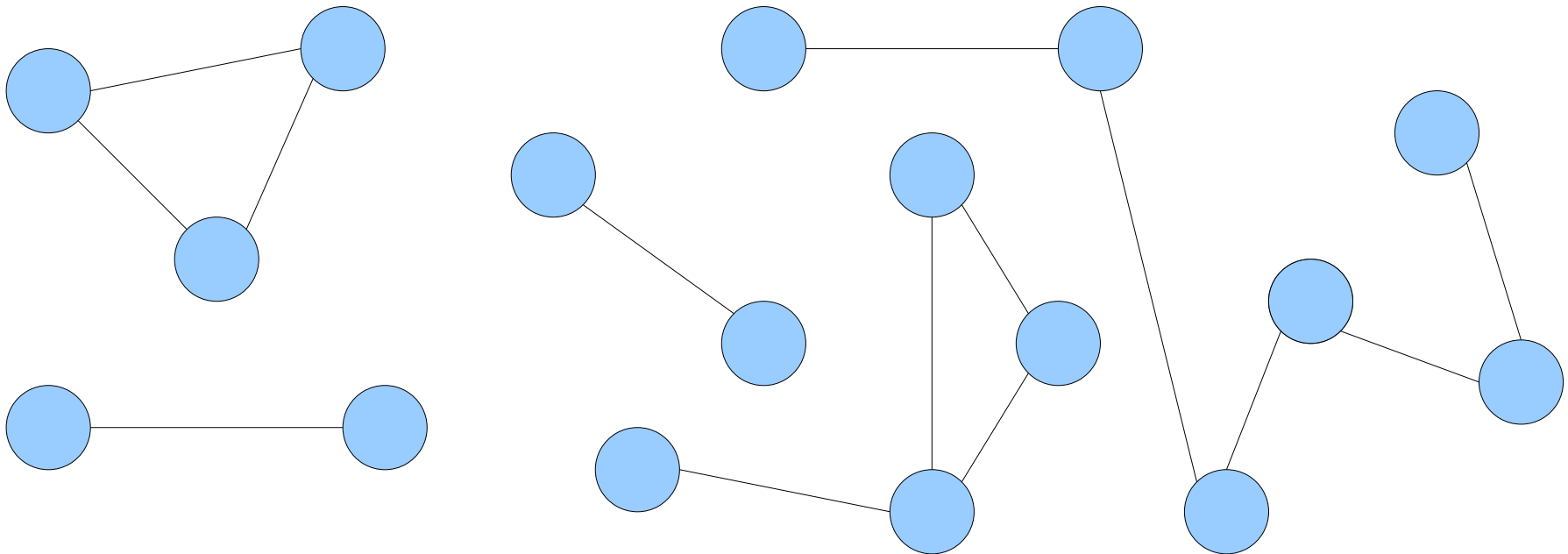
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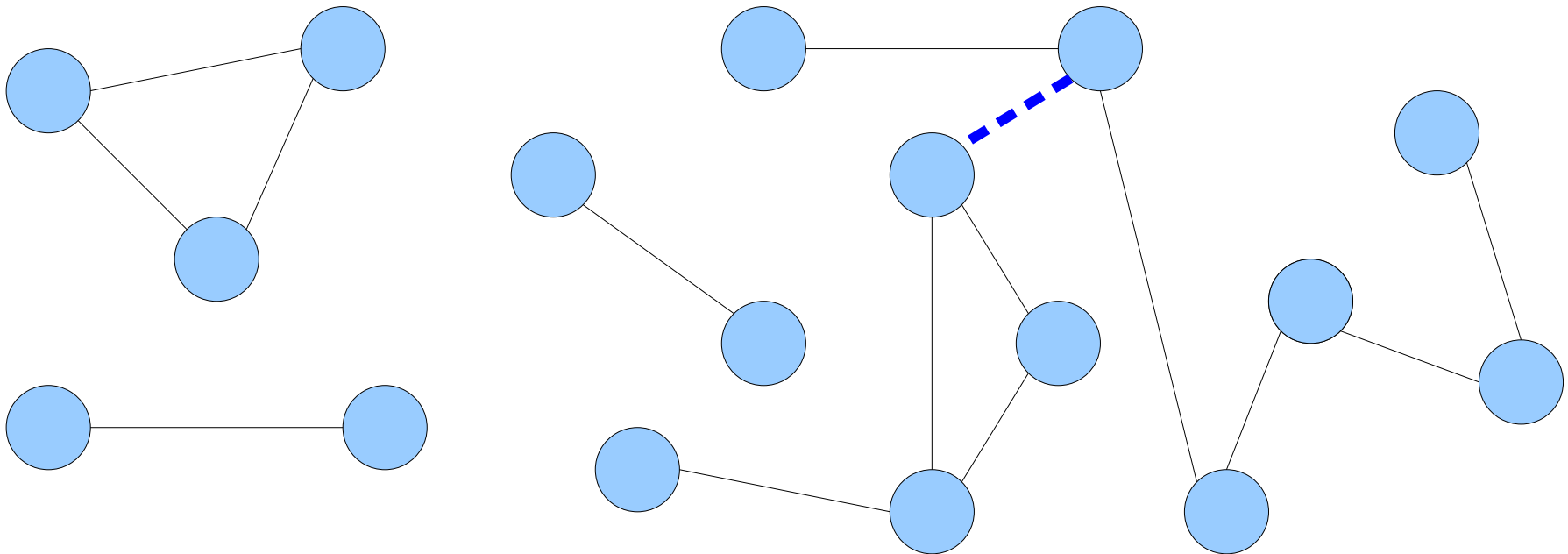
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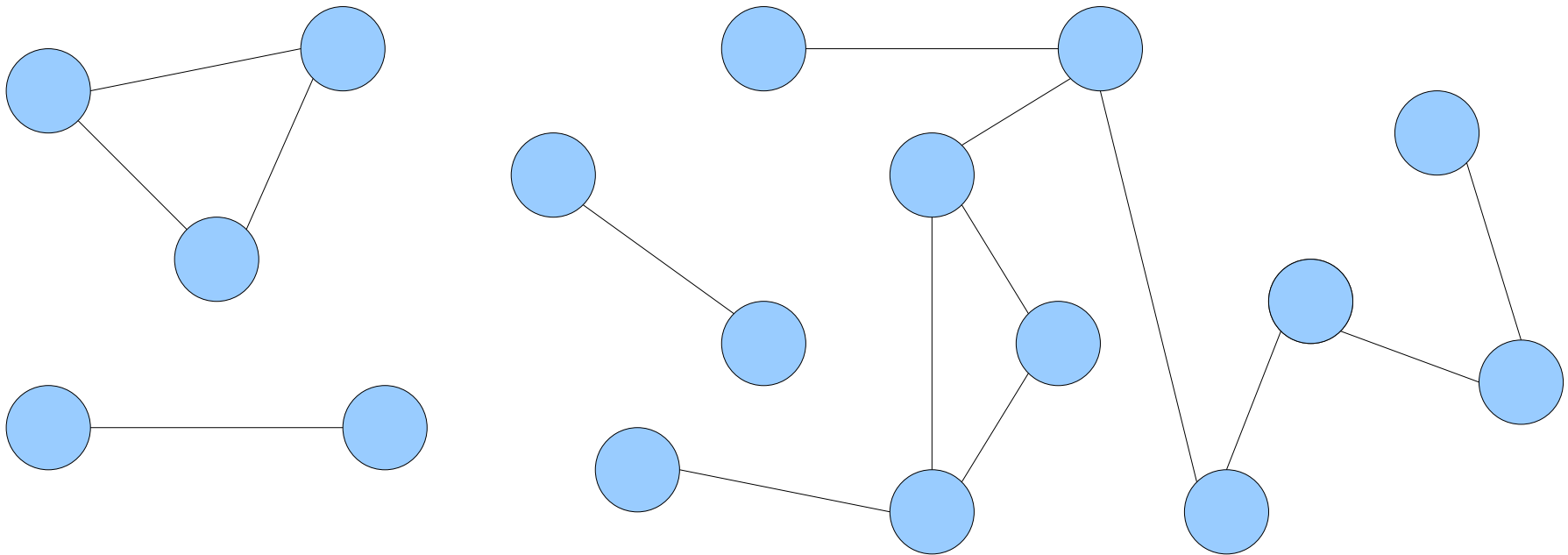
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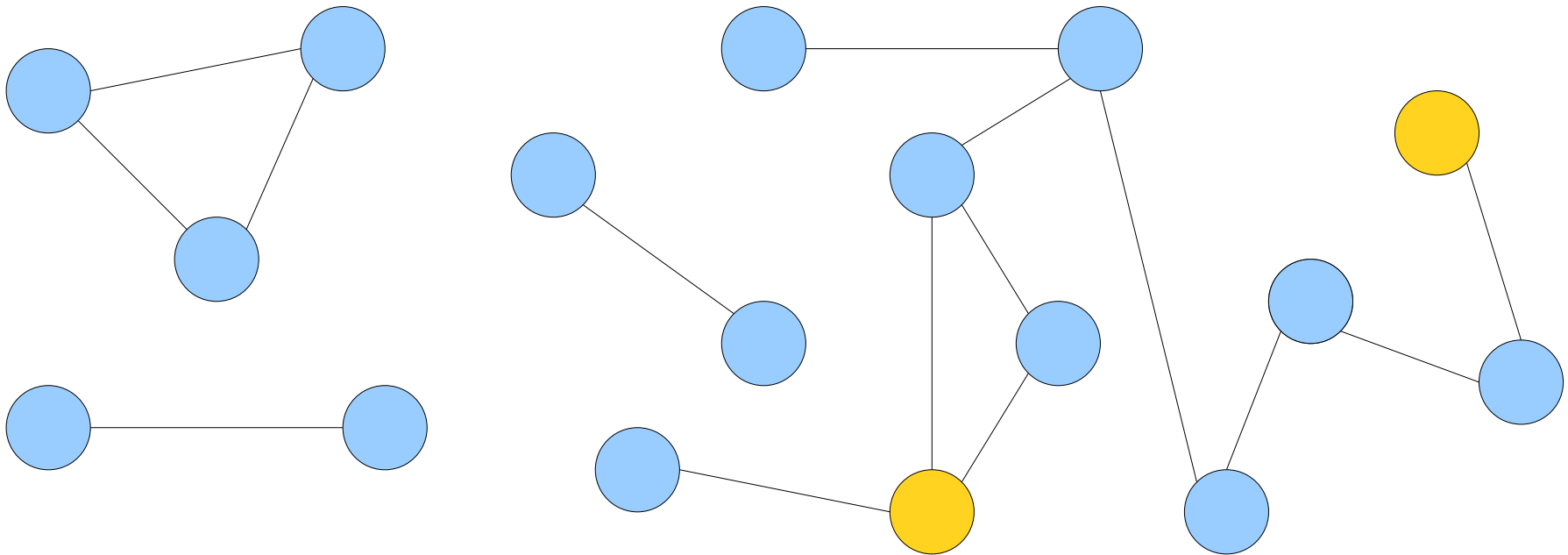
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Special Cases

- Last time, we covered the ***incremental connectivity problem*** in which edges can only be added and not removed.
- Today, we'll cover ***dynamic connectivity in forests***, a special case in which the graph is known to be a forest.
- Next time, we'll cover ***fully-dynamic connectivity***, in which there are no restrictions on which edges can be added and removed.

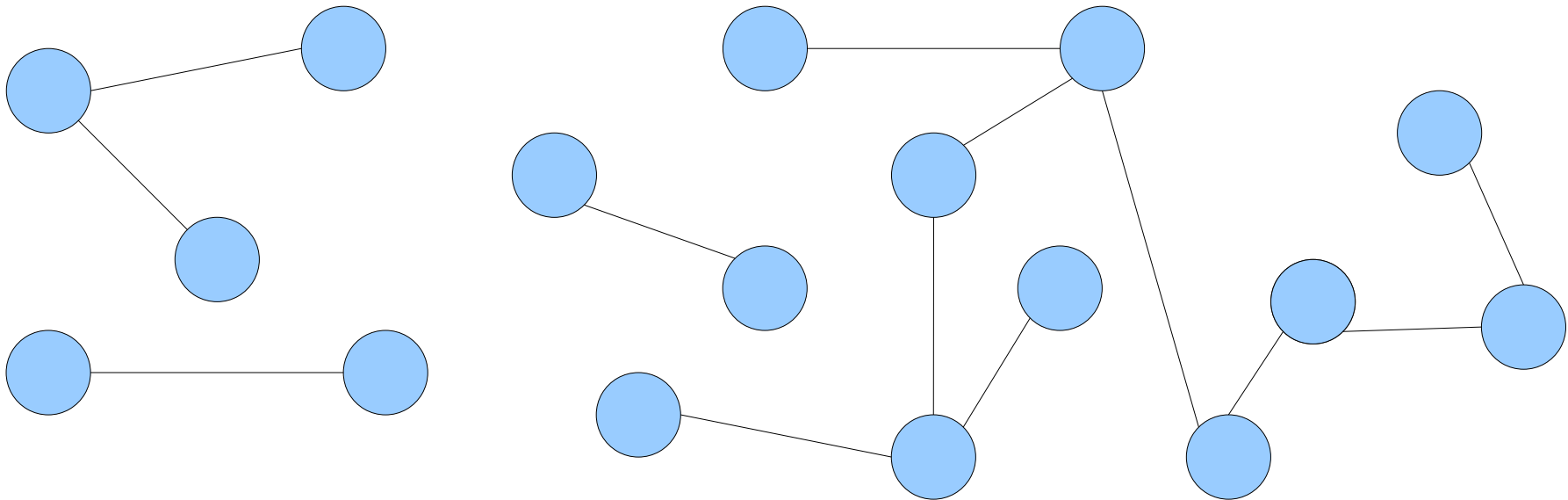
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- Consider the following special-case of the dynamic connectivity problem:

Maintain an undirected *forest* F so that edges may be inserted and deleted and connectivity queries may be answered efficiently.

- Each deleted edge splits a tree in two; each added edge joins two trees and never closes a cycle.

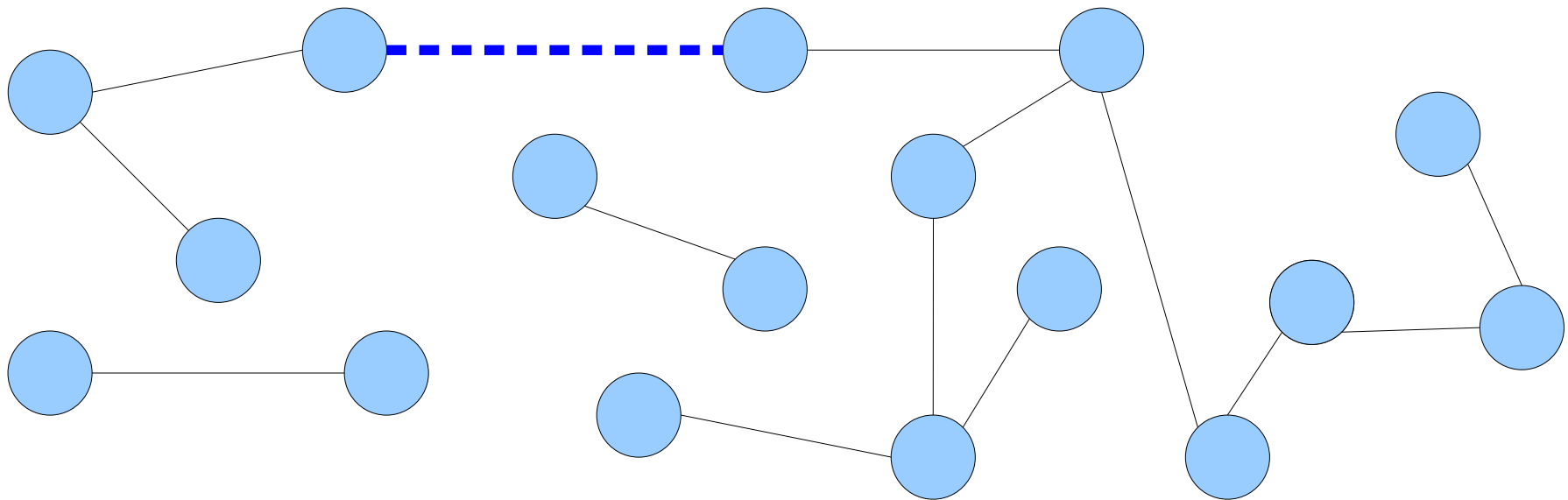


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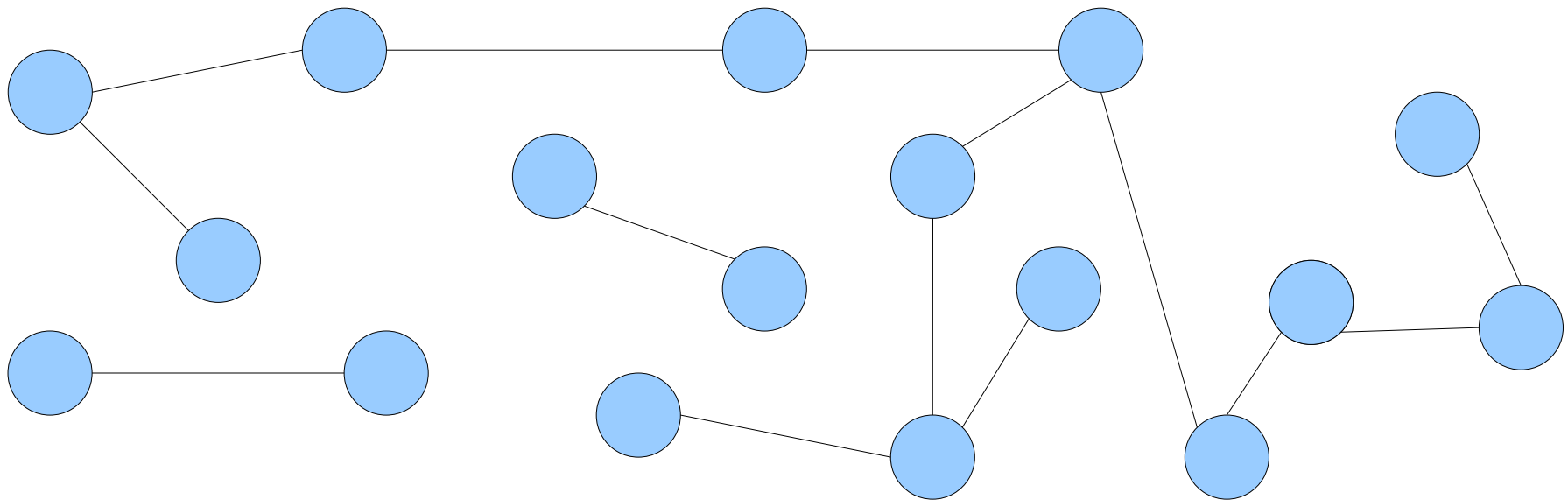


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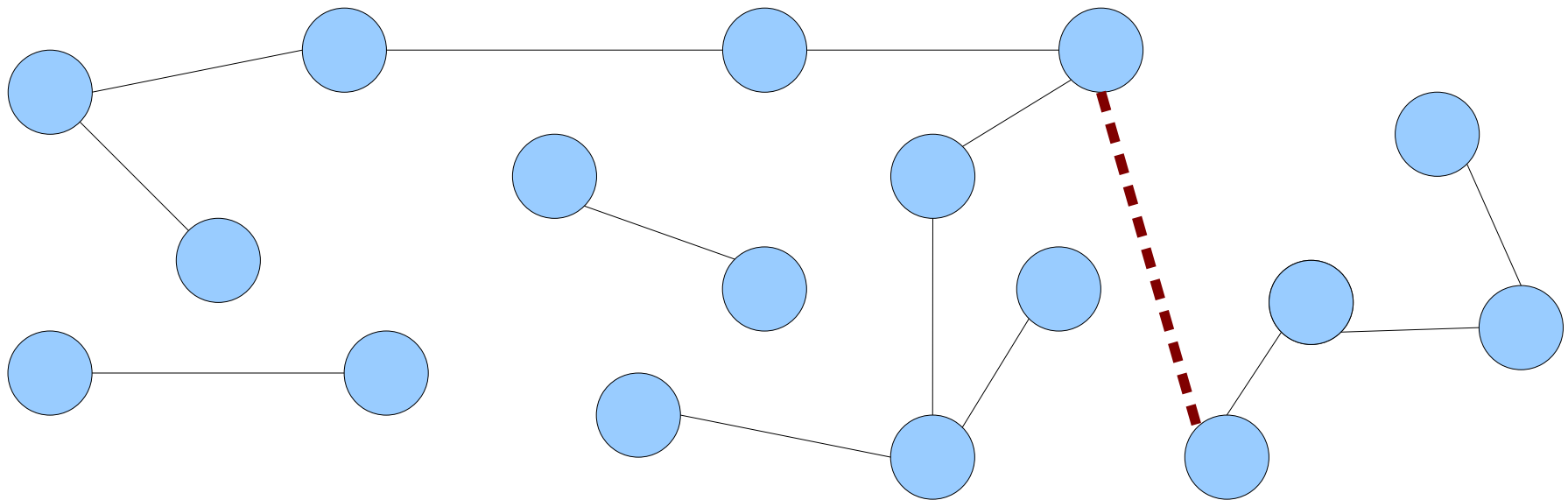


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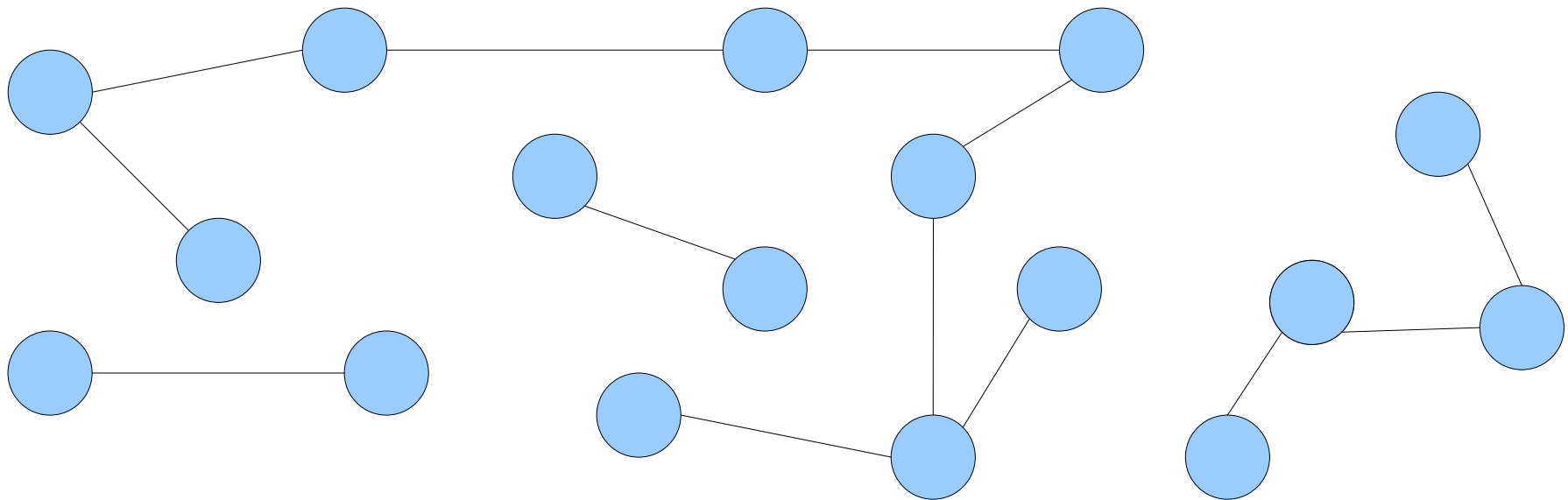


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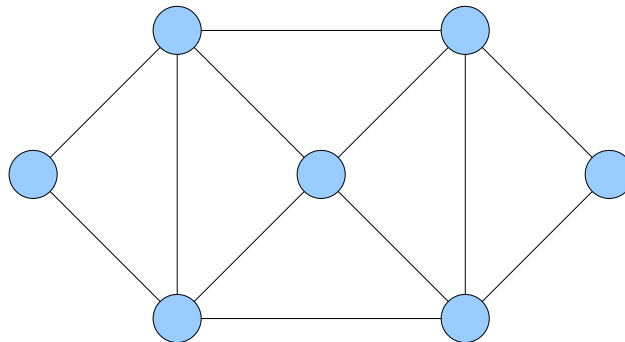
Dynamic Connectivity in Forests

- **Goal**: Support these three operations:
 - **link**(u, v): Add in edge uv . The assumption is that u and v are in separate trees.
 - **cut**(u, v): Cut the edge uv . The assumption is that the edge exists in the forest.
 - **are-connected**(u, v): Return whether u and v are connected.
- The data structure we'll develop can perform these operations time **$O(\log n)$** each.

Euler Tours

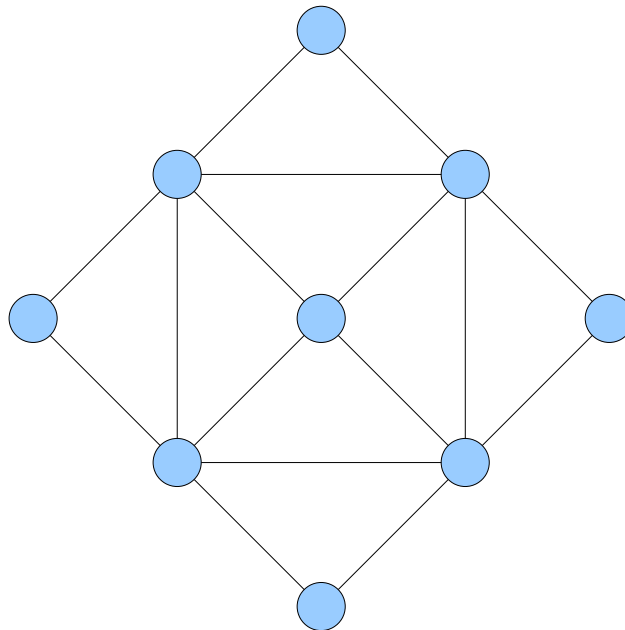
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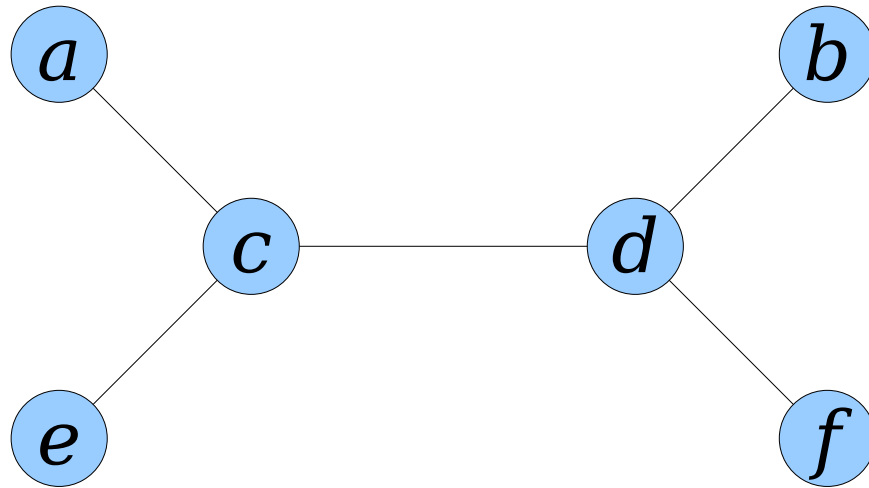


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- ***Classic Theorem 1:*** A graph G has a closed Euler tour if and only if G is connected and every node in G has even degree.
- ***Classic Theorem 2:*** A directed graph G has a closed Euler tour if and only if G is strongly connected and every node's indegree equals its outdegree.

Euler Tours on Trees

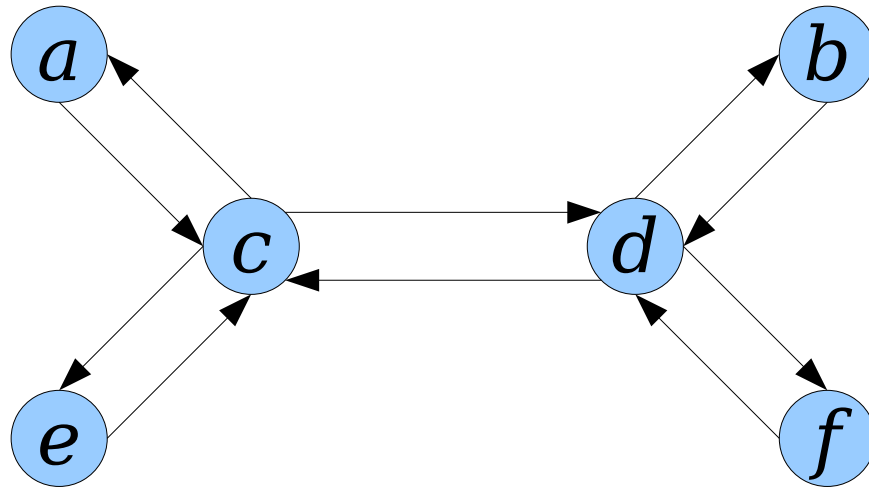
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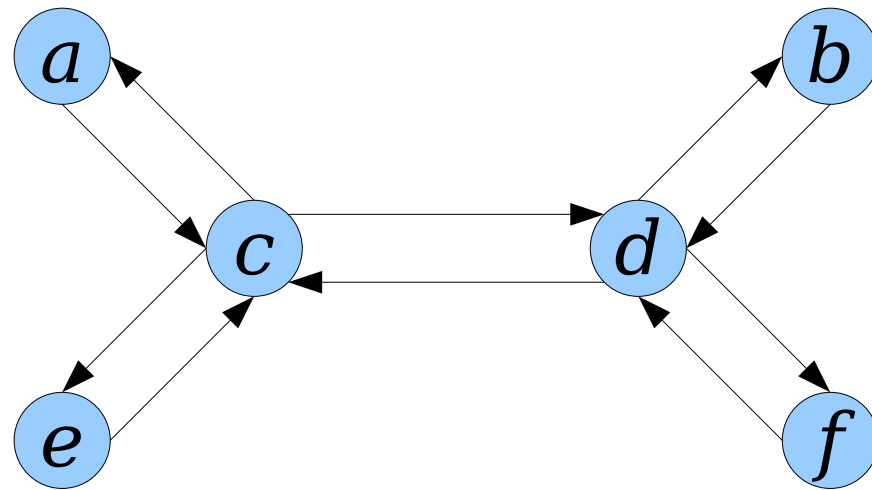
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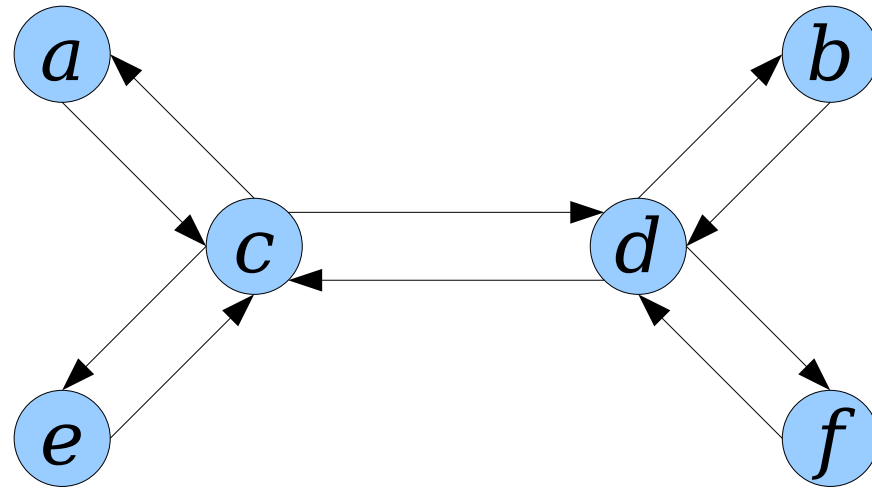


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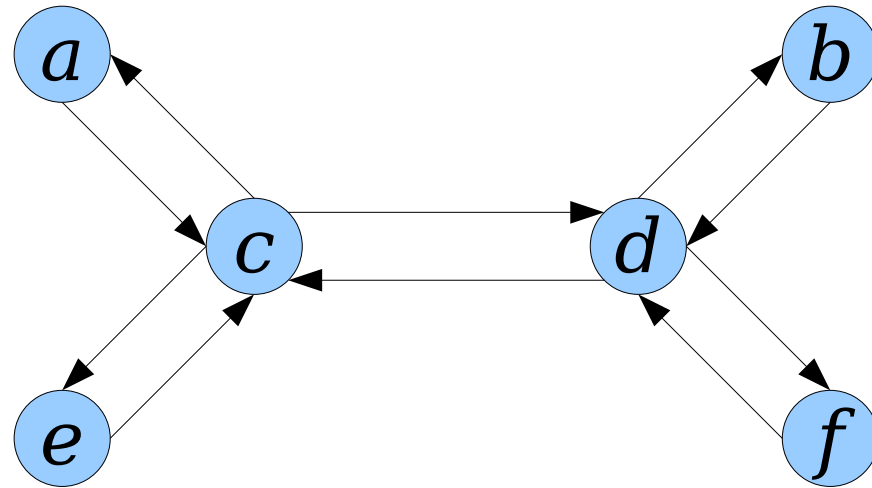


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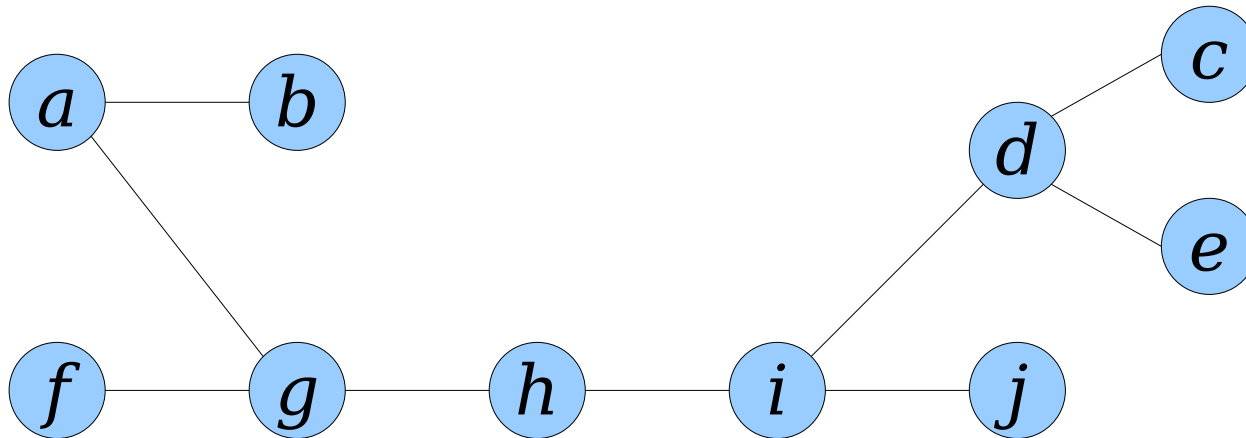


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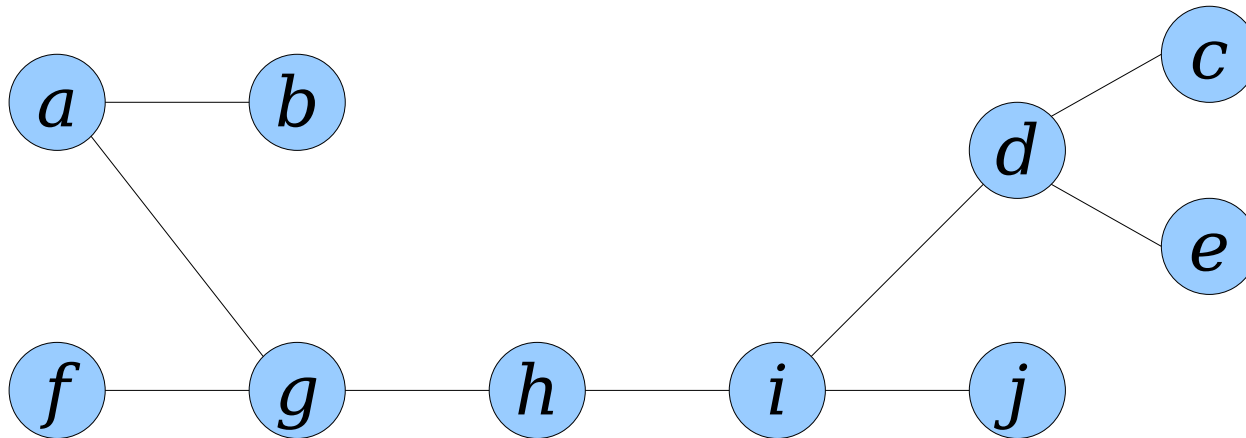
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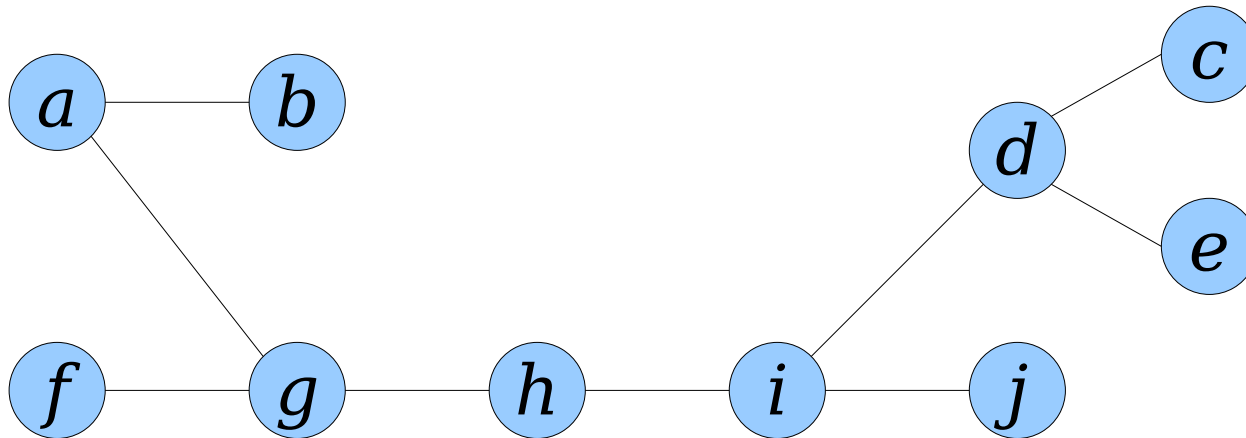
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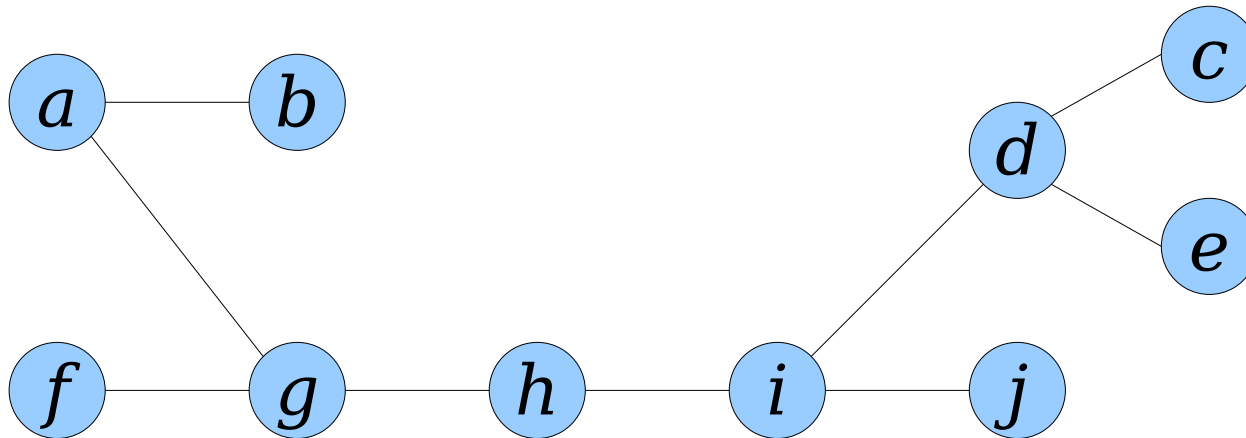
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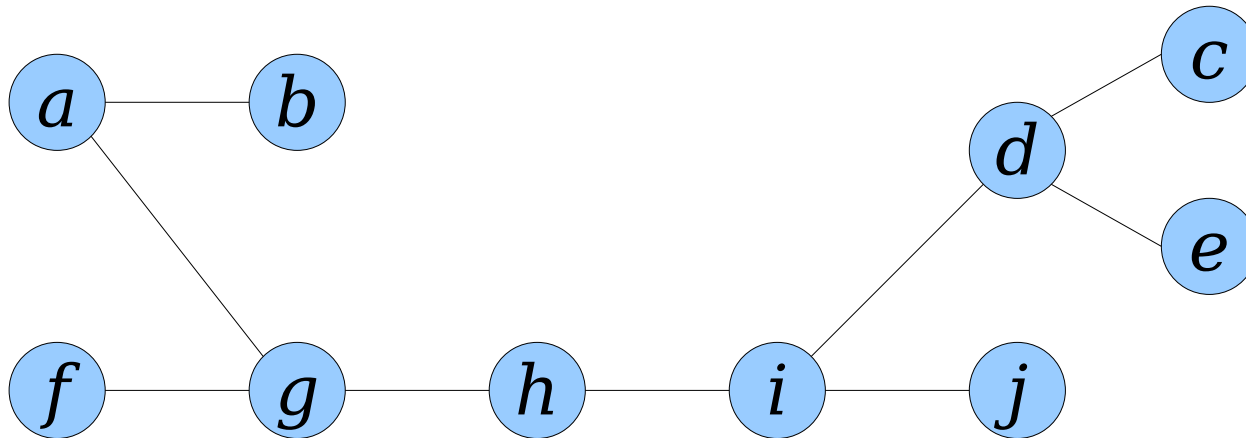
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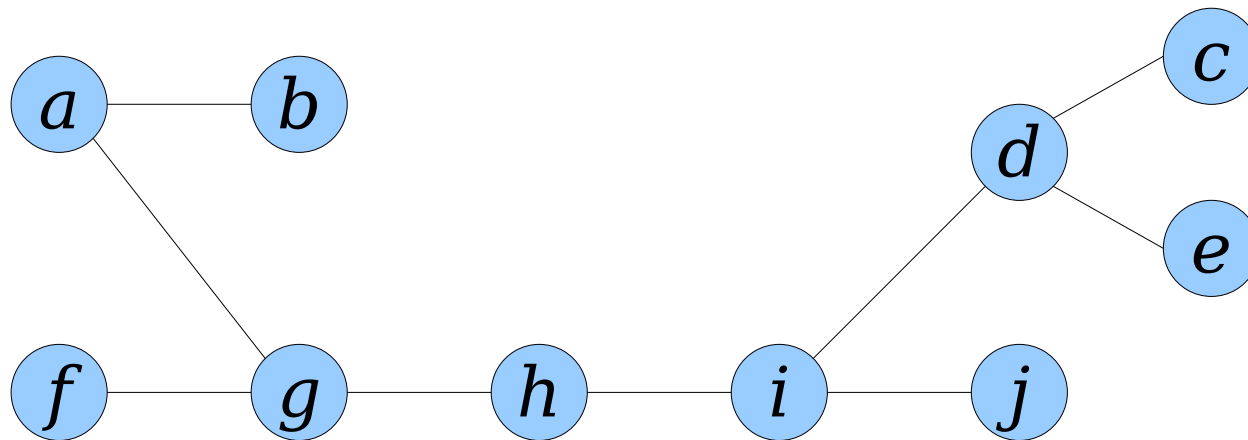
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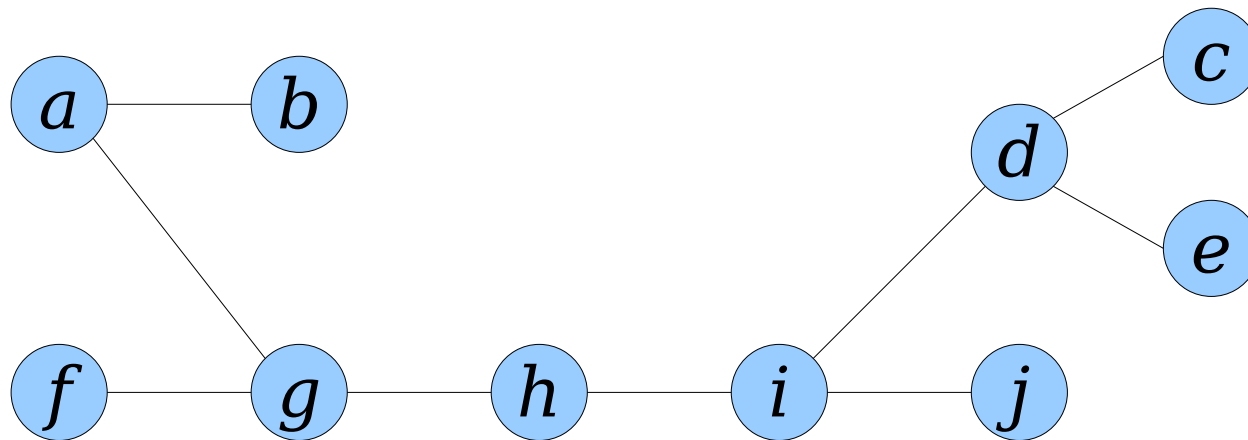
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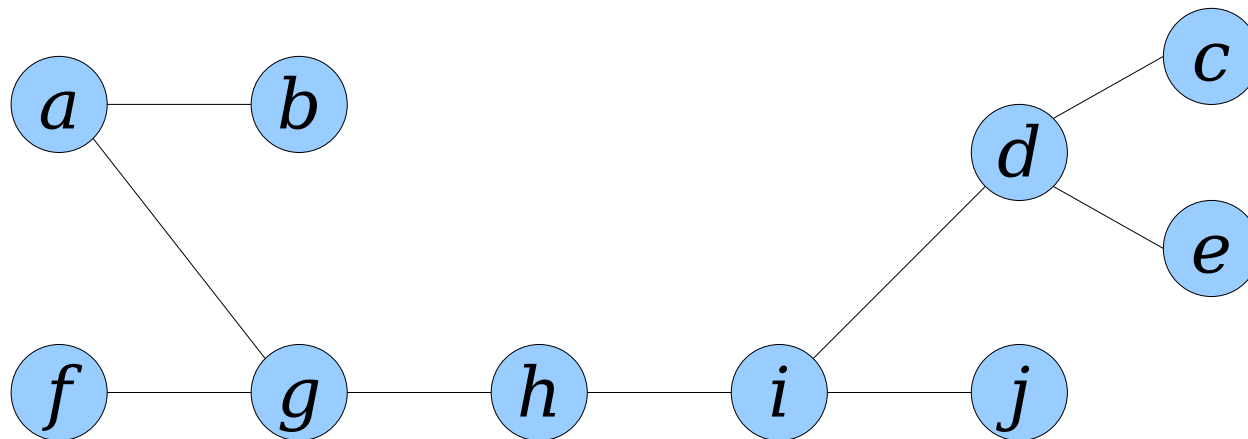
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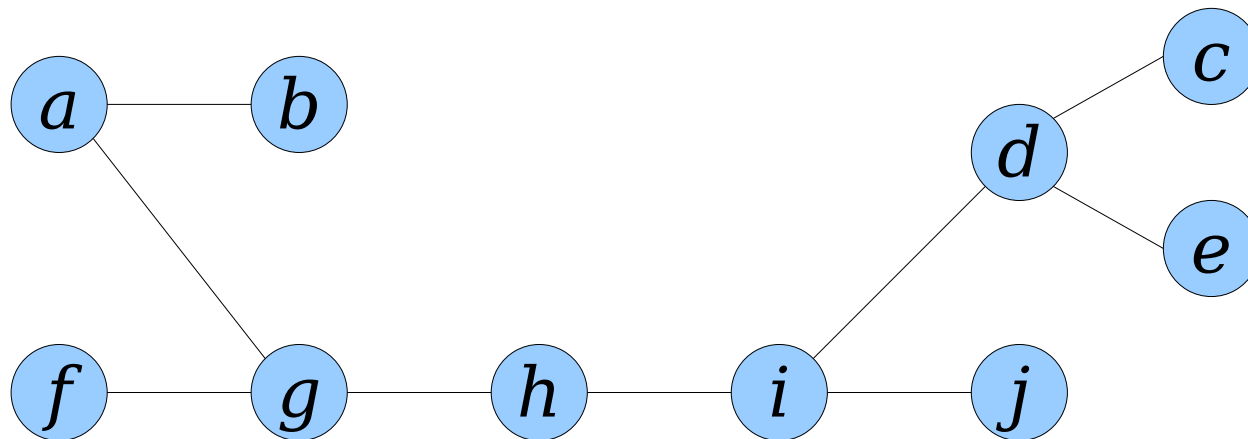
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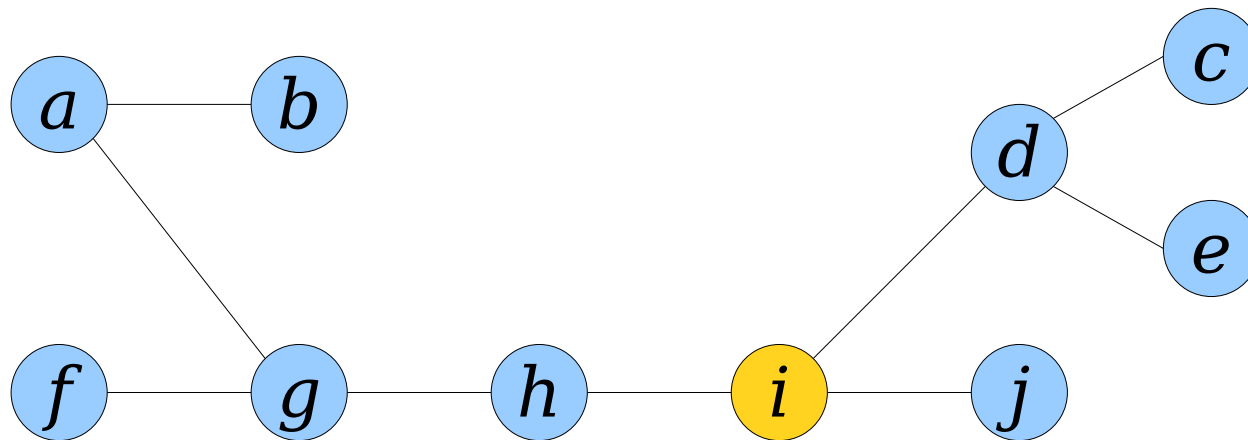
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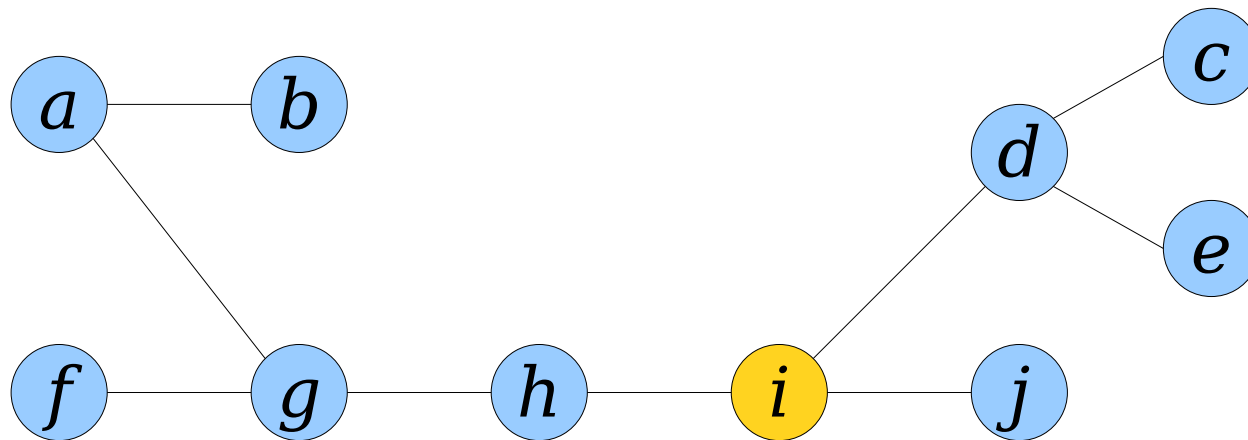
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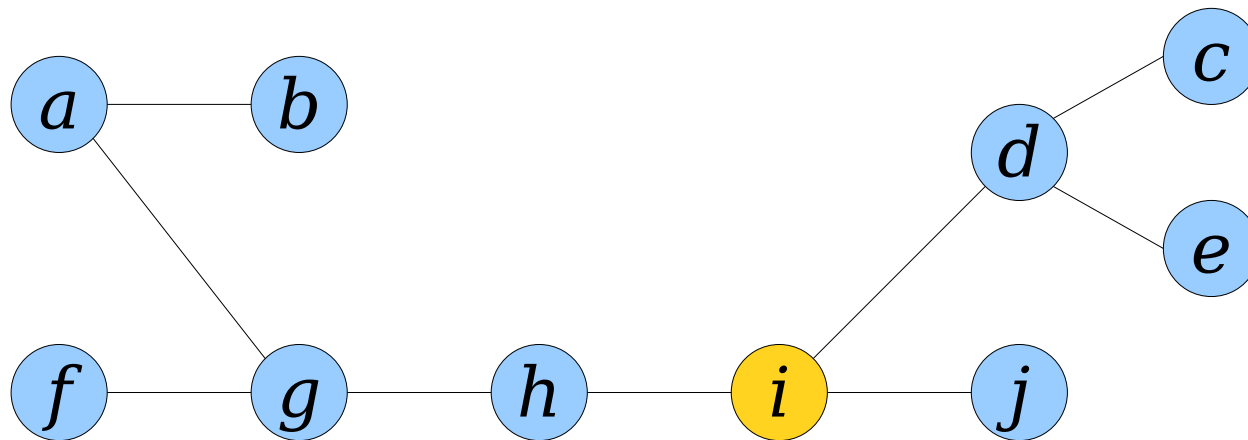
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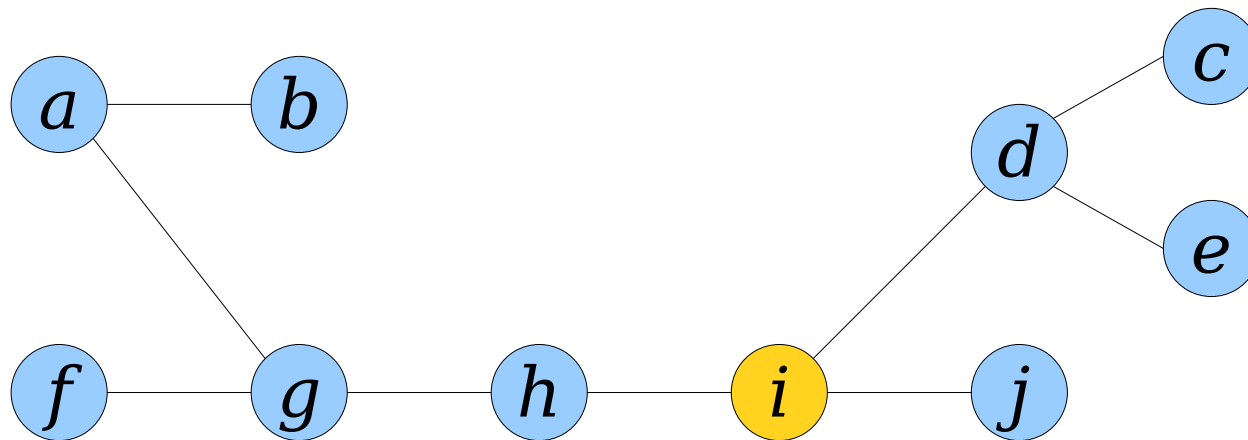
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Rerooting a Tour

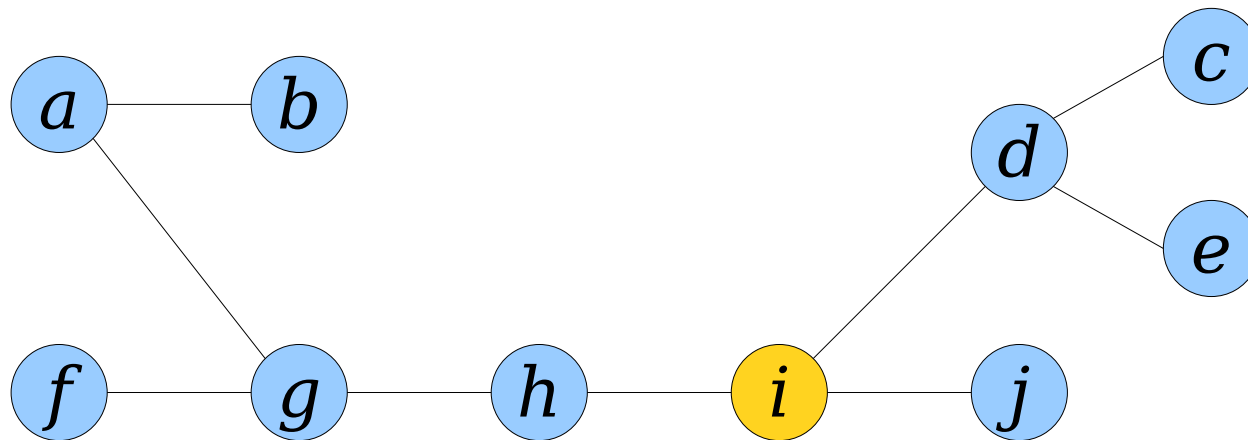
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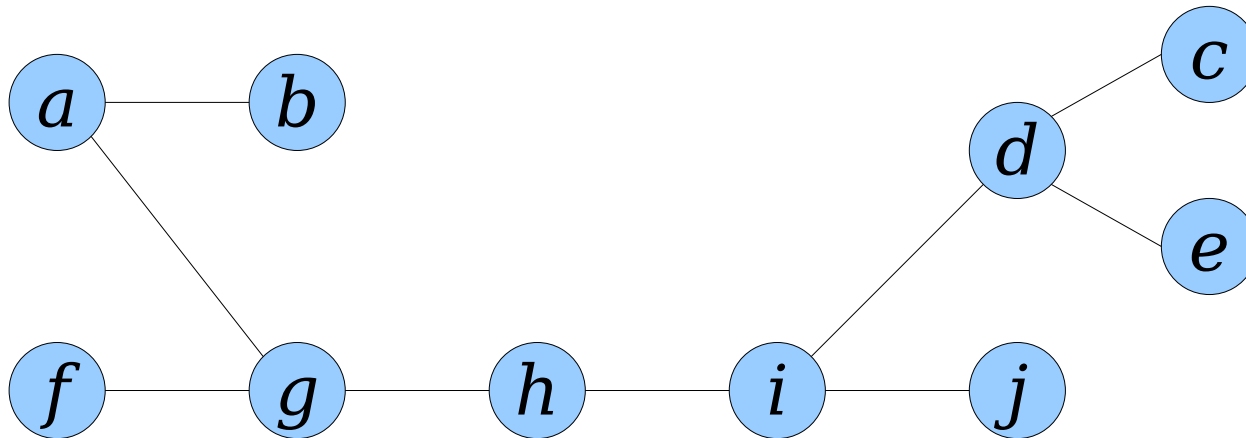
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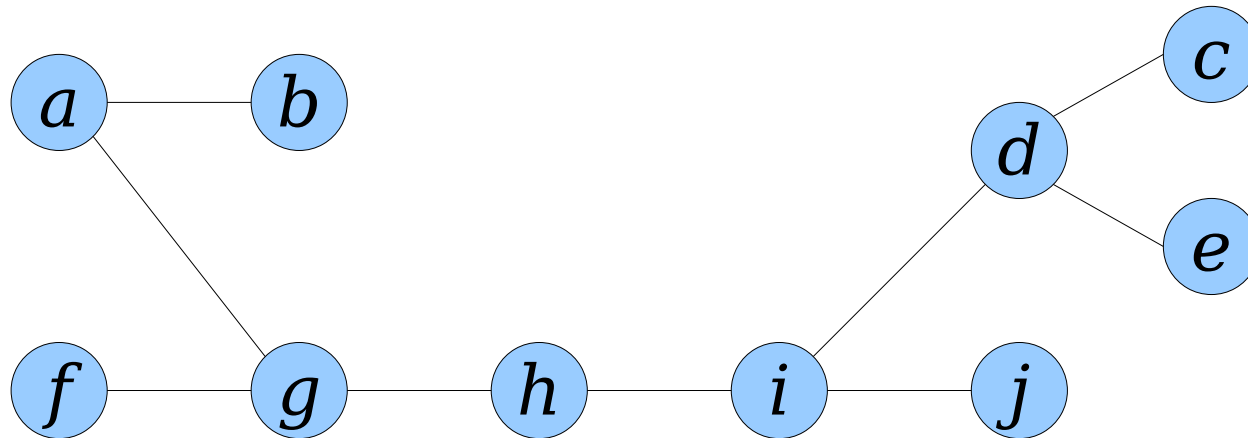
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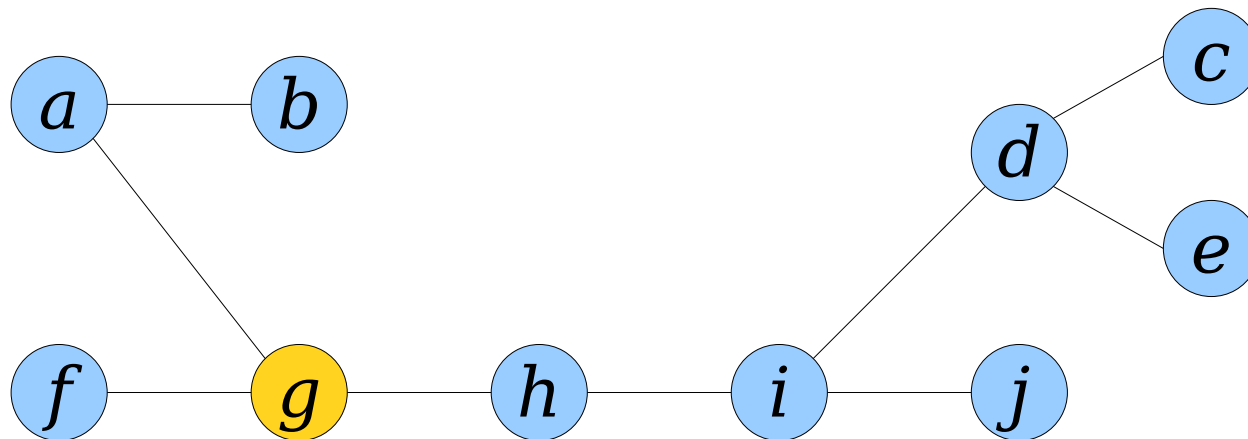
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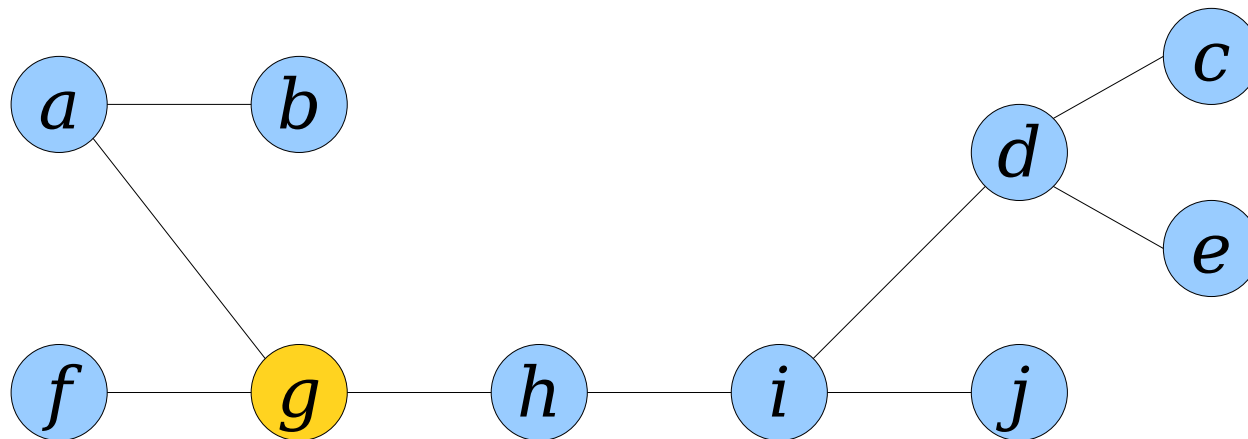
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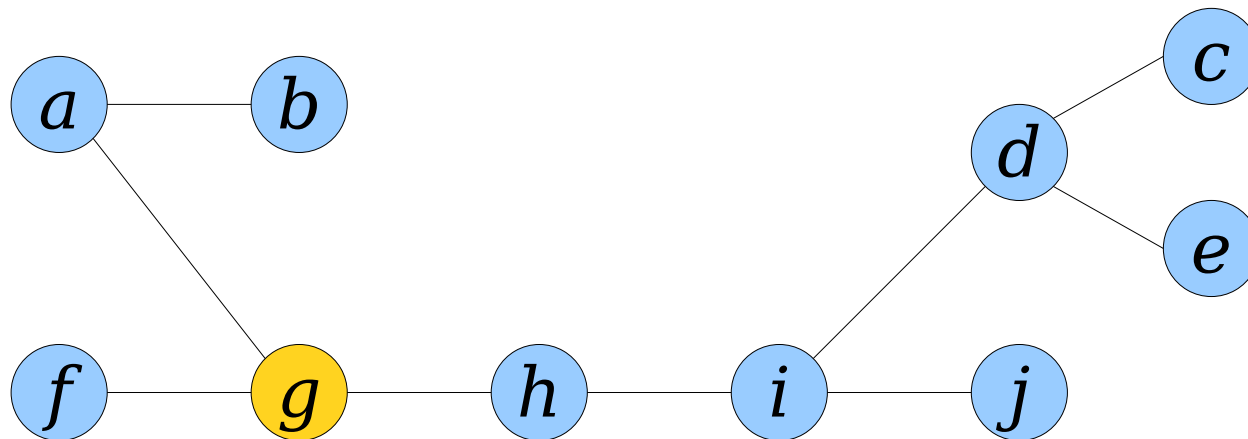
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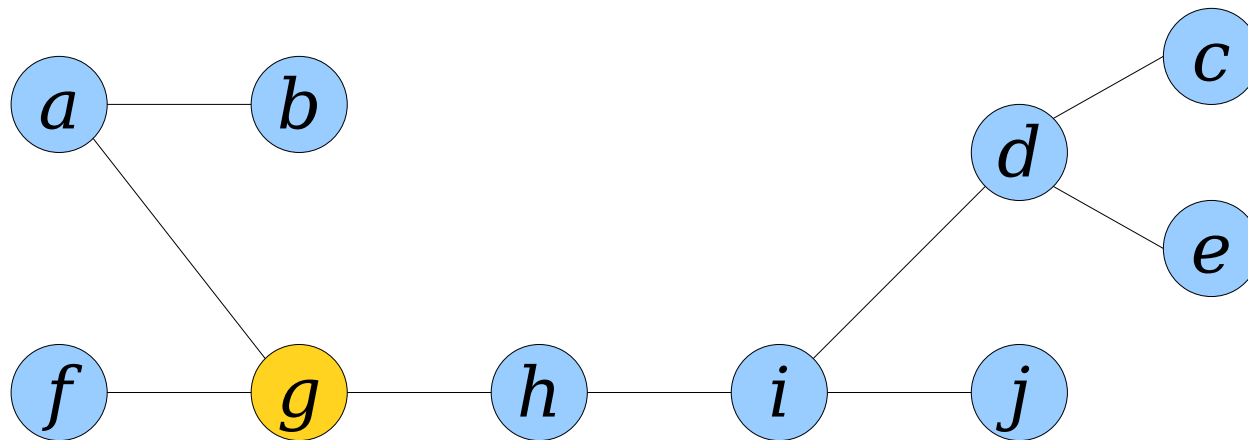
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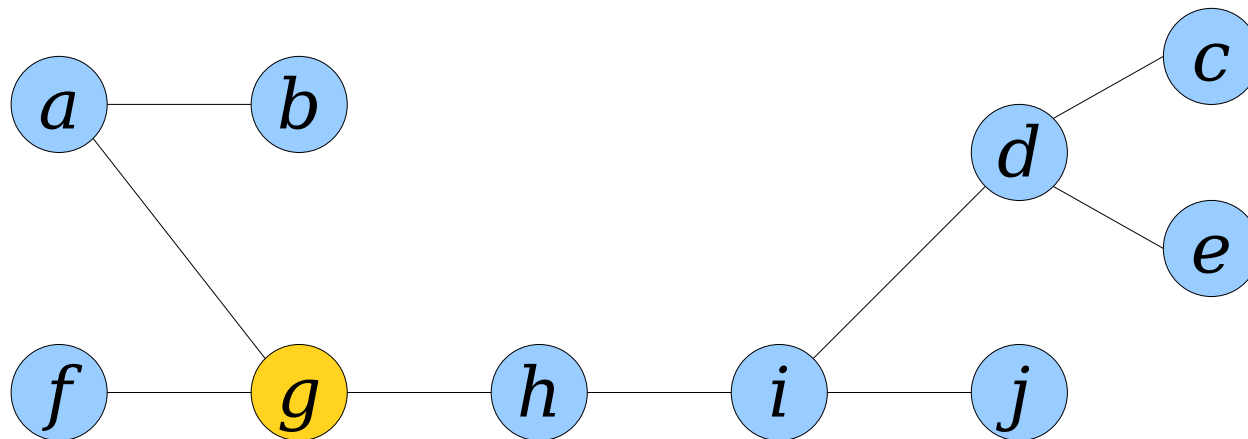
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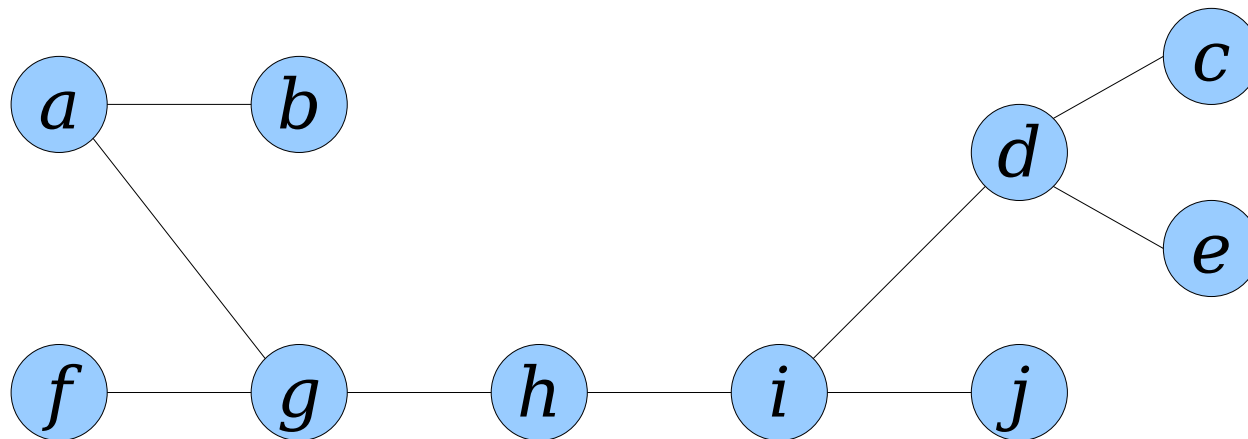
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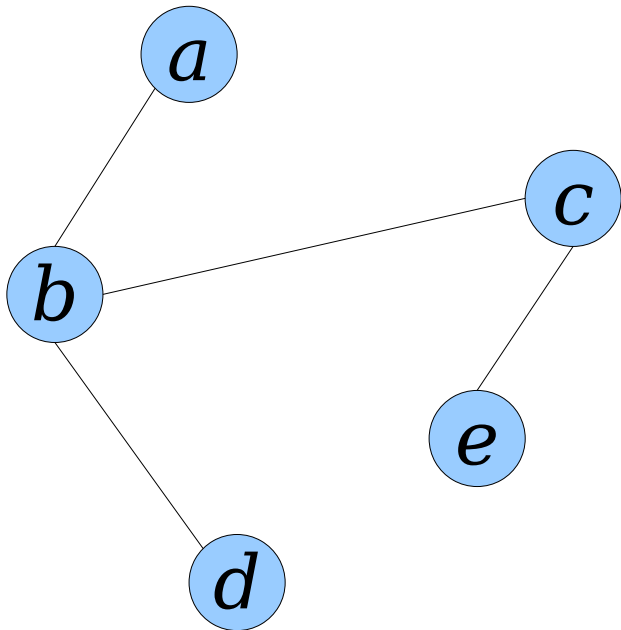
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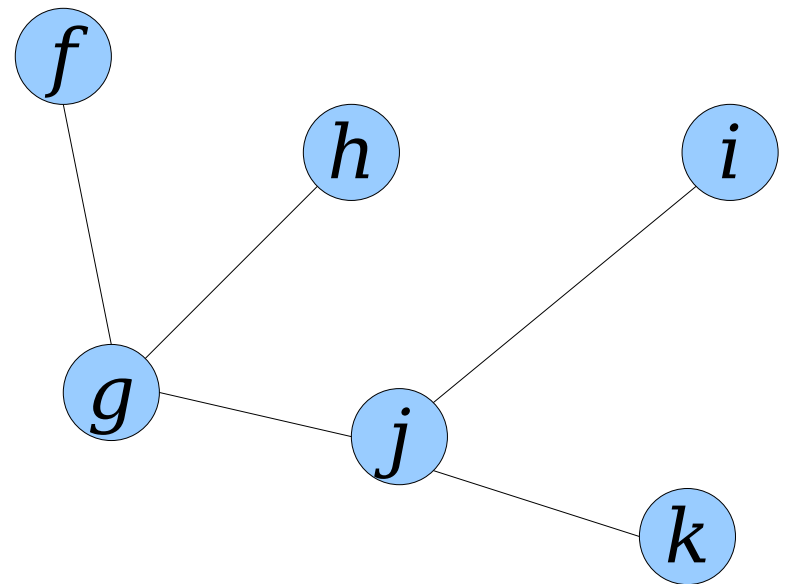
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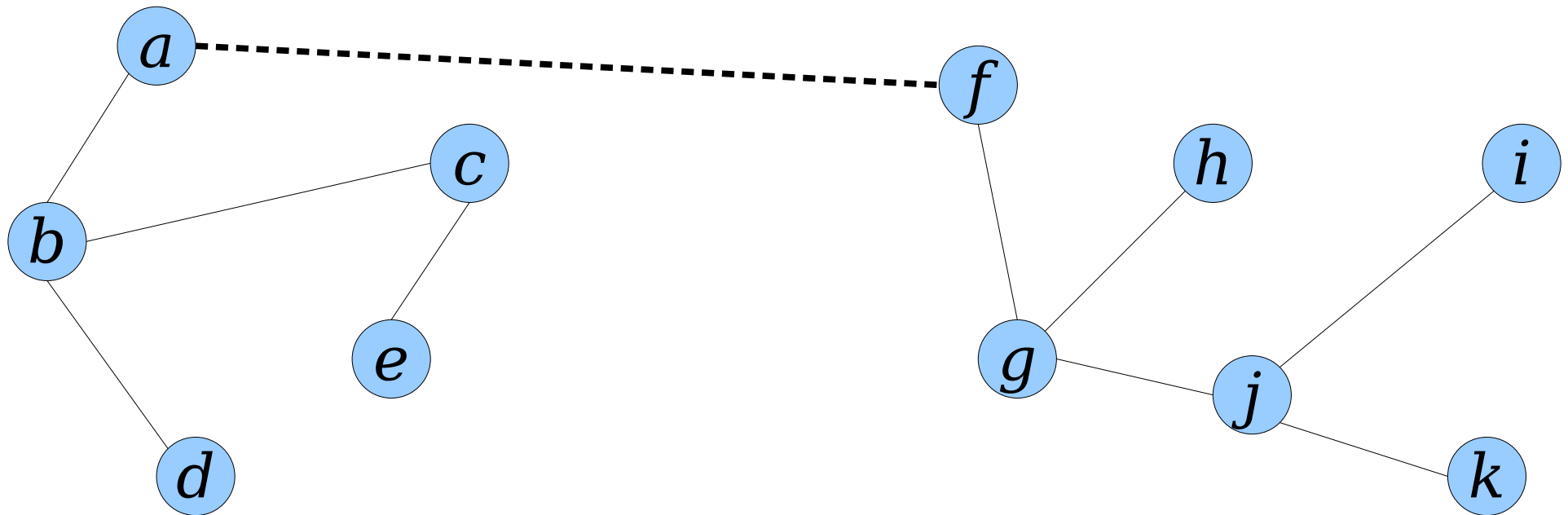
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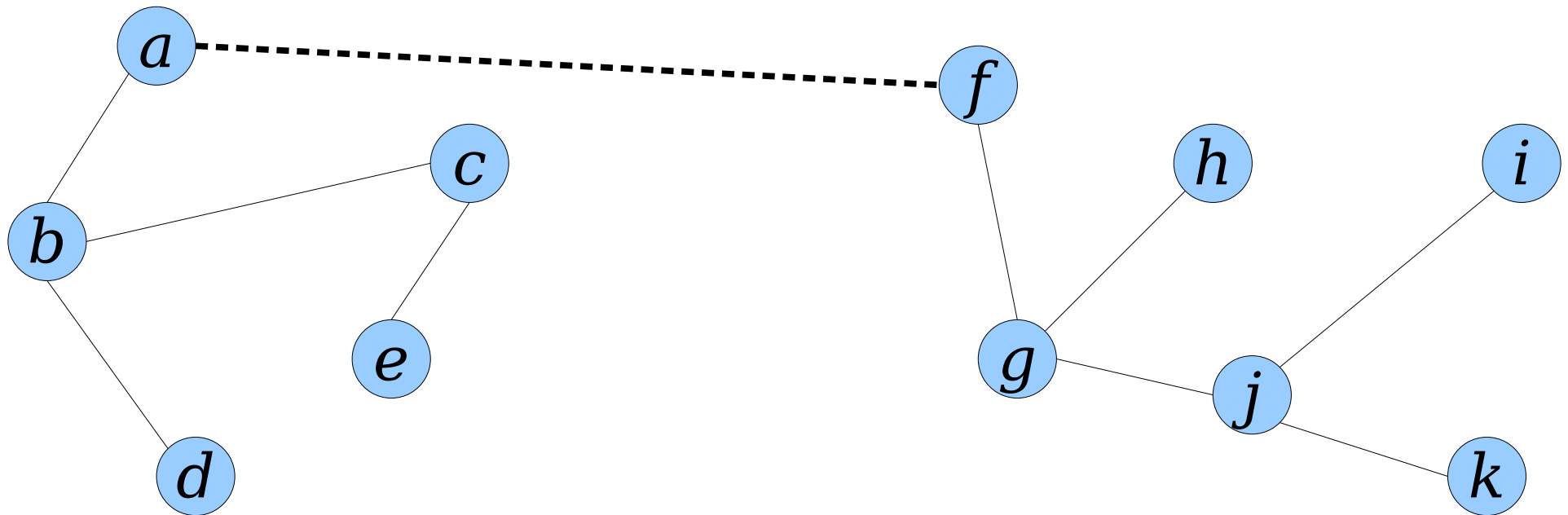


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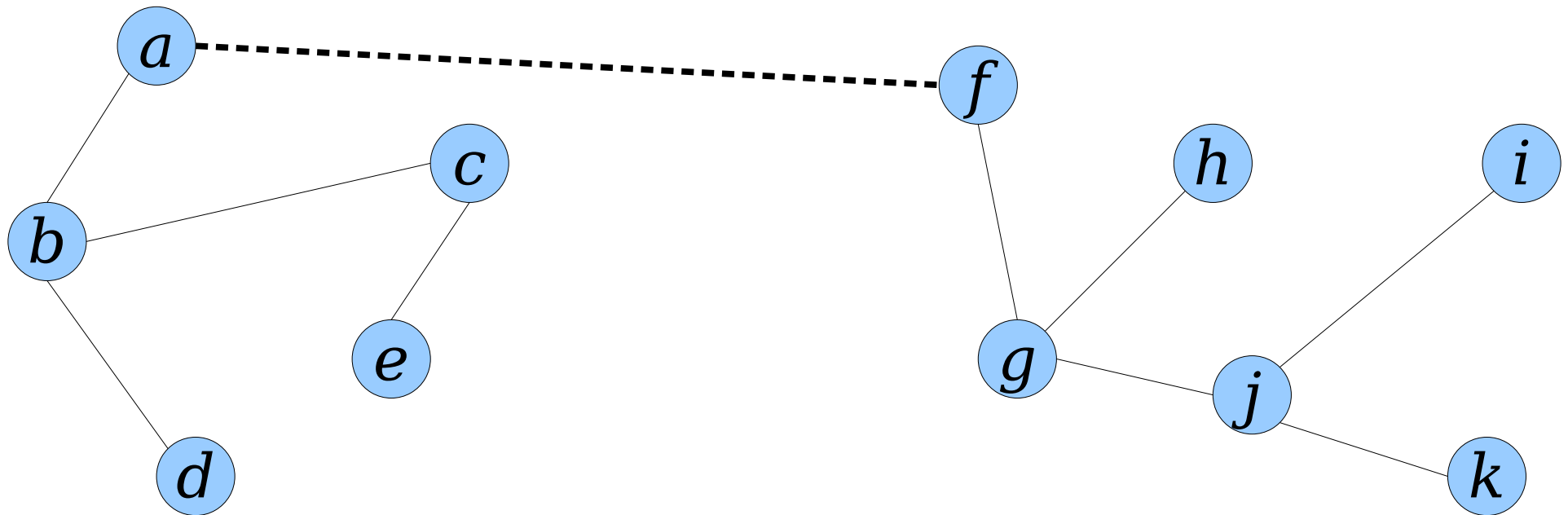


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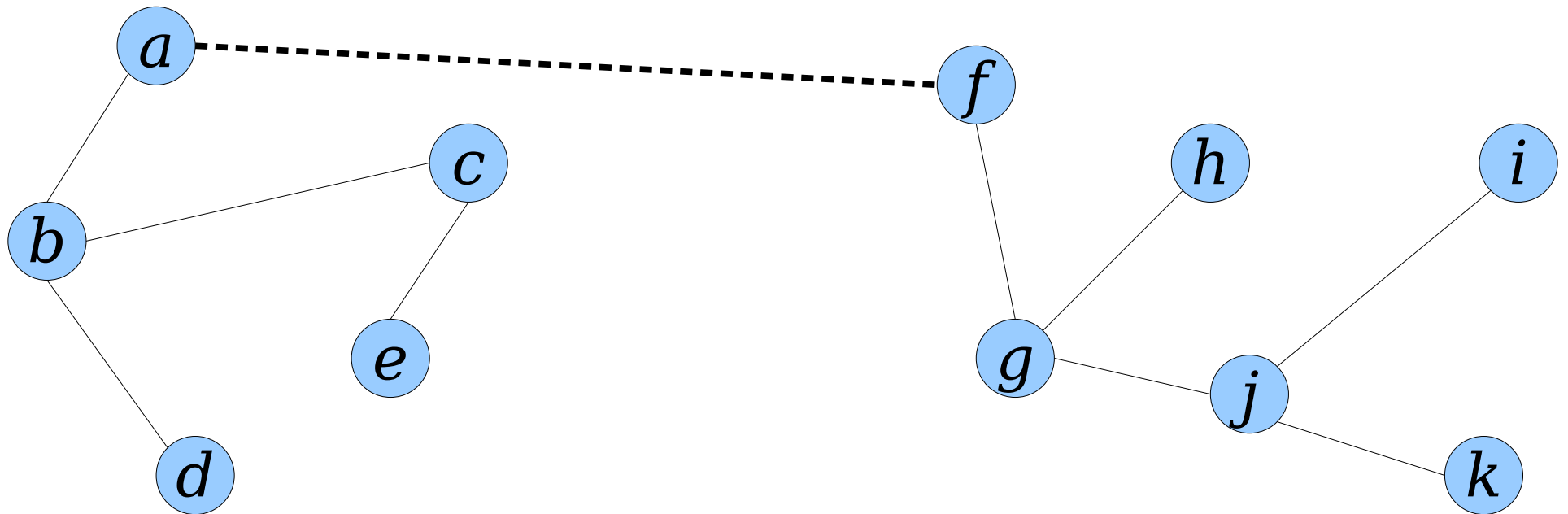


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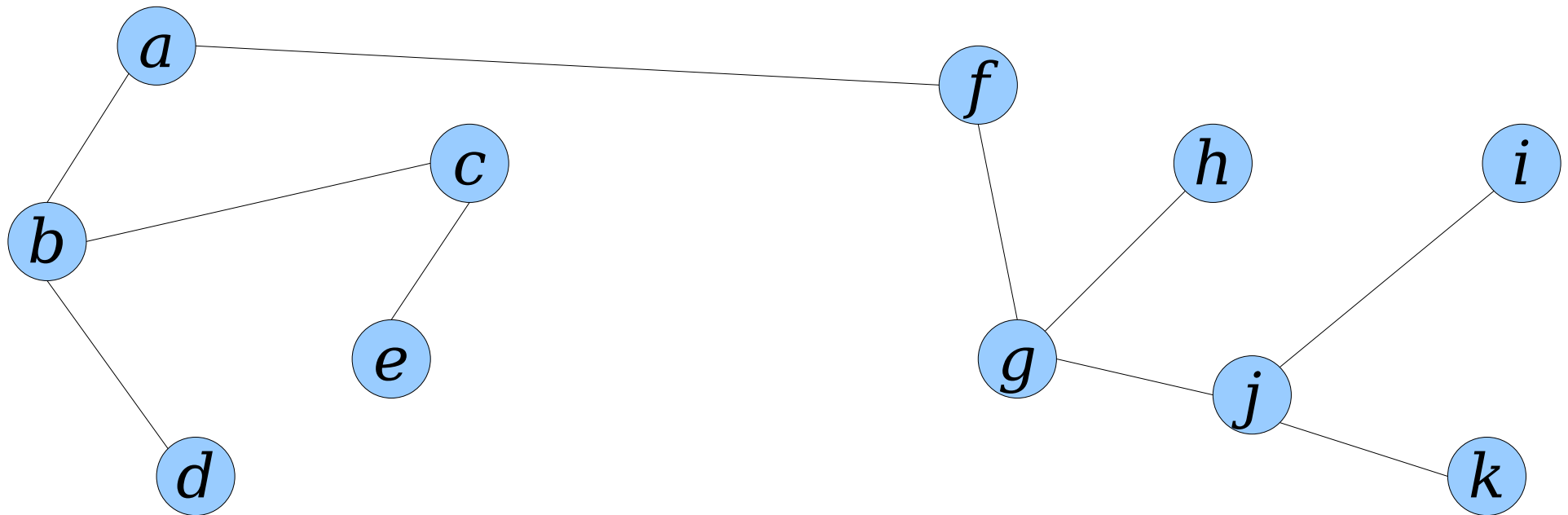
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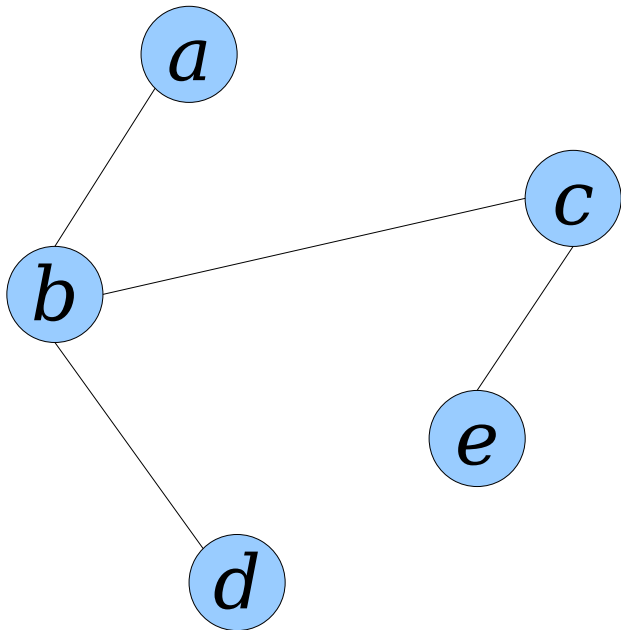
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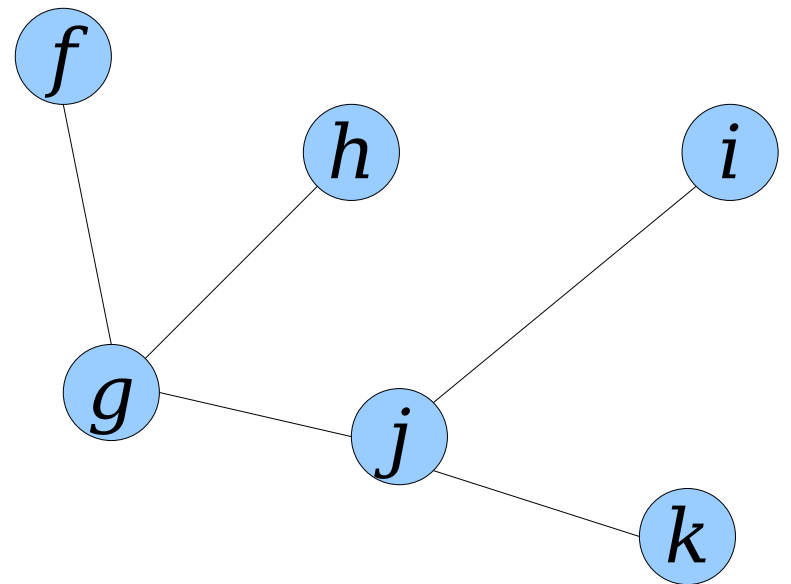
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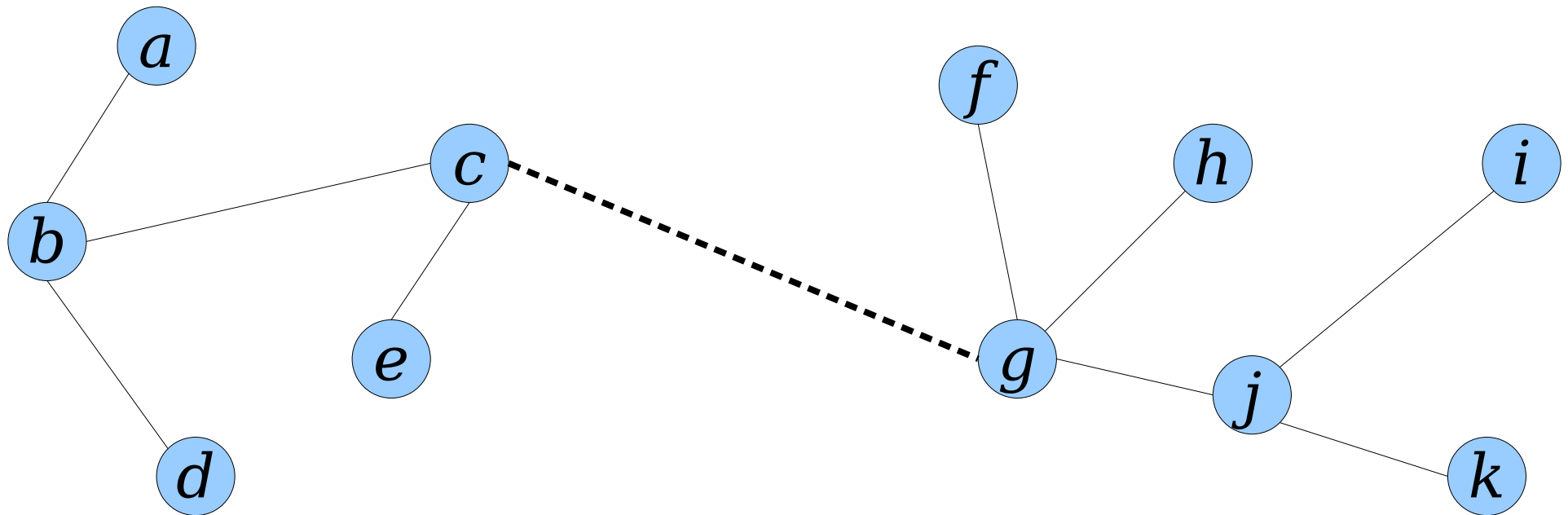
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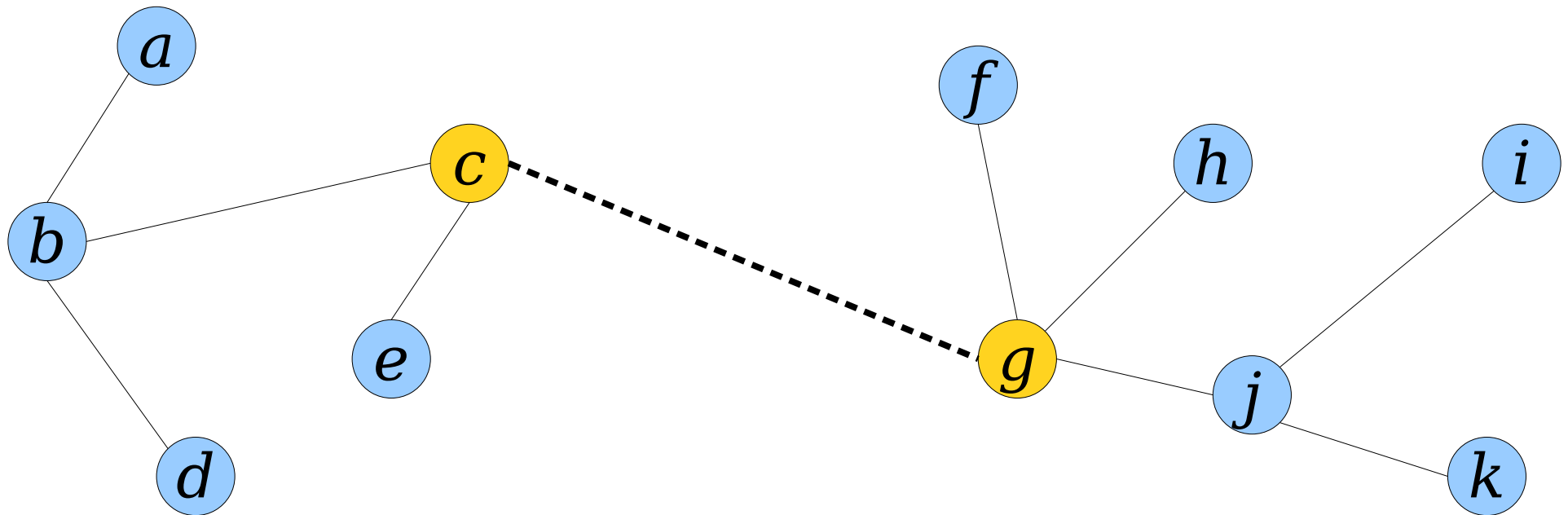


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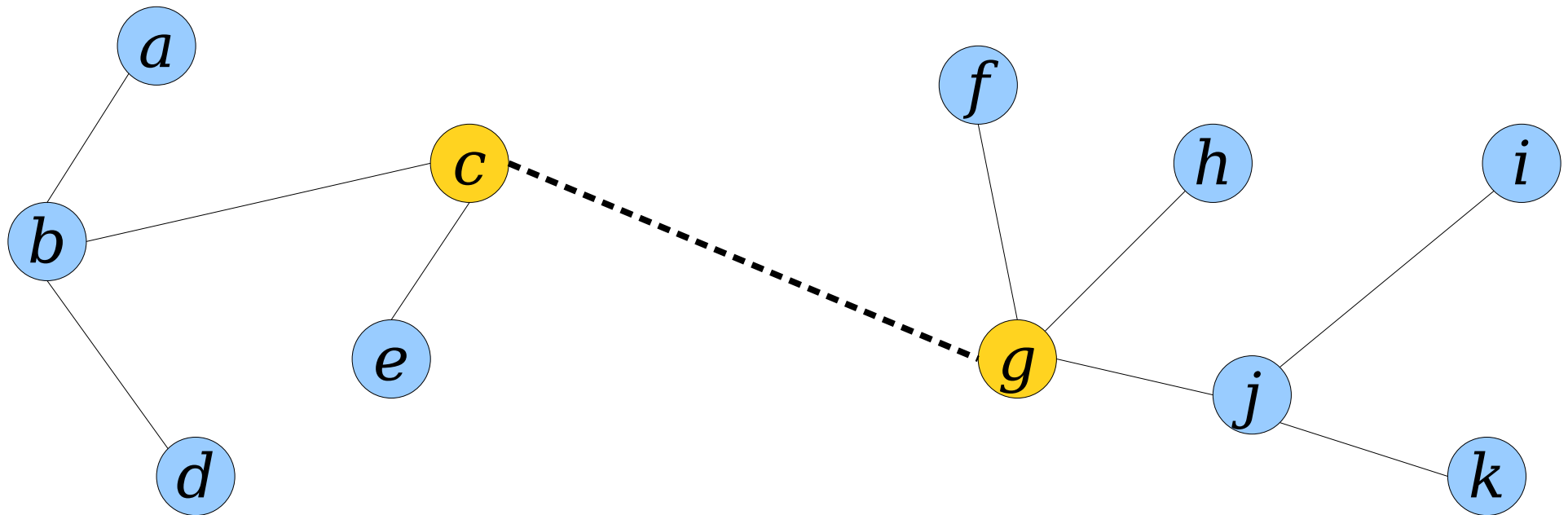


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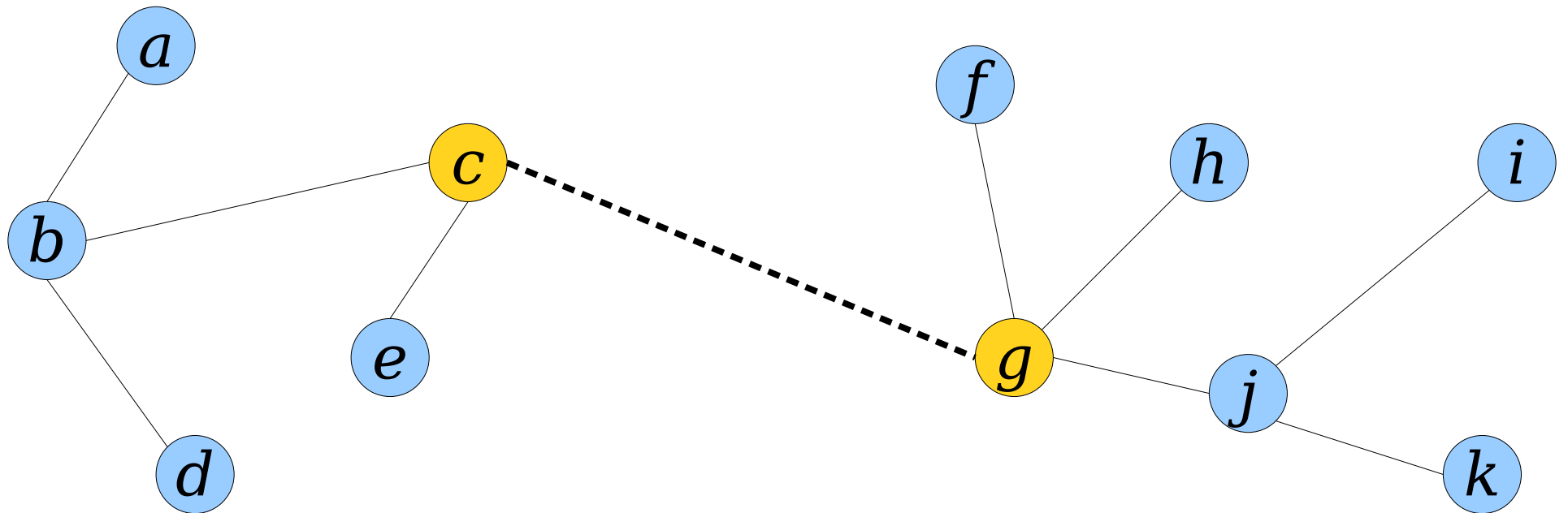


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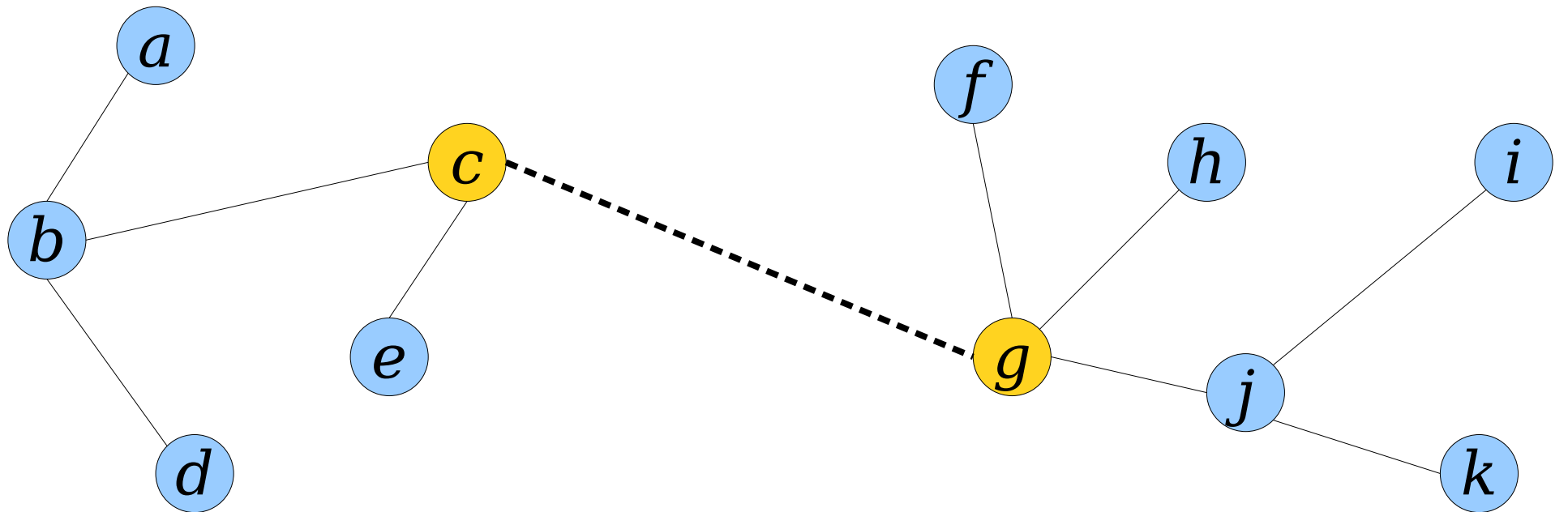


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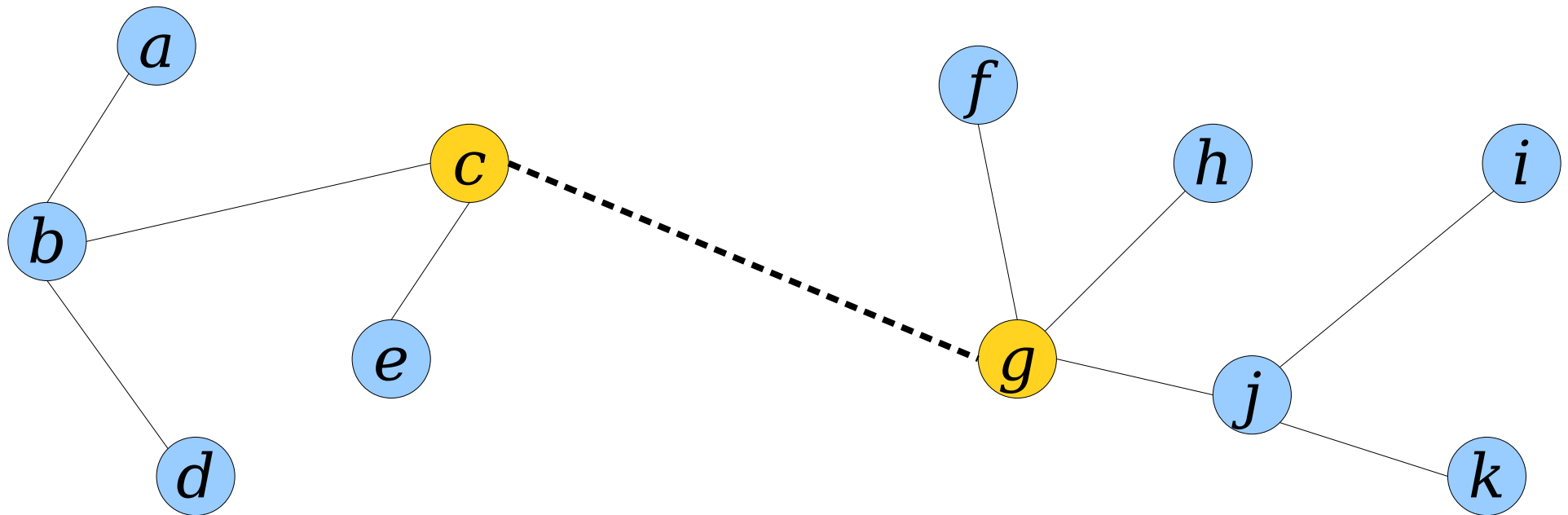


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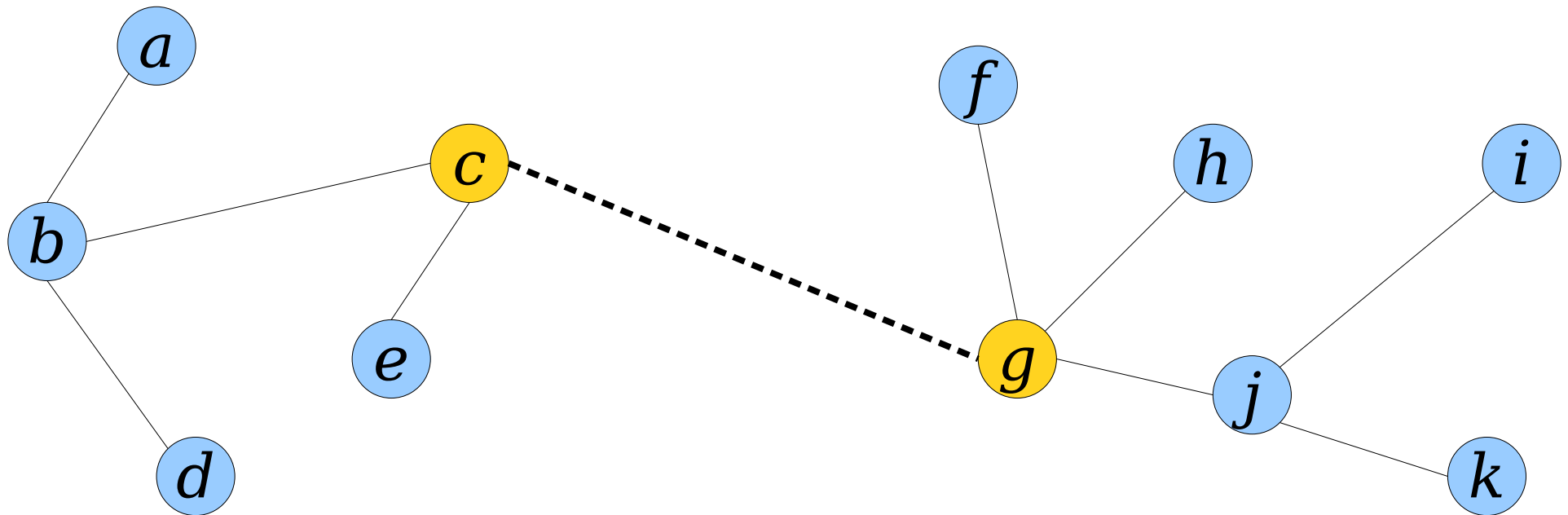


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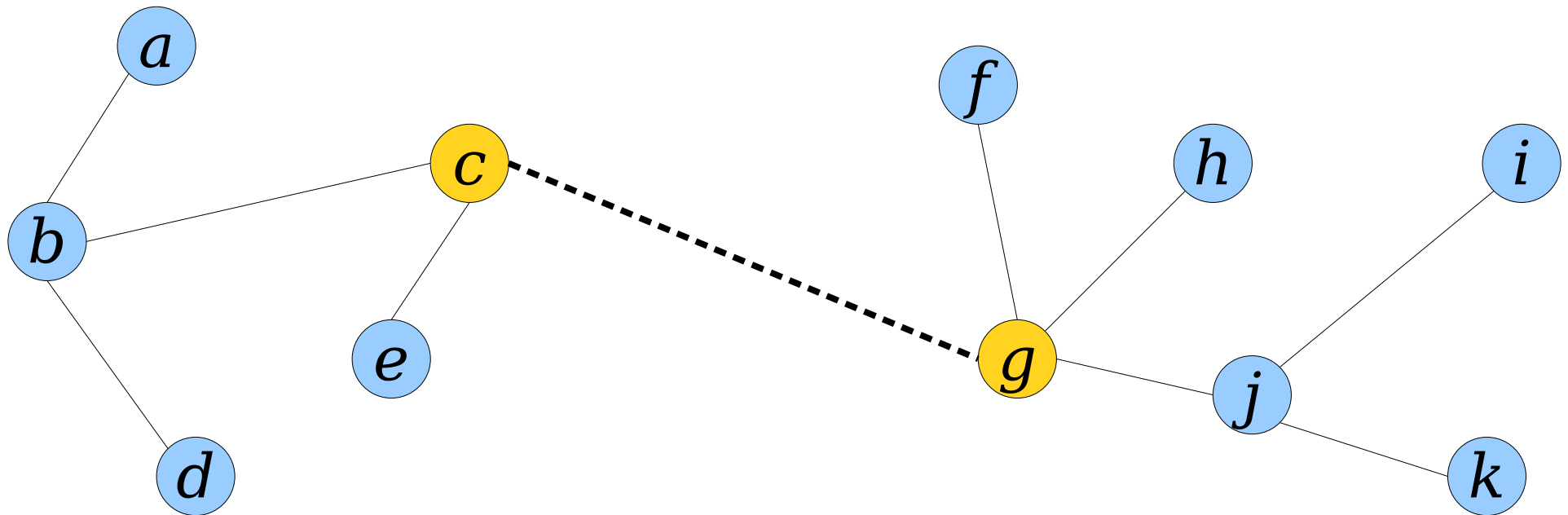


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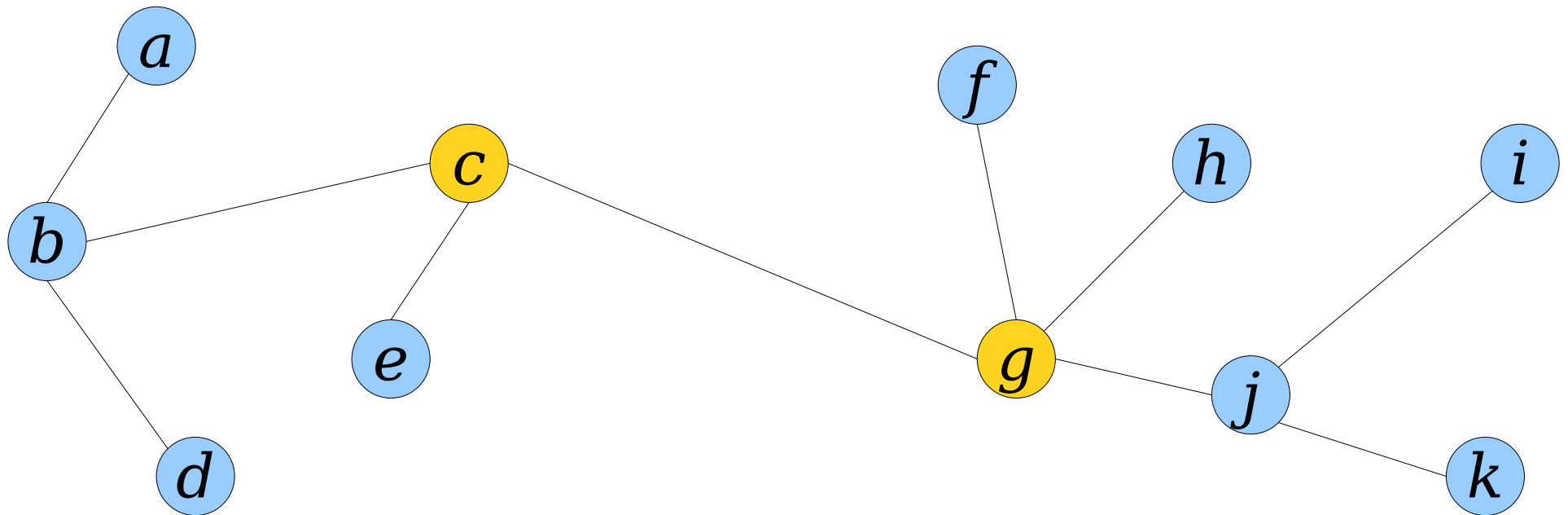
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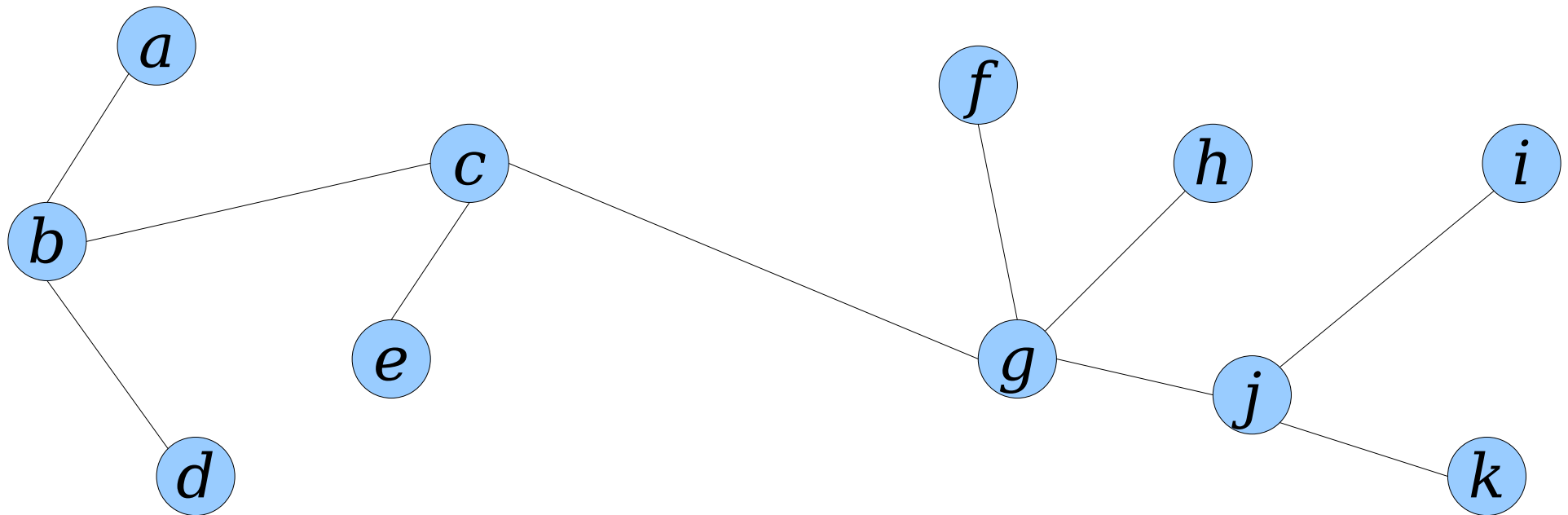
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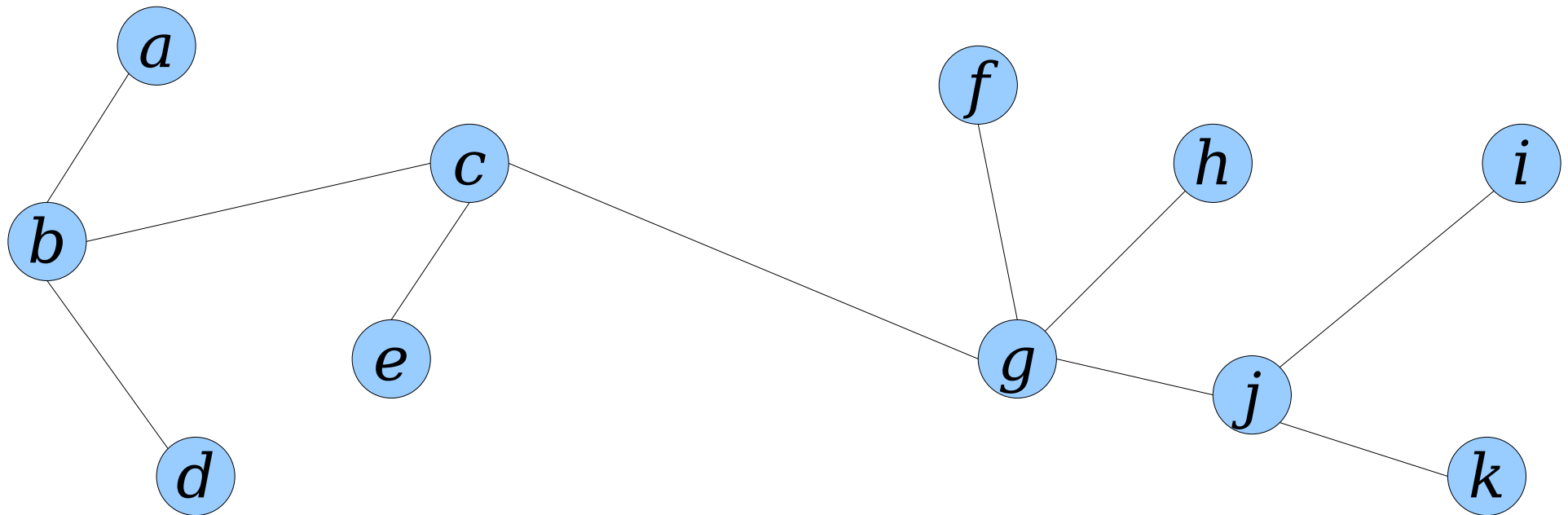
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- To **link**(u, v):
 - Let E_1 and E_2 be Euler tours of T_1 and T_2 , respectively.
 - **reroot**(u).
 - **reroot**(v).
 - Concatenate $E_1 uv E_2 vu$.

Euler Tours and Dynamic Trees

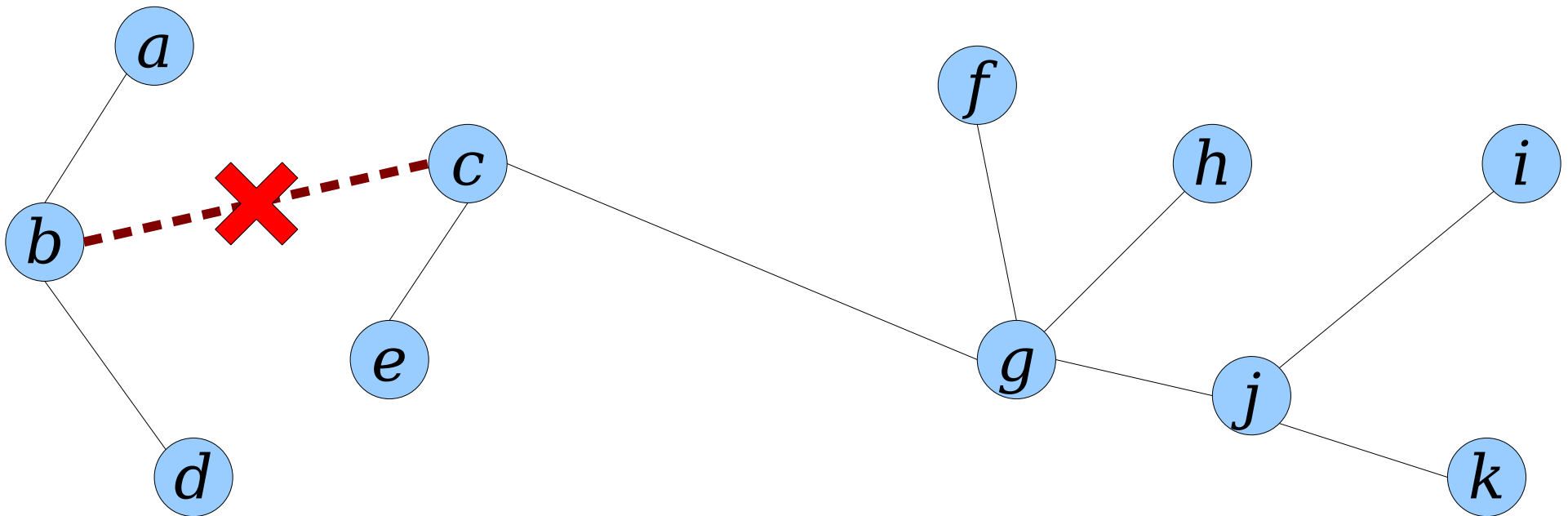
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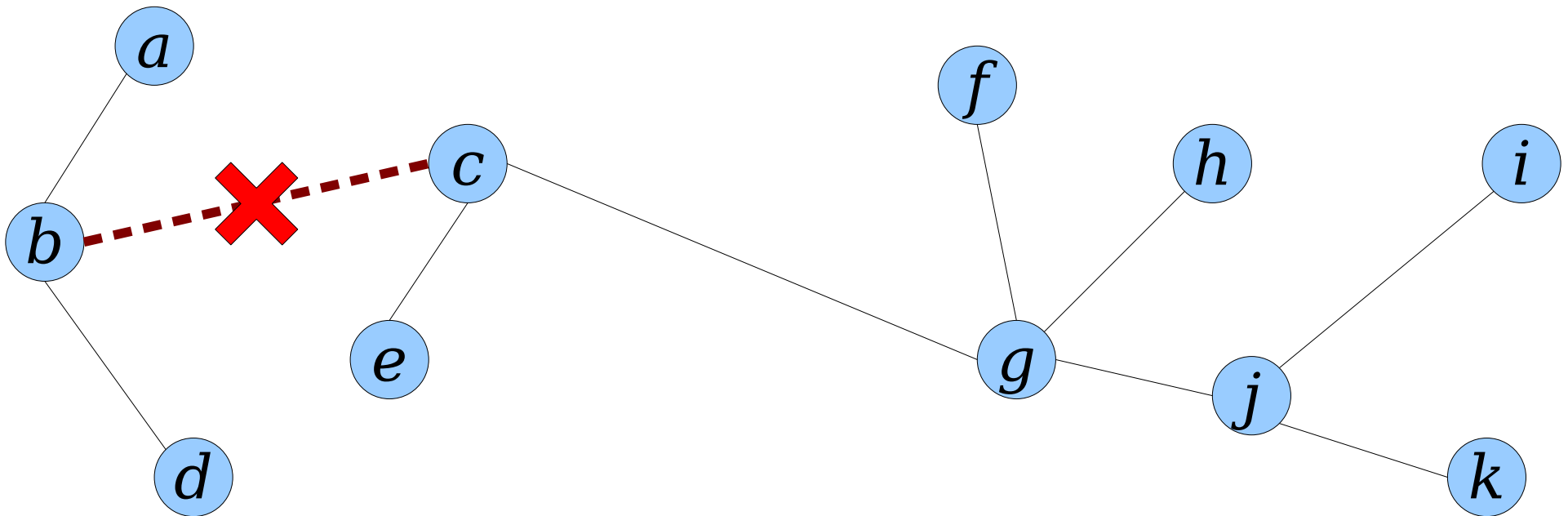
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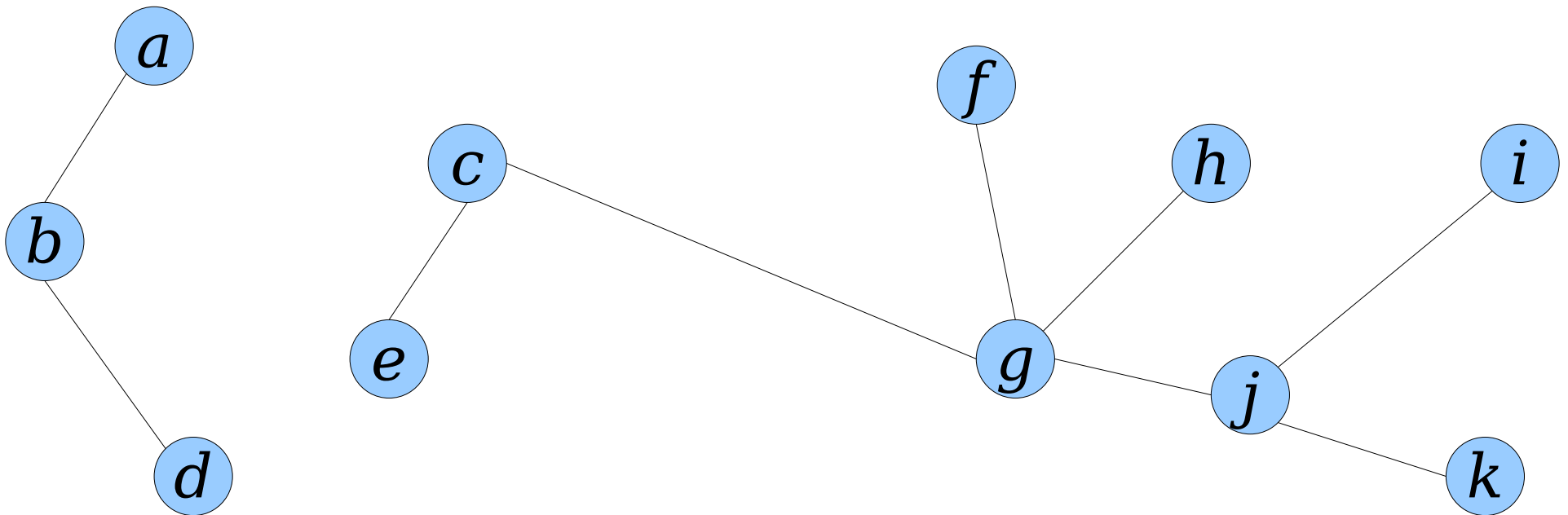
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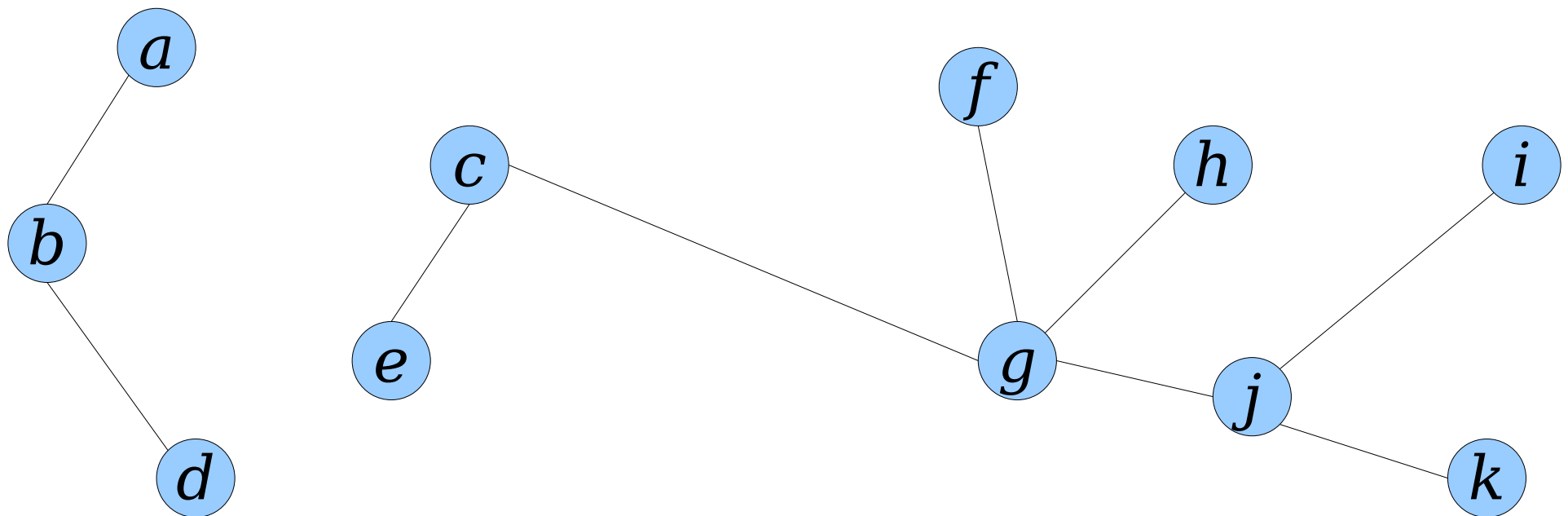
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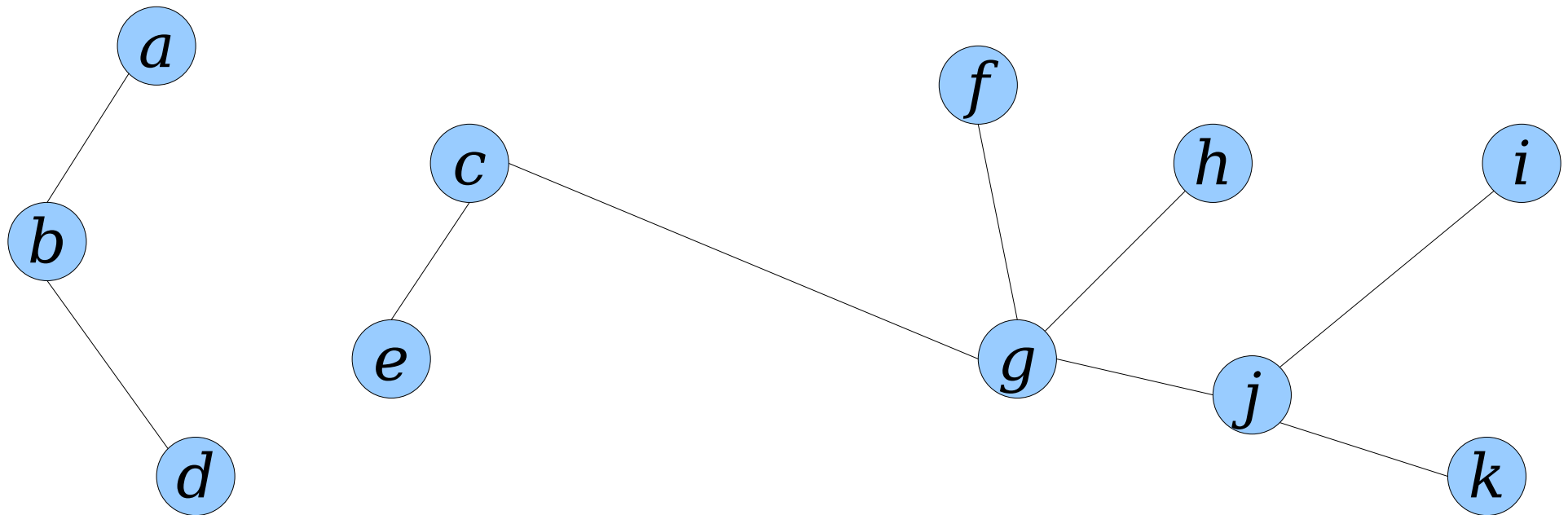
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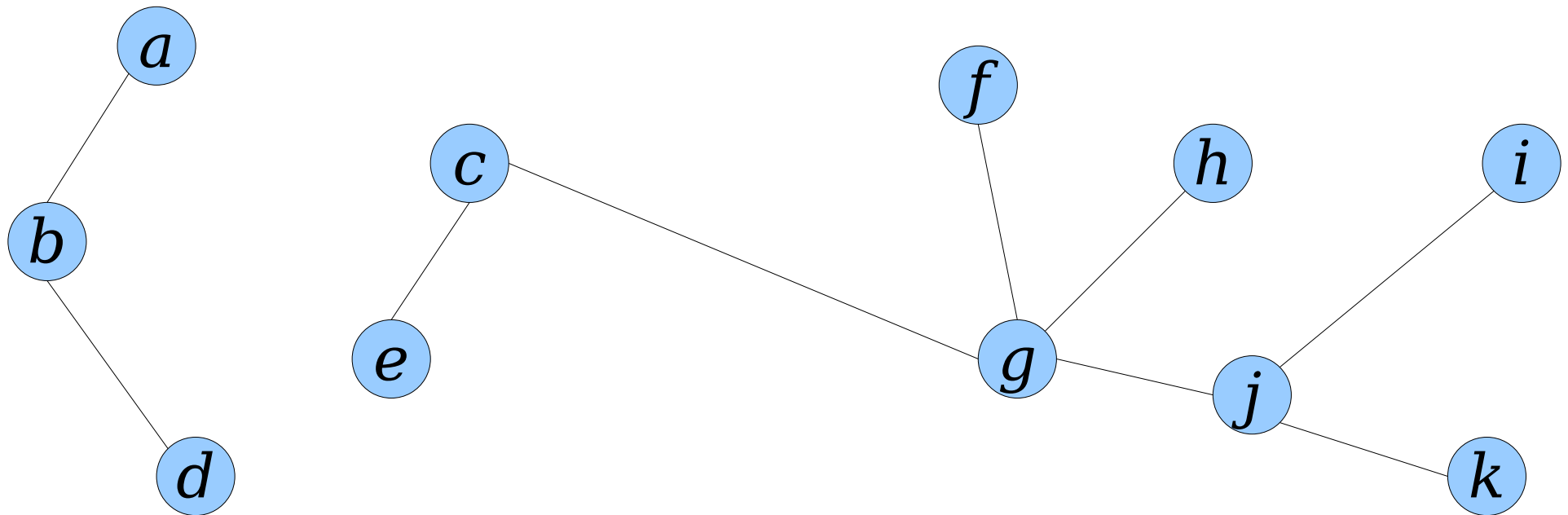
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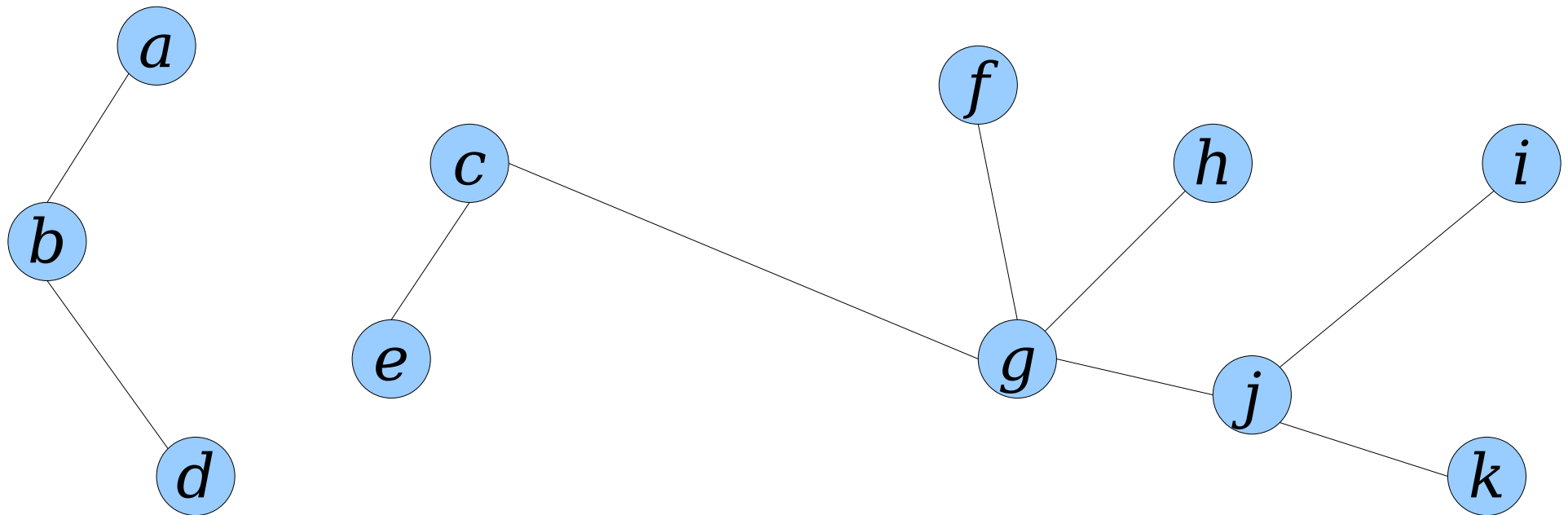


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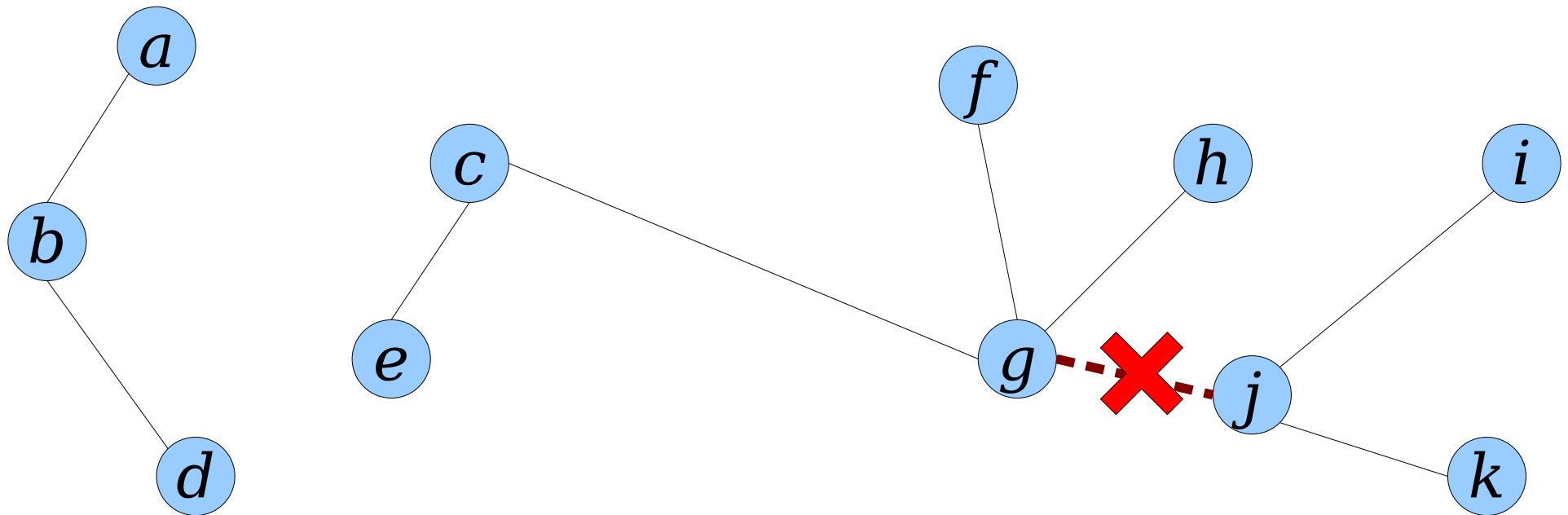


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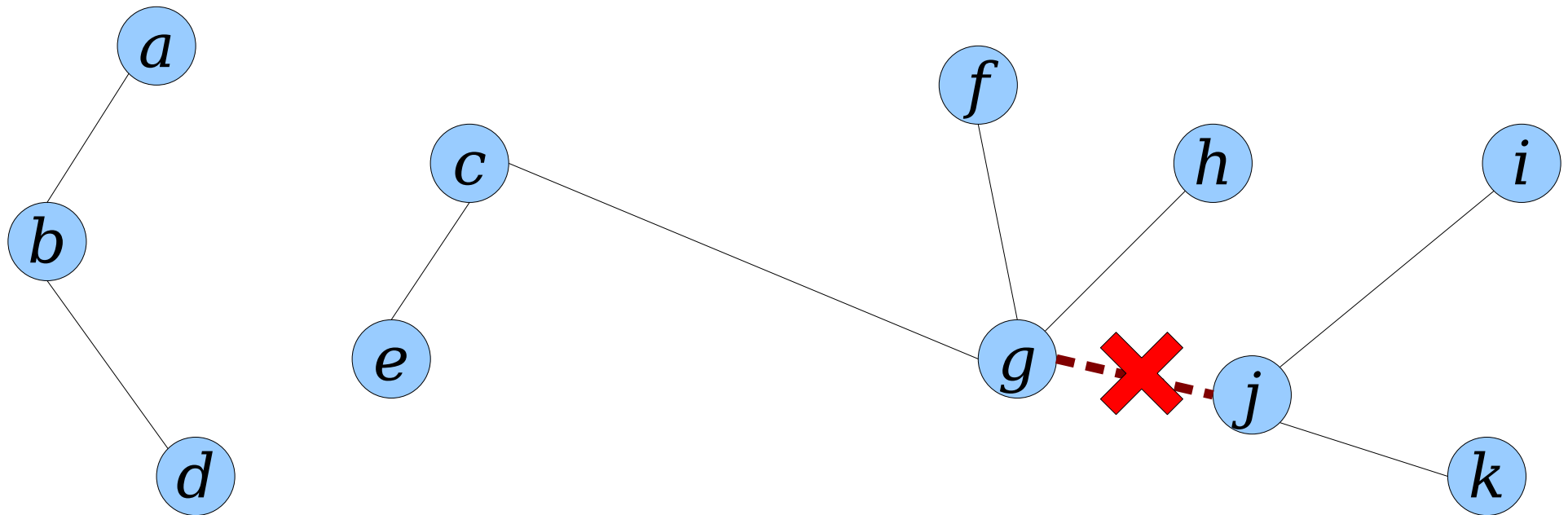


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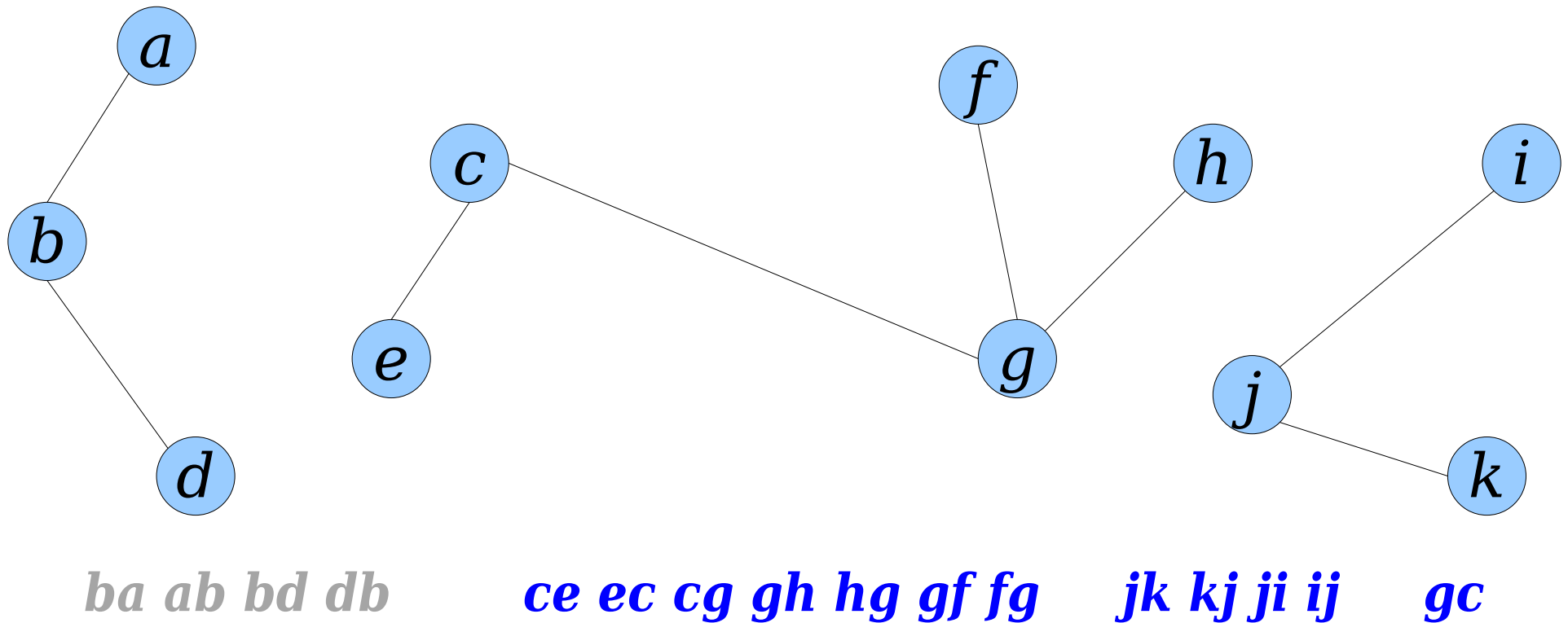


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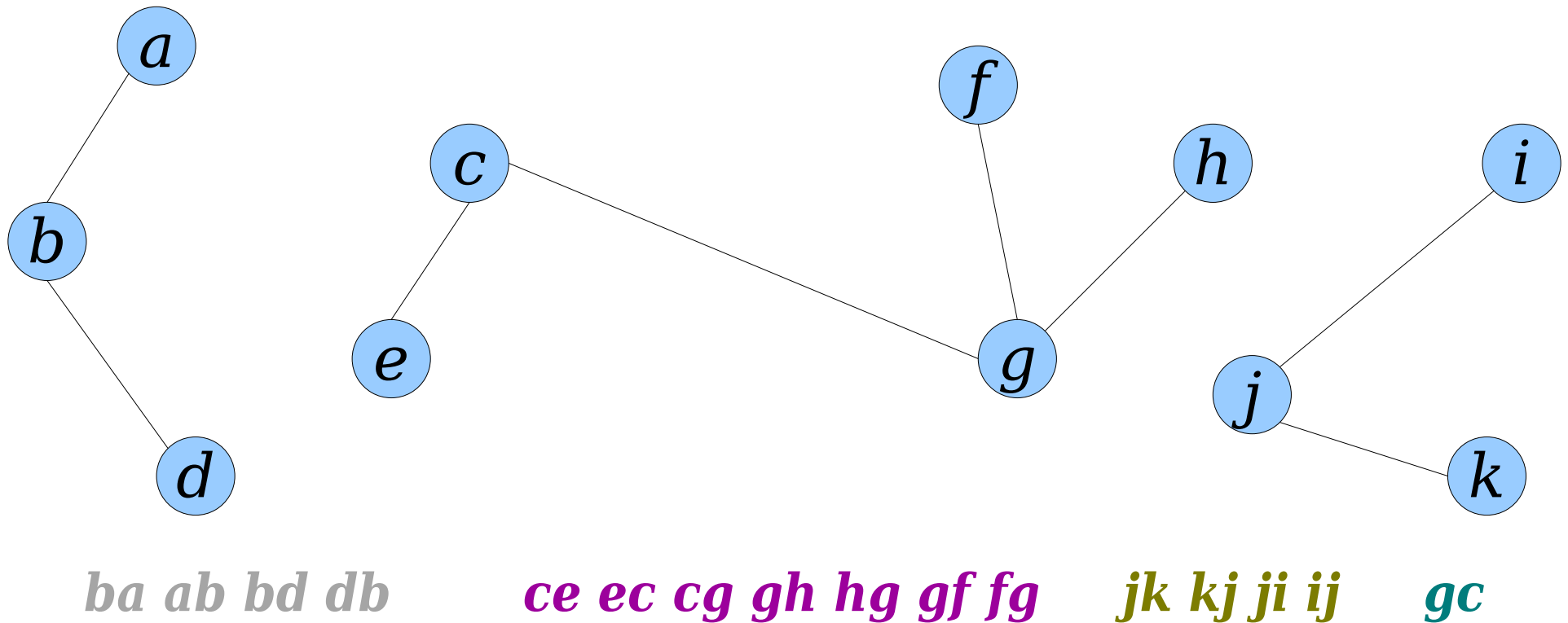
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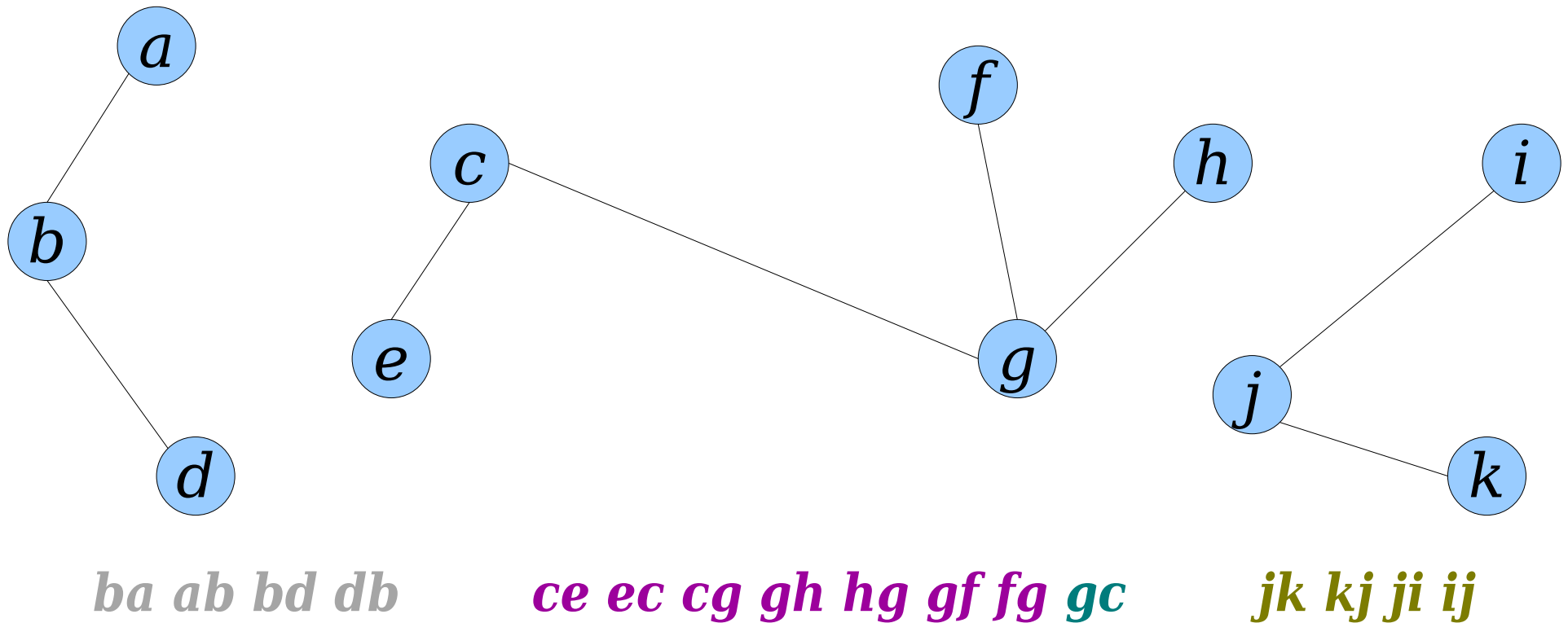
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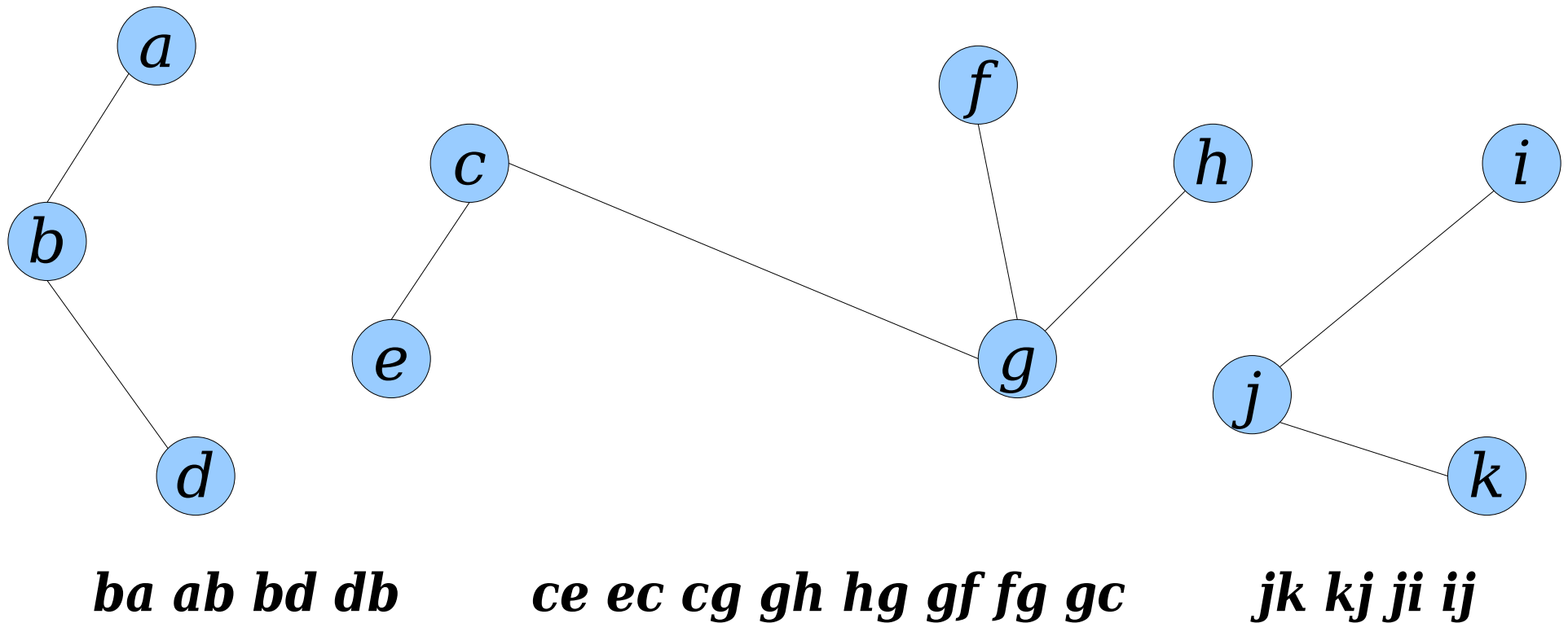
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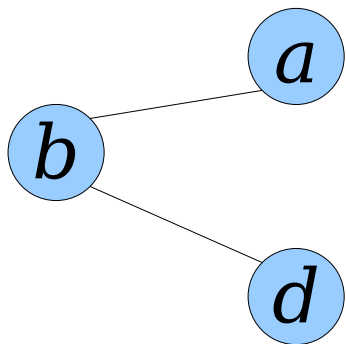


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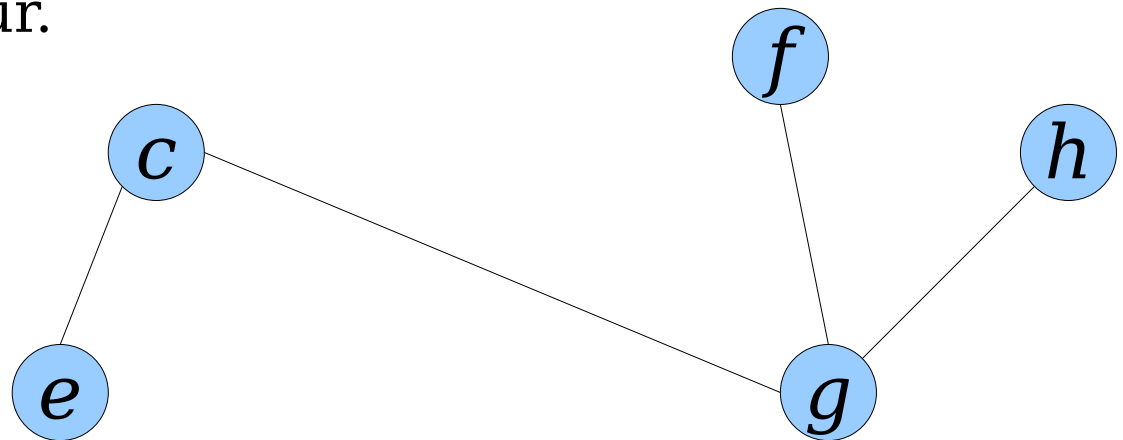
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- To perform **cut**(u, v):
 - Let E be the Euler tour containing uv and vu .
 - Remove uv and vu from E to form E_1, E_2 , and E_3 .
 - Then E_1E_3 and E_2 are Euler tours of the two new trees.

Checking Connectivity

- We also need a way to answer queries of the form **are-connected**(u, v).
- This query focuses on *nodes*, but our Euler tours store *edges*.
- **Cute Trick:** Introduce a self-loop on each node that represents the node itself. Add that to each tour as a proxy for the node itself.
- Now, we can answer **are-connected**(x, y) by seeing if xx and yy are part of the same tour.



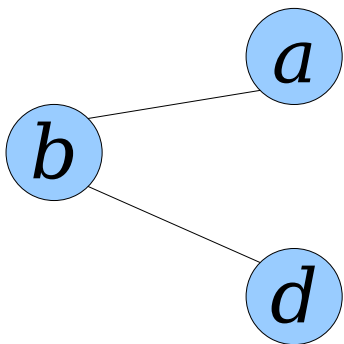
ba ab bd db



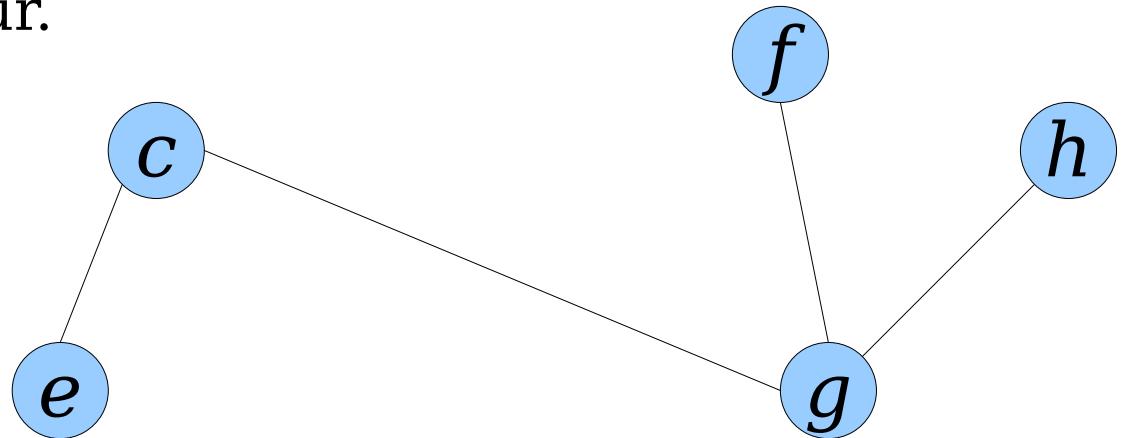
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- **Cute Trick:** Introduce a self-loop on each node that represents the node itself. Add that to each tour as a proxy for the node itself.
- Now, we can answer **are-connected**(x, y) by seeing if xx and yy are part of the same tour.



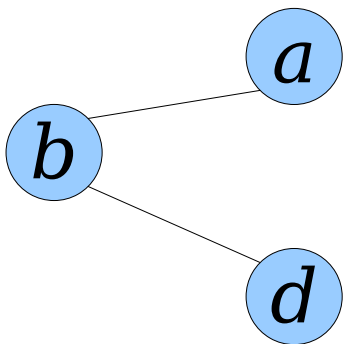
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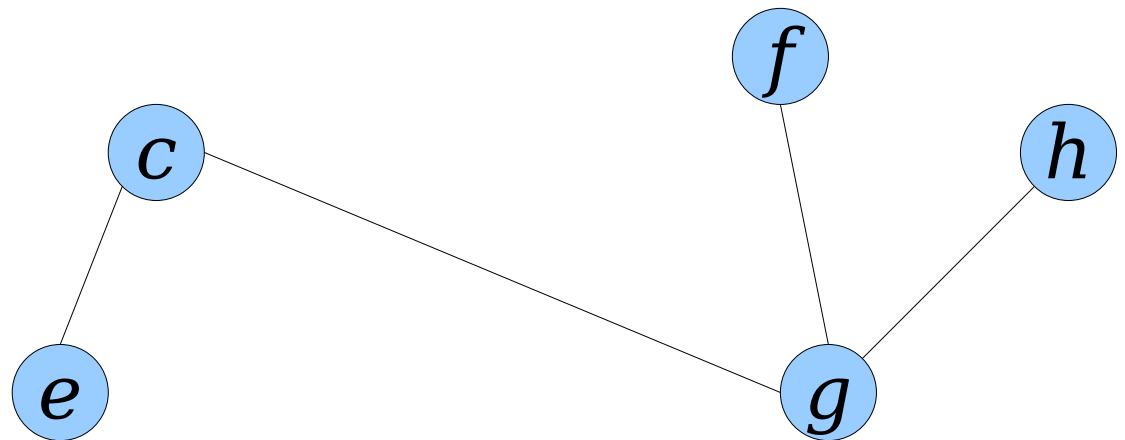
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Checking Connectivity

- This also makes it a lot easier to reroot a tour at a node x .
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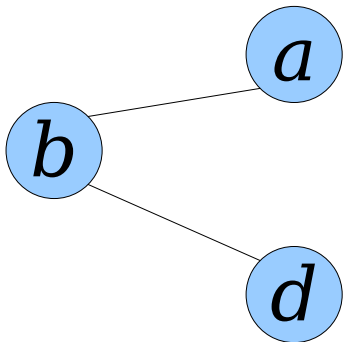
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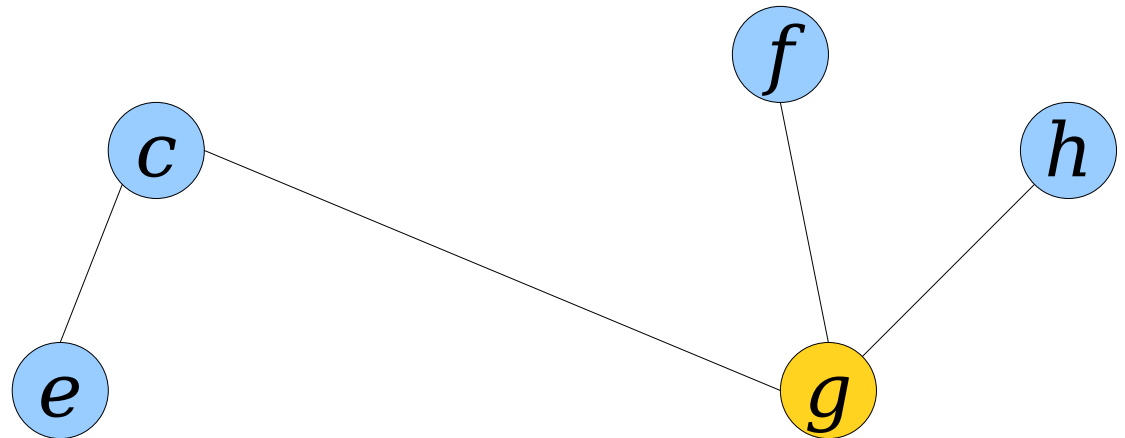
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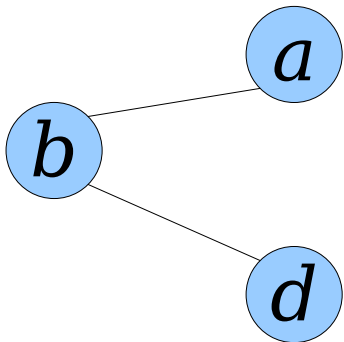
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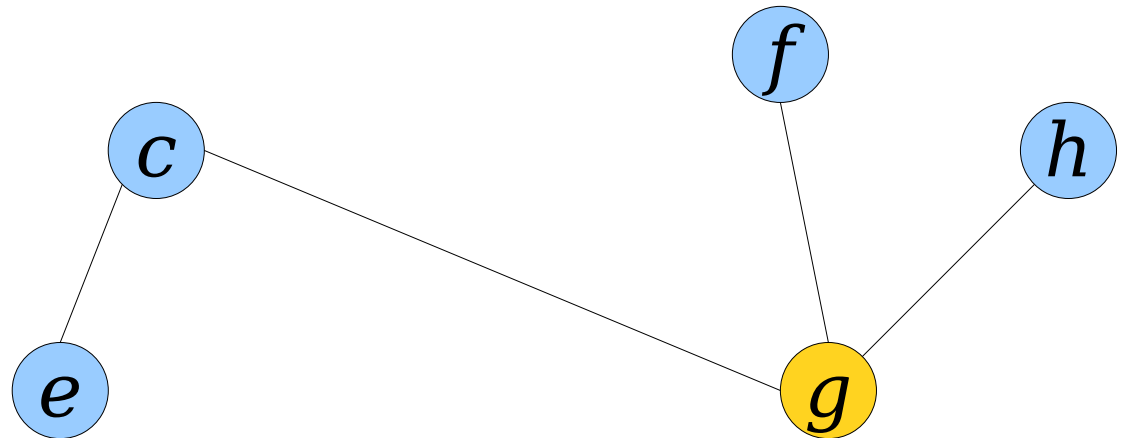
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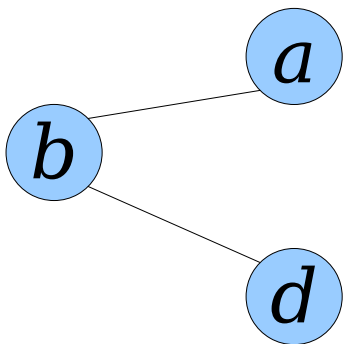
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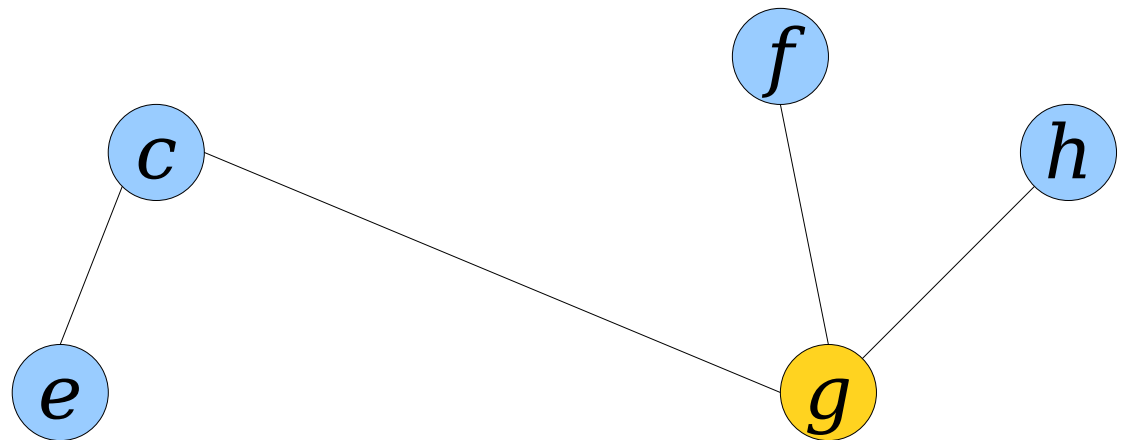
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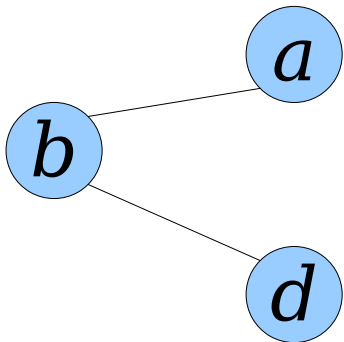
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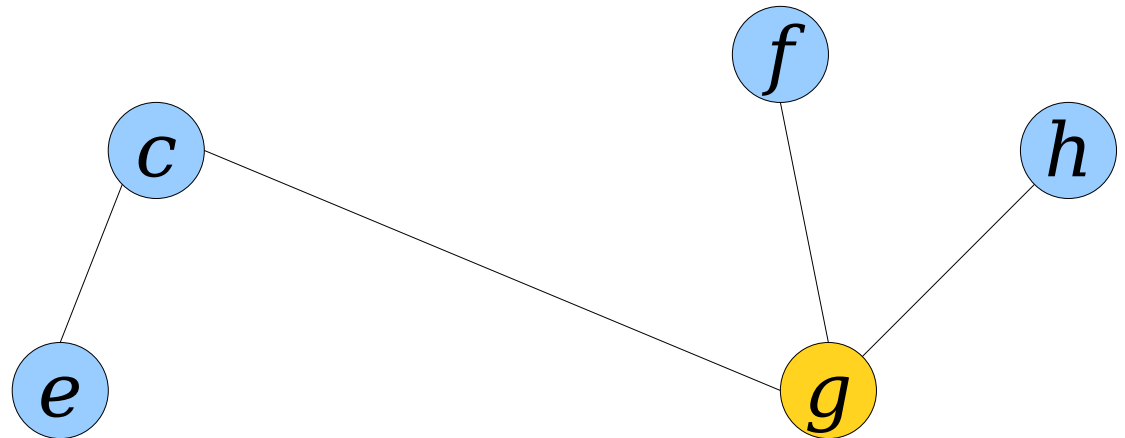
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aa

b

bb

c

cc

d

dd

e

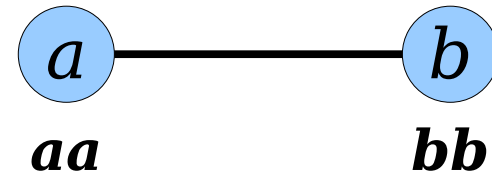
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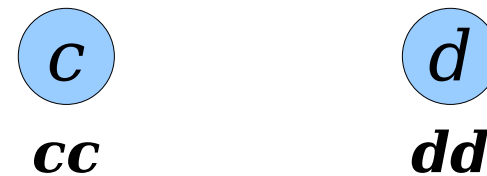
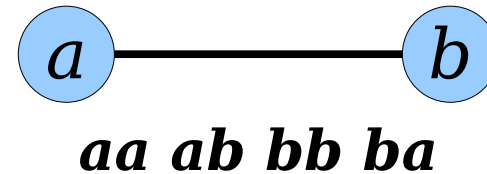
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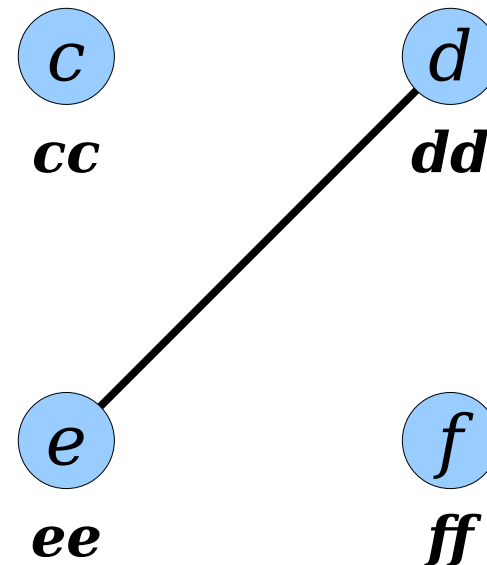
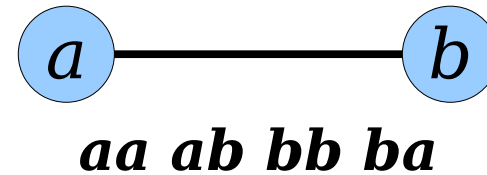
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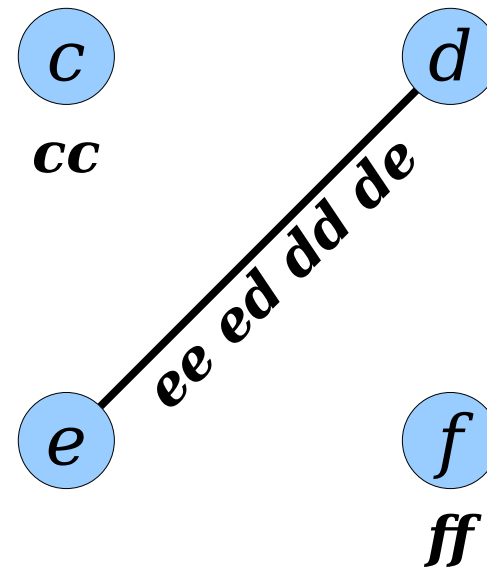
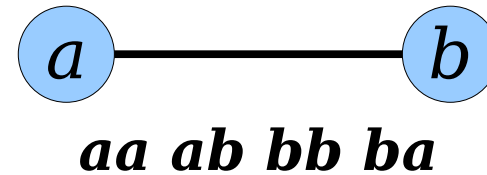
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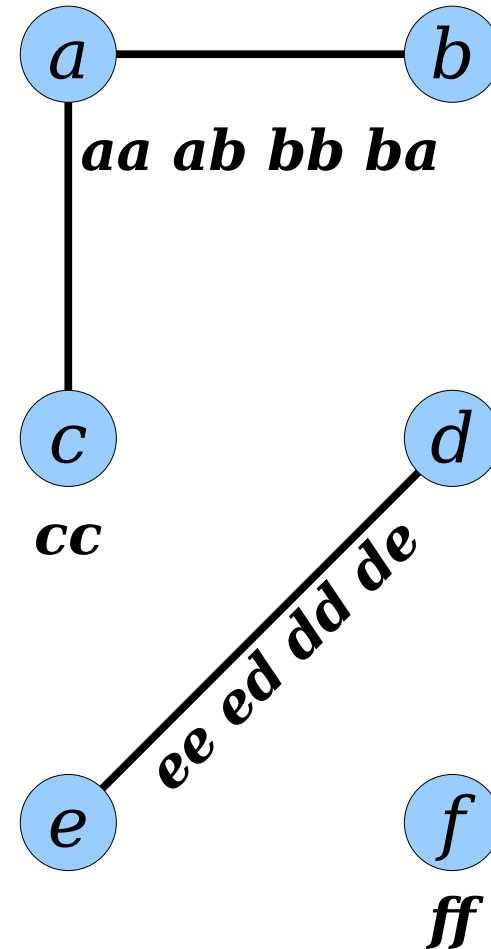
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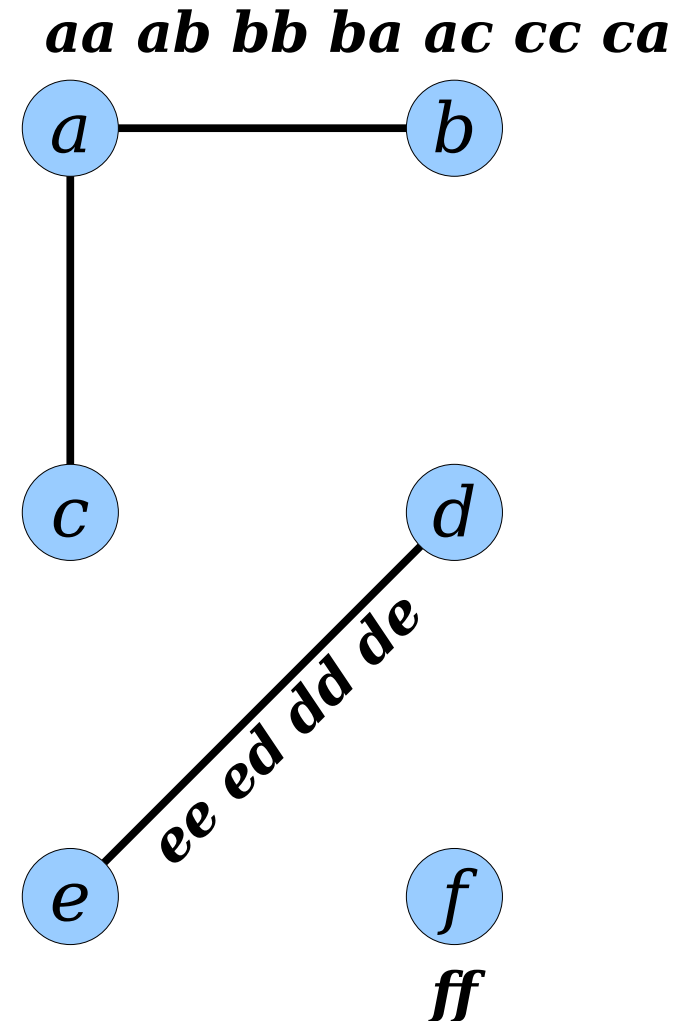
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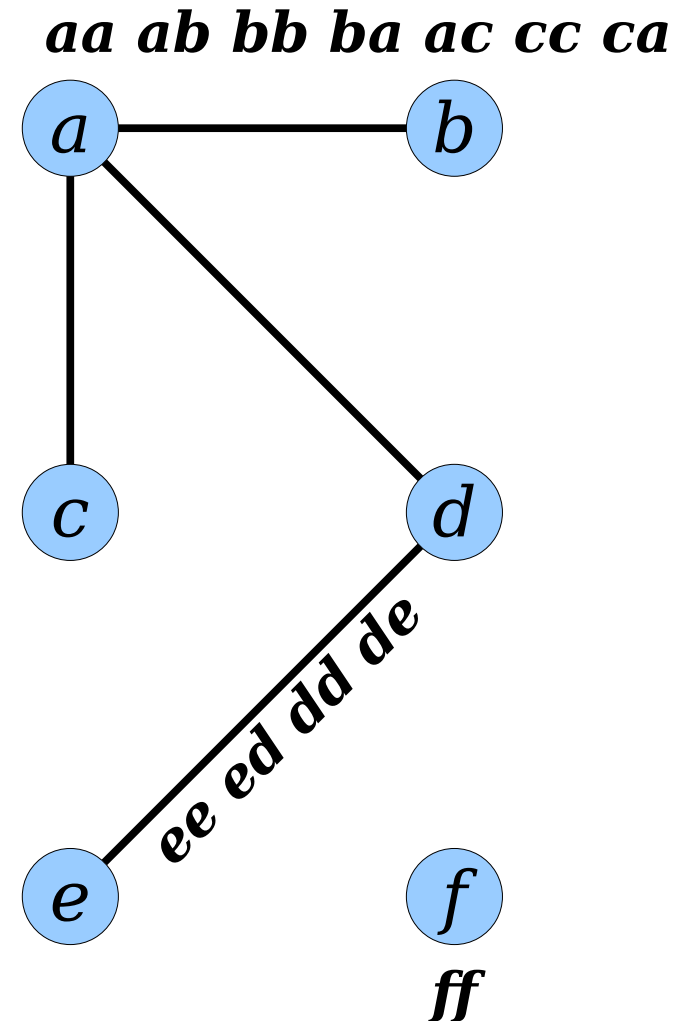
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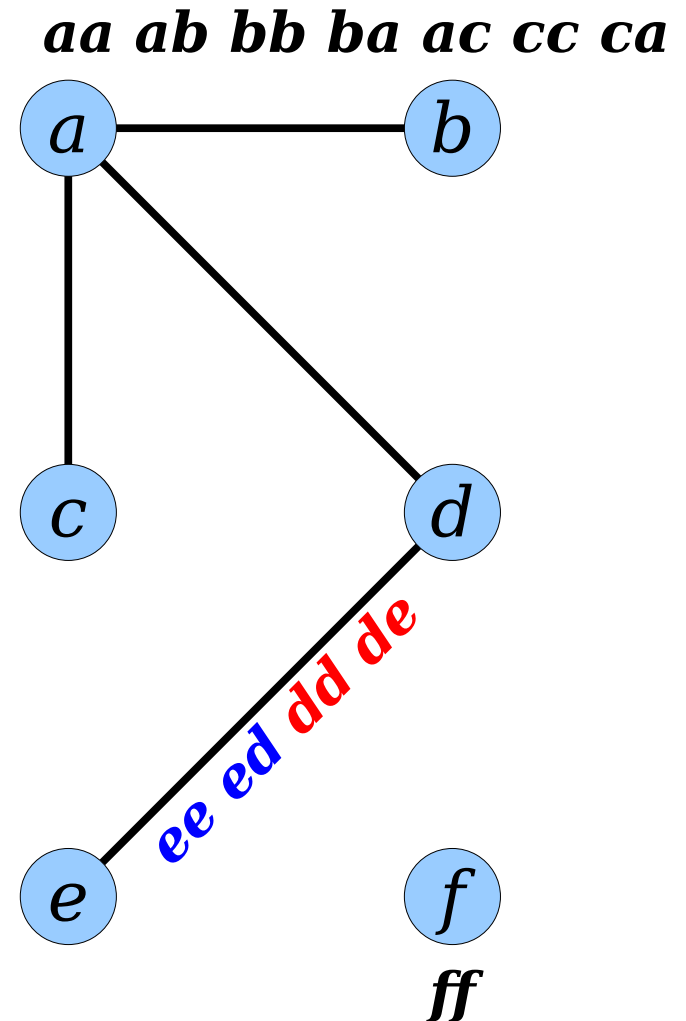
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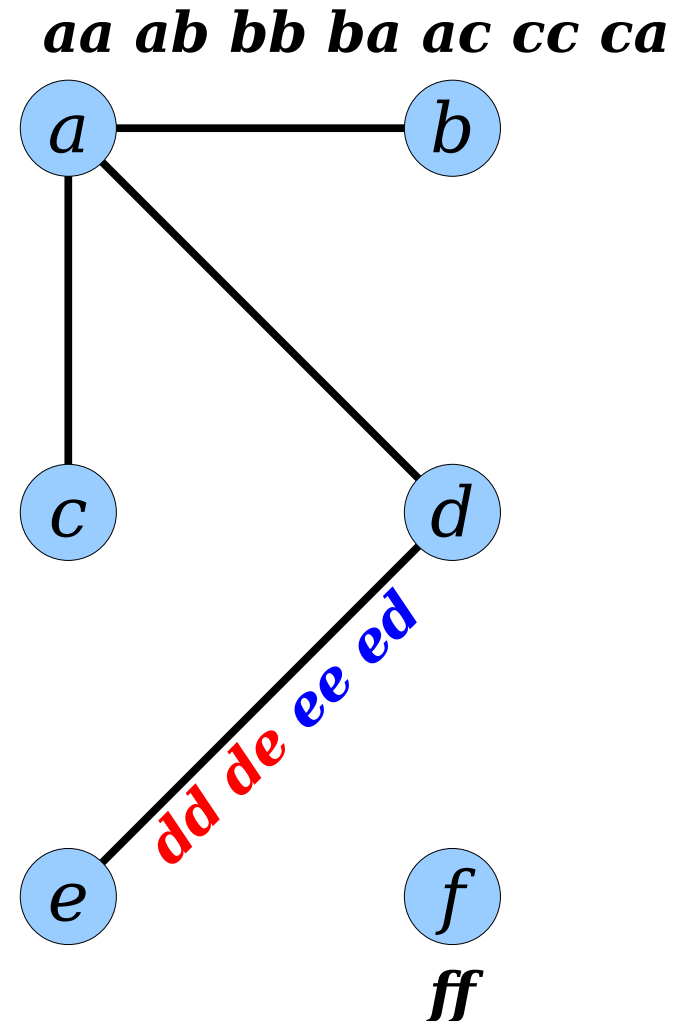
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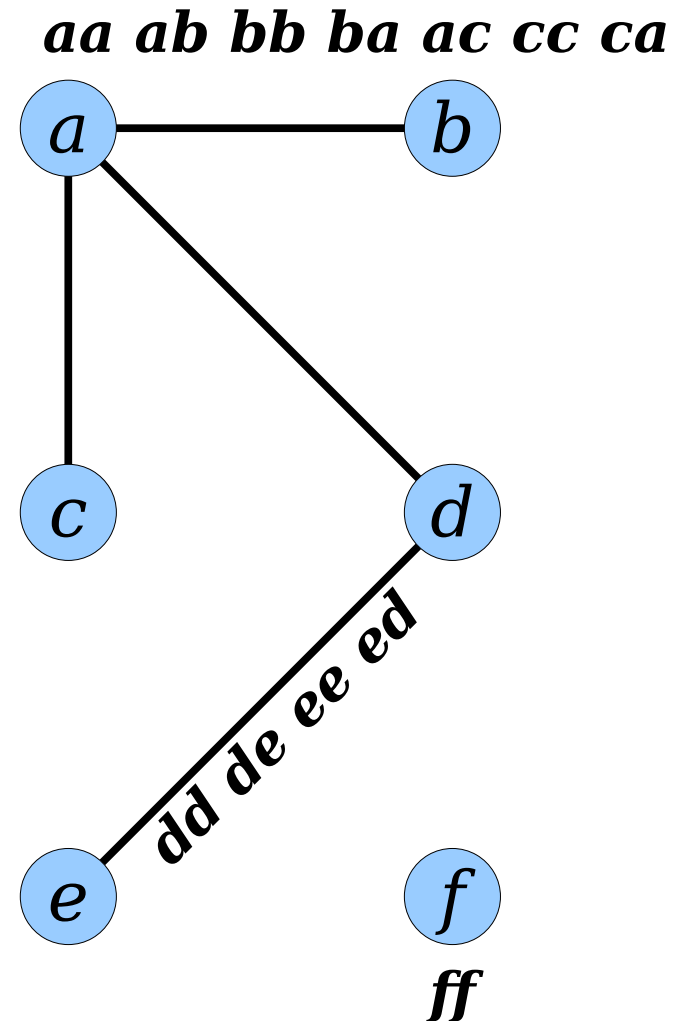
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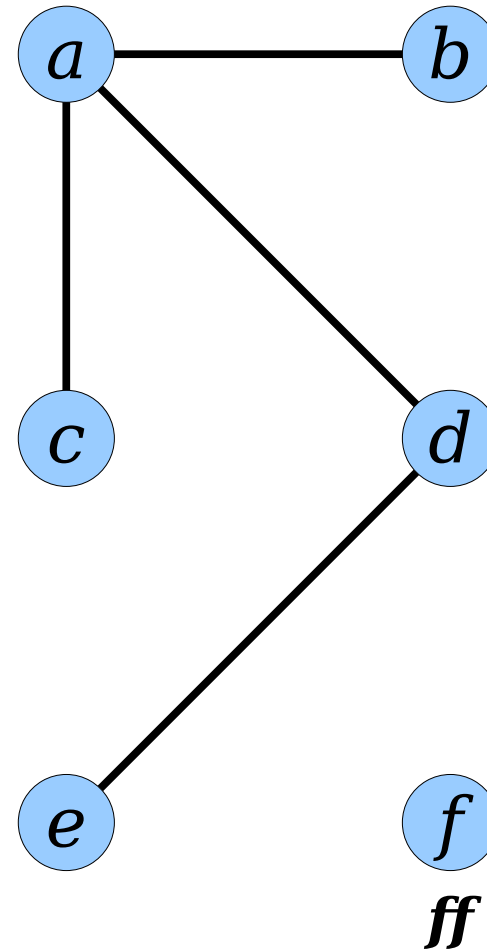
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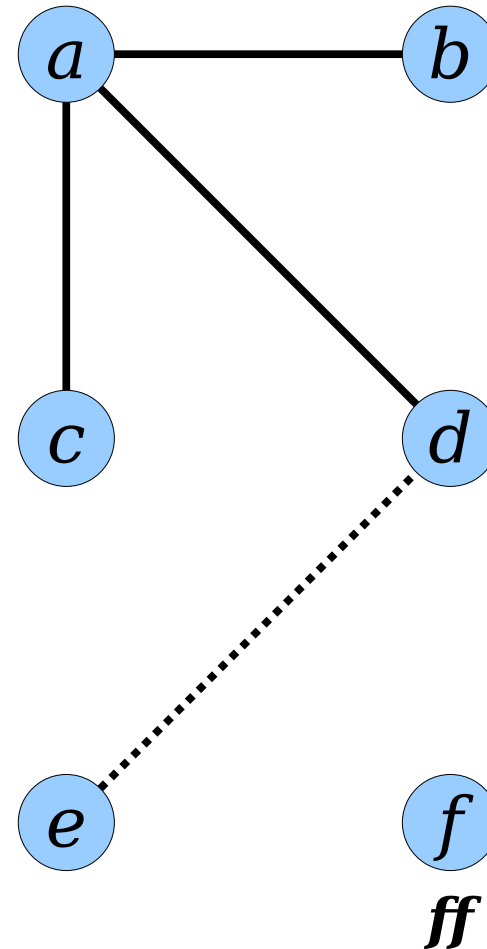
aa ab bb ba ac cc ca ad dd de ee ed da



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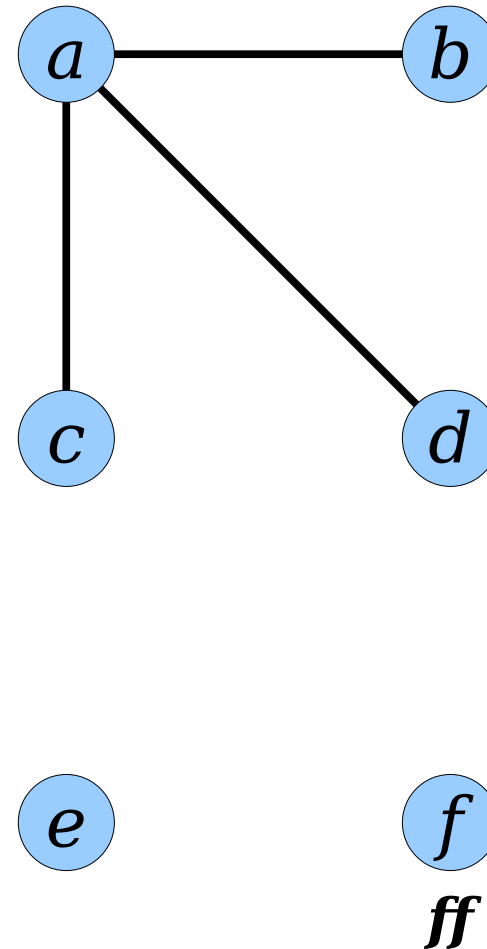
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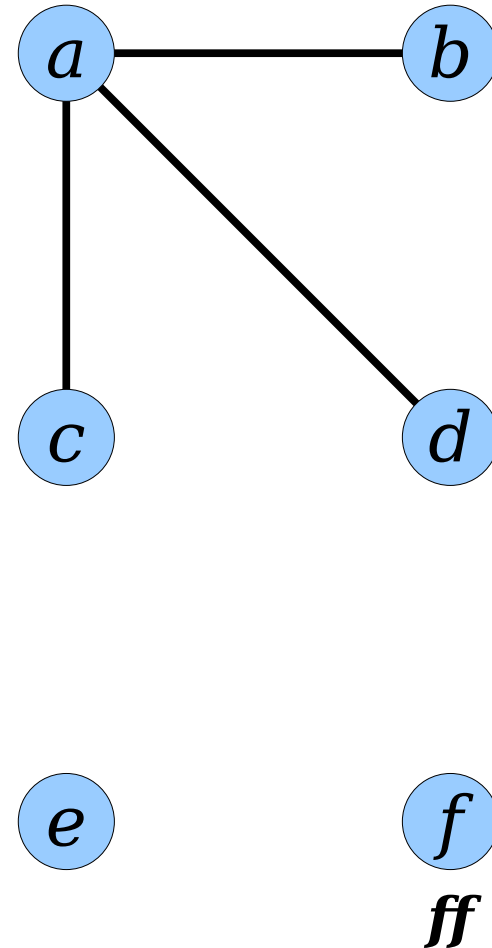
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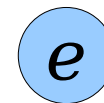
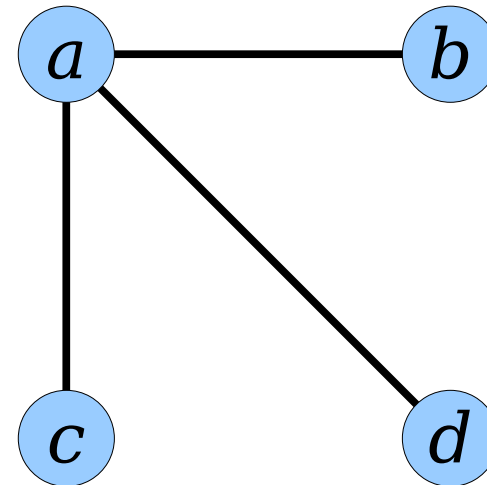
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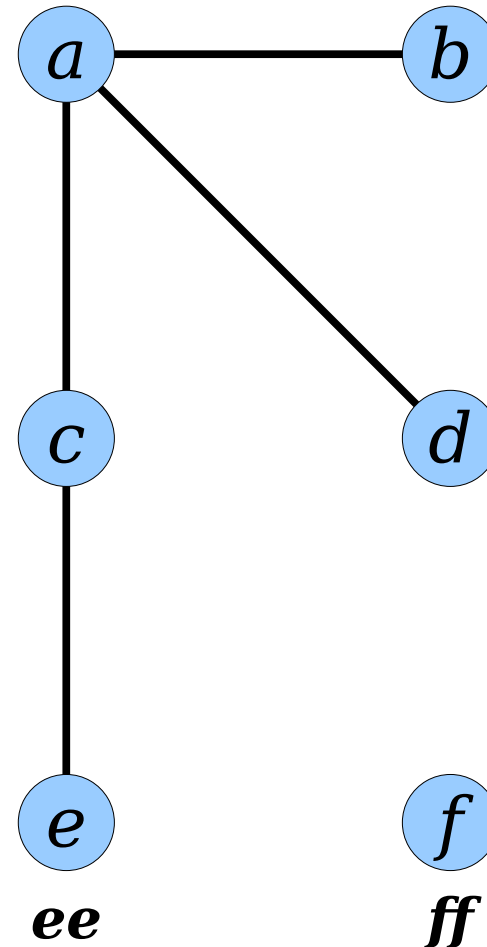


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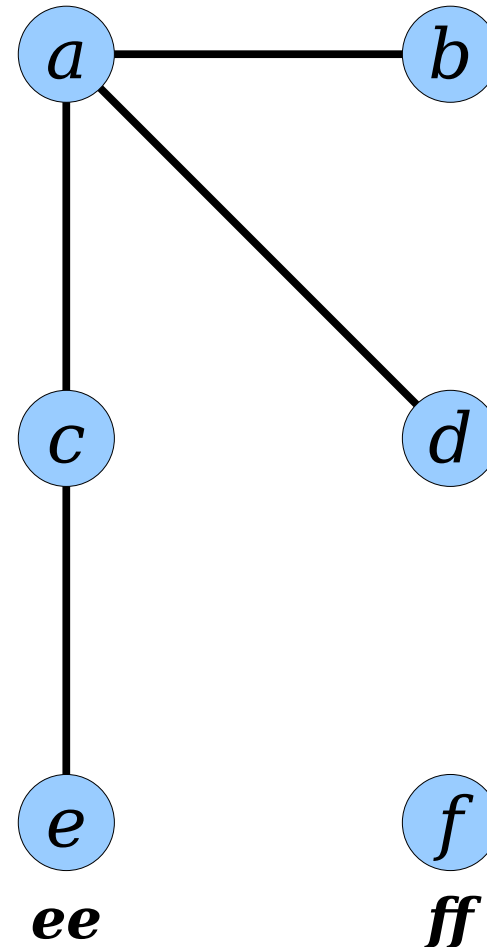
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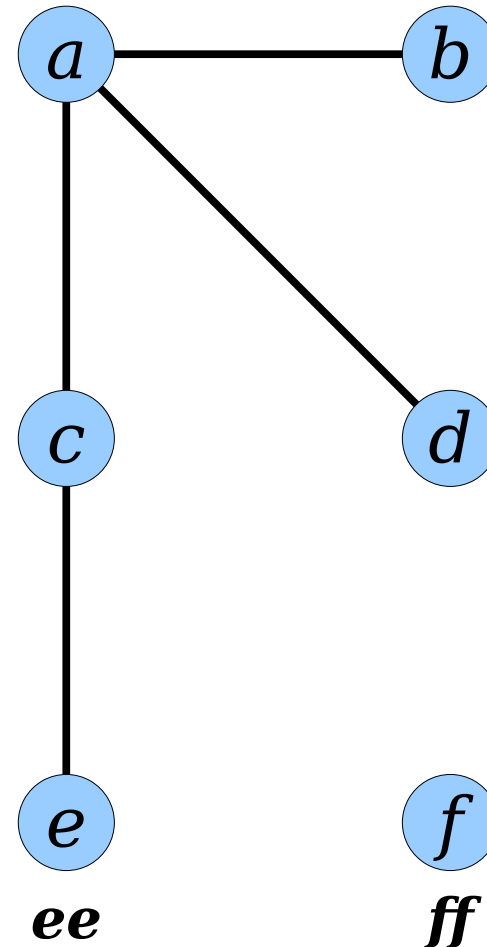
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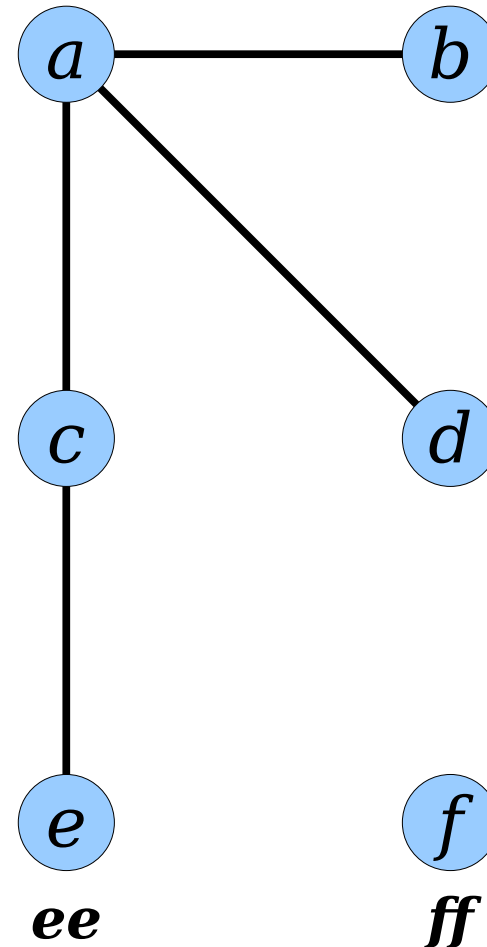
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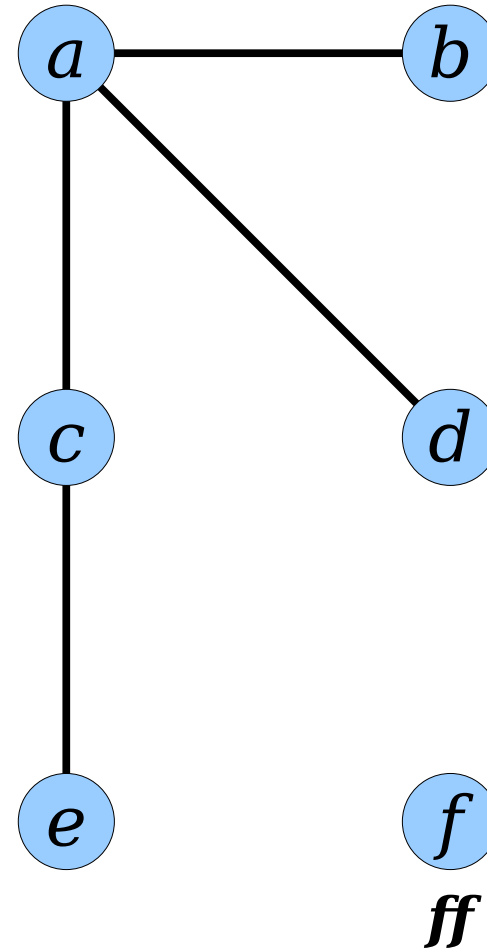
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cc ca ad dd da aa ab bb ba ac ce ee ec



Implementing This Approach

The Story So Far

- We've seen how to implement *reroot*, *link*, *cut*, and *are-connected* in terms of operations on Euler tours.
- The efficiency of those operations depend on how we choose to encode our sequences.
- **Question:** What data structure should we use to store those sequences?

Representation Issues

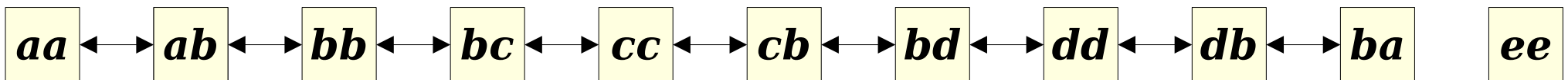
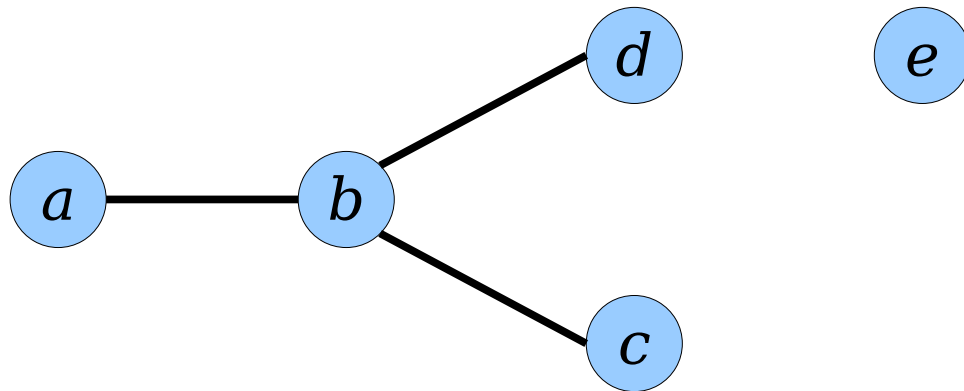
- We need a representation that lets us perform the following operations:
 - Locate specific edges (*reroot*, *link*, *cut*, *are-connected*).
 - Split a sequence at a point (*reroot*, *cut*).
 - Join two sequences together (*reroot*, *link*).
 - Remove an edge from a sequence (*cut*).
 - Append an edge to a sequence (*link*).
 - Check if two edges are in the same sequence (*are-connected*).
- What data structures might be appropriate here?

Answer at

<https://pollev.com/cs166spr23>

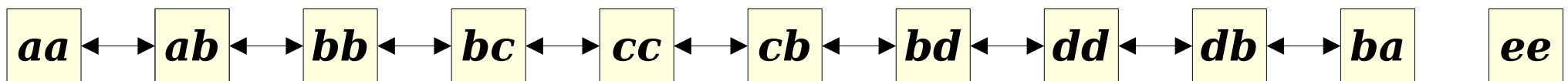
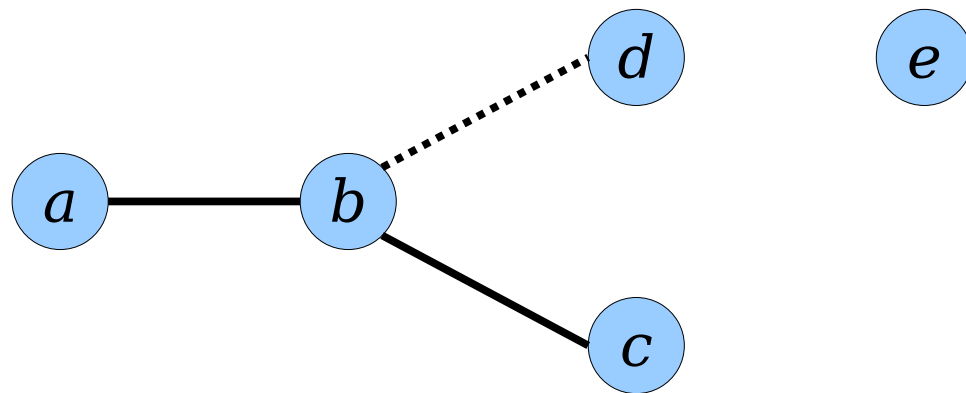
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 - Assuming we have a hash table telling us where edges are, we can split, join, and rotate tours in time $O(1)$.



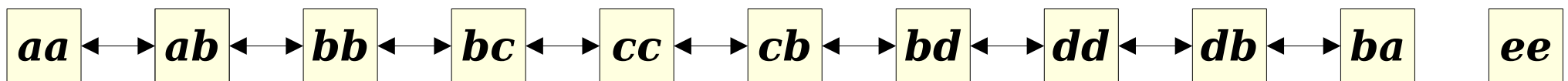
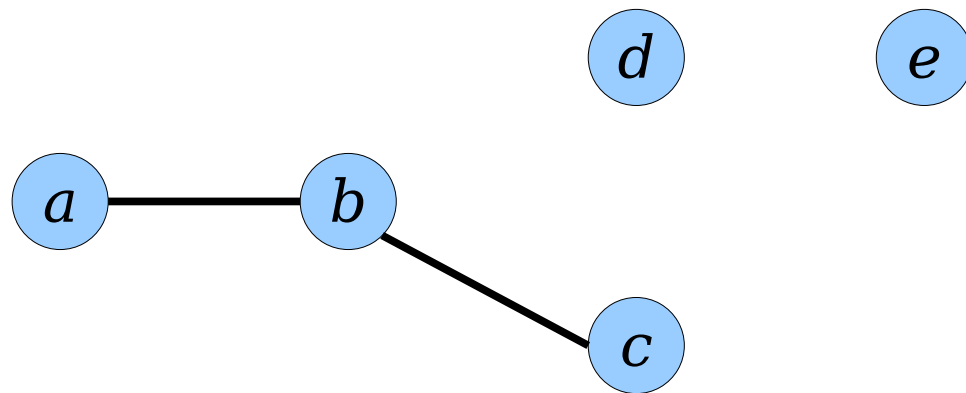
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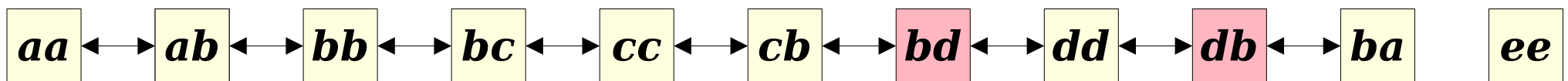
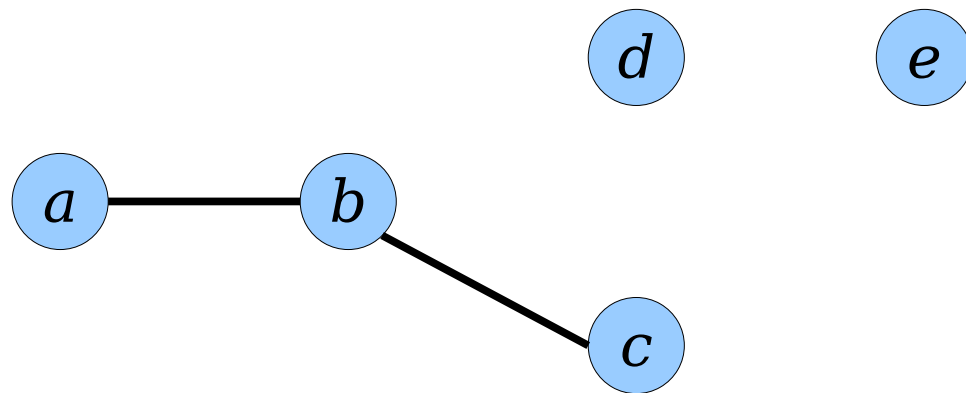
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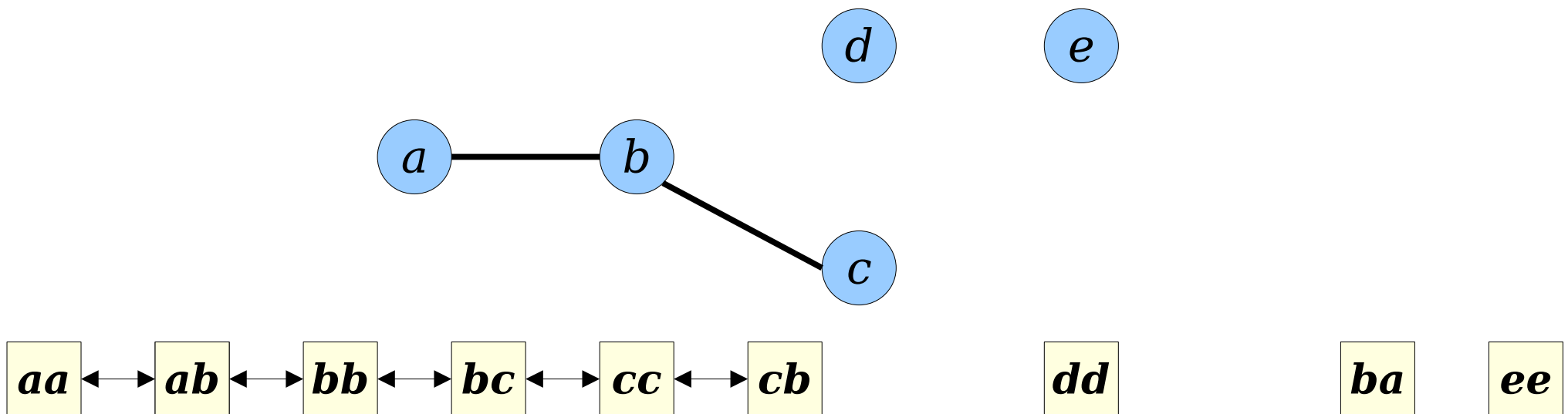
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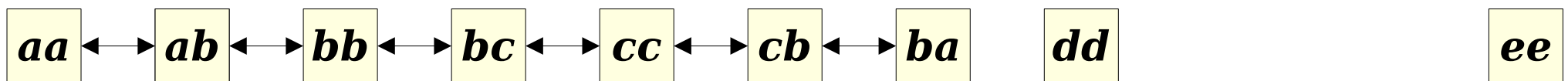
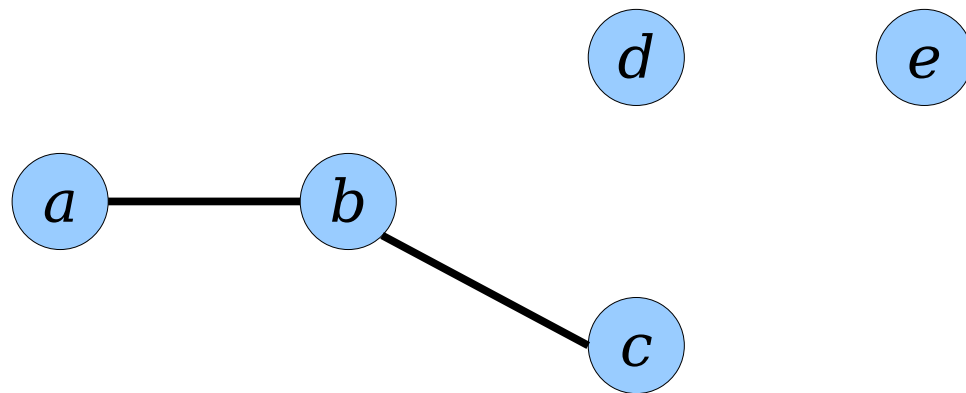
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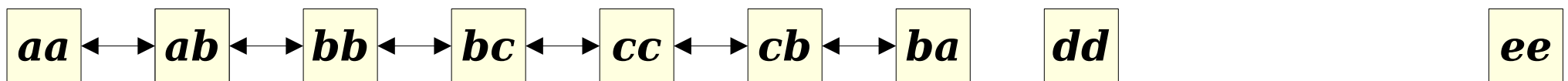
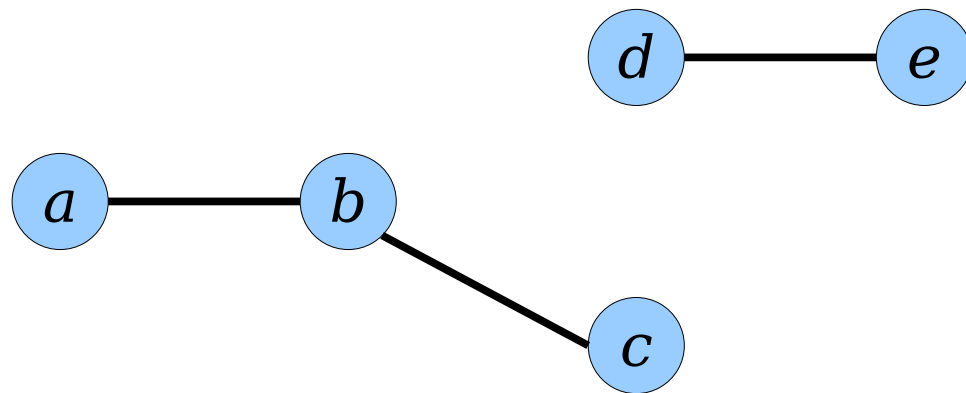
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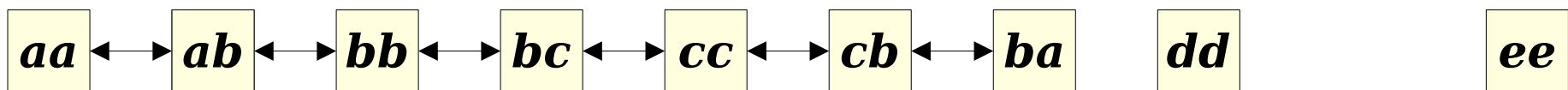
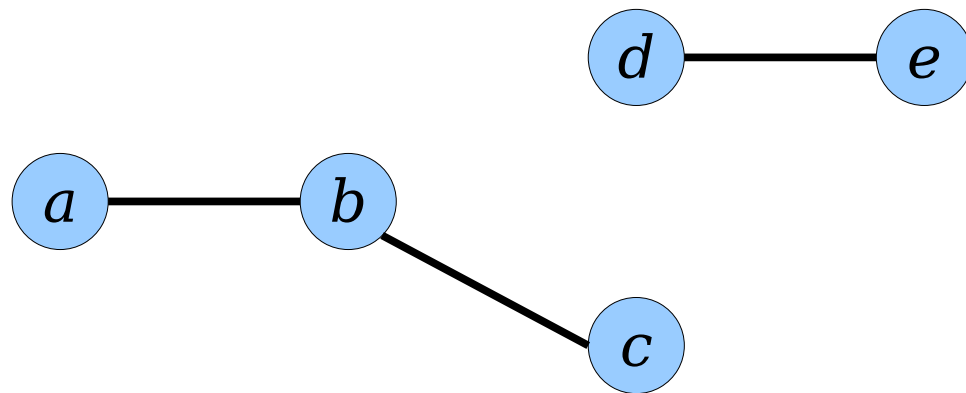
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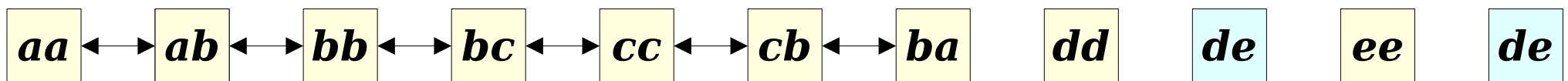
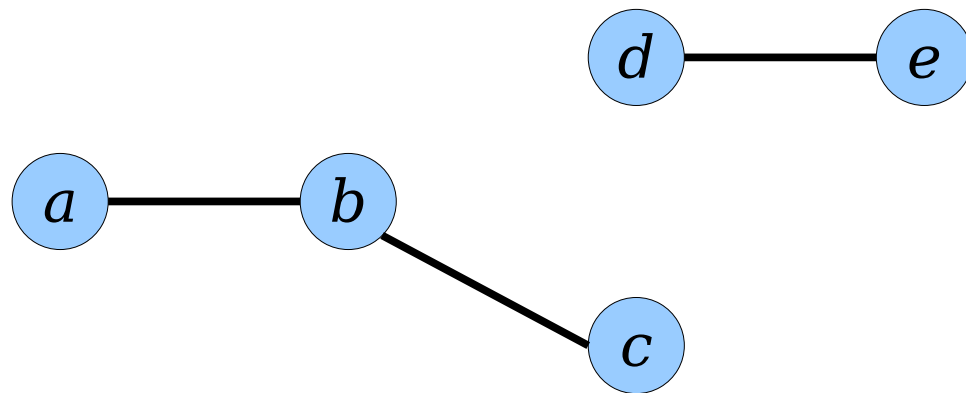
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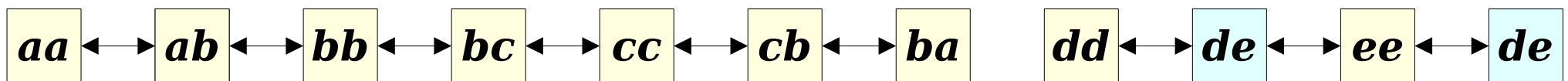
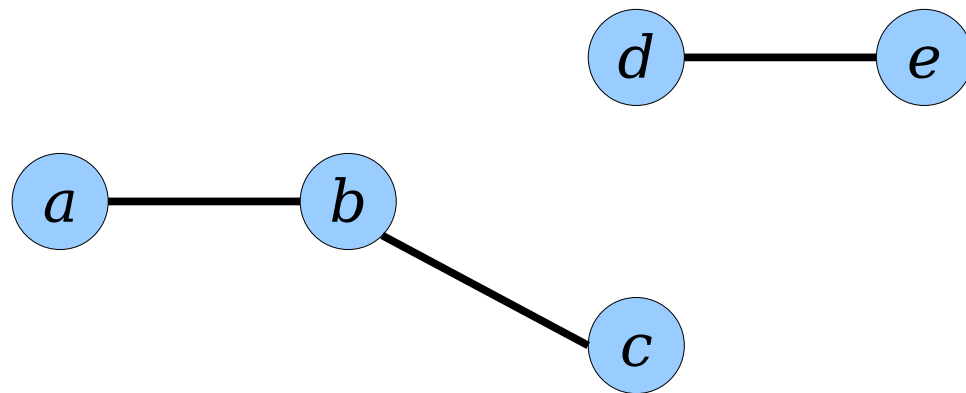
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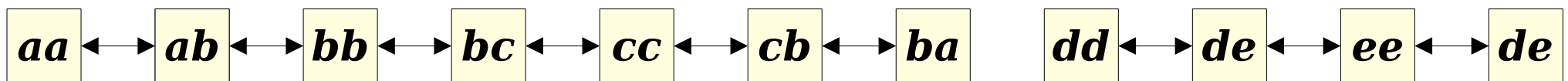
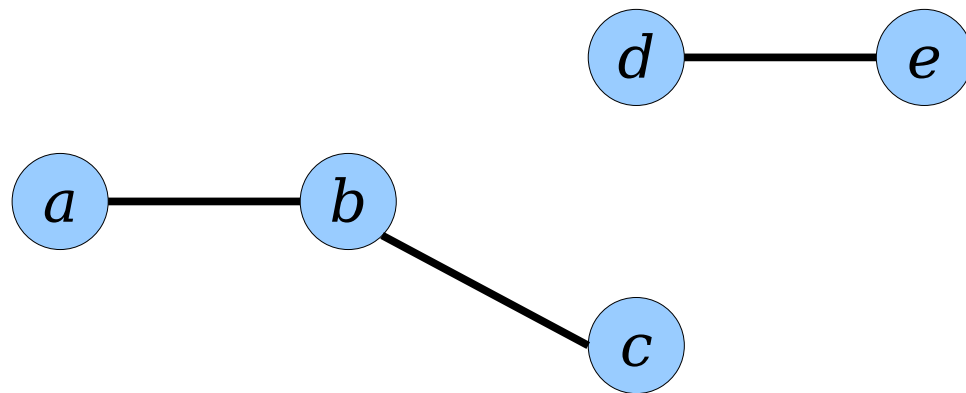
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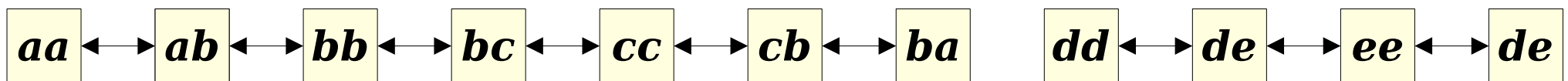
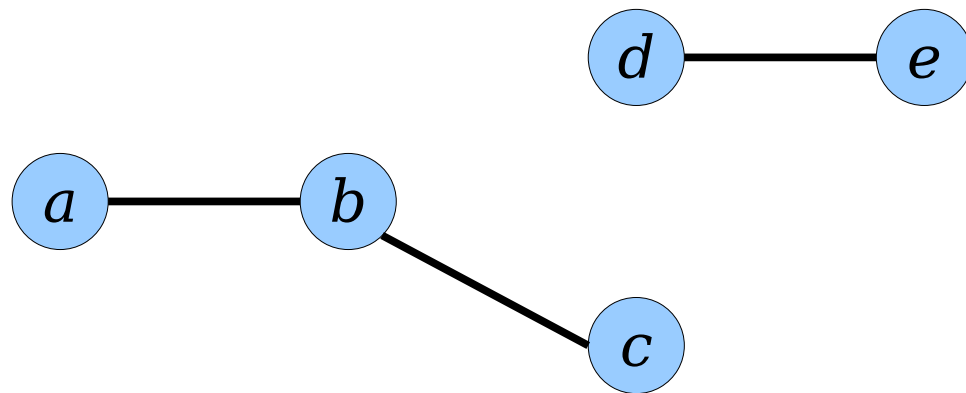
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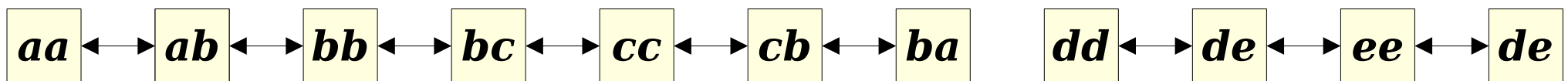
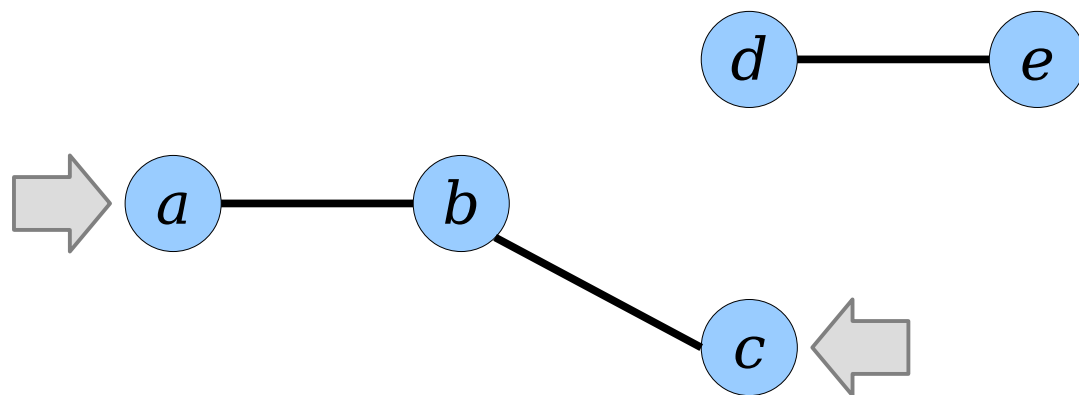
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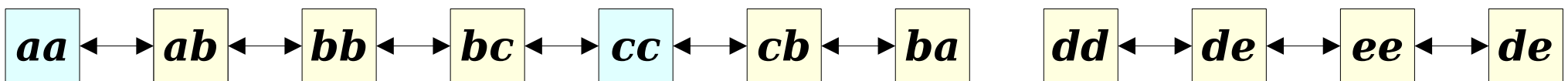
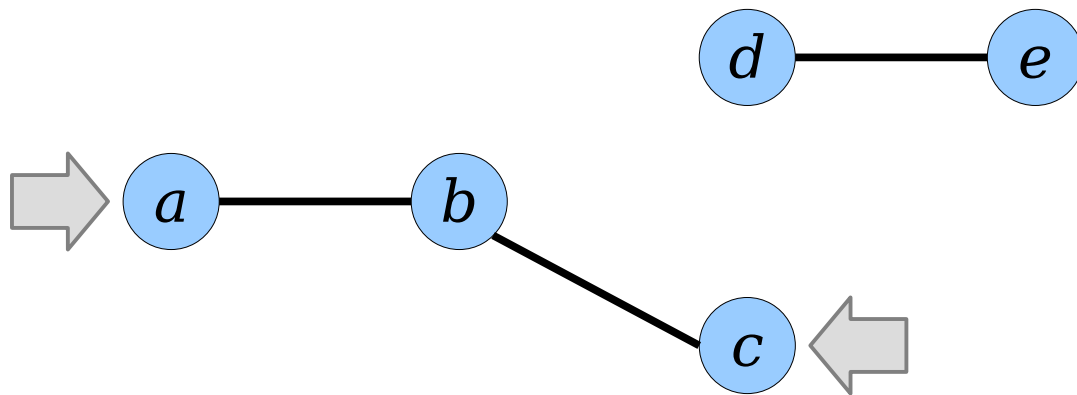
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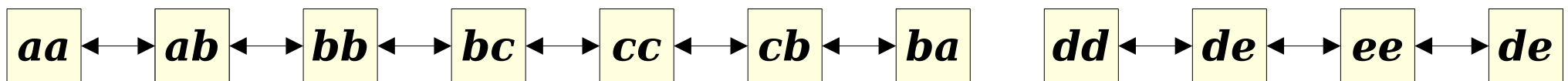
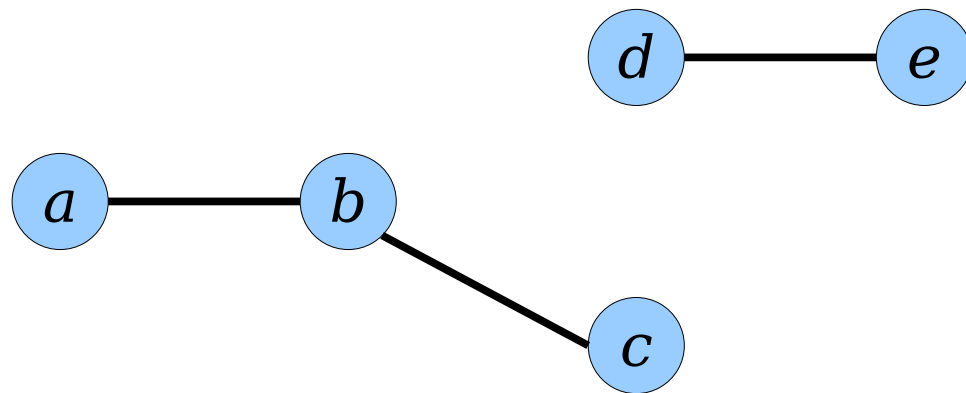
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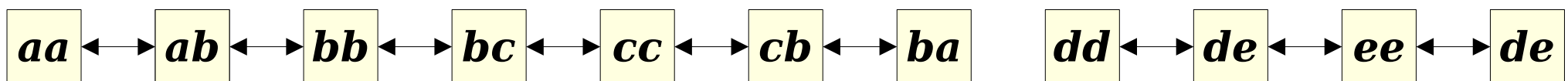
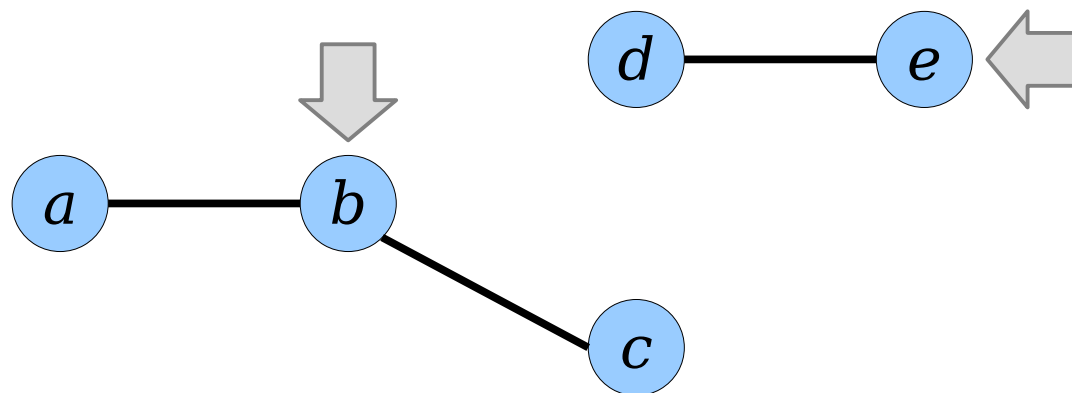
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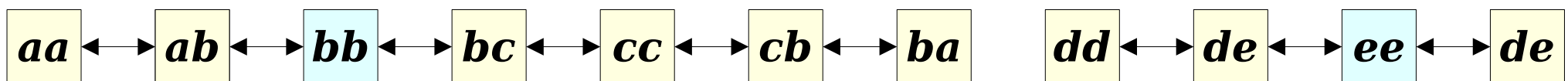
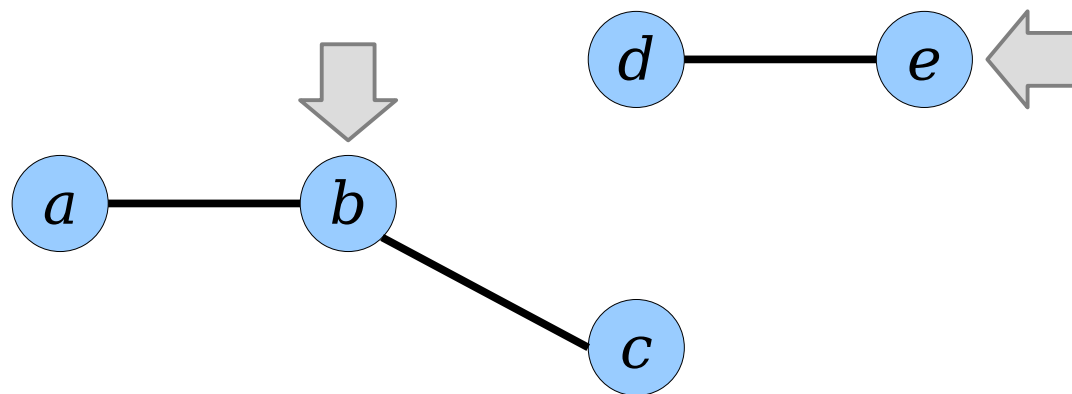
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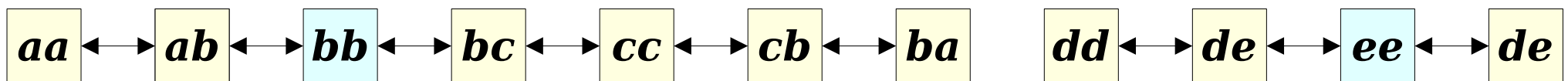
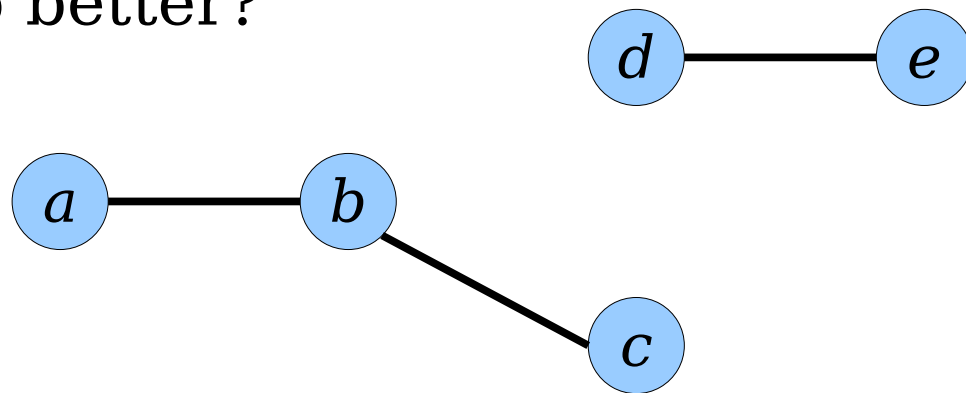
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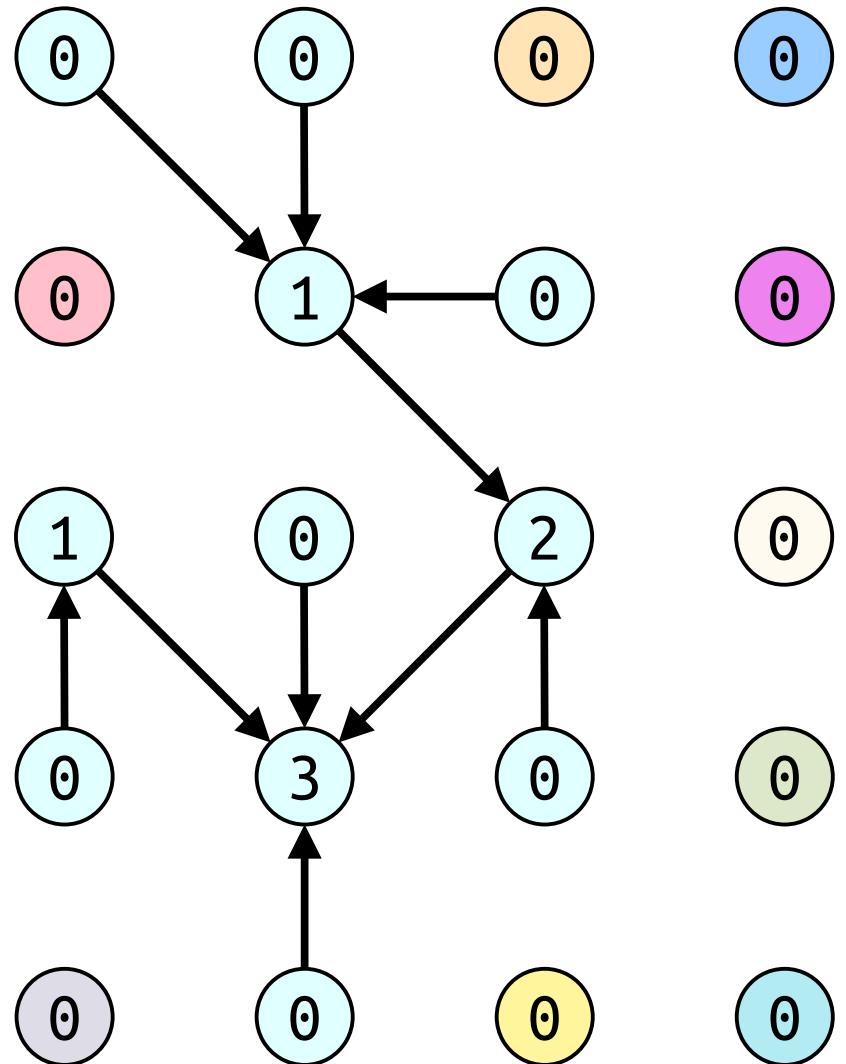
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- Can we do better?



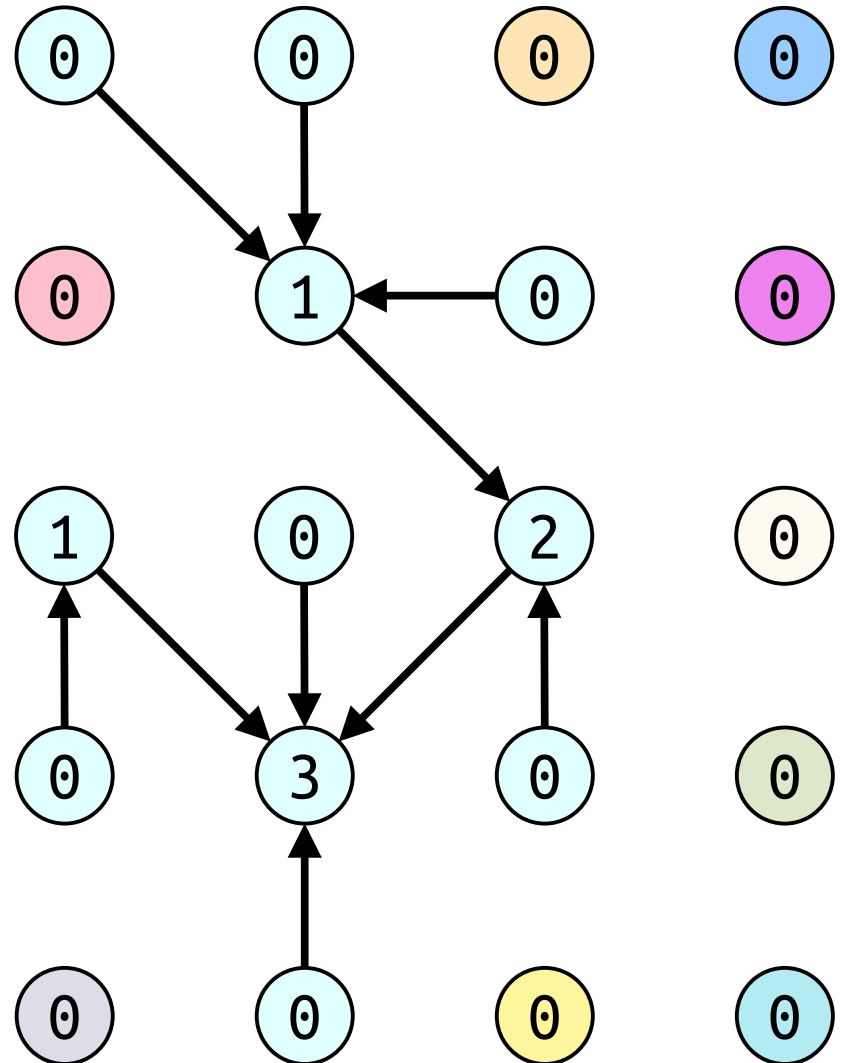
Representation Issues

- In incremental connectivity, we selected a representative for each CC.
- We then had elements store parent pointers that formed a path to the representative.
- Could we do something like that here?



Representation Issues

- The idea of using trees to store representatives is a good one.
 - If the trees are wide and flat, it won't take too long to find the representative.
 - If we don't have to update "too many" pointers when CC's change, our operations can run quickly.
- The trees we used last time won't (immediately) work here.
 - We have to store the elements of the tour in sequential order. There was no such notion of order in disjoint set forests.
 - In disjoint-set forests, linked items can never be cut, allowing for some clever optimizations.
- What's another tree we can use?



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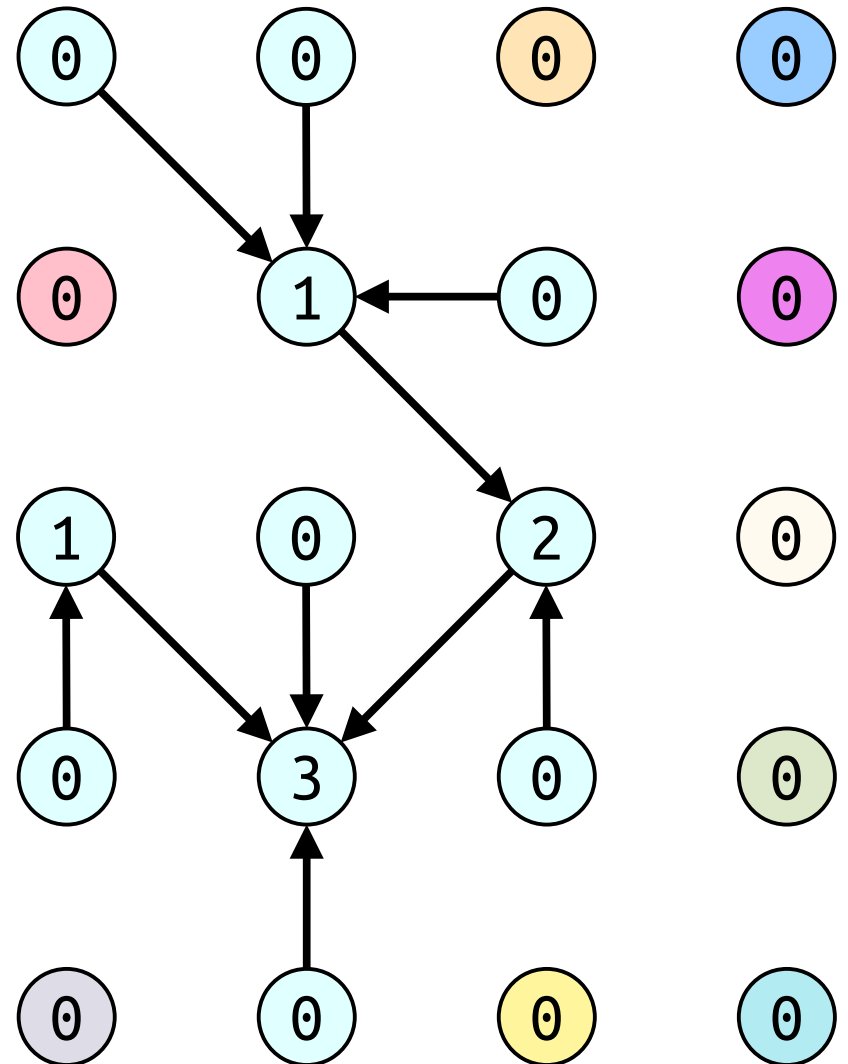
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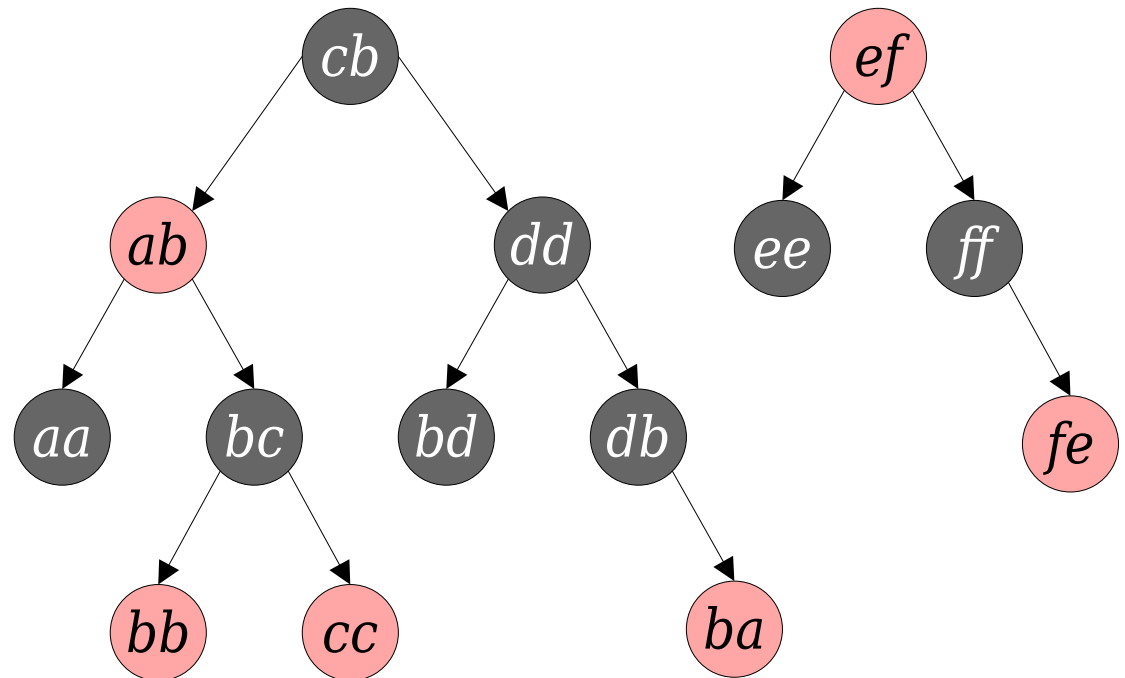
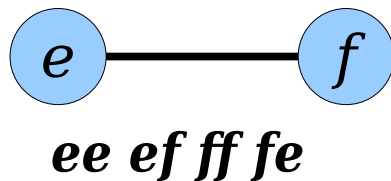
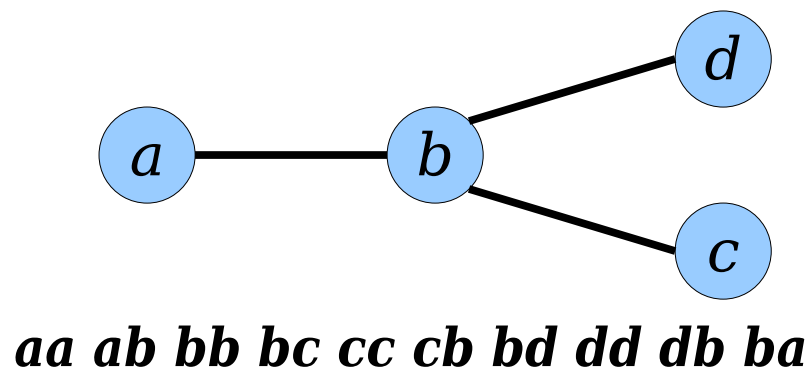
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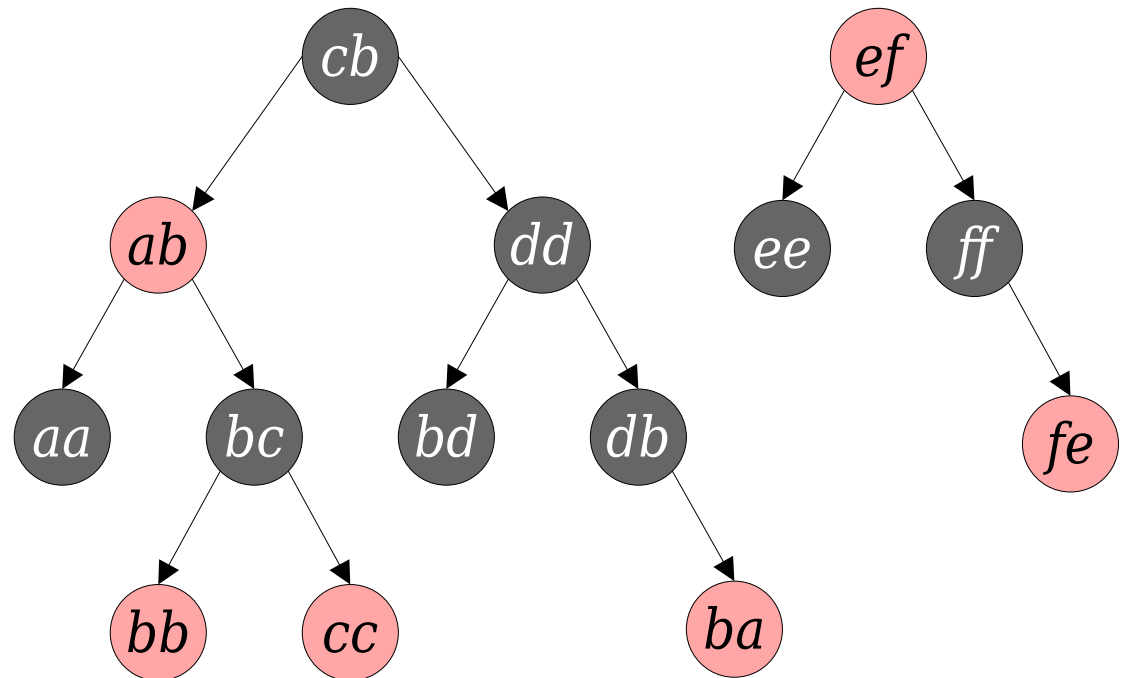
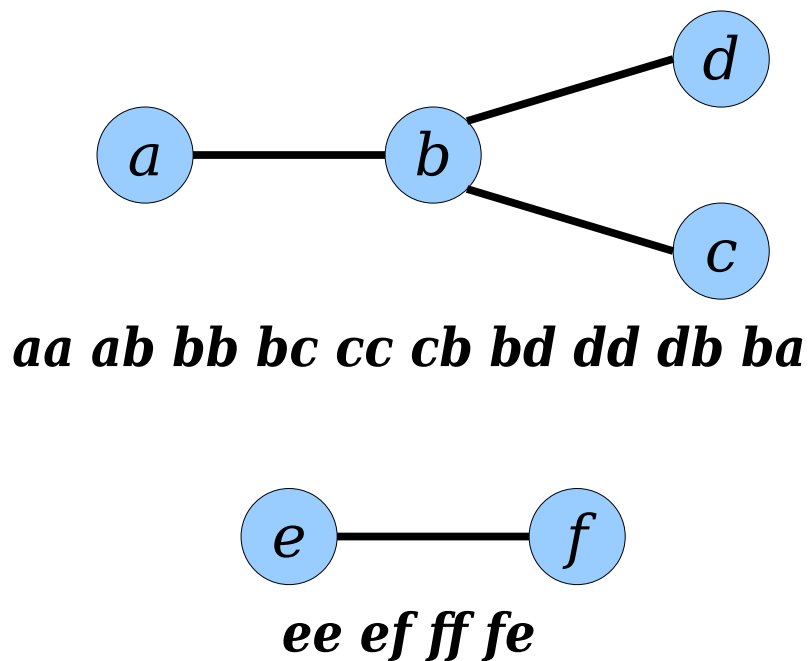
Binary Search(less) Trees

- **Idea 2:** Store our sequences in a balanced BST, sorted by their position within the sequence.
- We'll use the *shape* and *algorithm* of a BST, but won't have the ability to conventionally search the tree top-down.
- We'll rely on the fact that we have external pointers that let us jump to items within the BST.



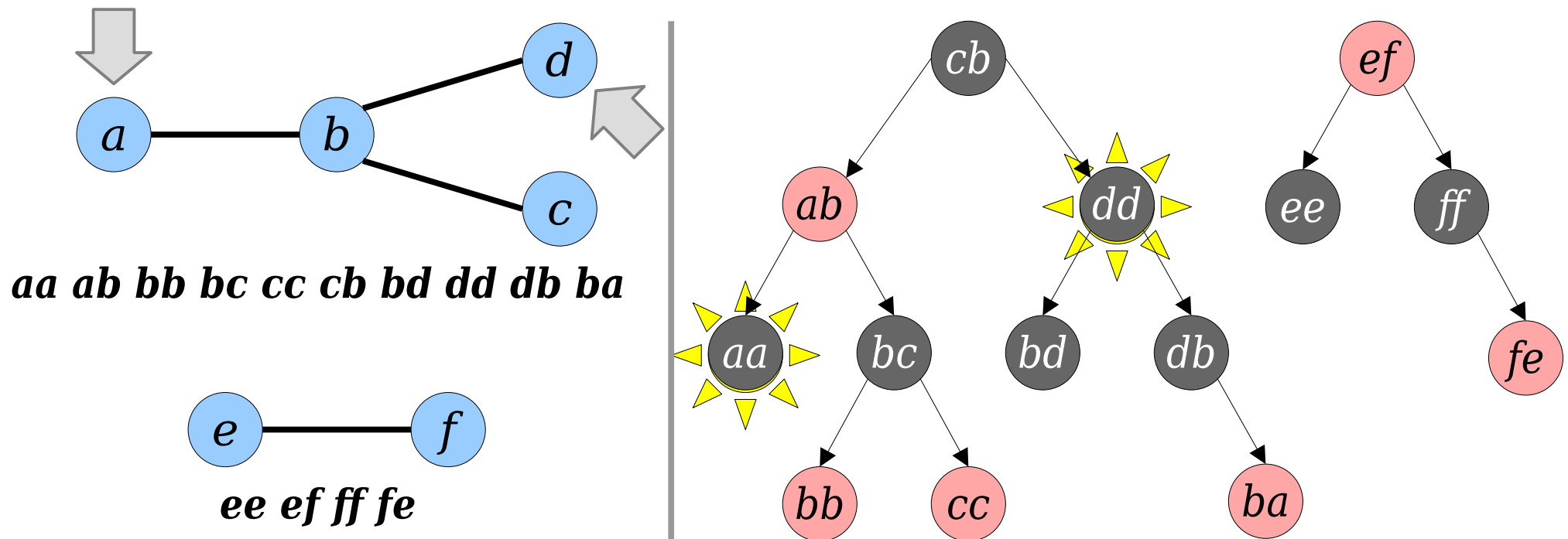
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- We can now answer *are-connected*(x, y) in time $O(\log n)$.
 - Find xx and yy using our auxiliary lookup table.
 - Walk up from xx and yy to the roots of their trees.
 - See if they're the same root.



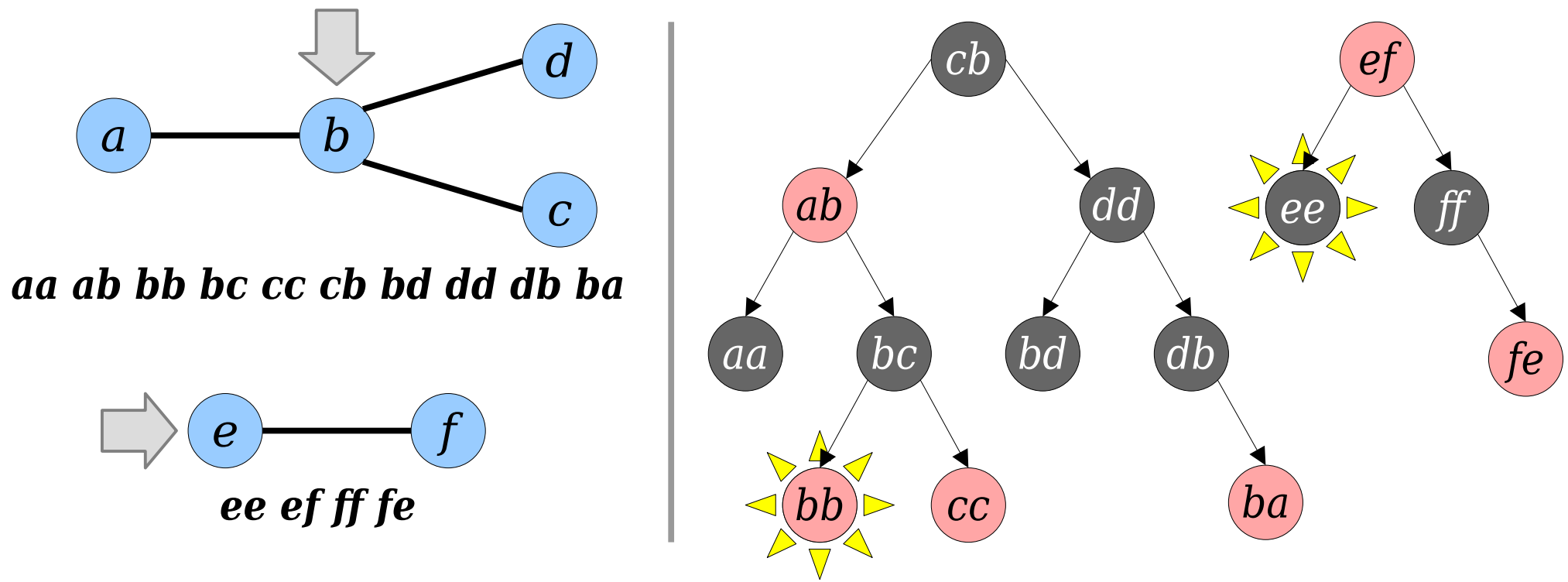
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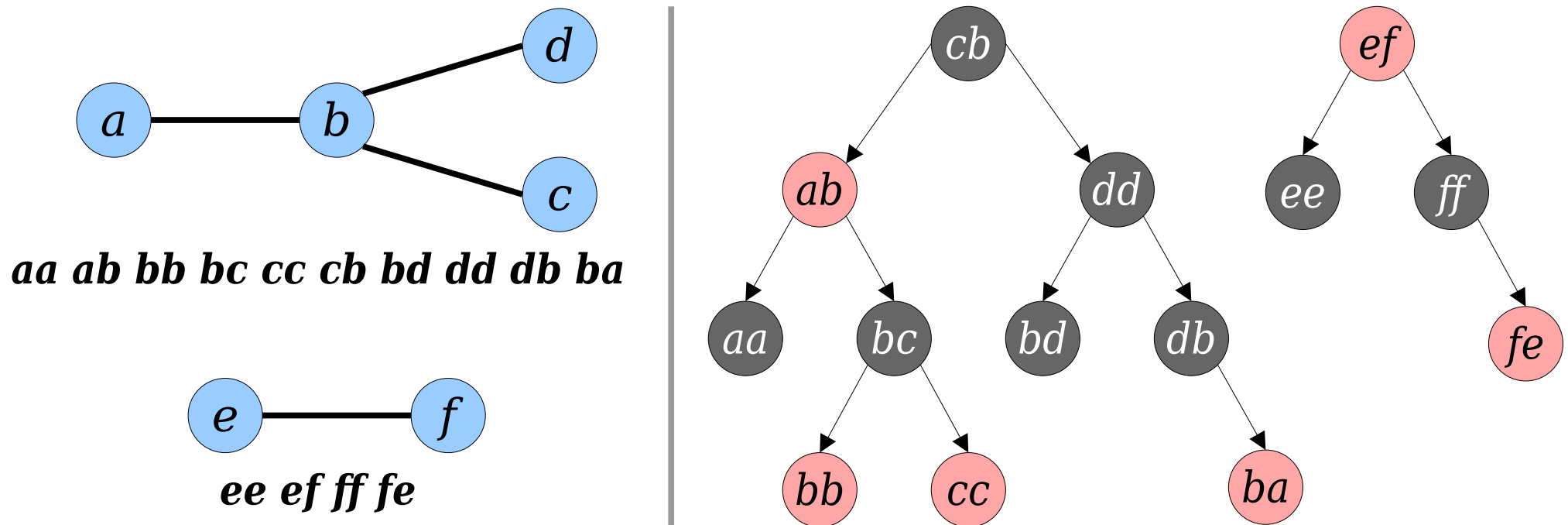
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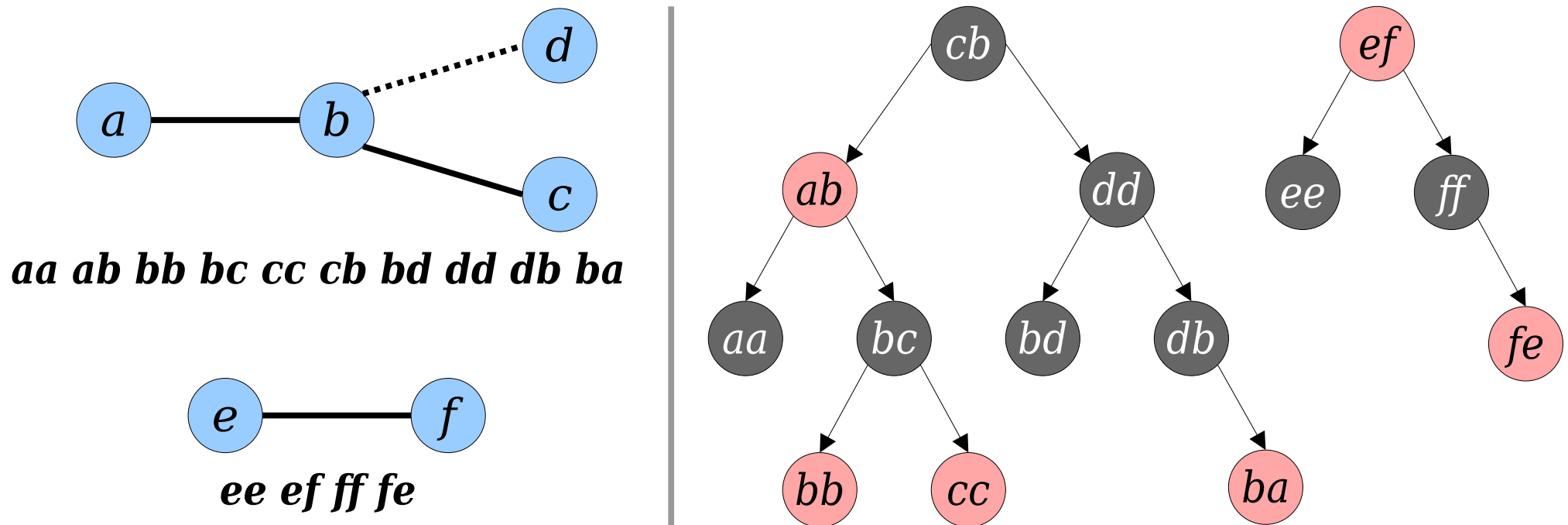
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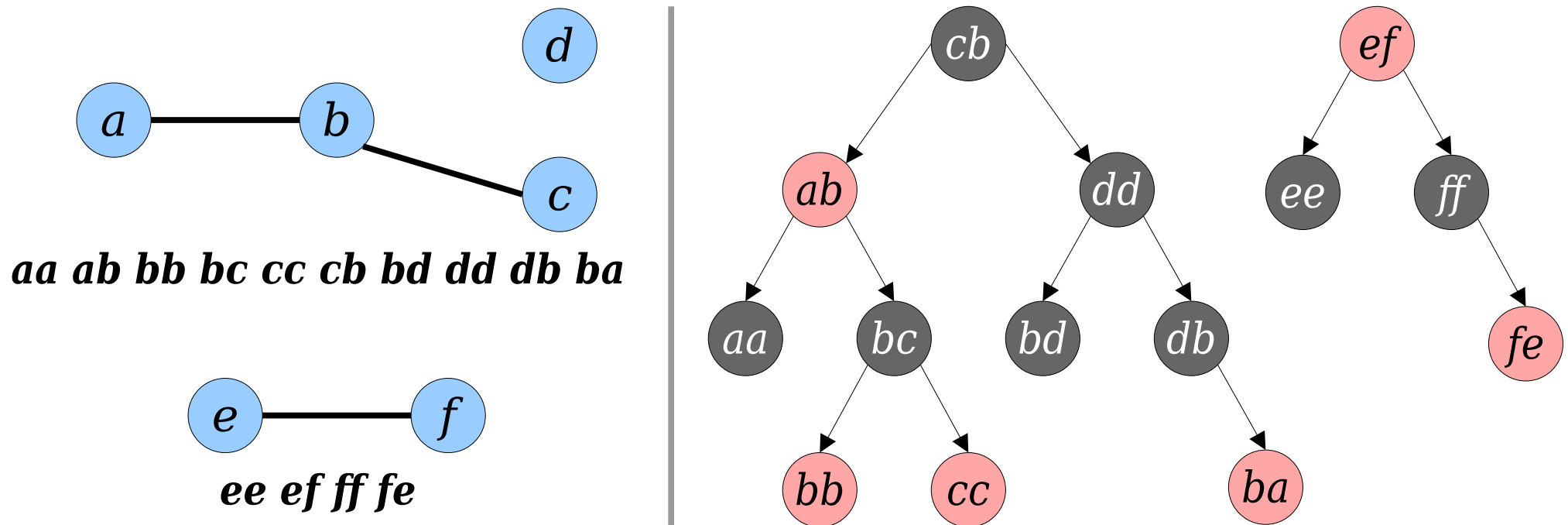
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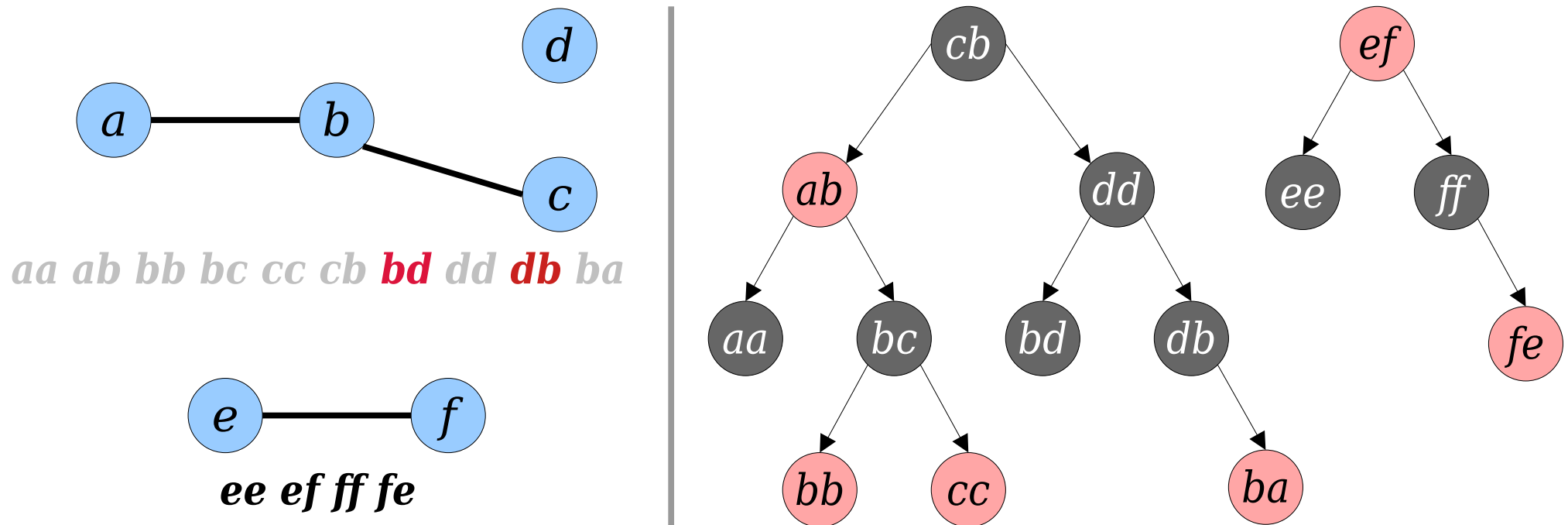
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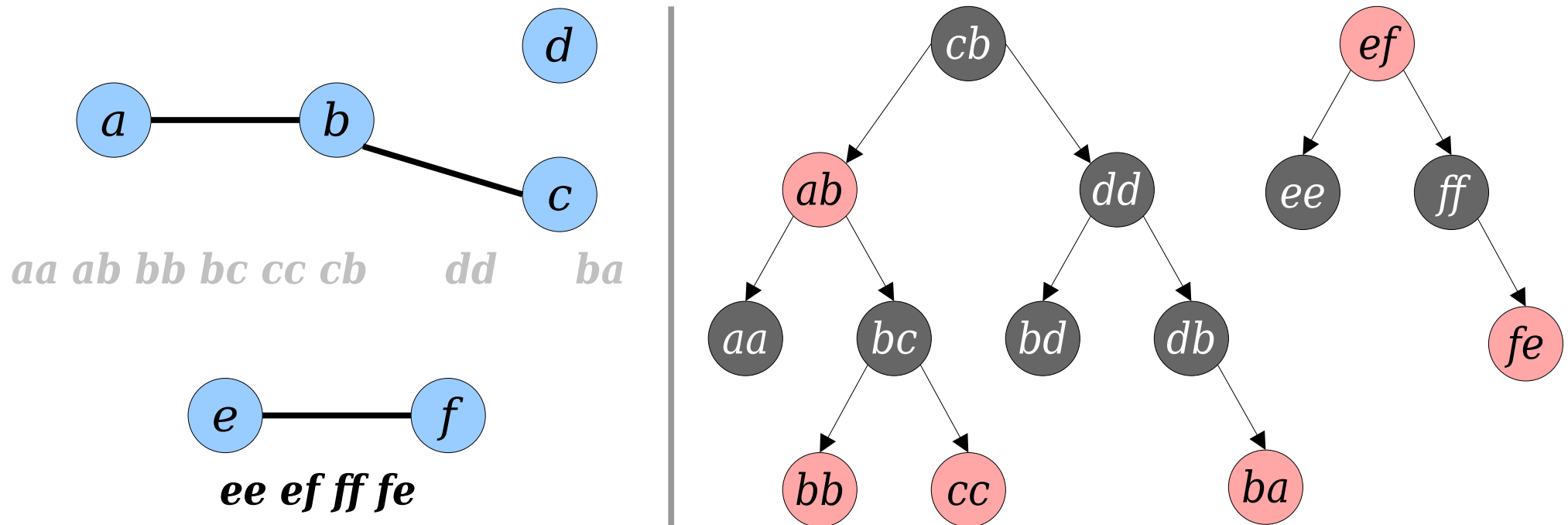
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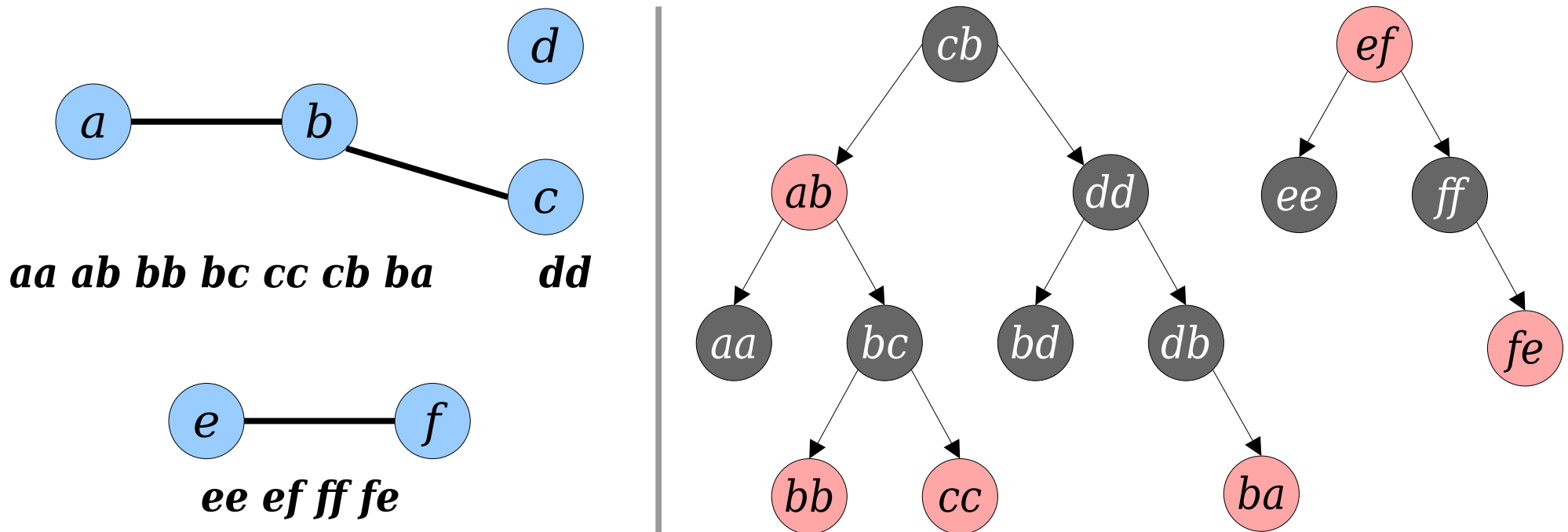
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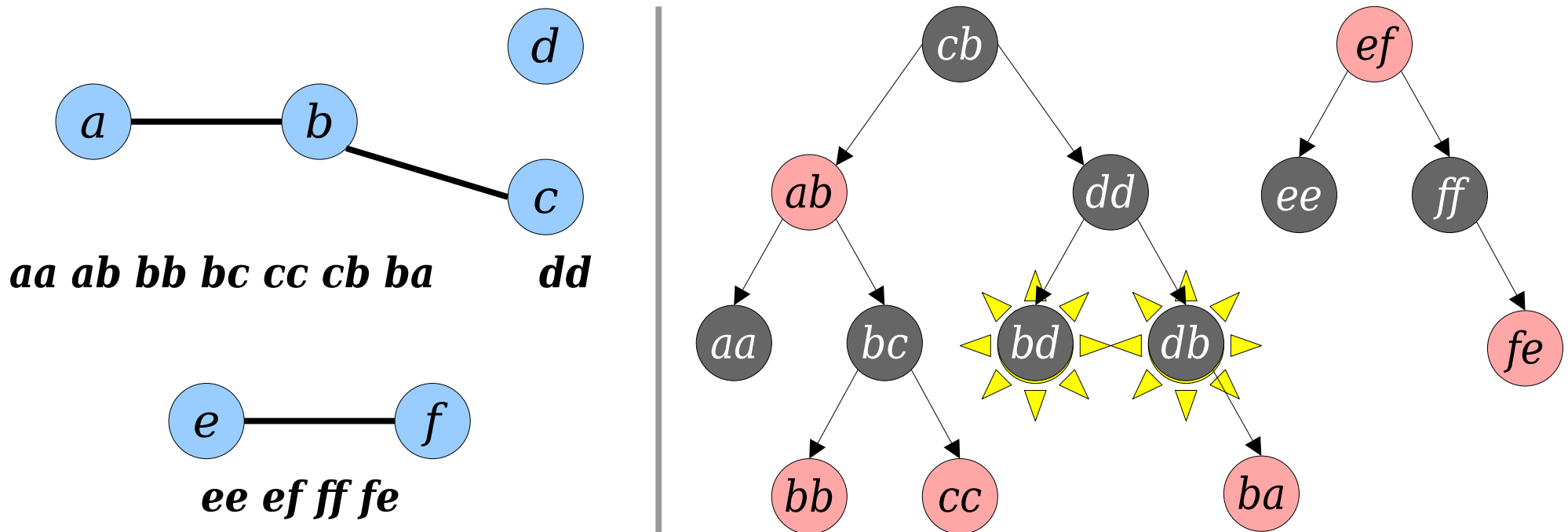
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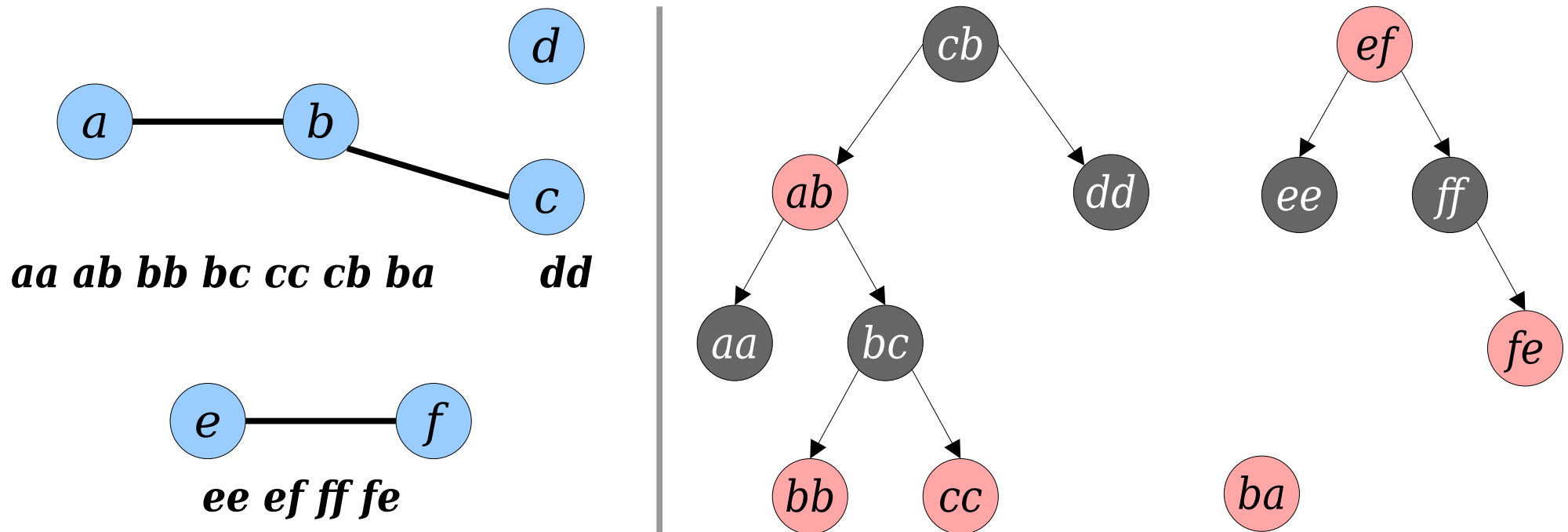
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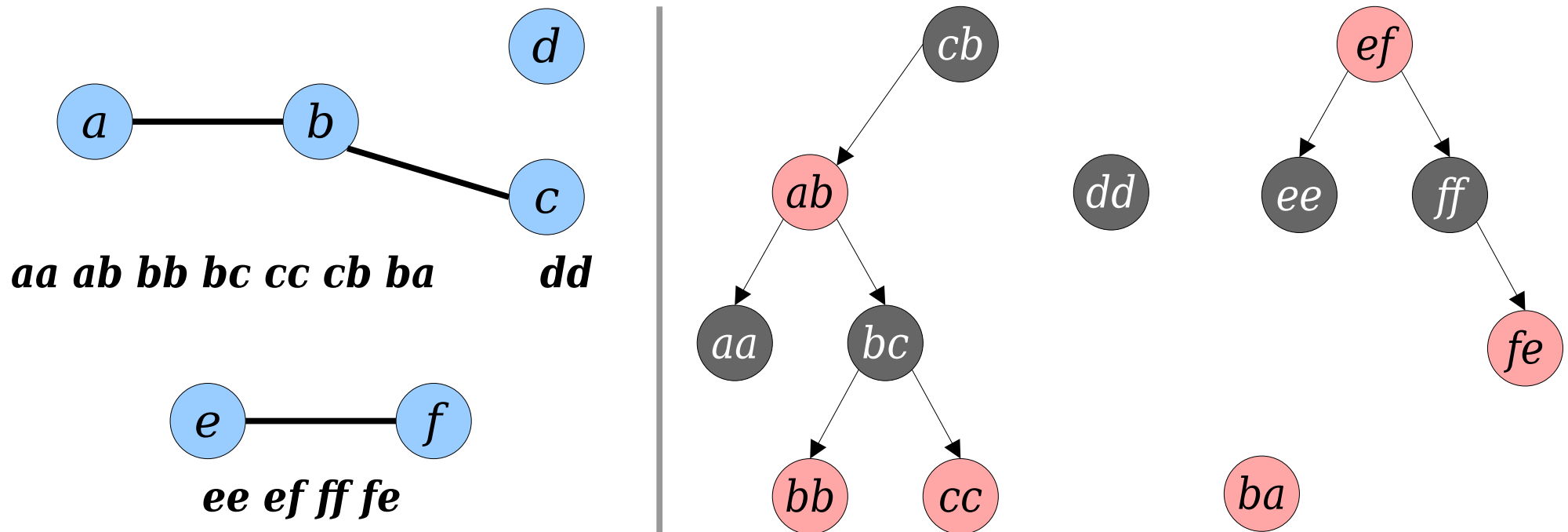
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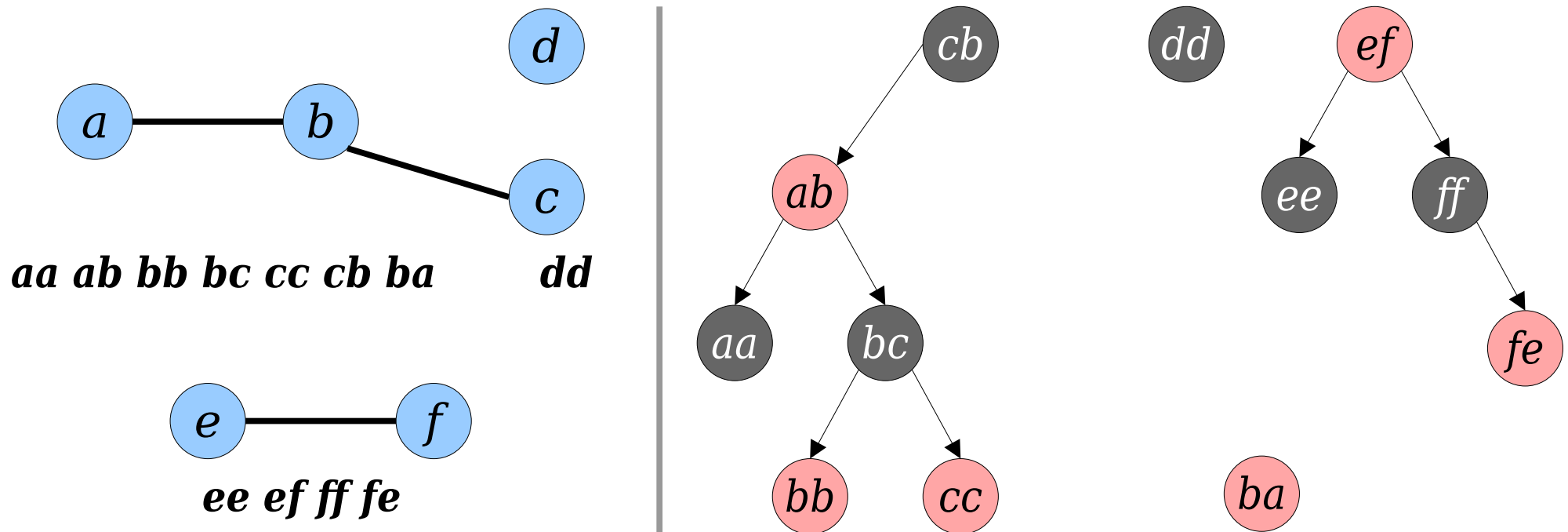
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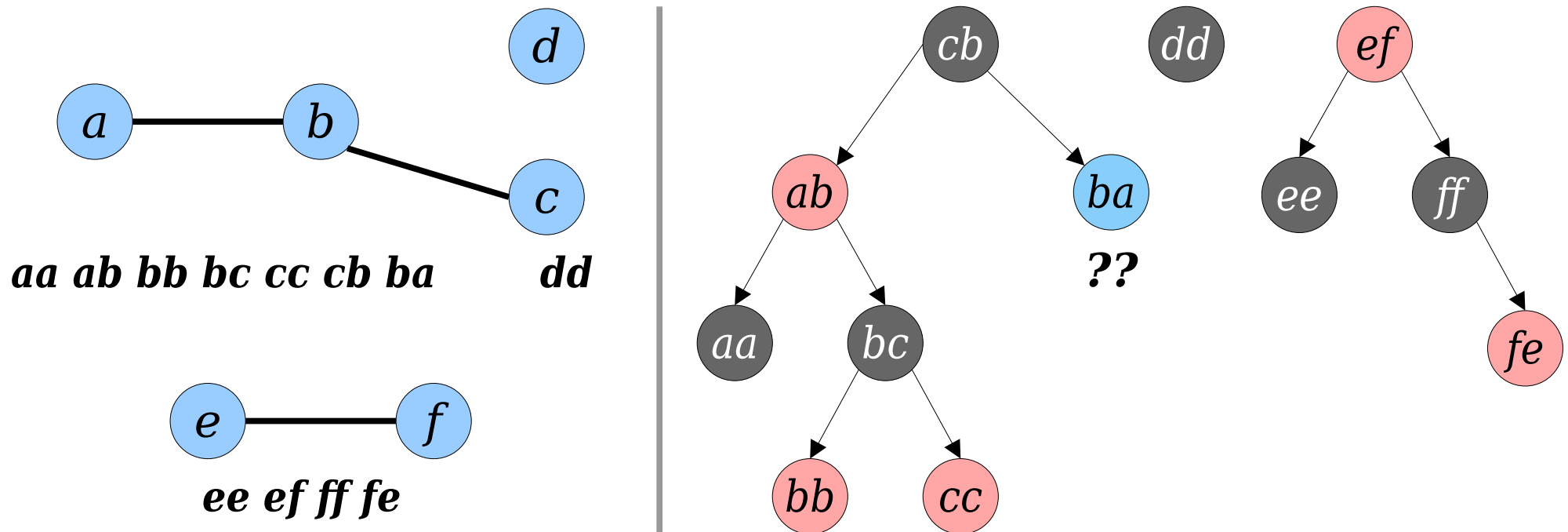
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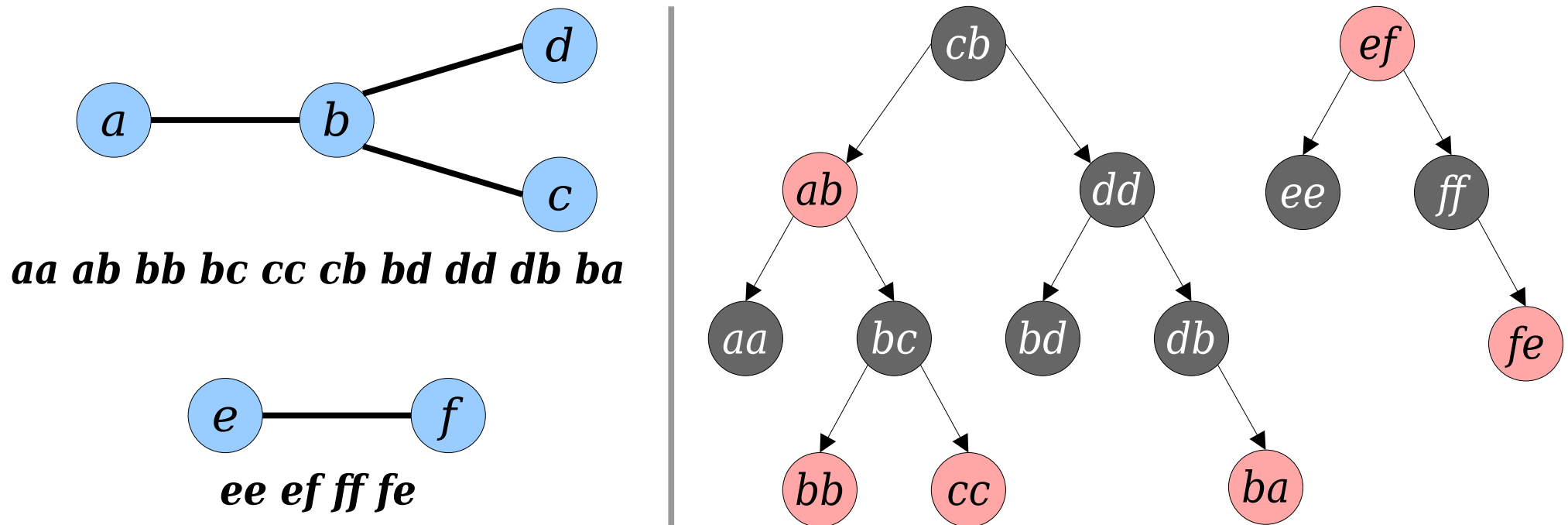
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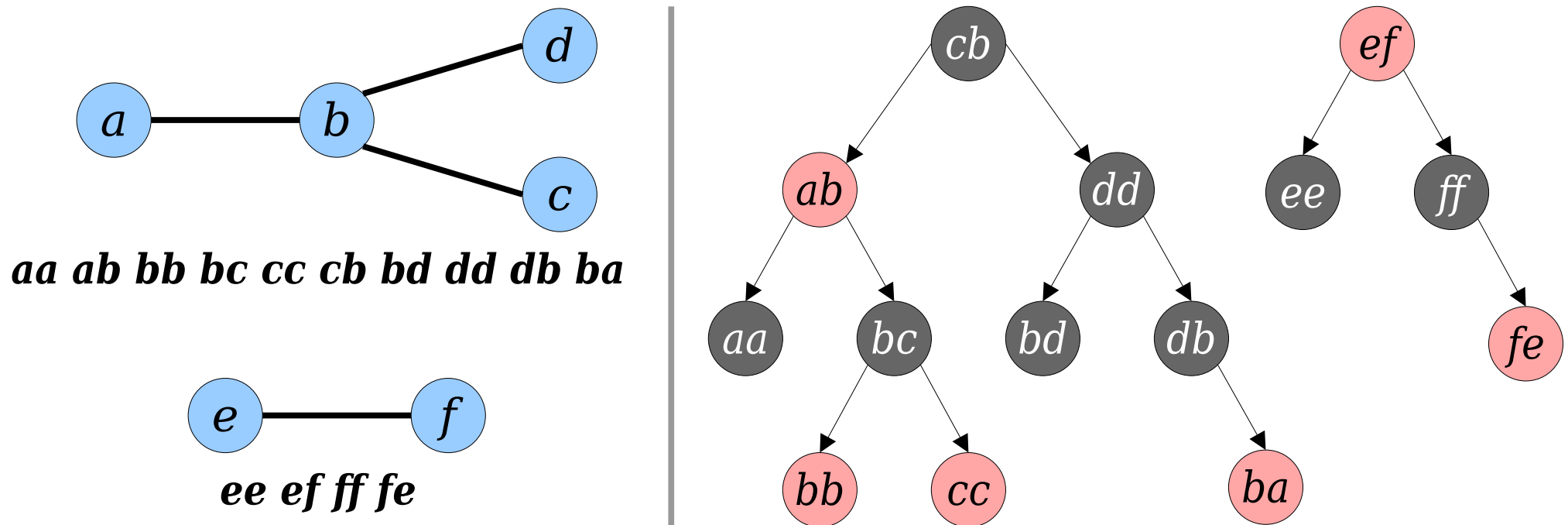
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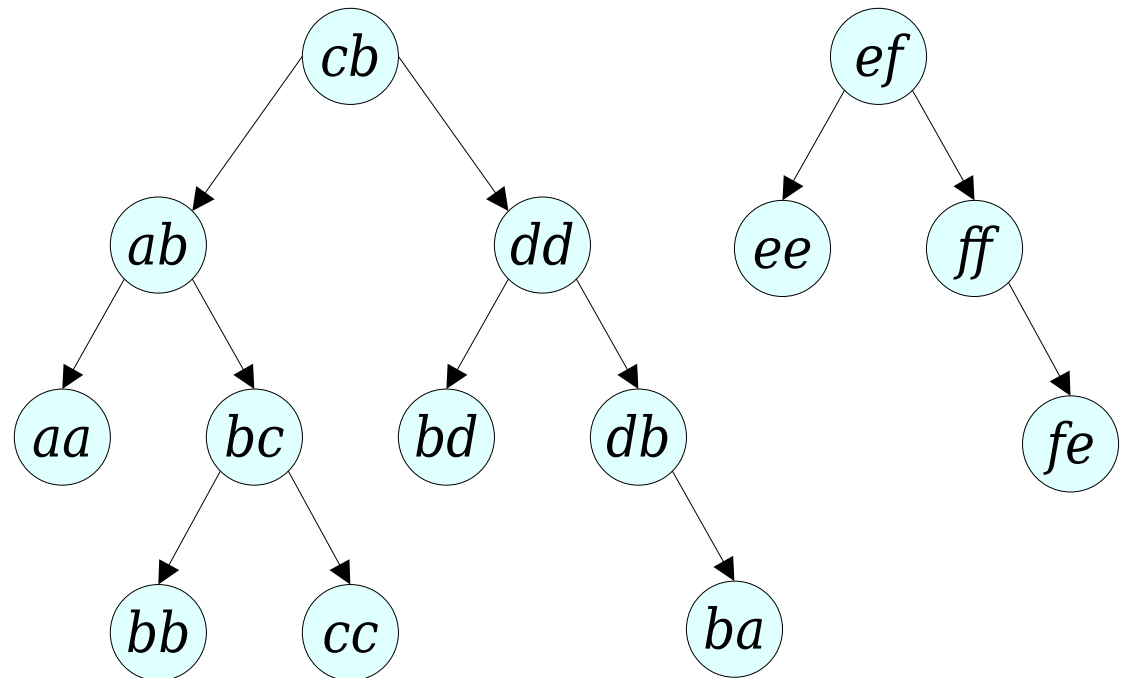
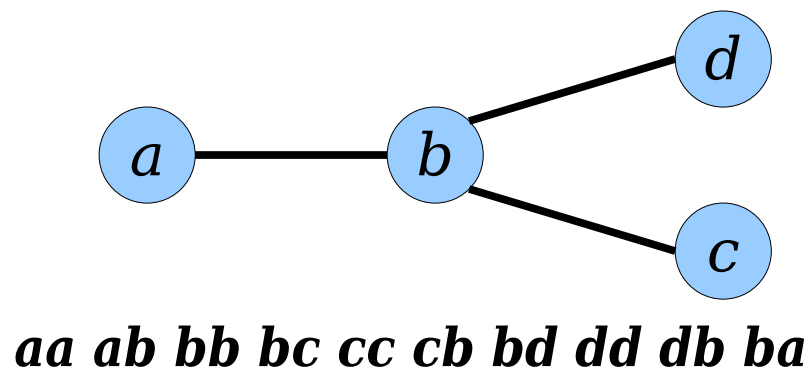
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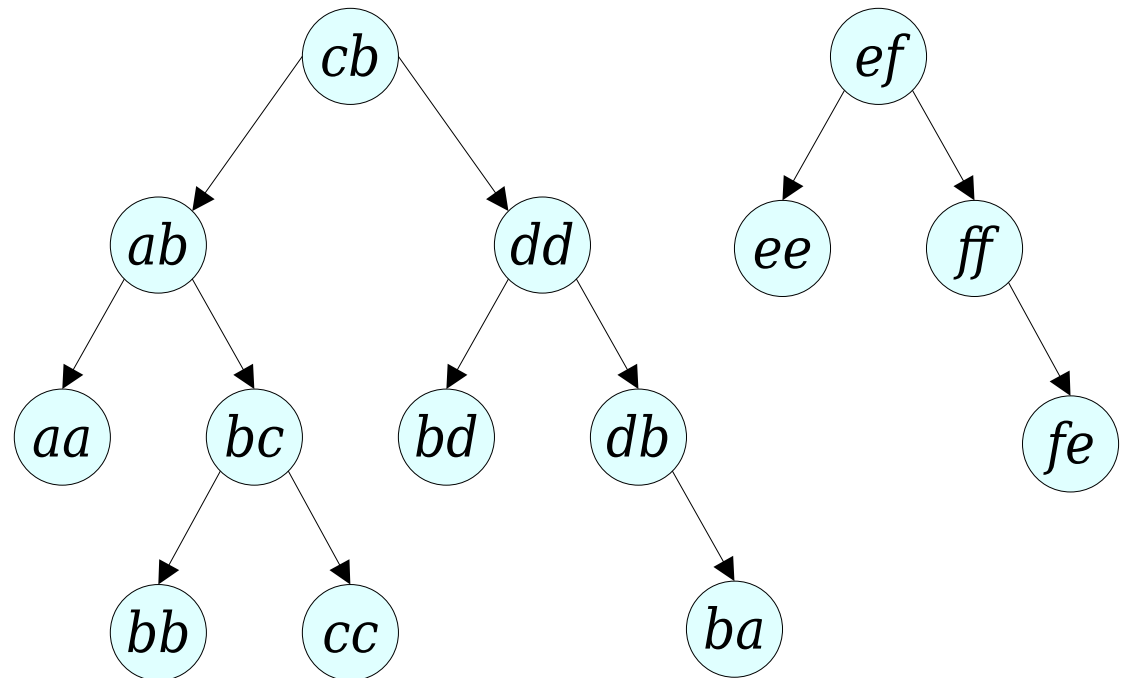
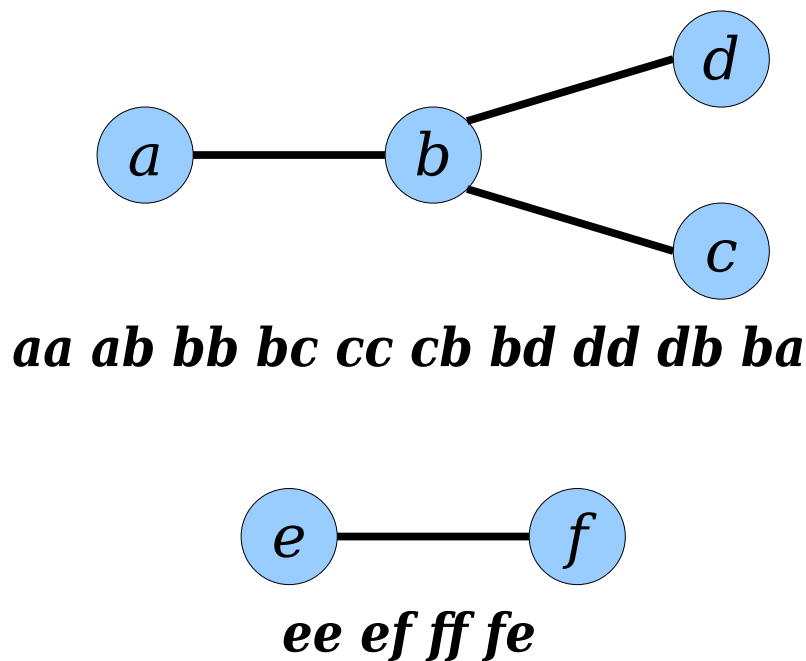
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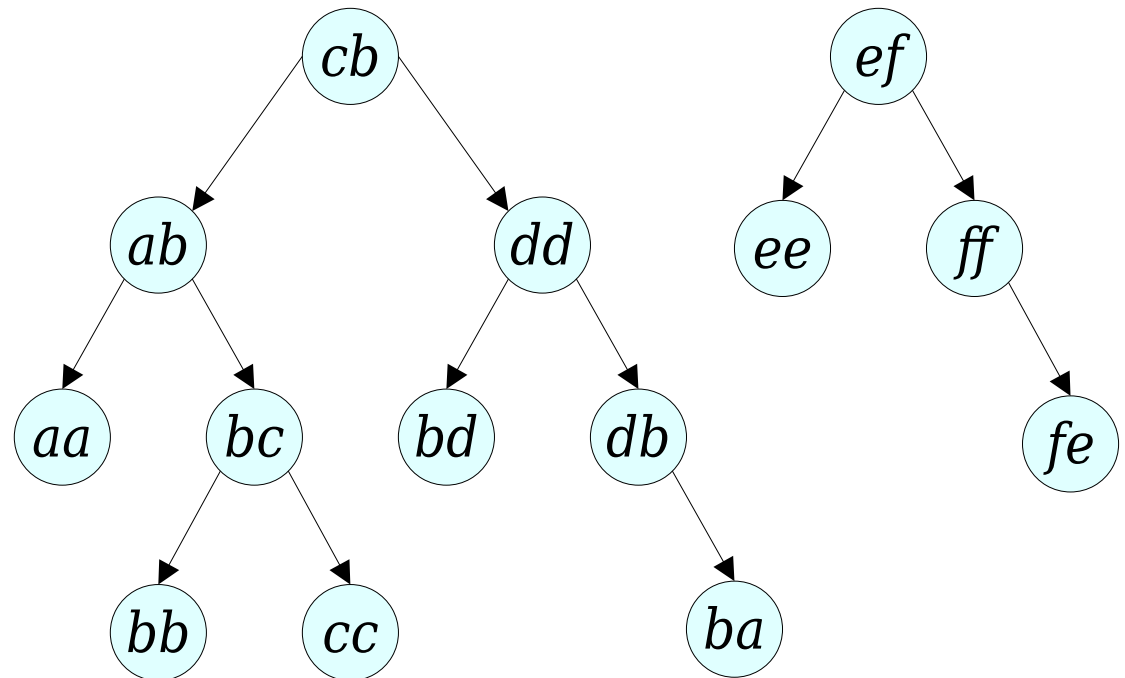
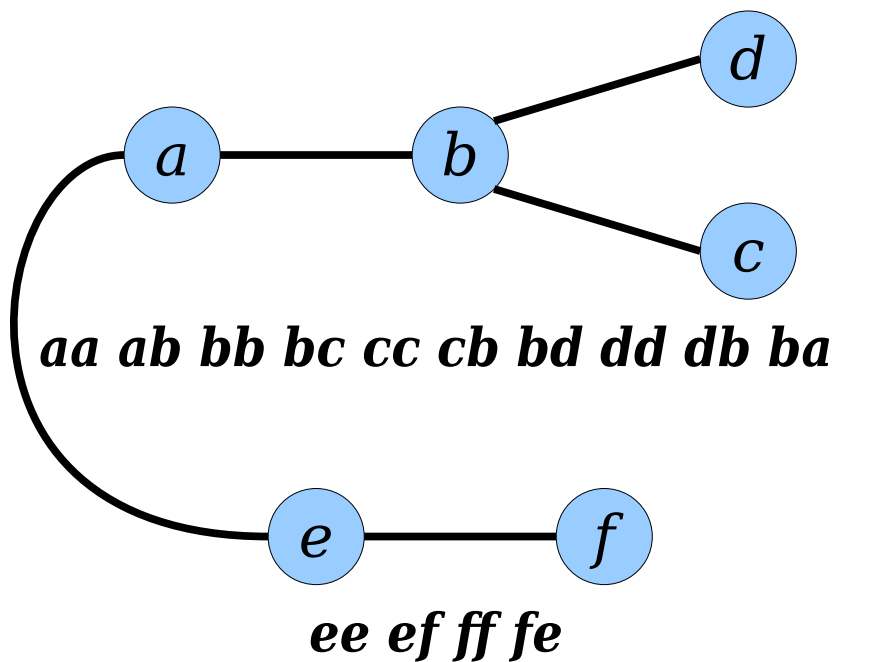
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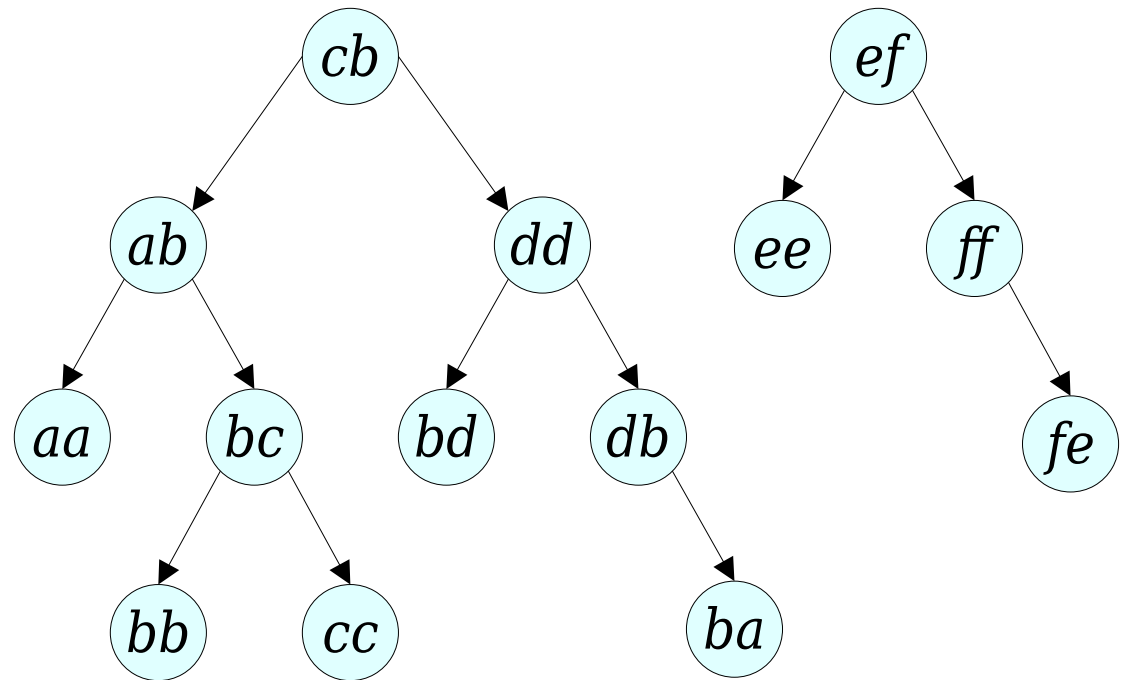
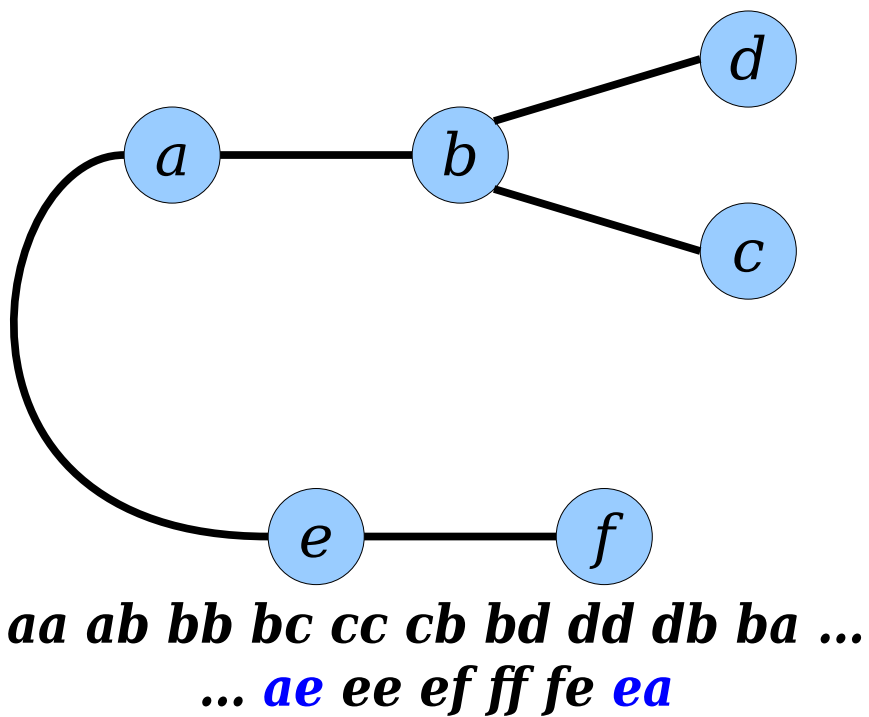
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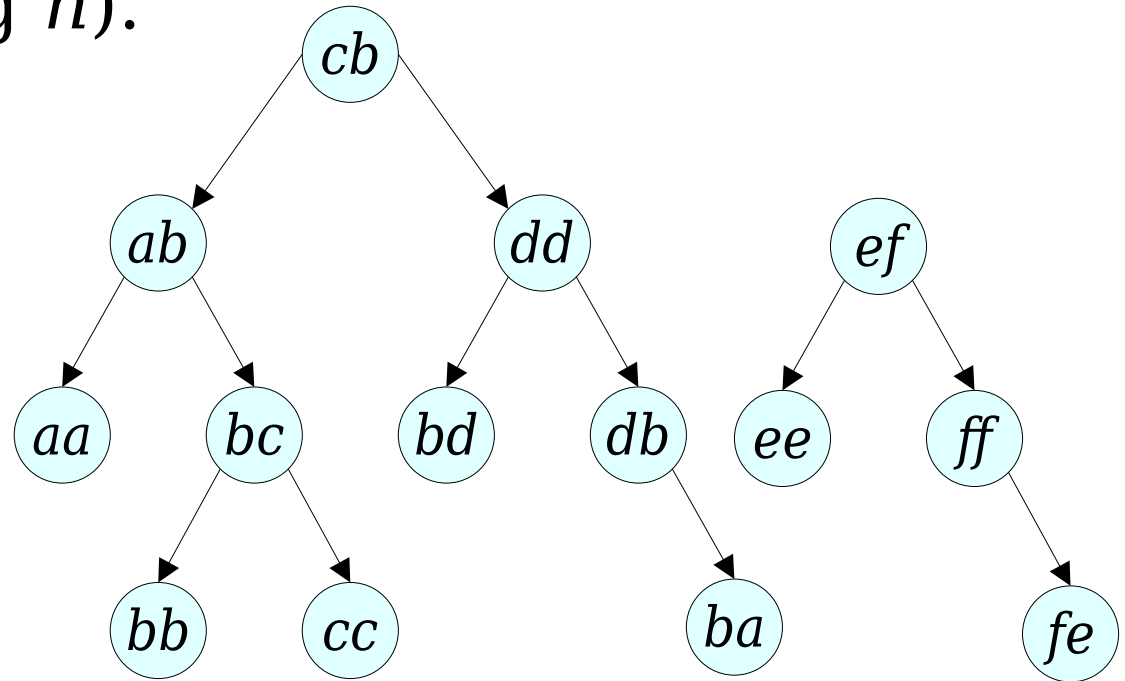
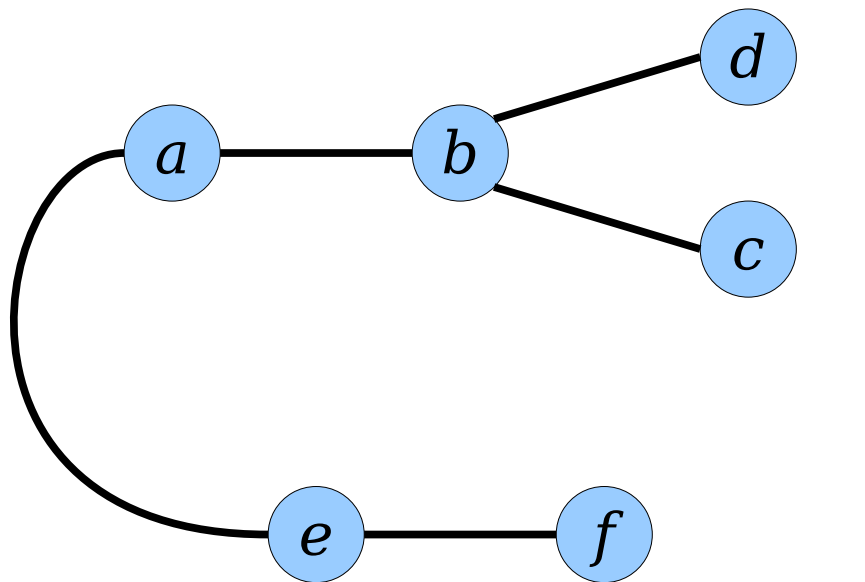
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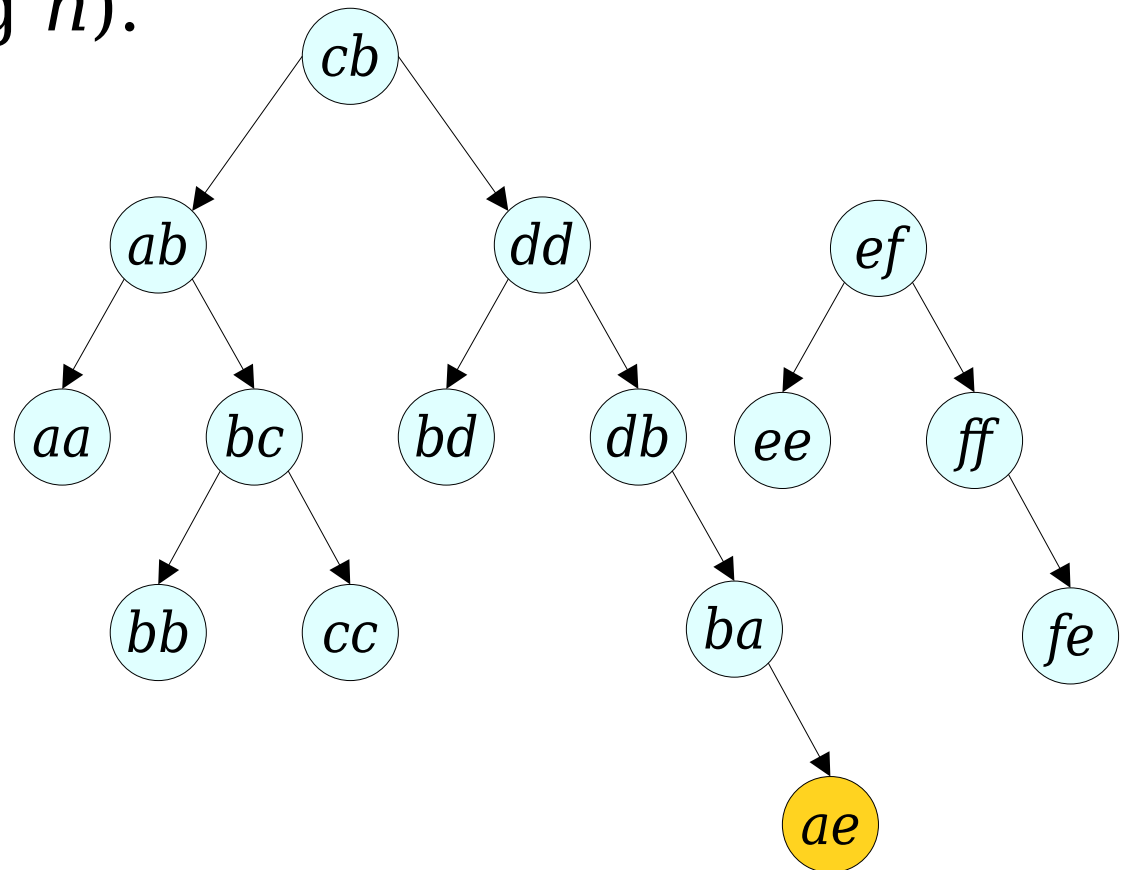
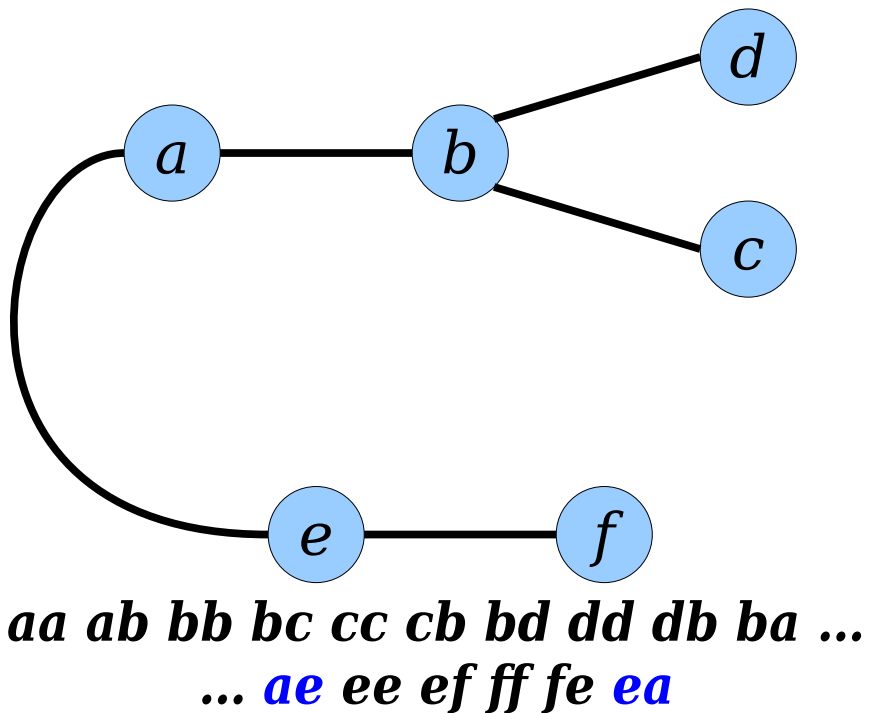
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aa ab bb bc cc cb bd dd db ba ...
... ae ee ef ff fe ea

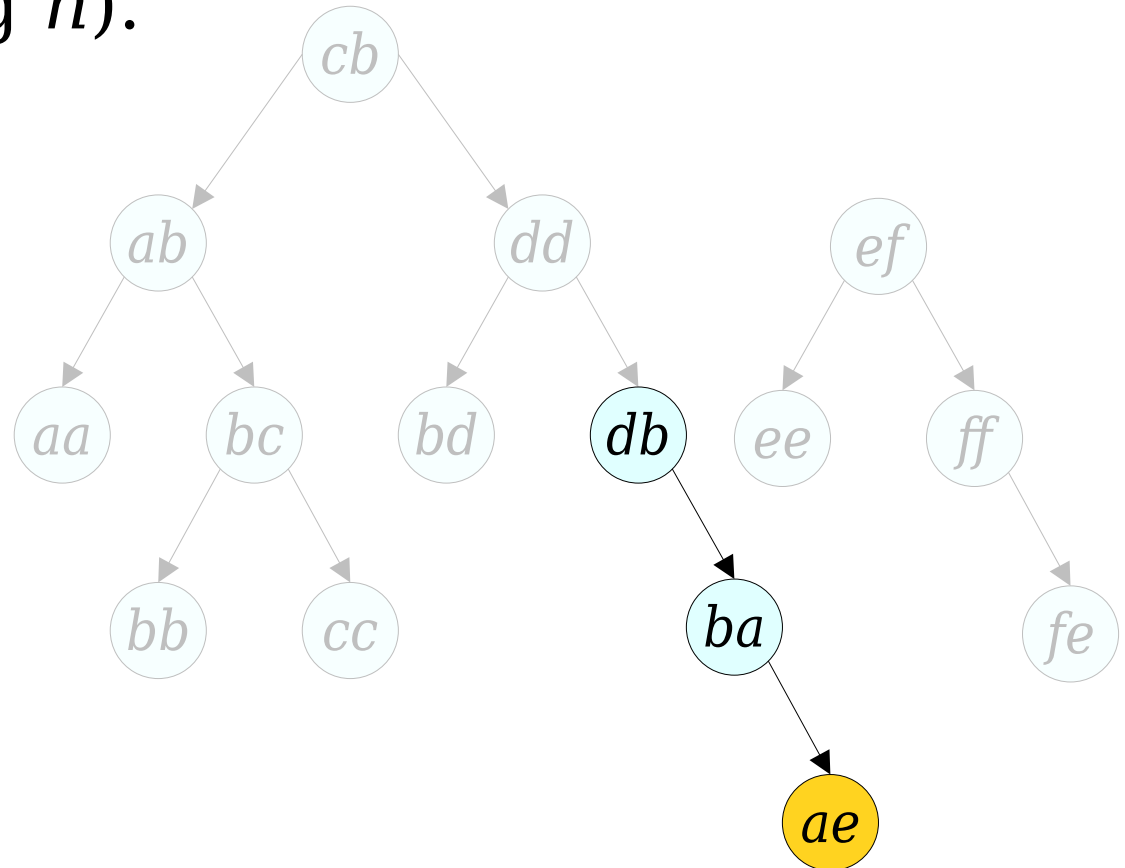
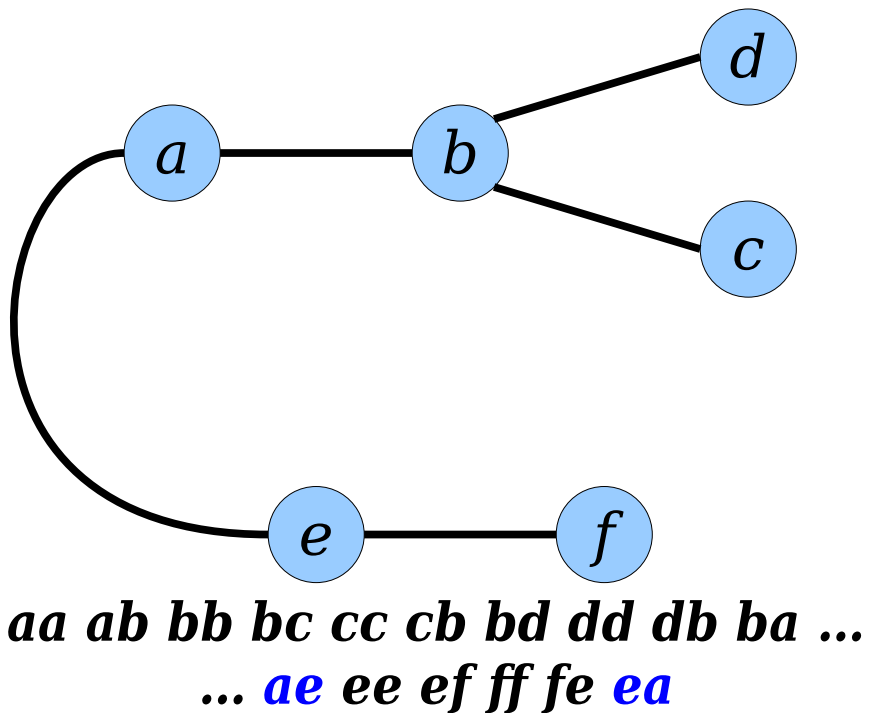
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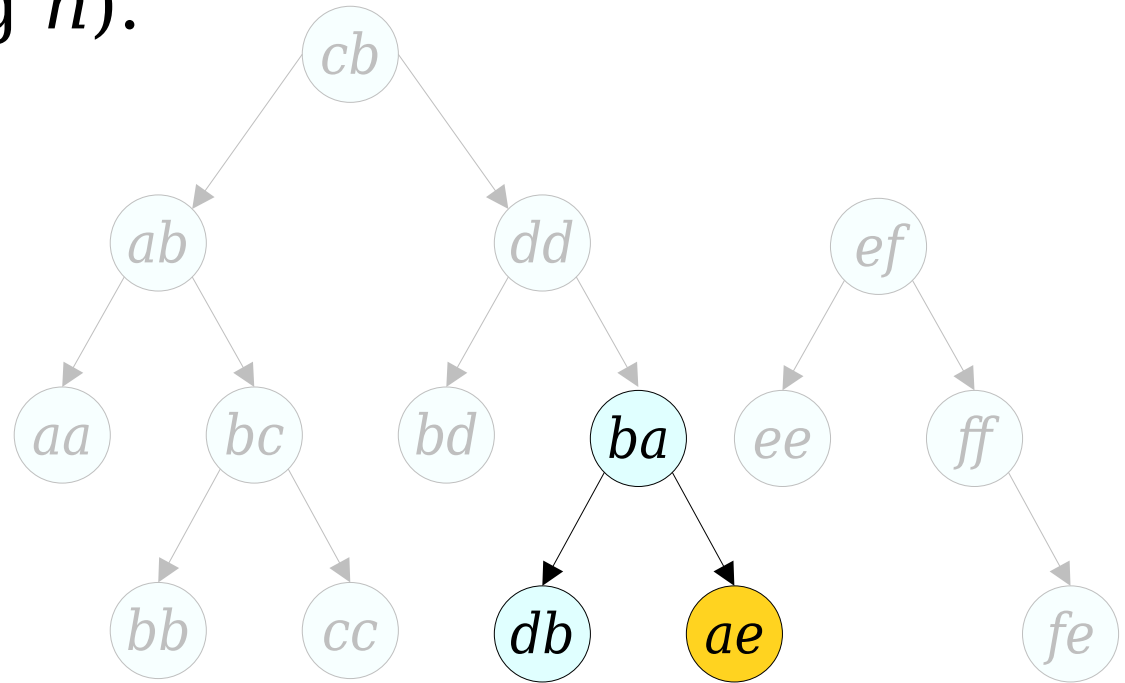
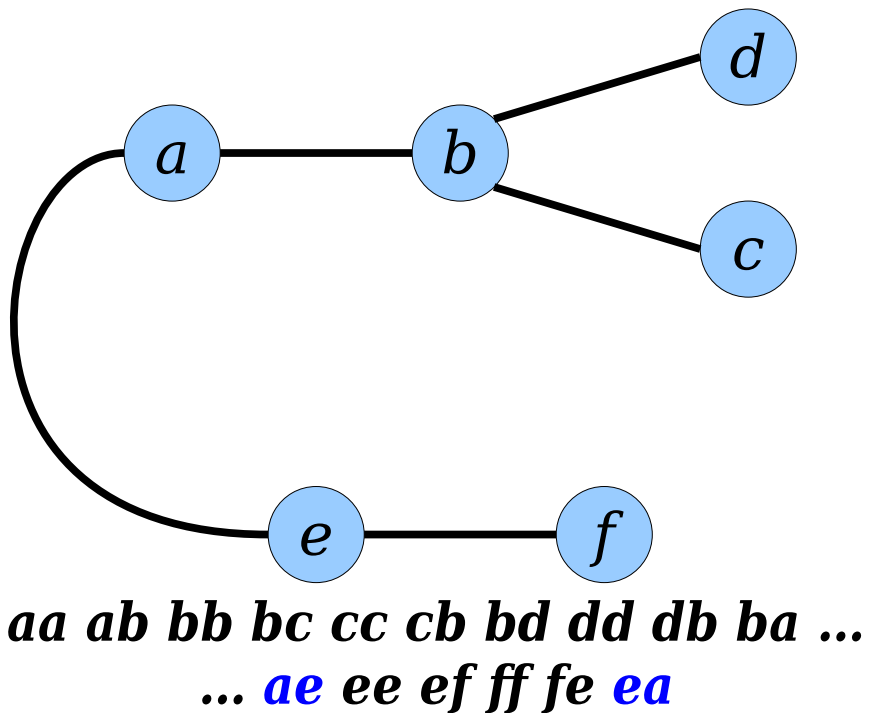
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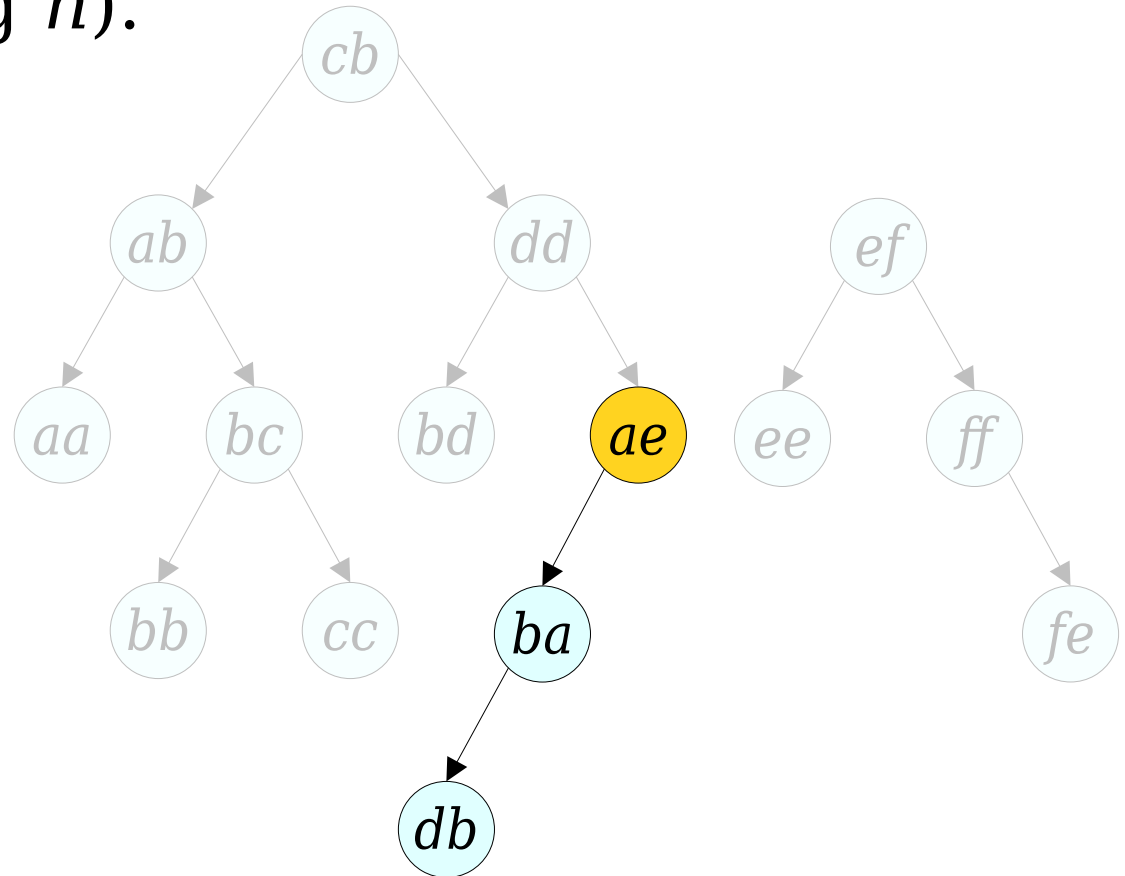
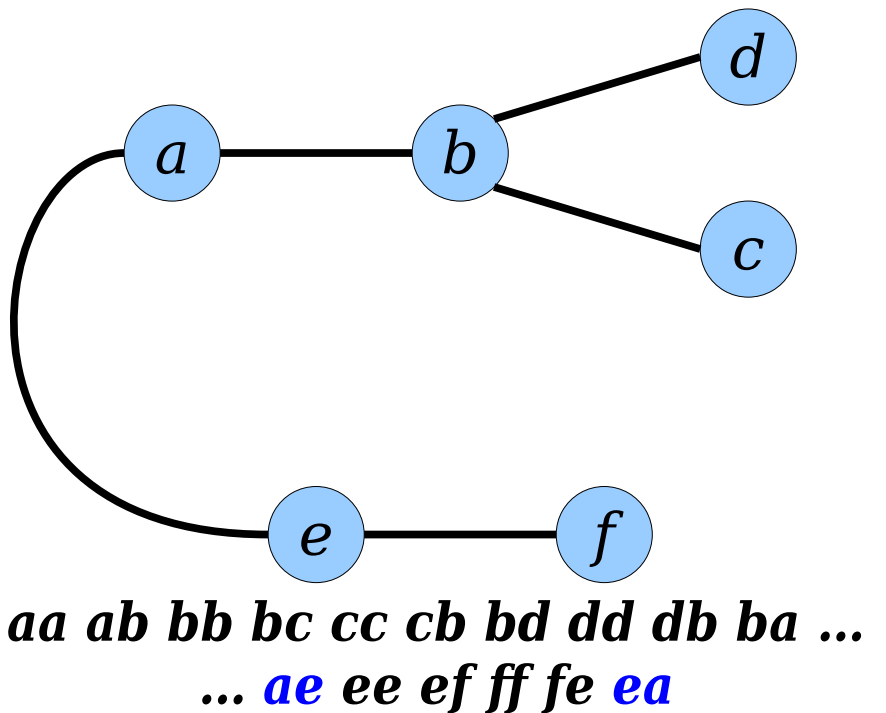
Binary Search(less) Trees

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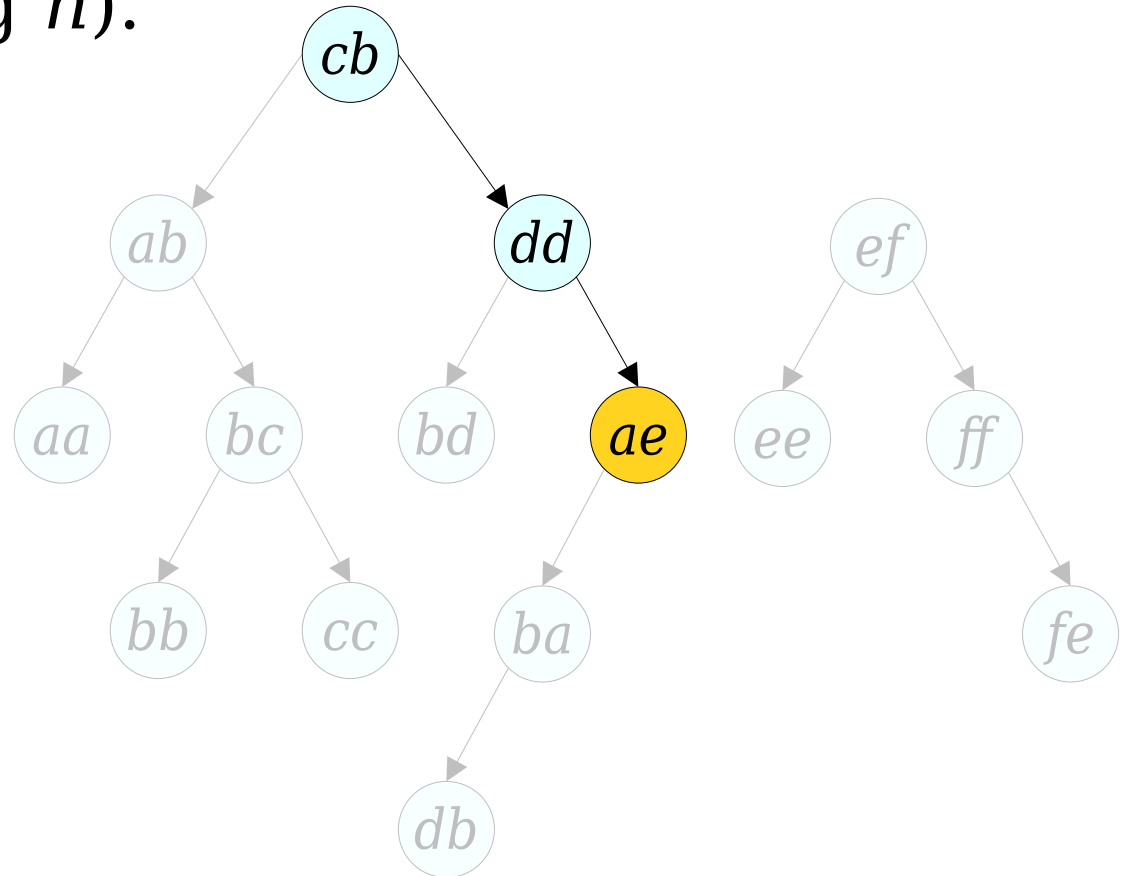
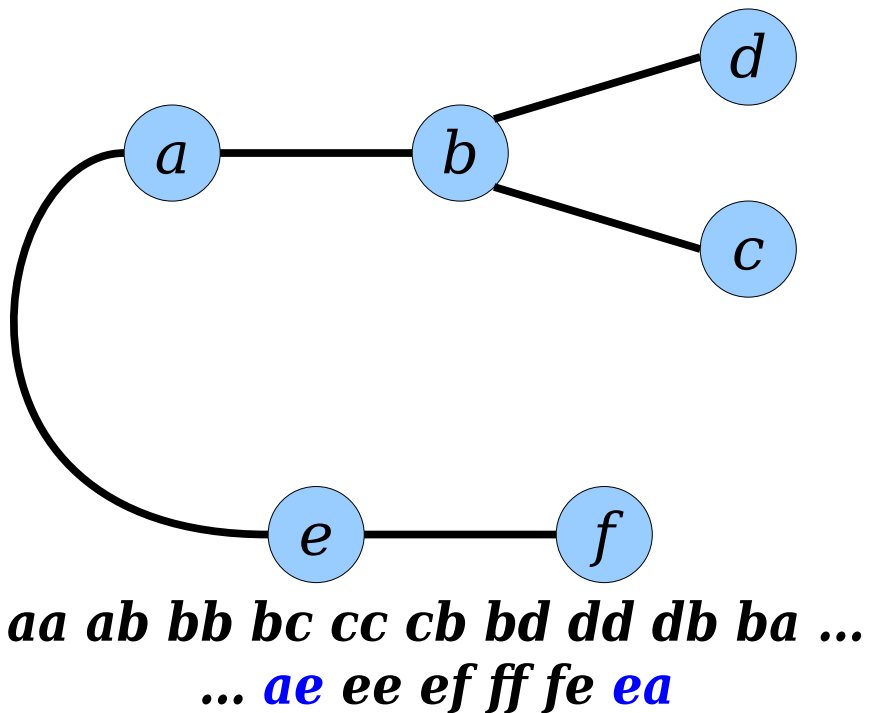
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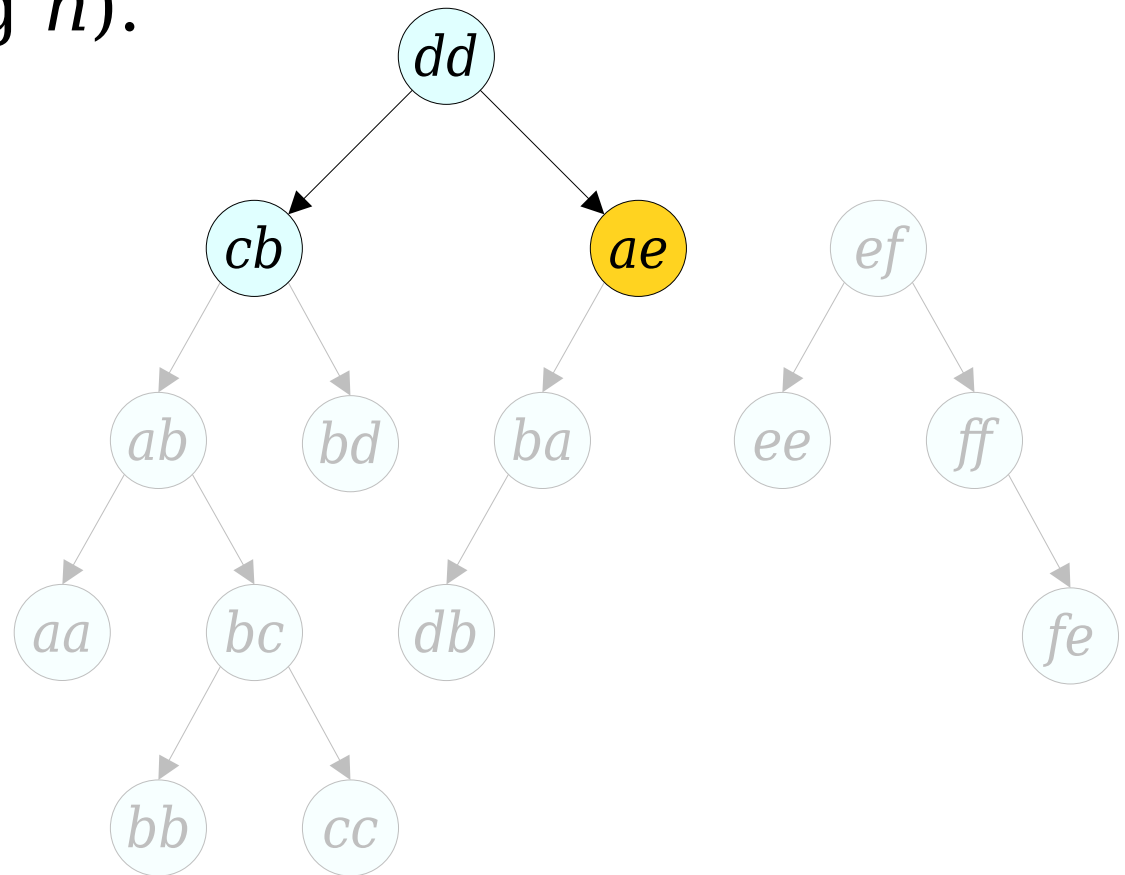
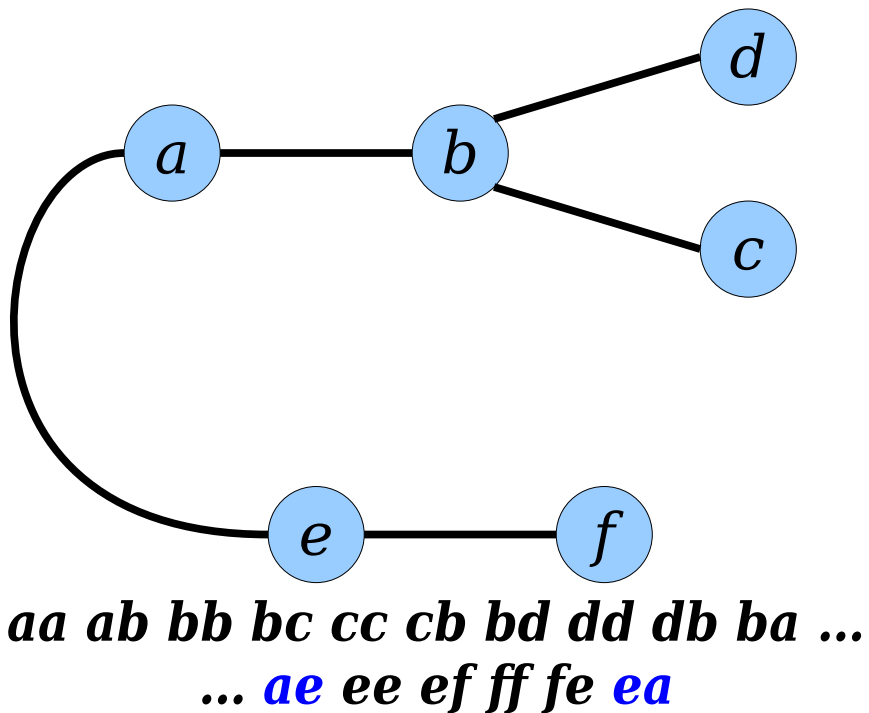
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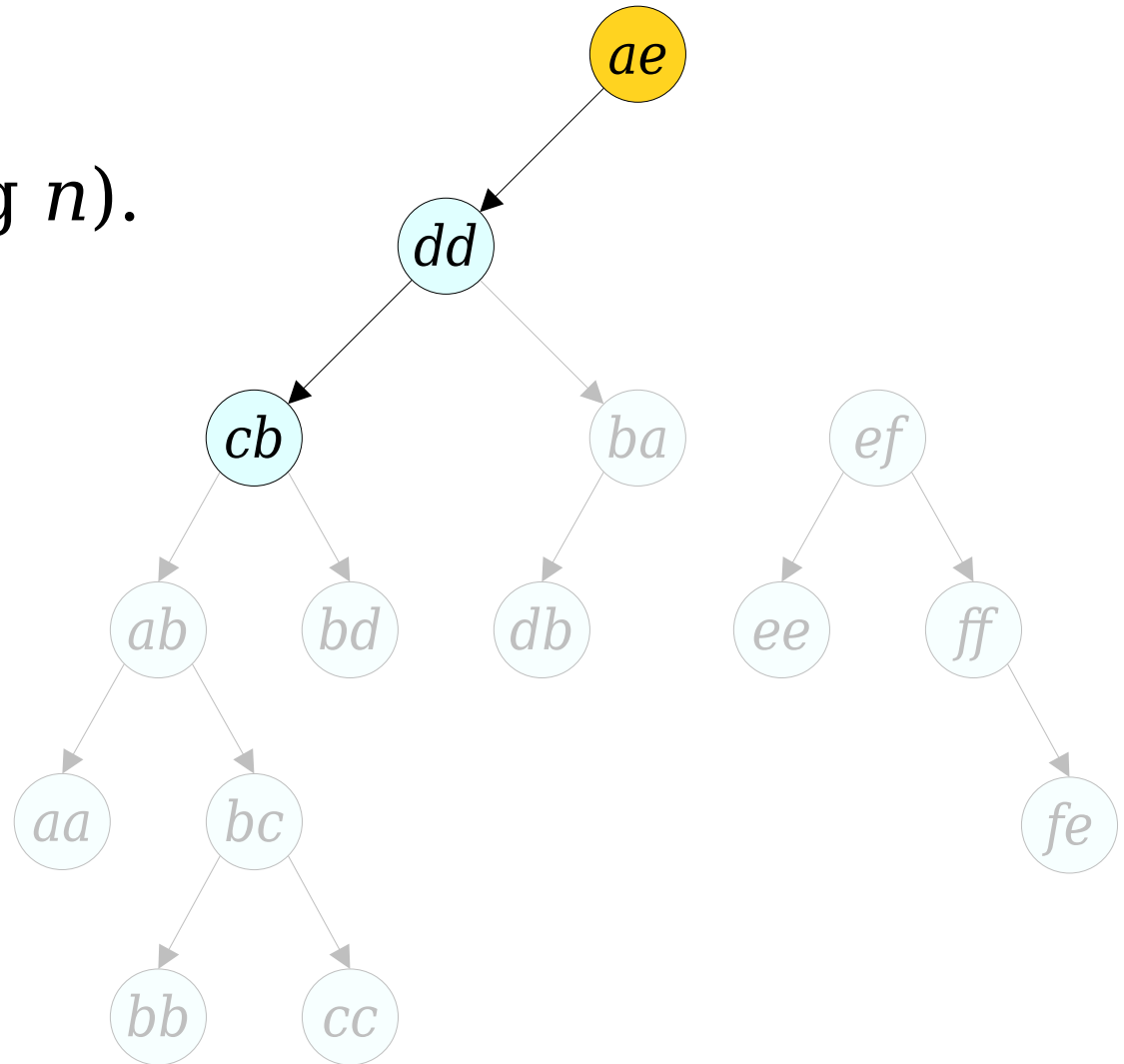
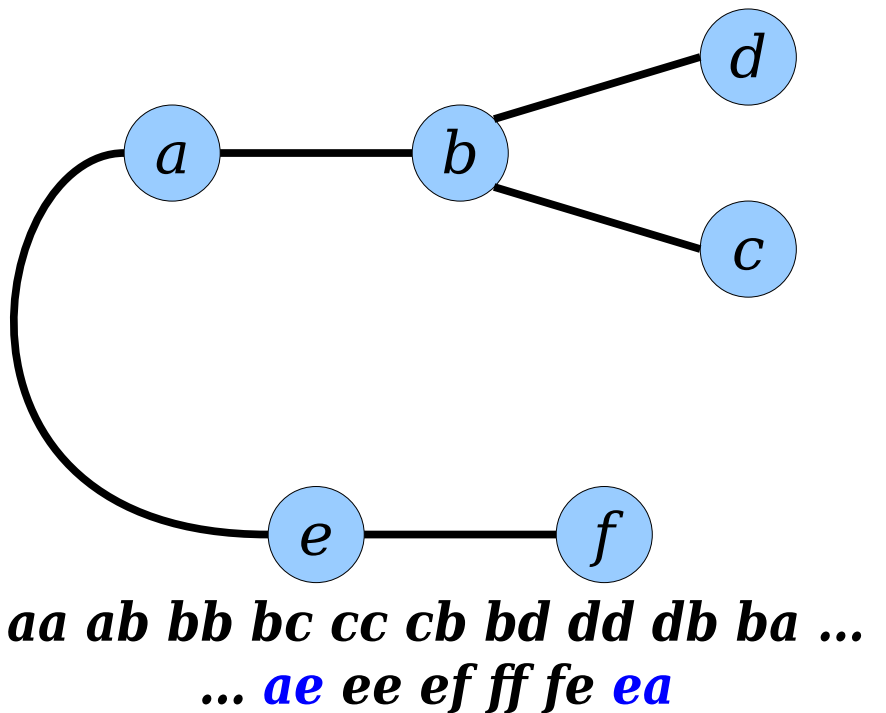
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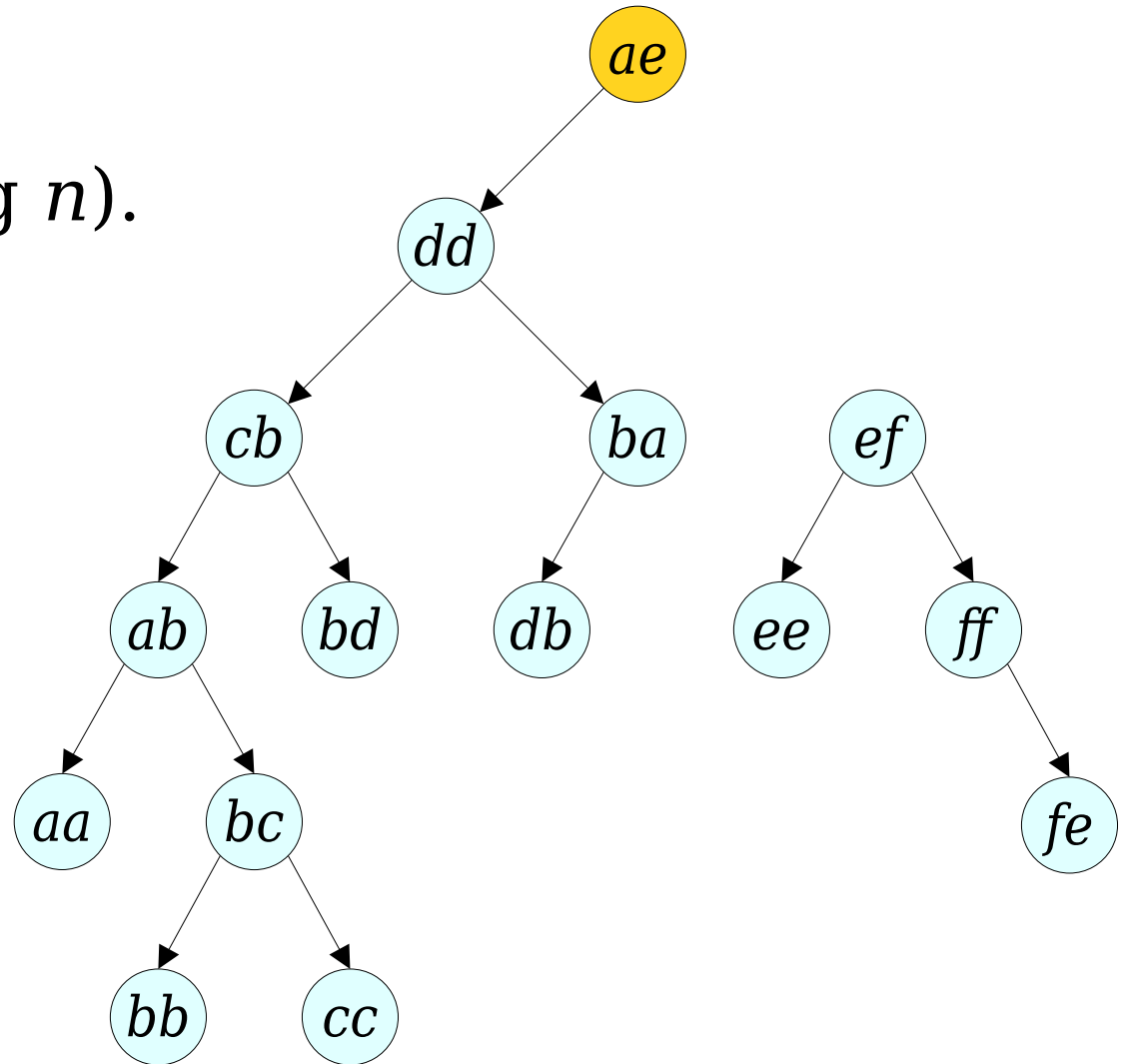
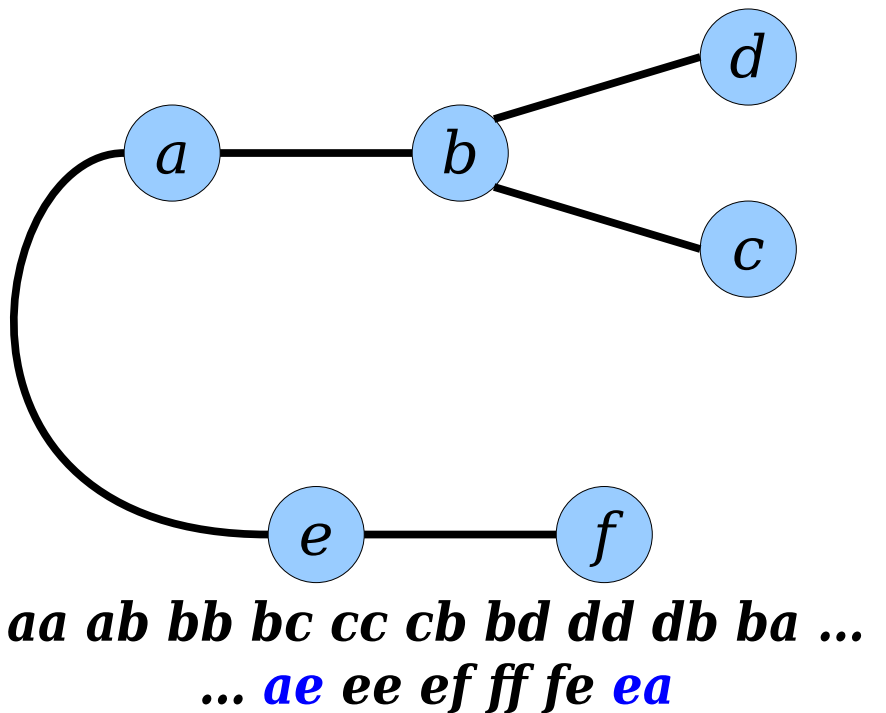
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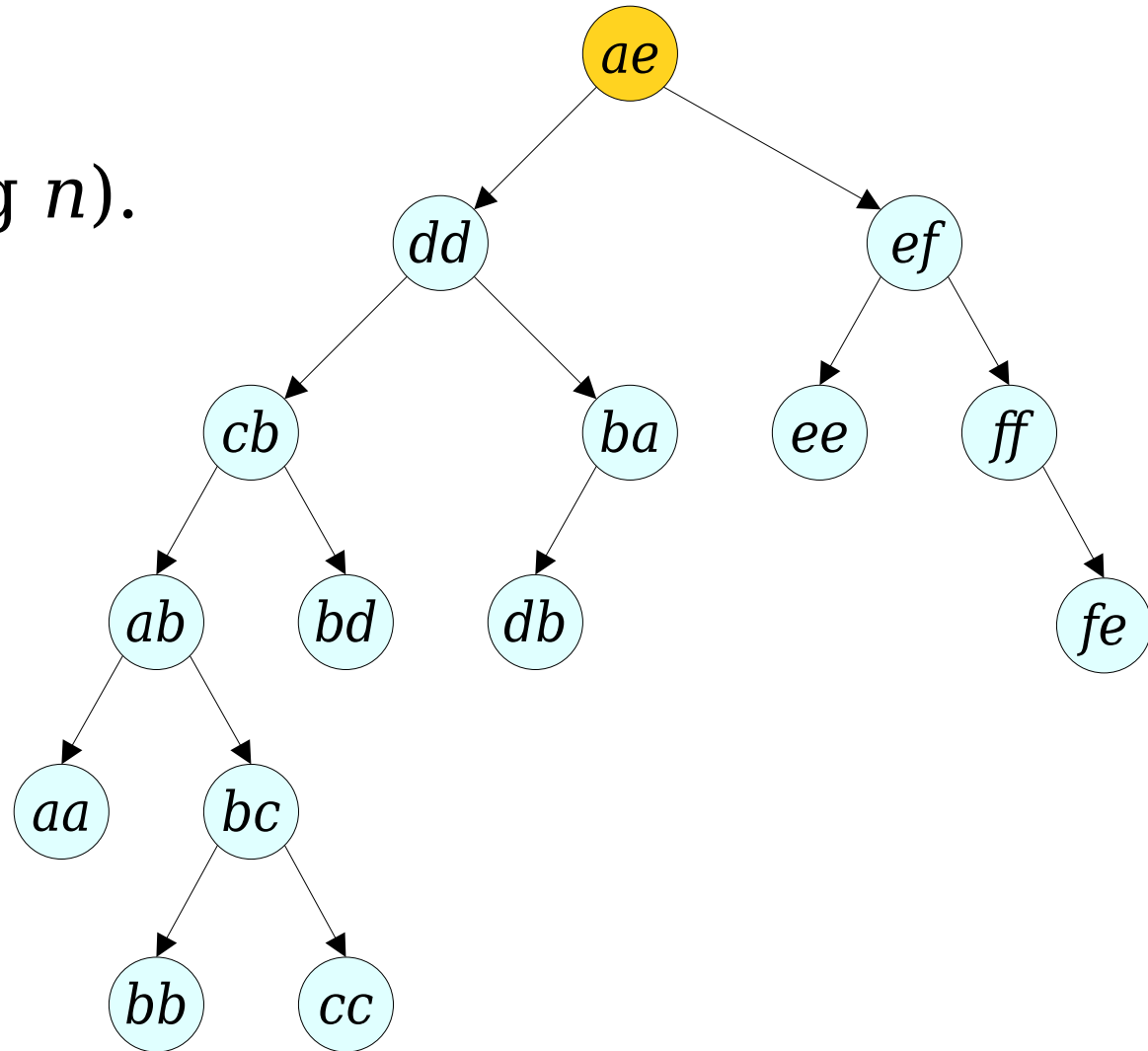
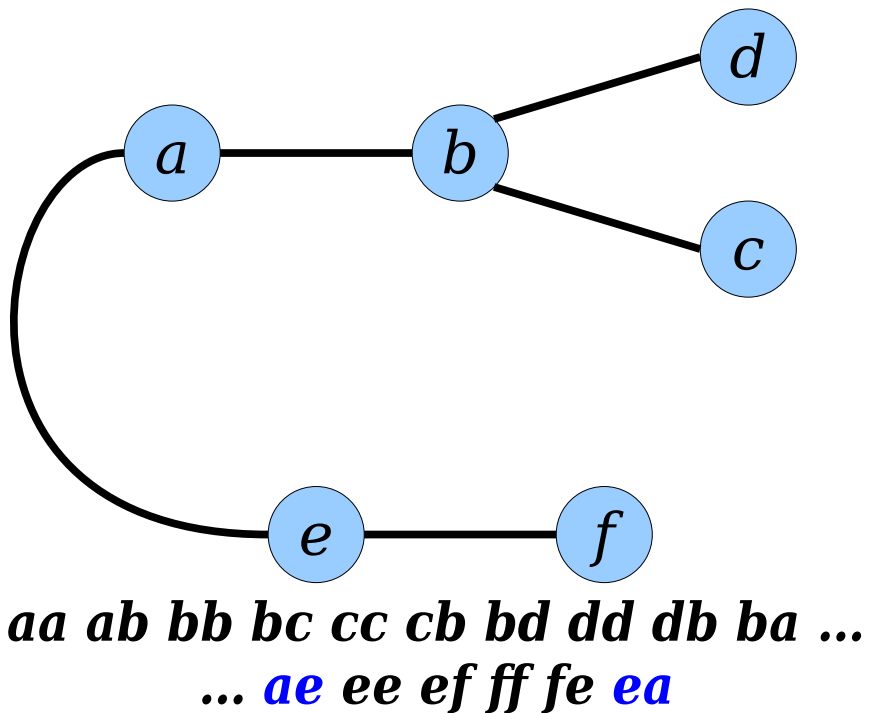
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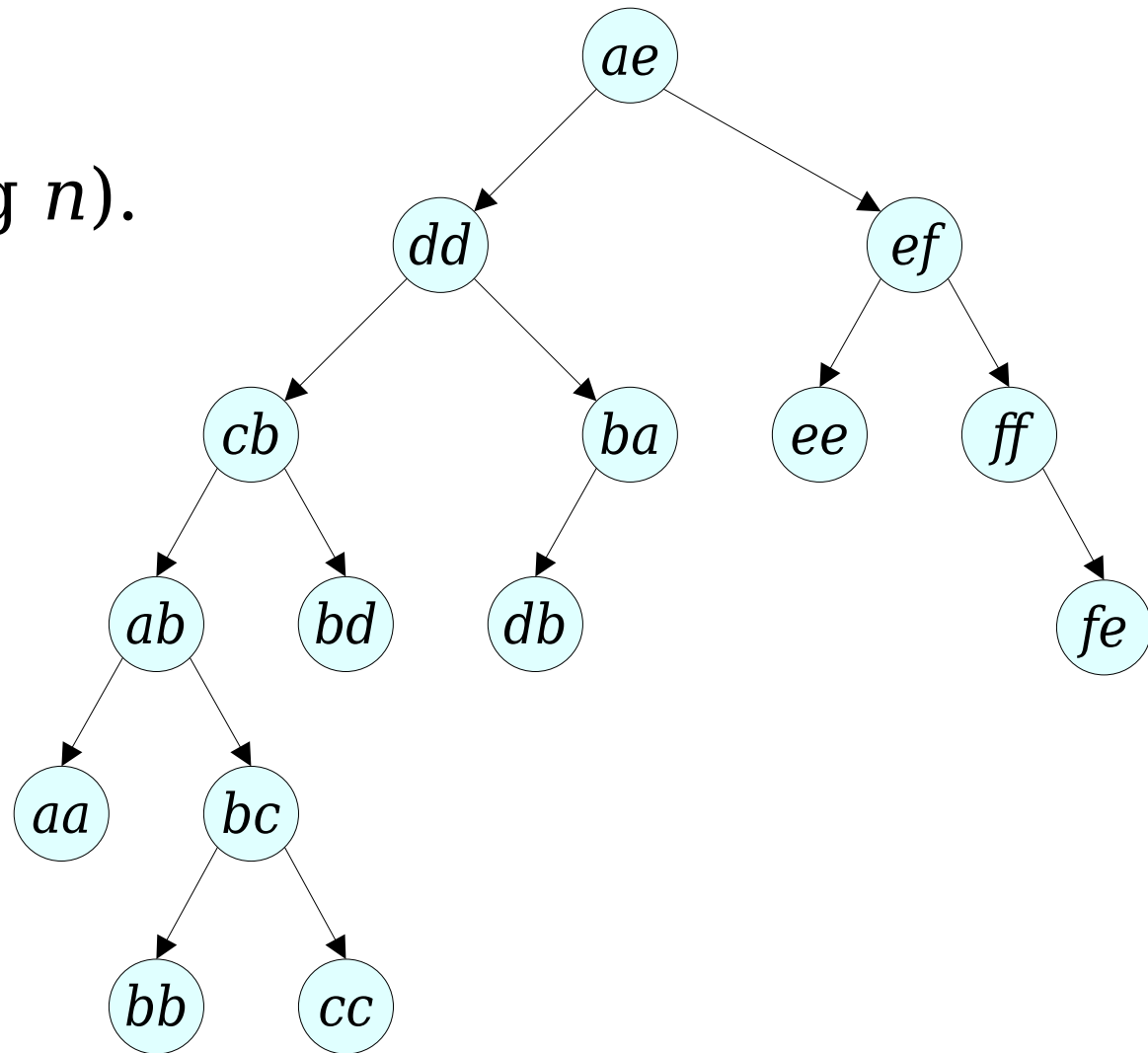
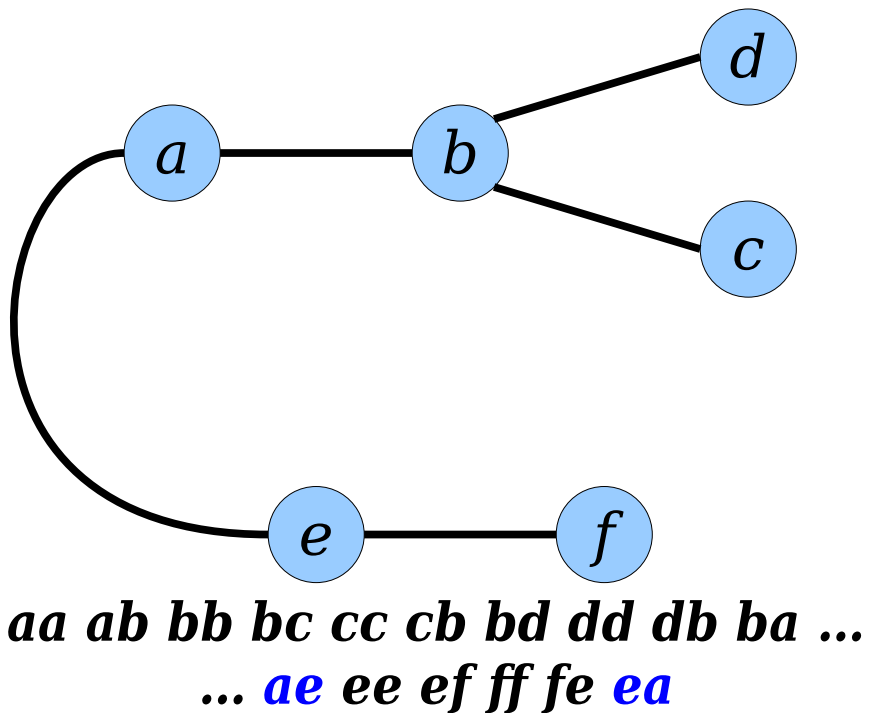
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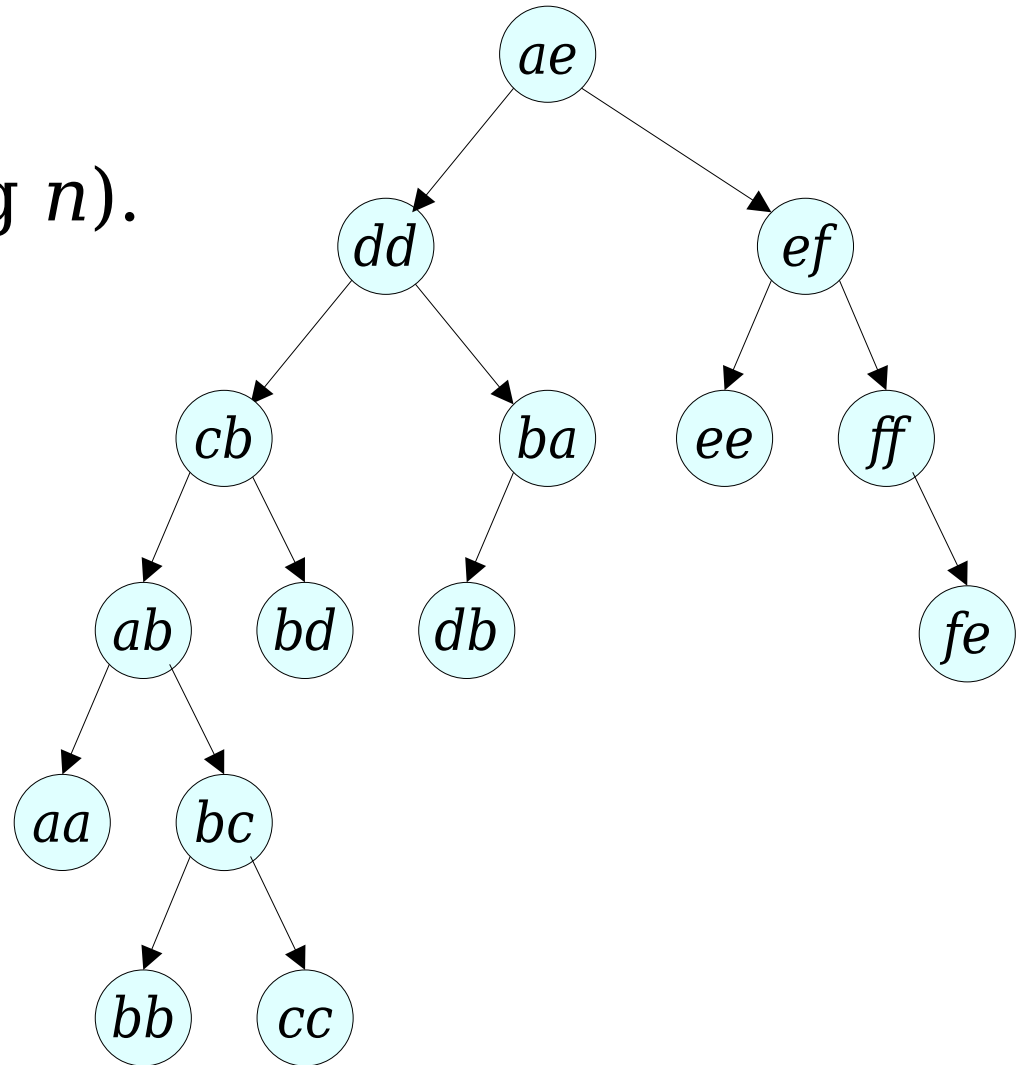
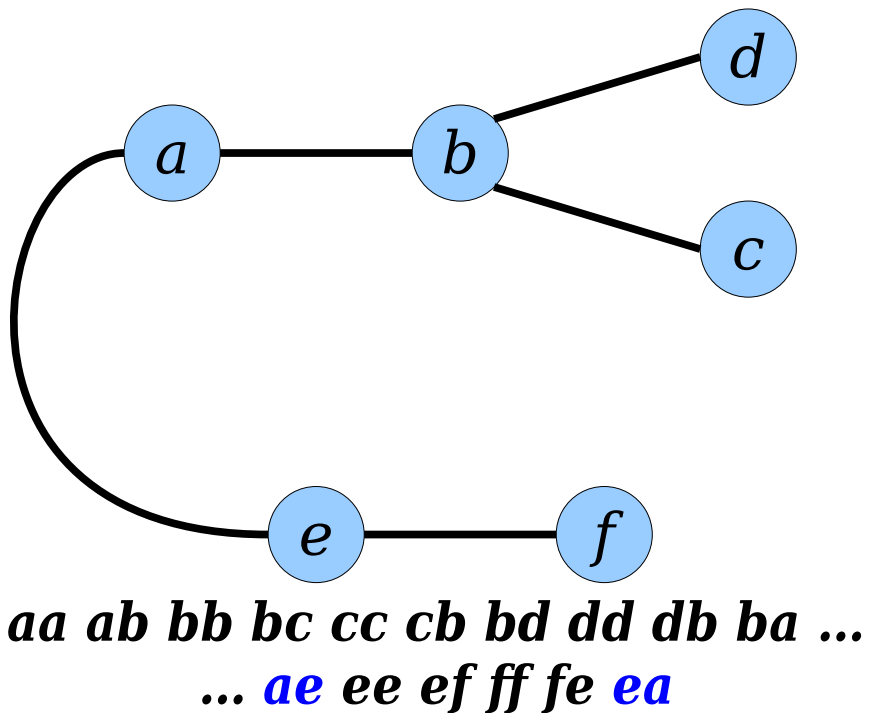
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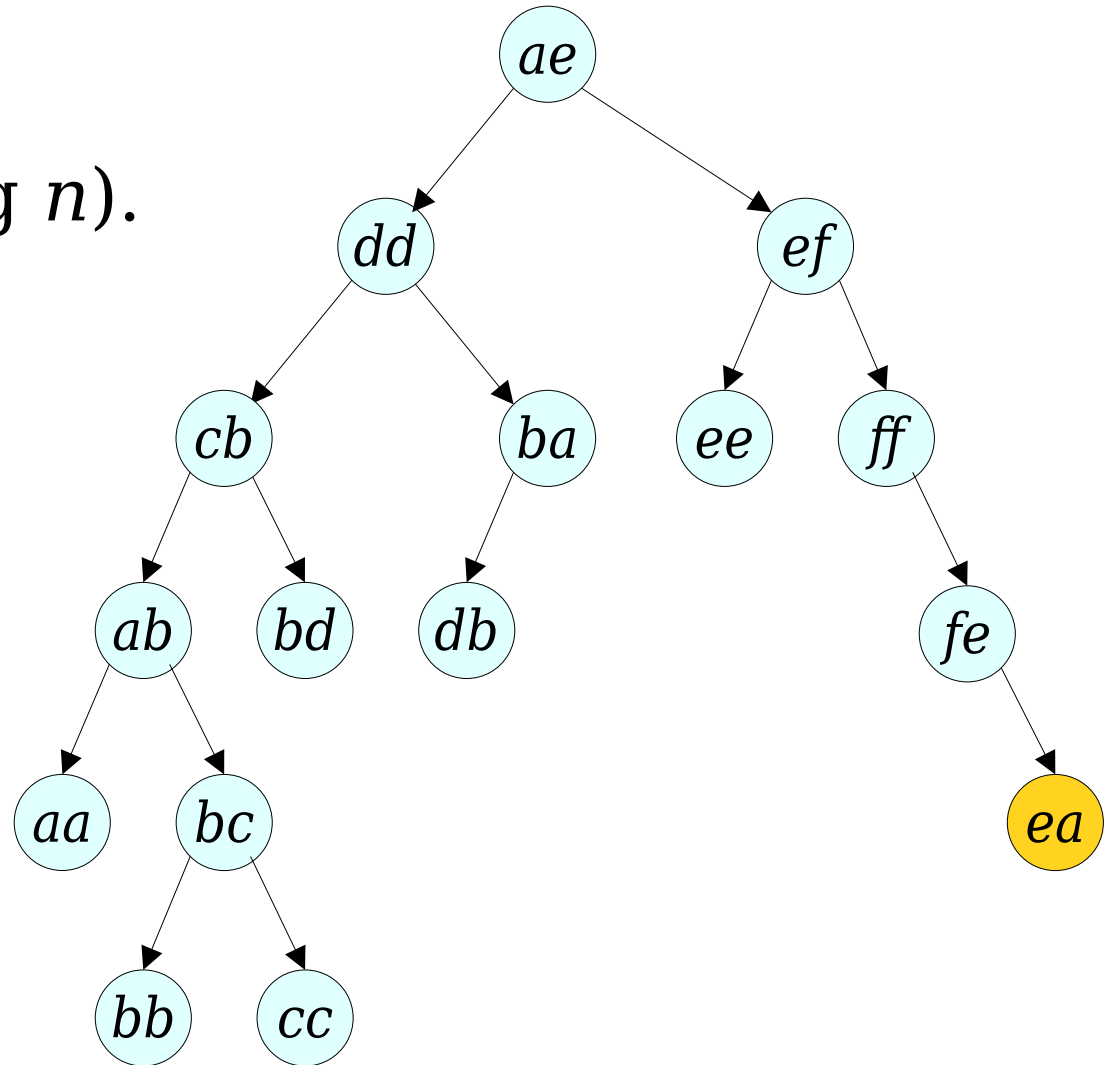
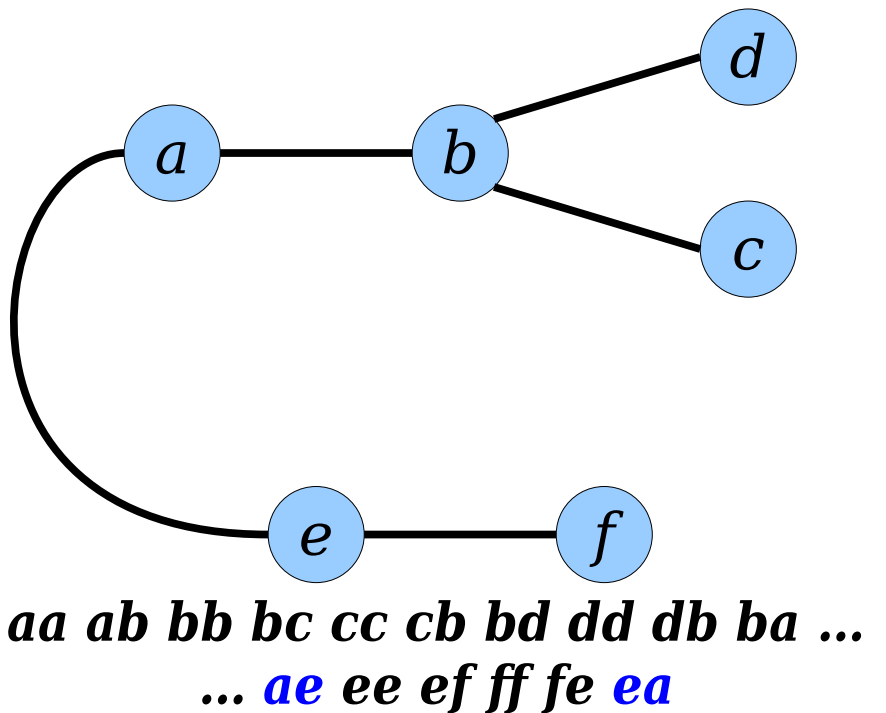
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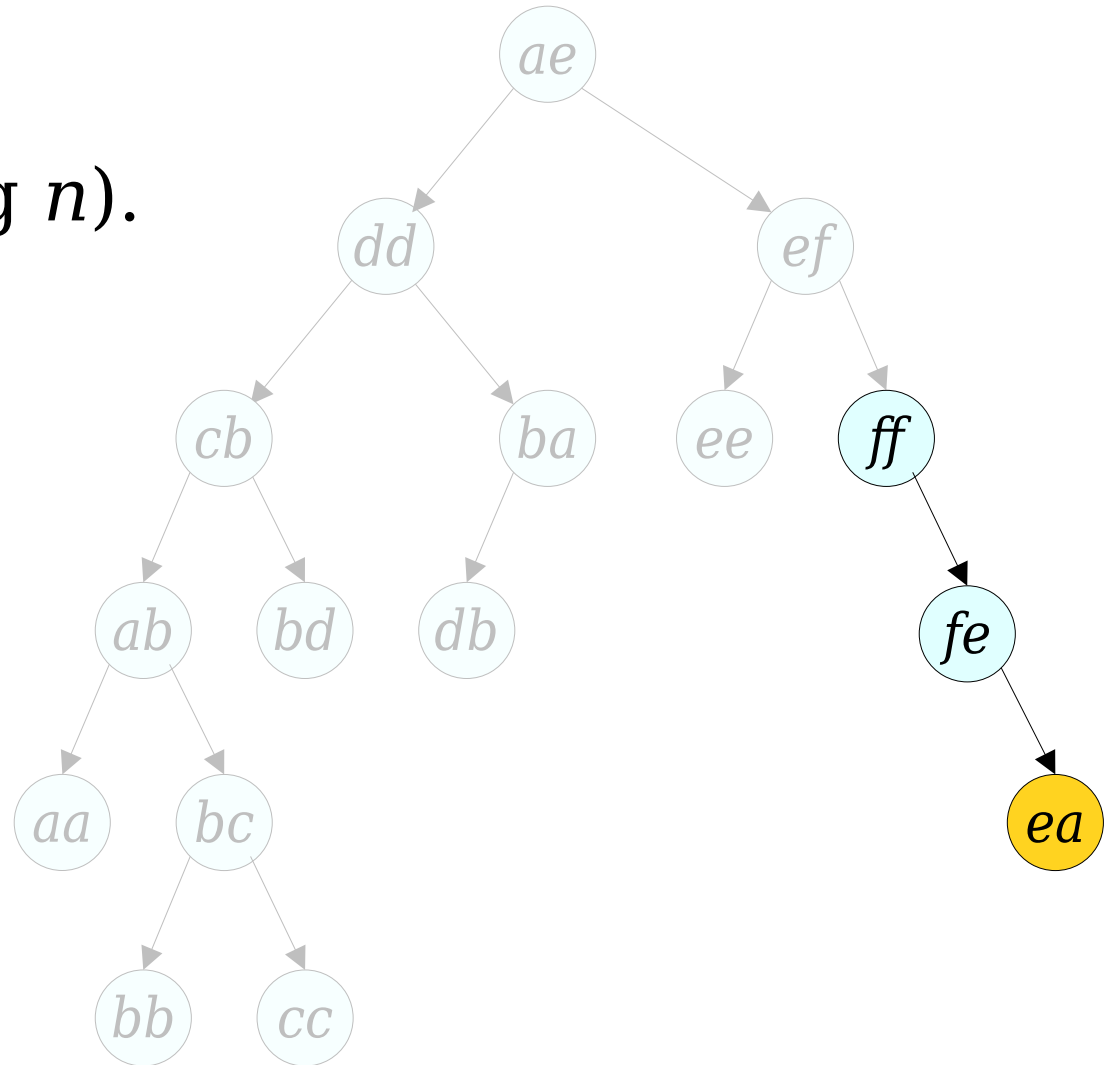
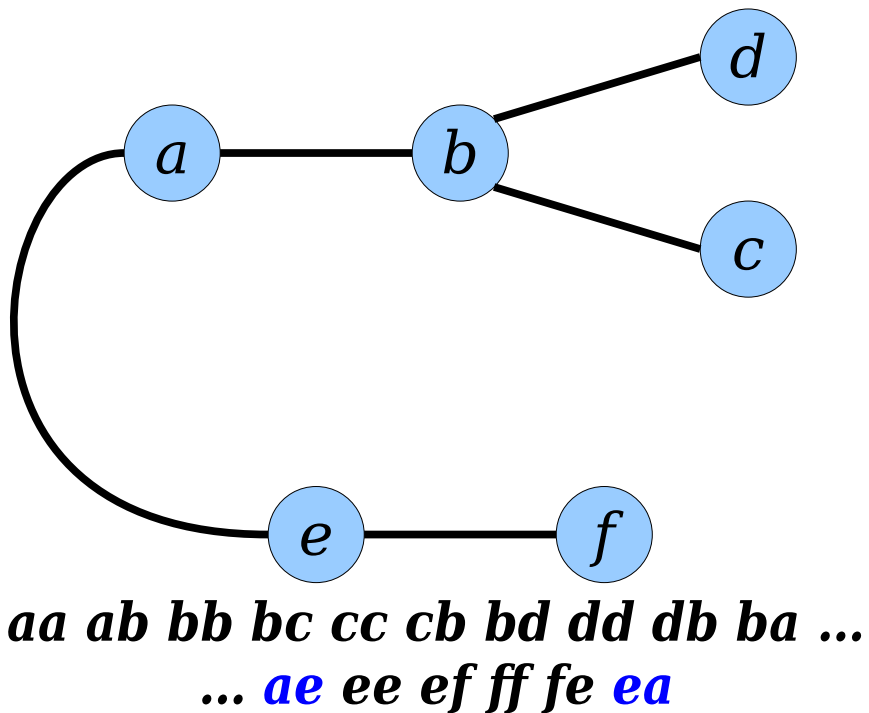
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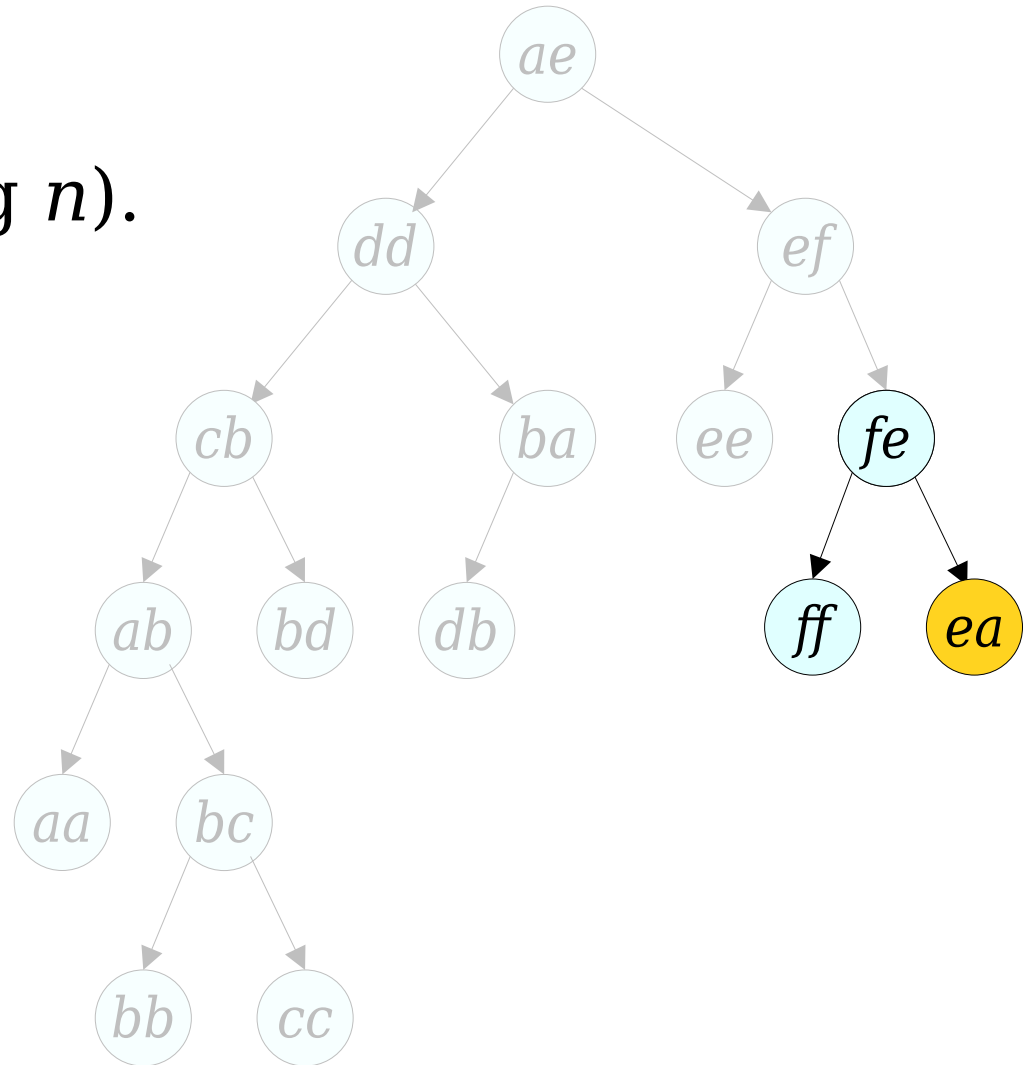
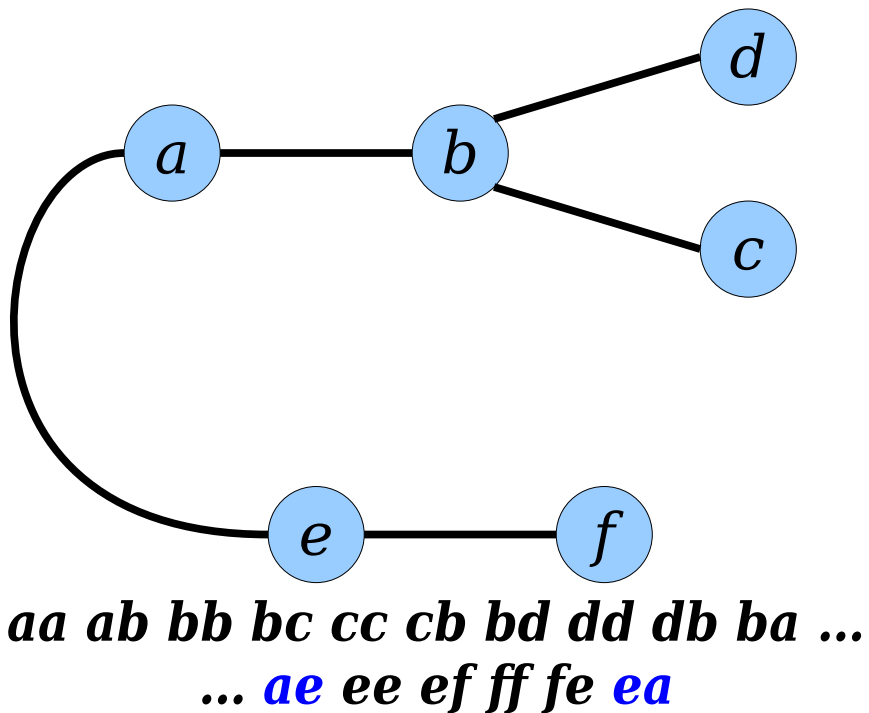
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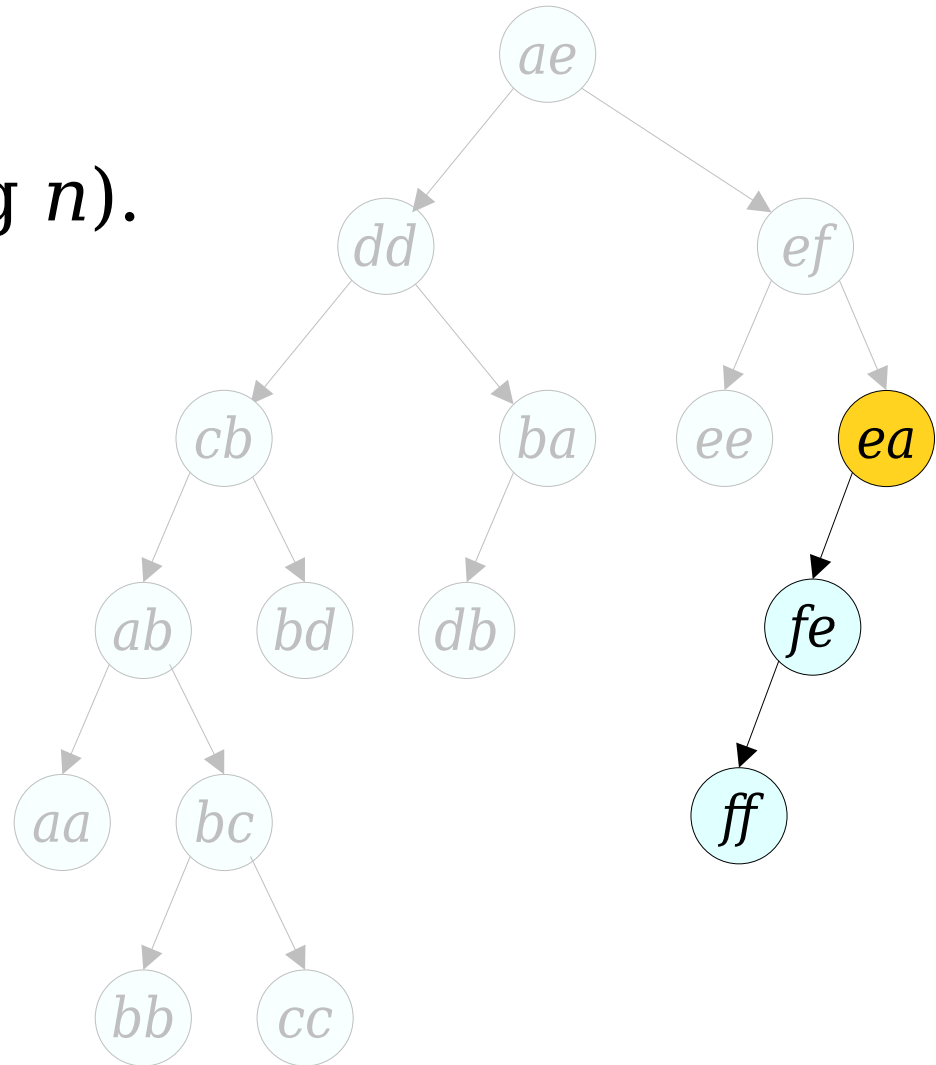
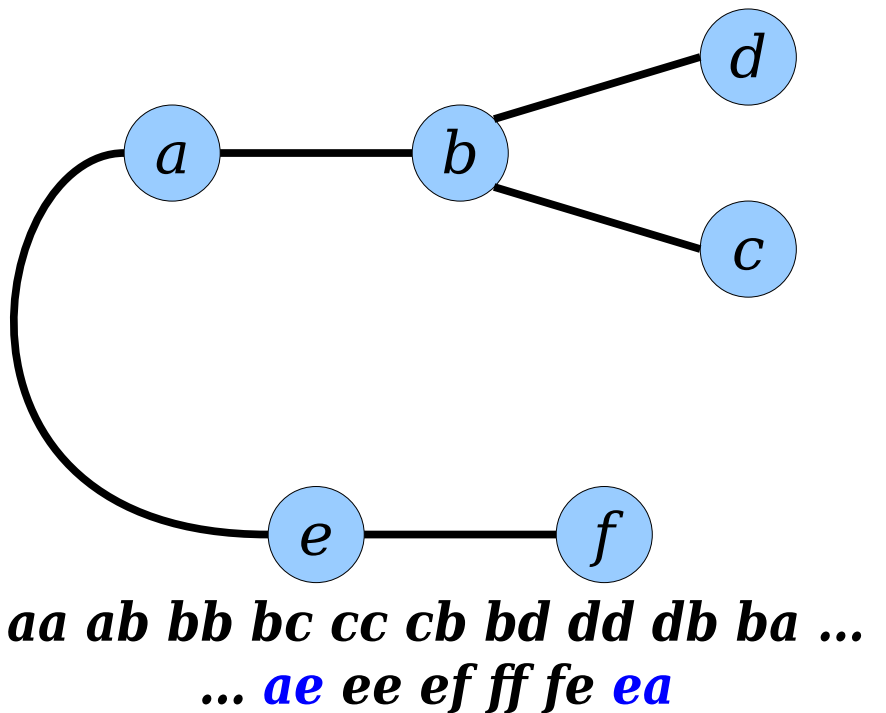
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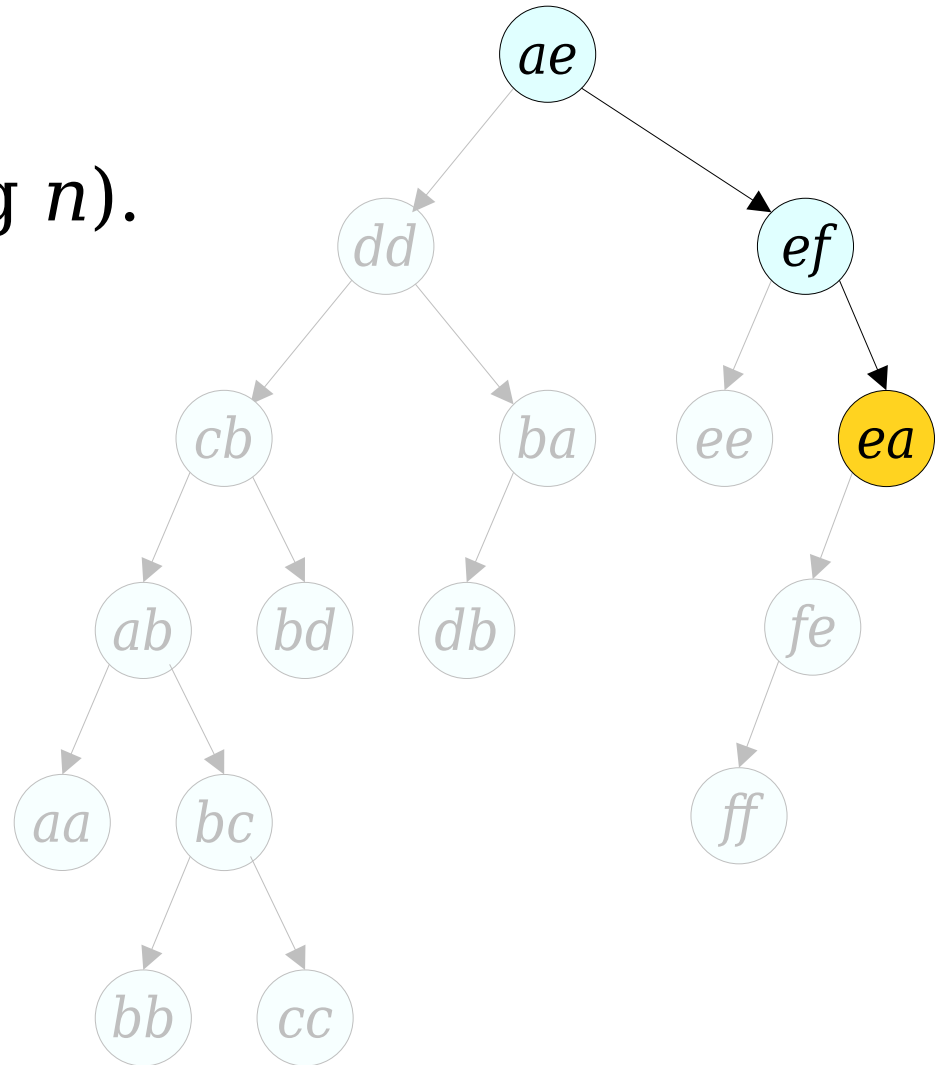
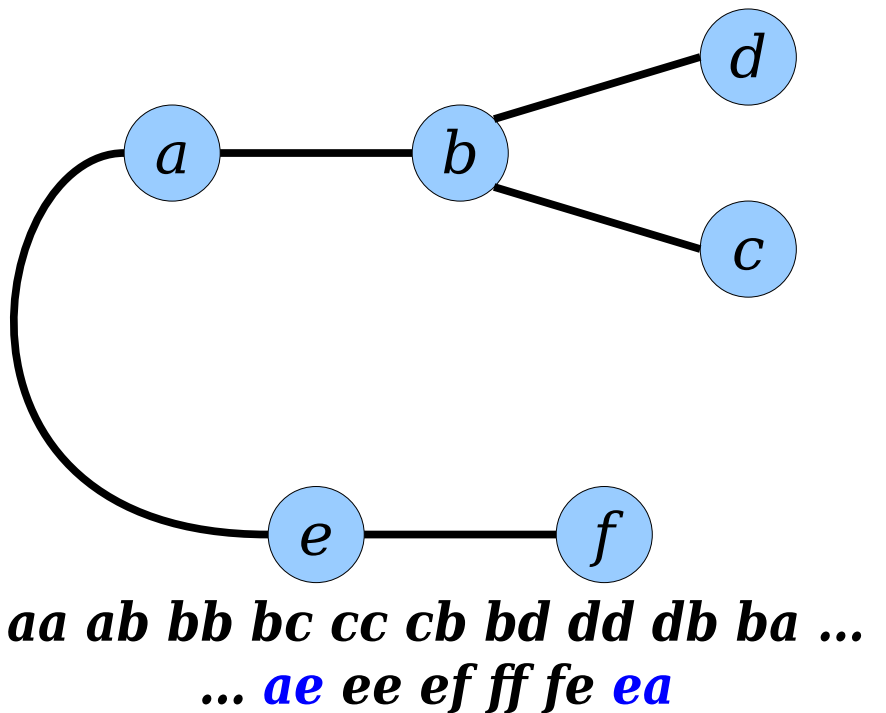
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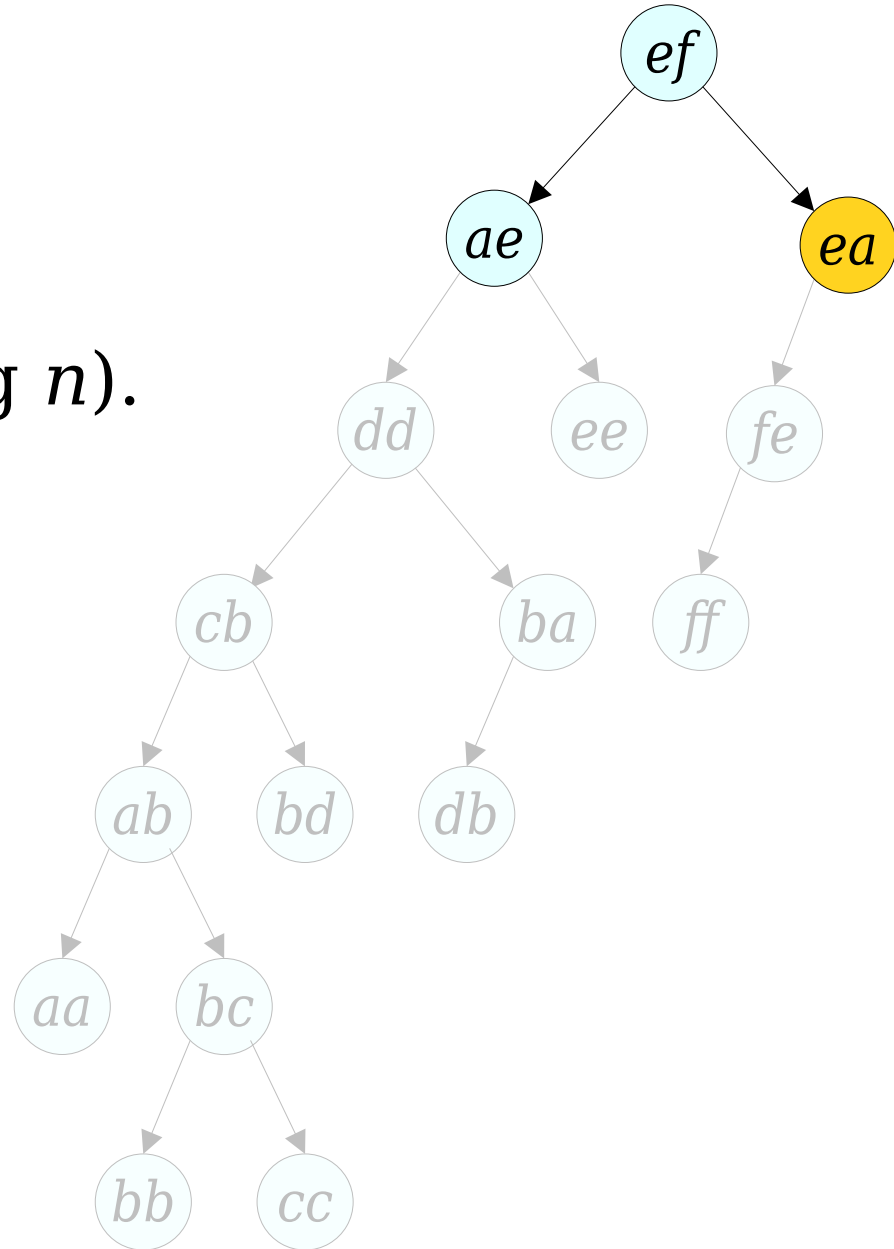
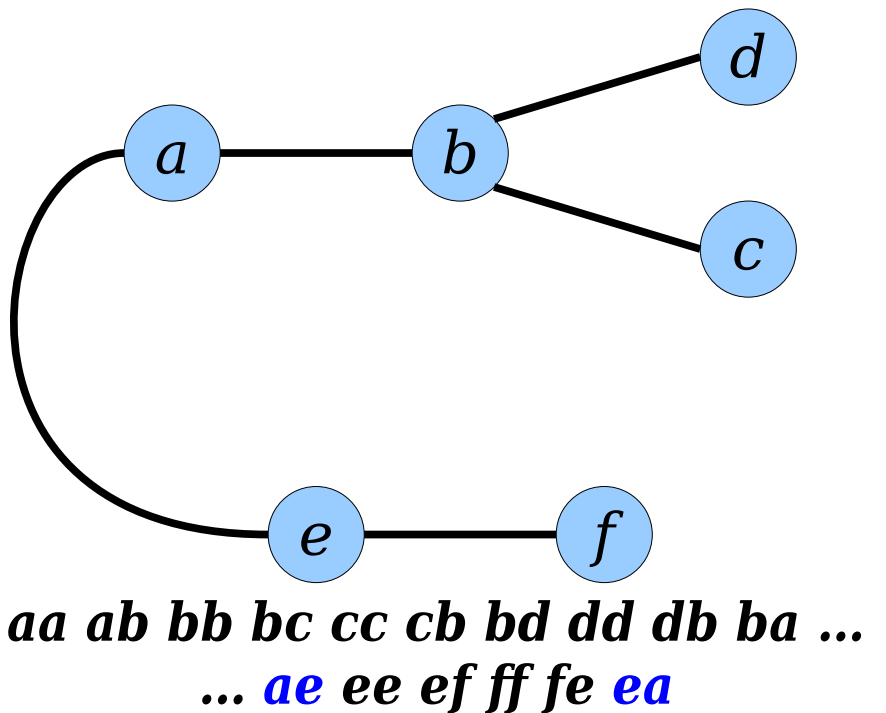
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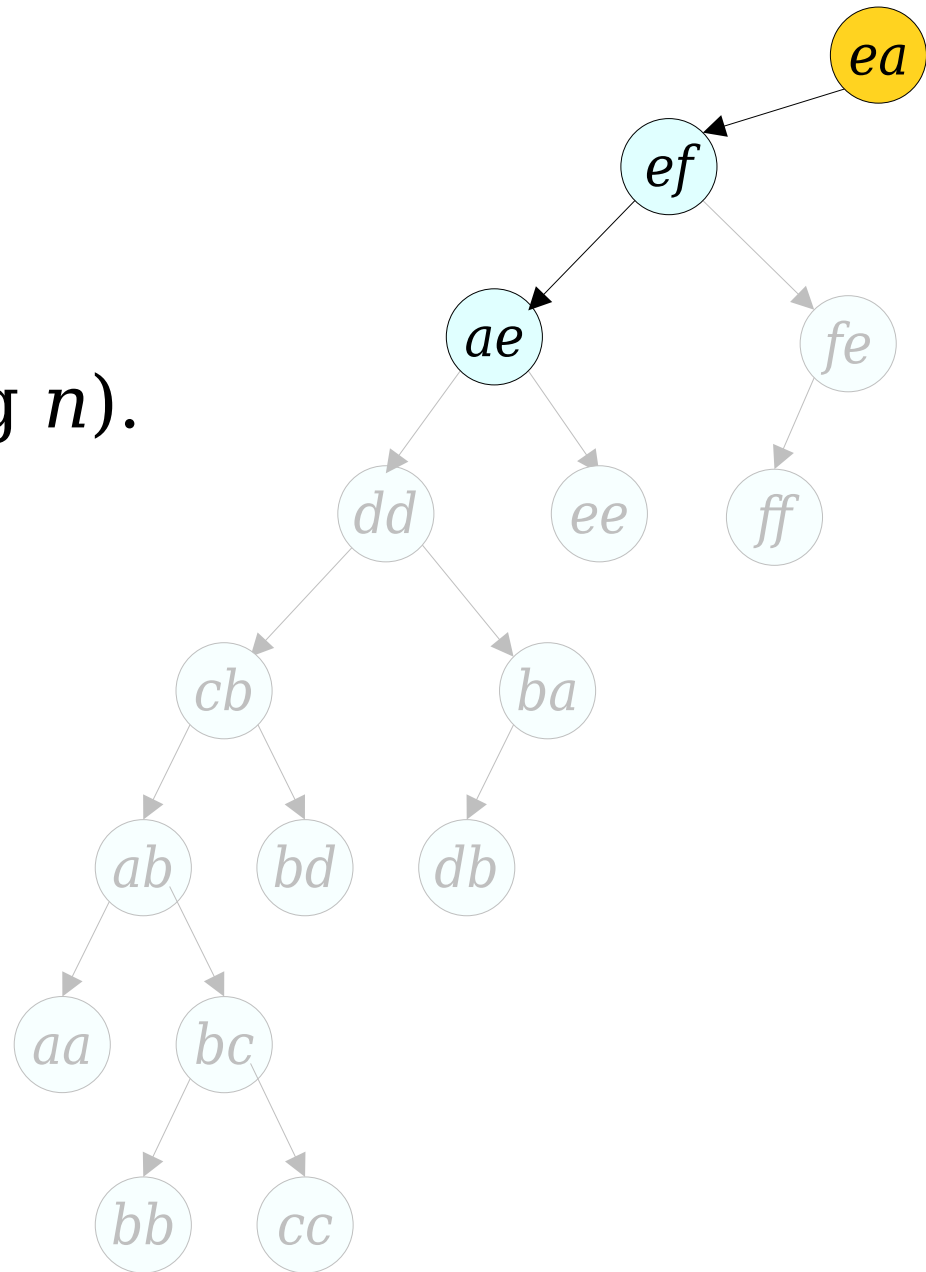
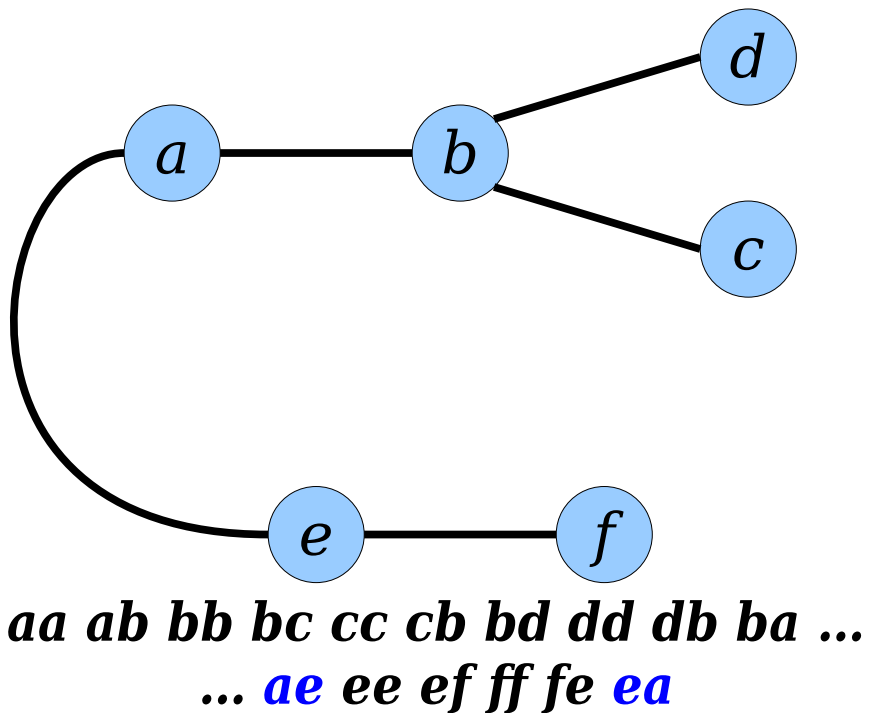
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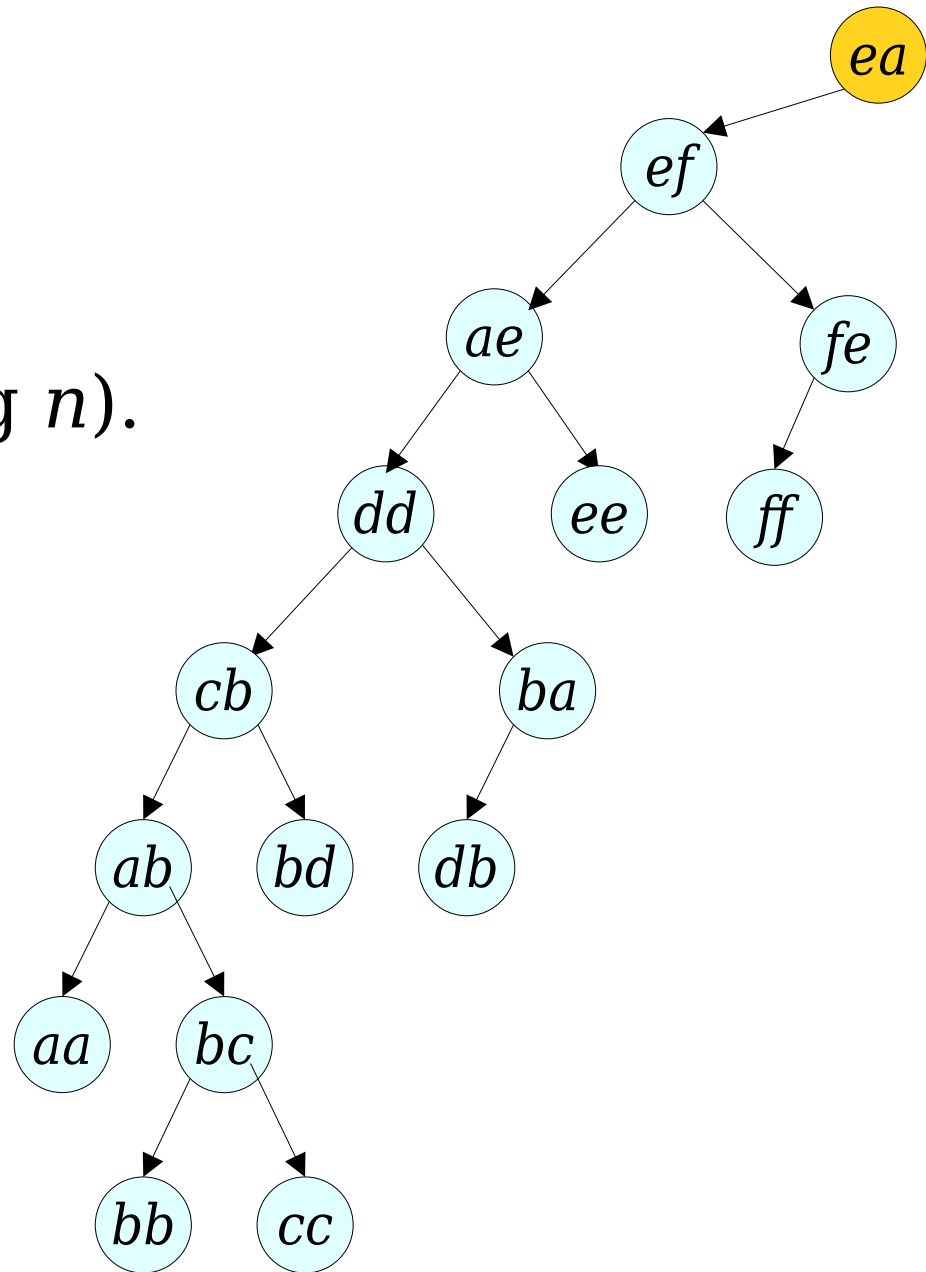
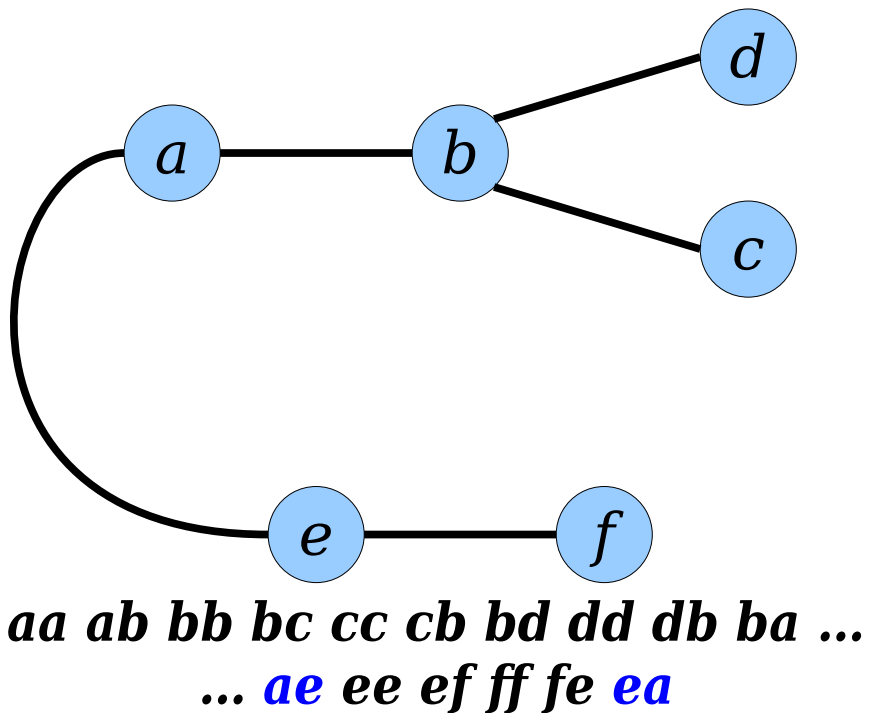
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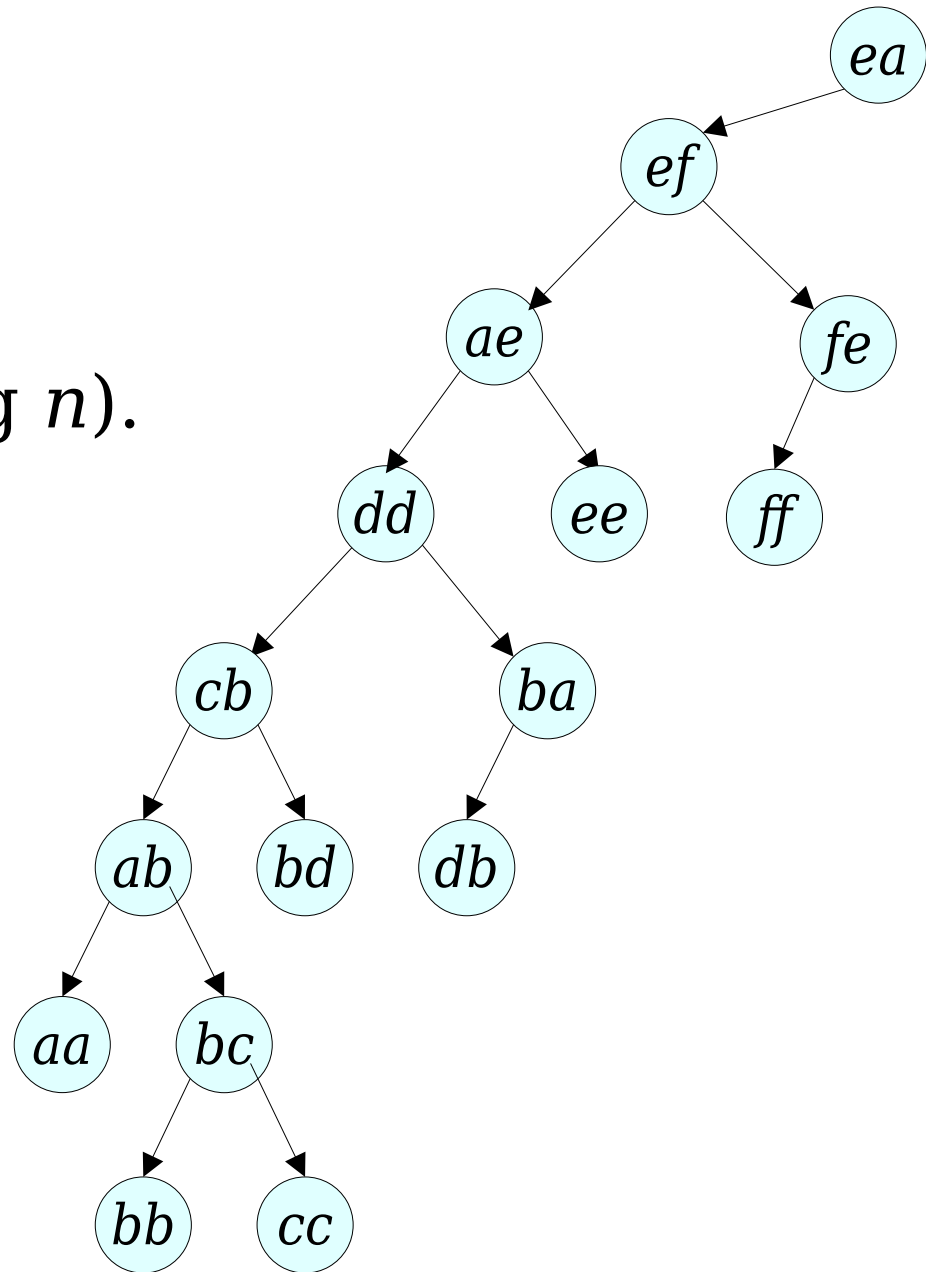
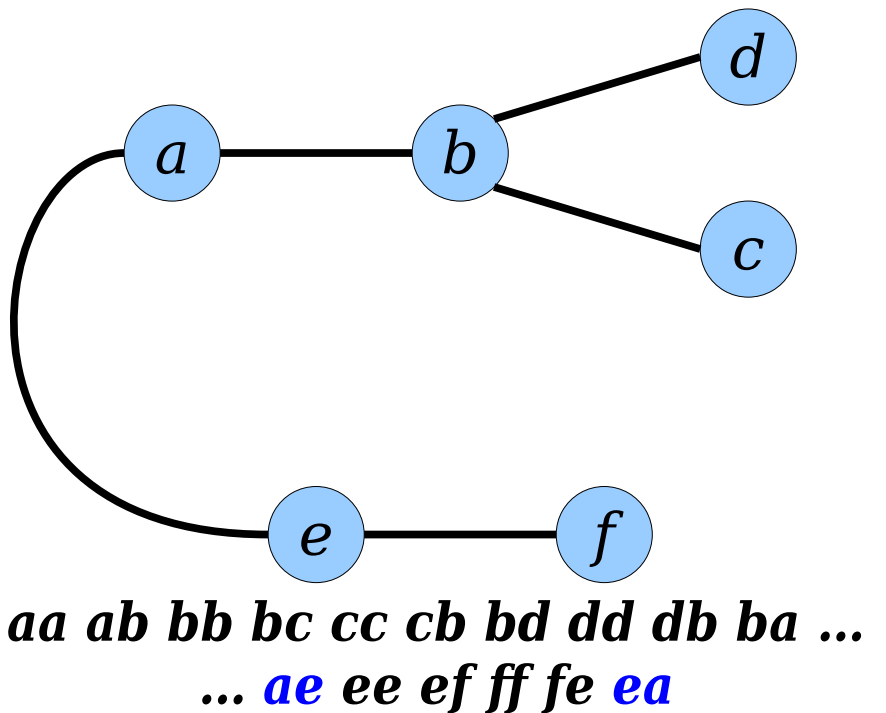
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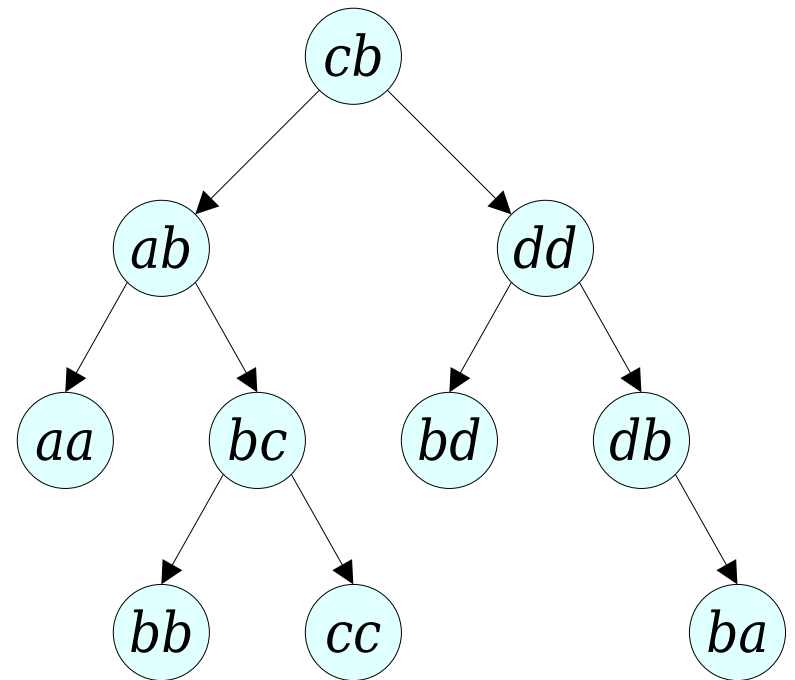
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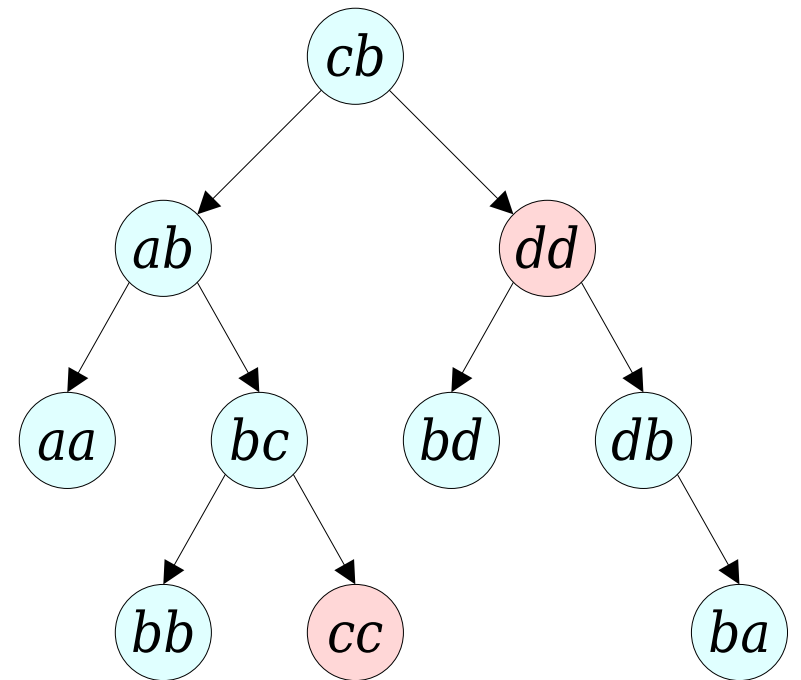
Euler Tour Trees

- To answer *are-connected*(x, y):



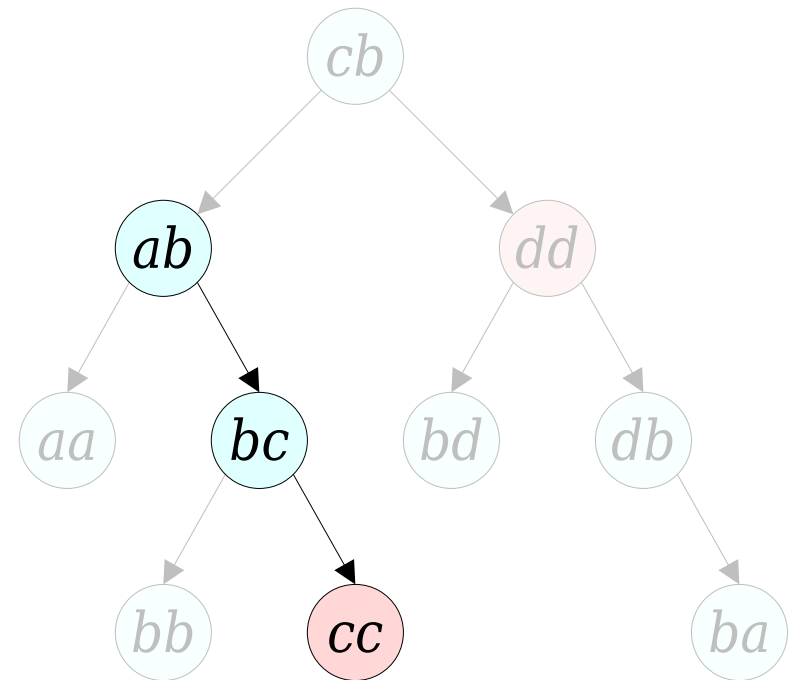
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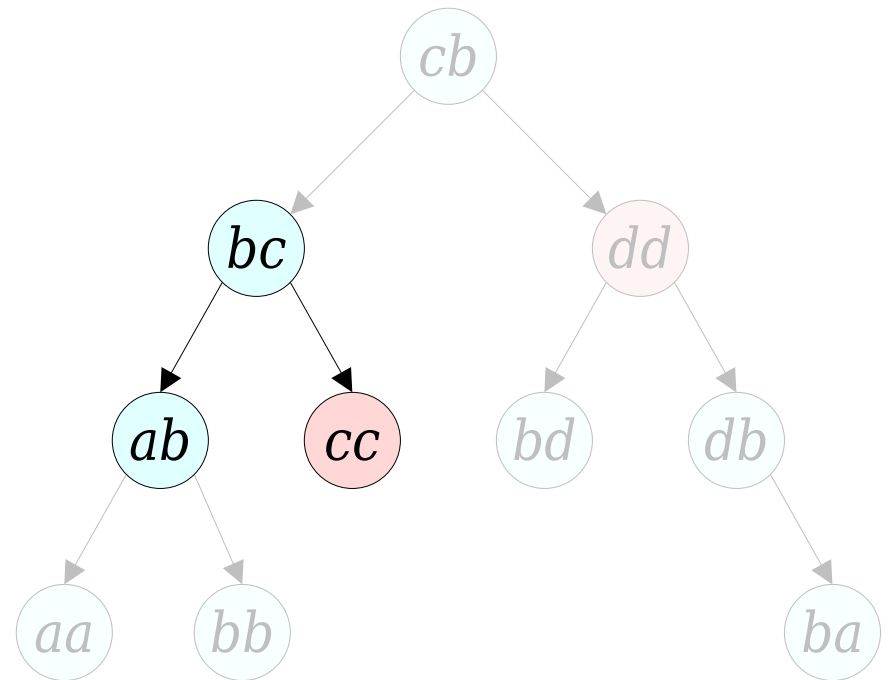
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- To answer *are-connected*(x, y):
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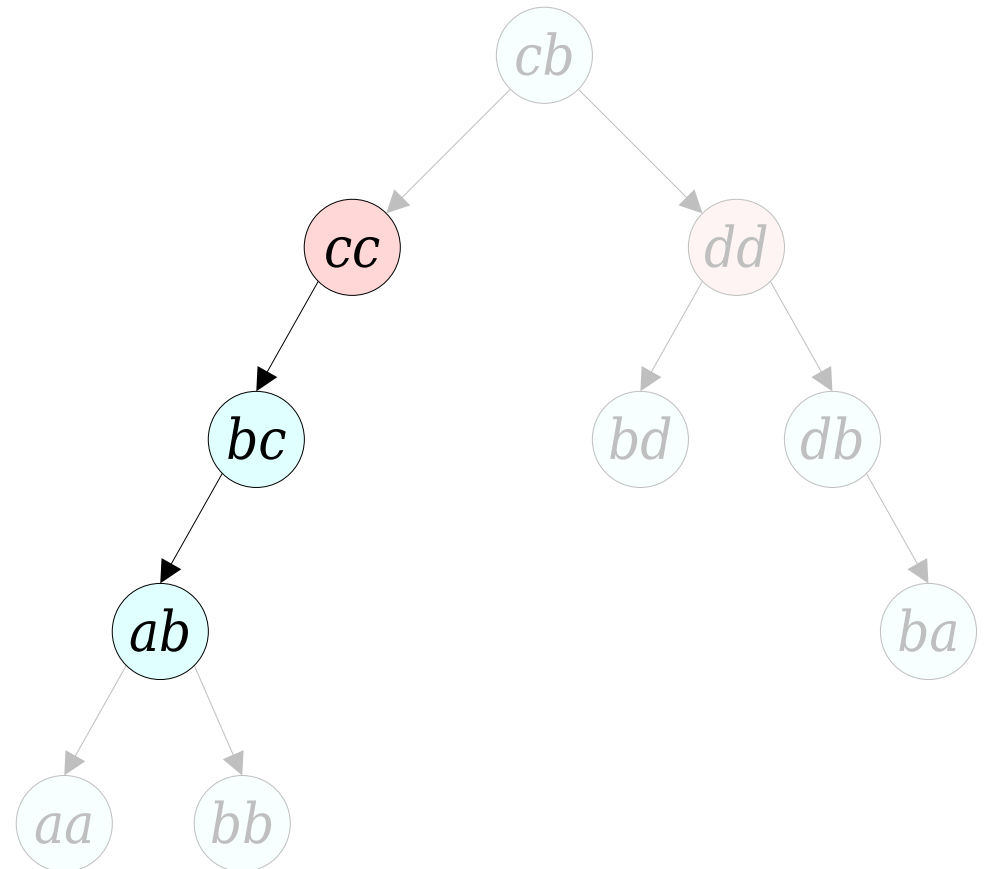
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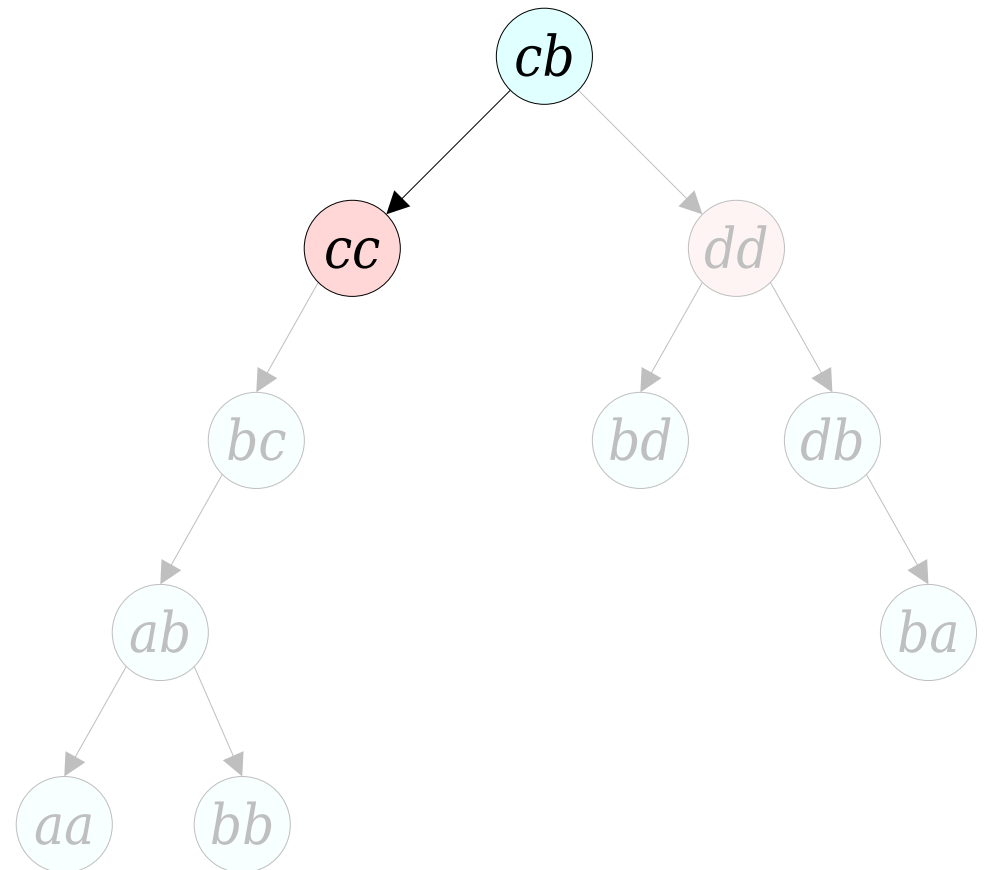
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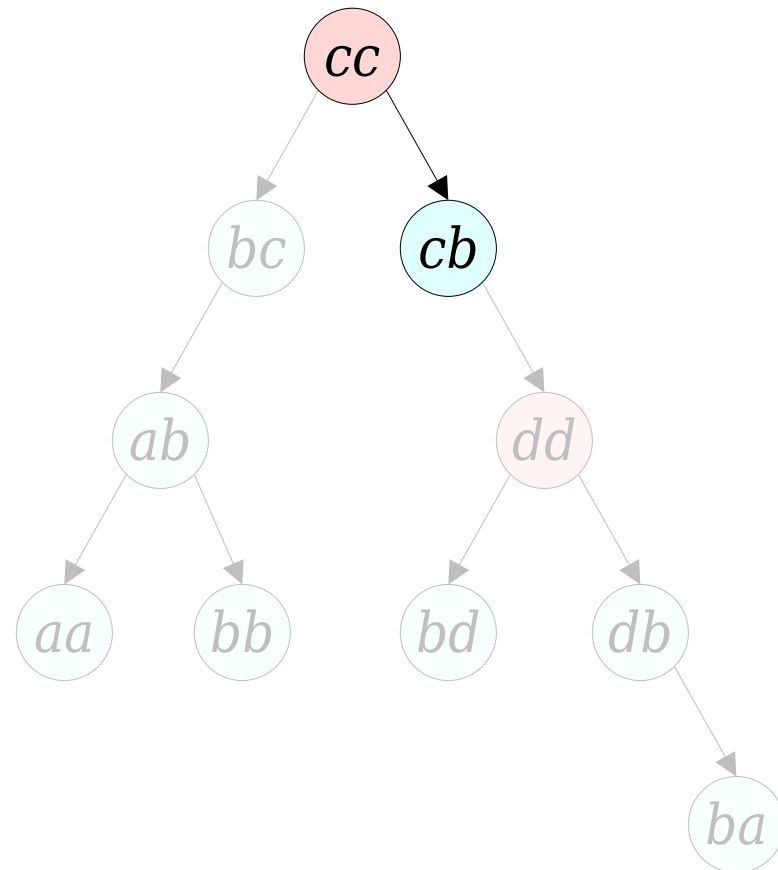
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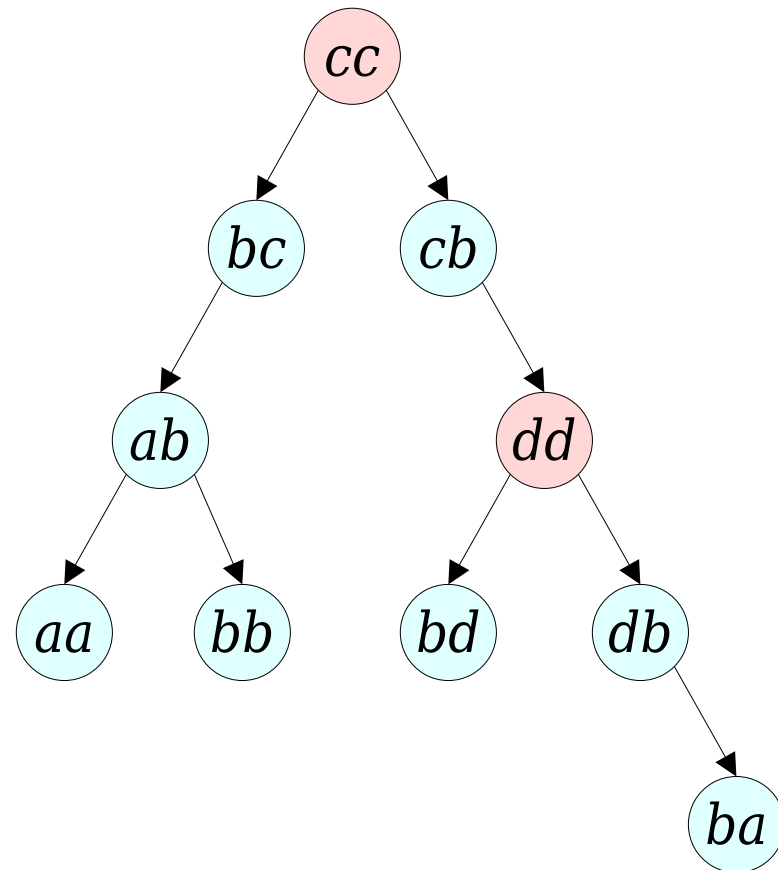
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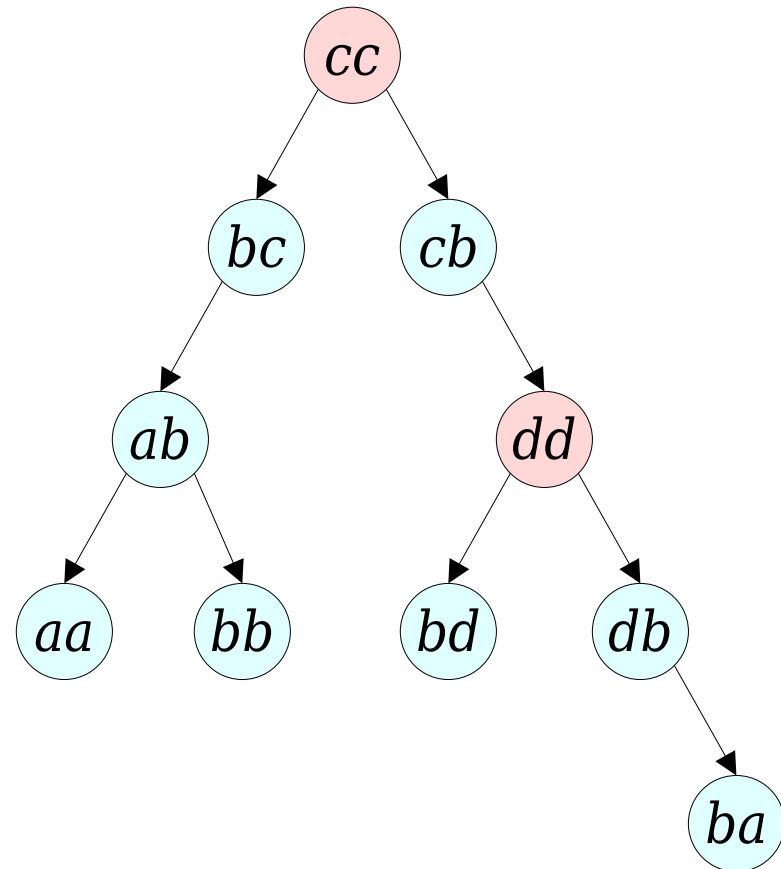
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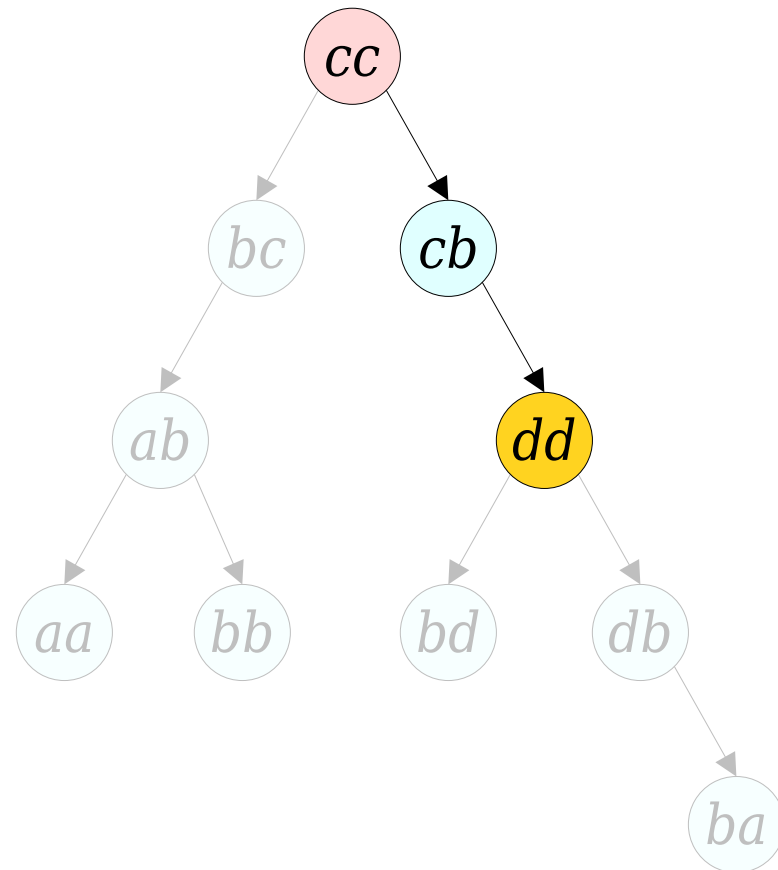
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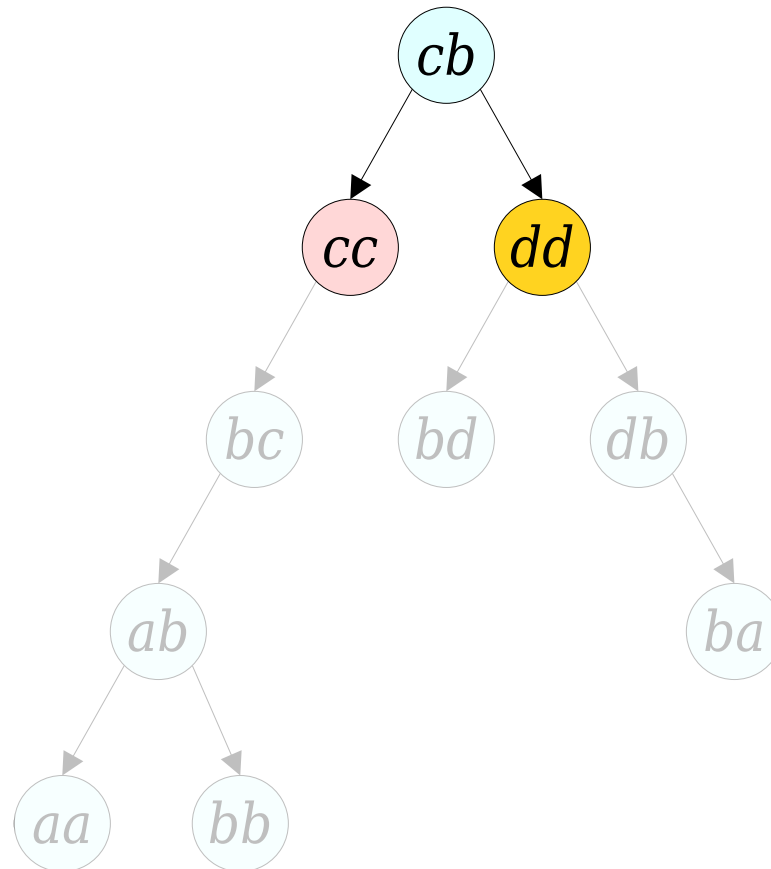
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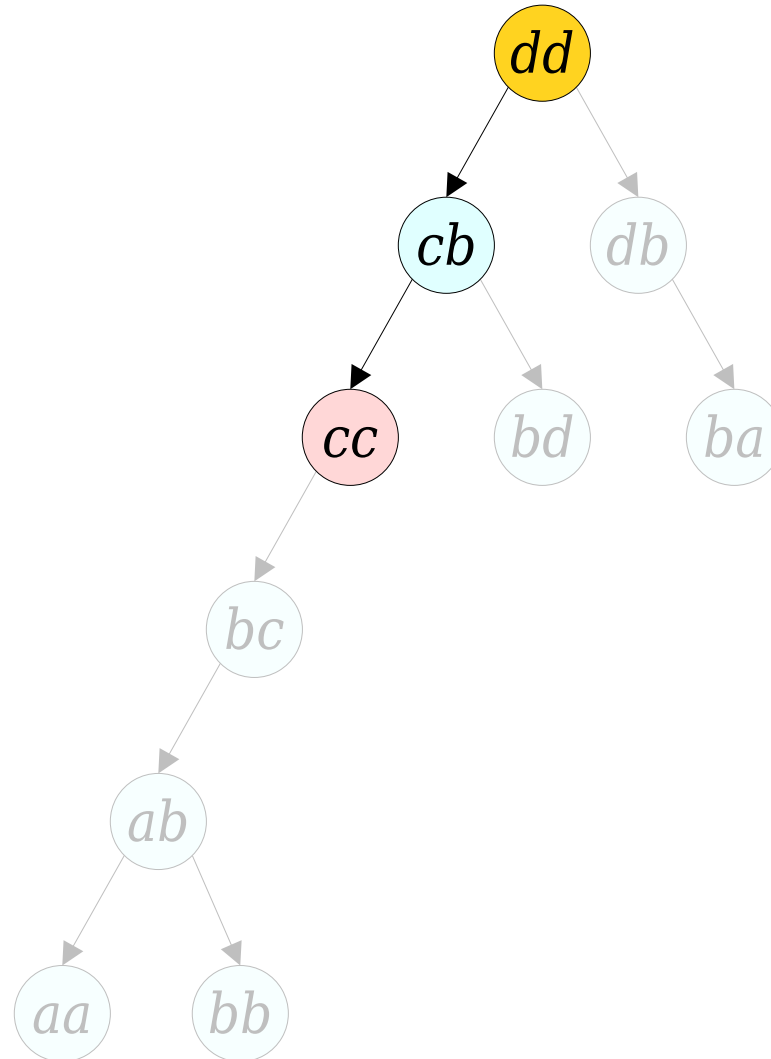
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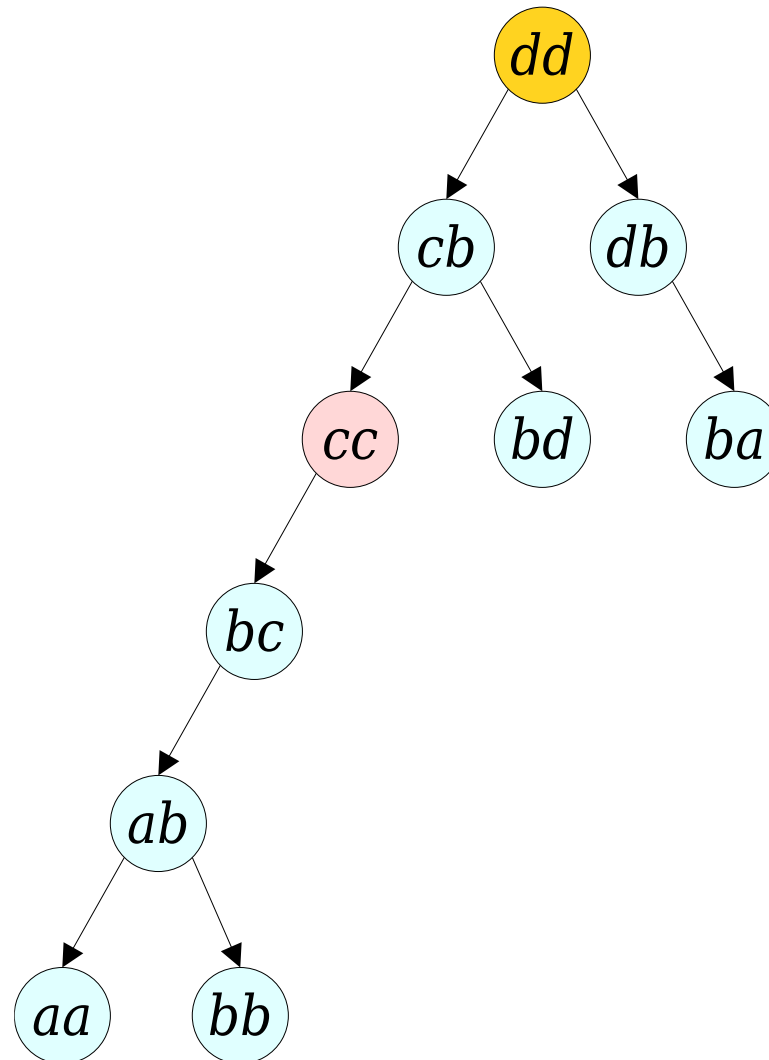
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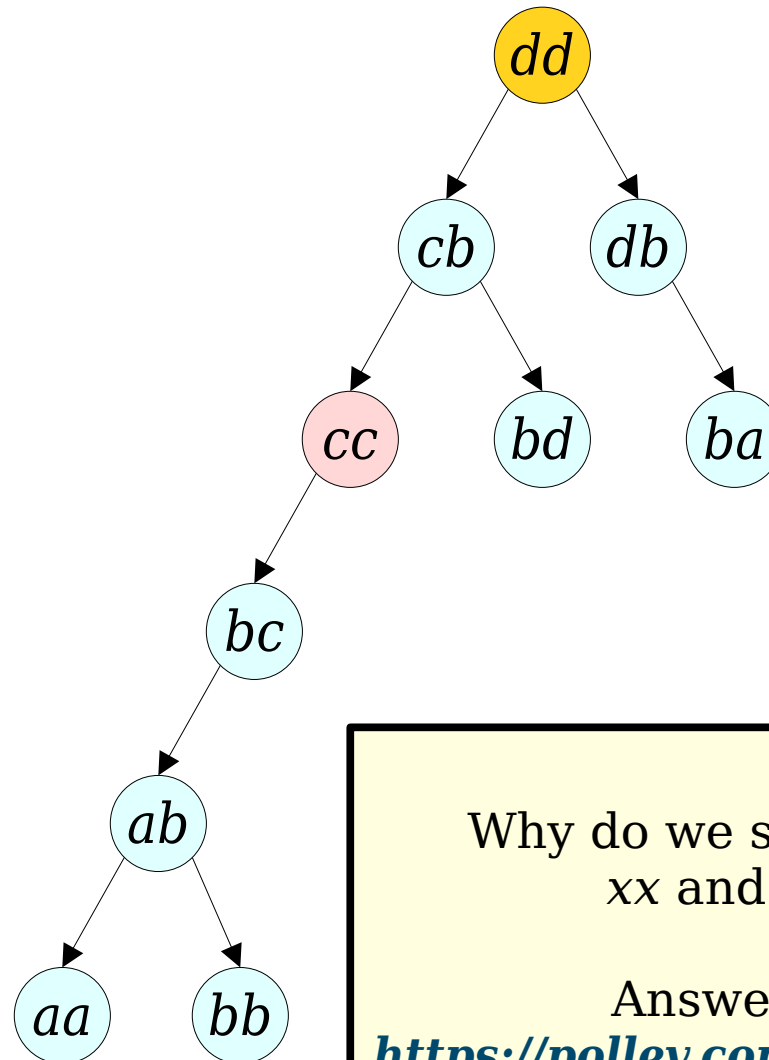
Euler Tour Trees

- To answer *are-connected*(x, y):
 - Splay xx .
 - Splay yy .



Euler Tour Trees

- To answer *are-connected*(x, y):
 - Splay xx .
 - Splay yy .
 - Return whether xx was encountered on the second splay.
- Amortized cost: **$O(\log n)$** .



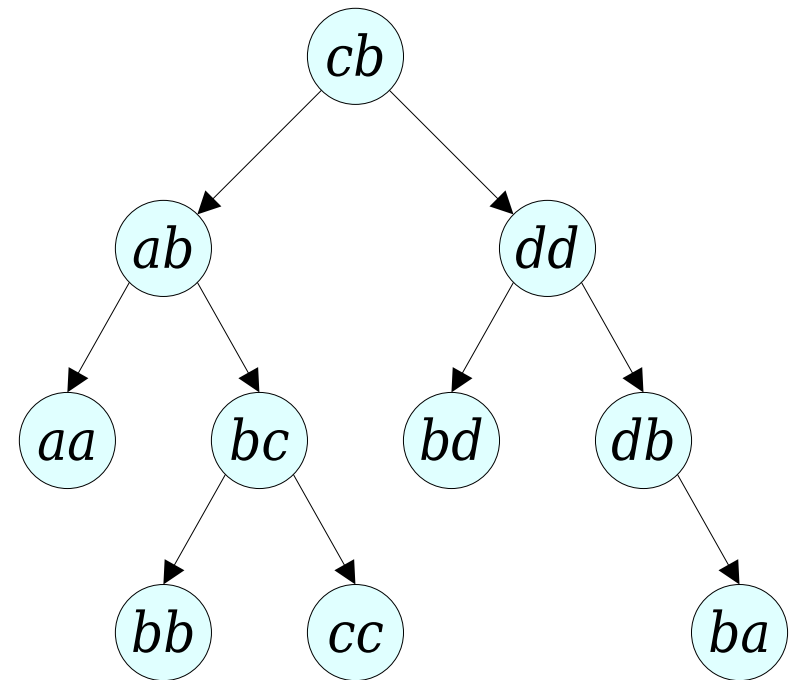
Why do we splay both
 xx and yy ?

Answer at

<https://pollev.com/cs166spr23>

Euler Tour Trees

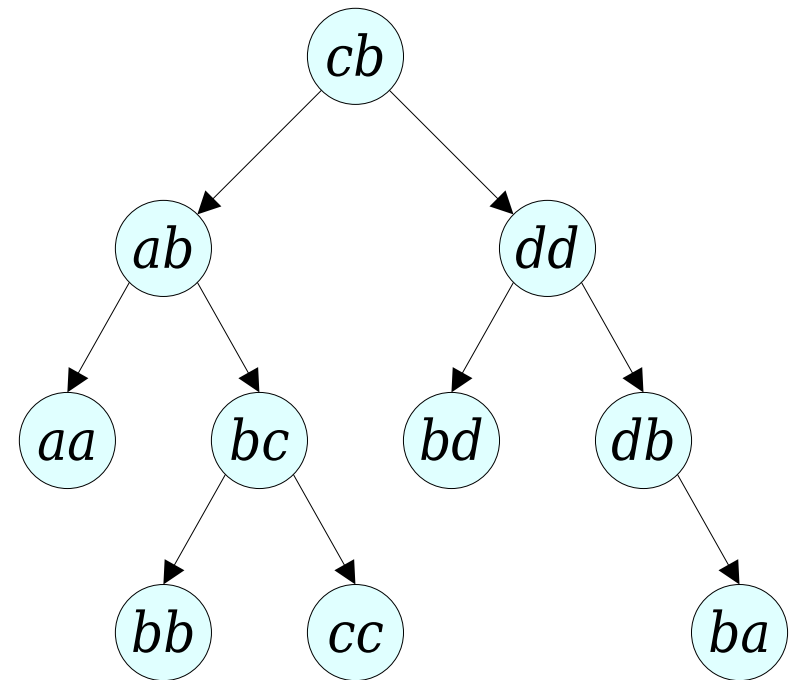
- To *reroot*(x):



aa ab bb bc cc cb bd dd db ba

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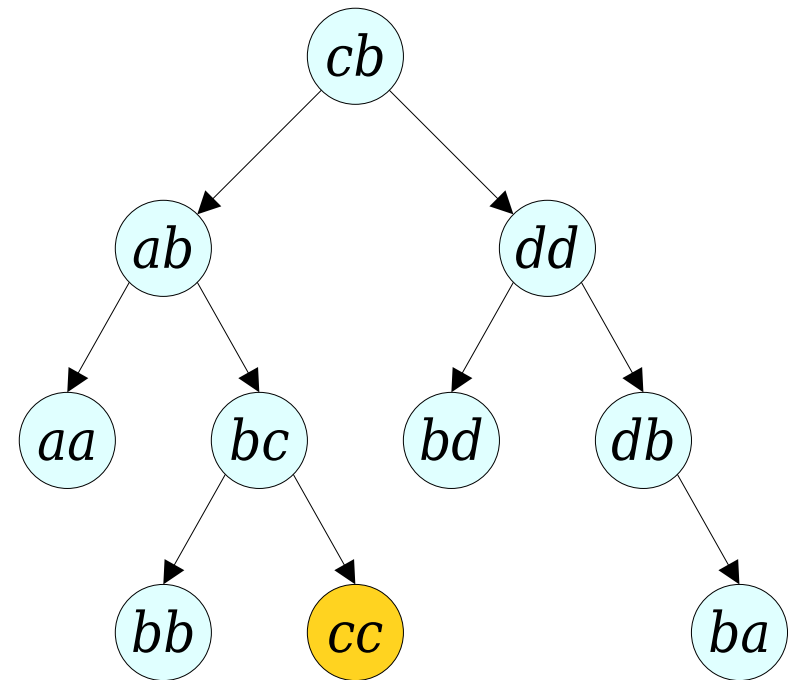
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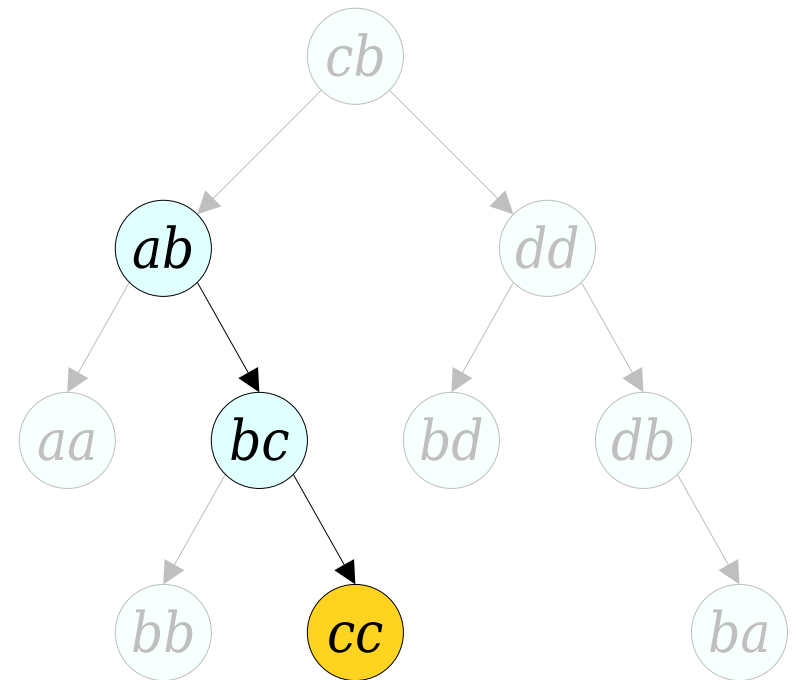
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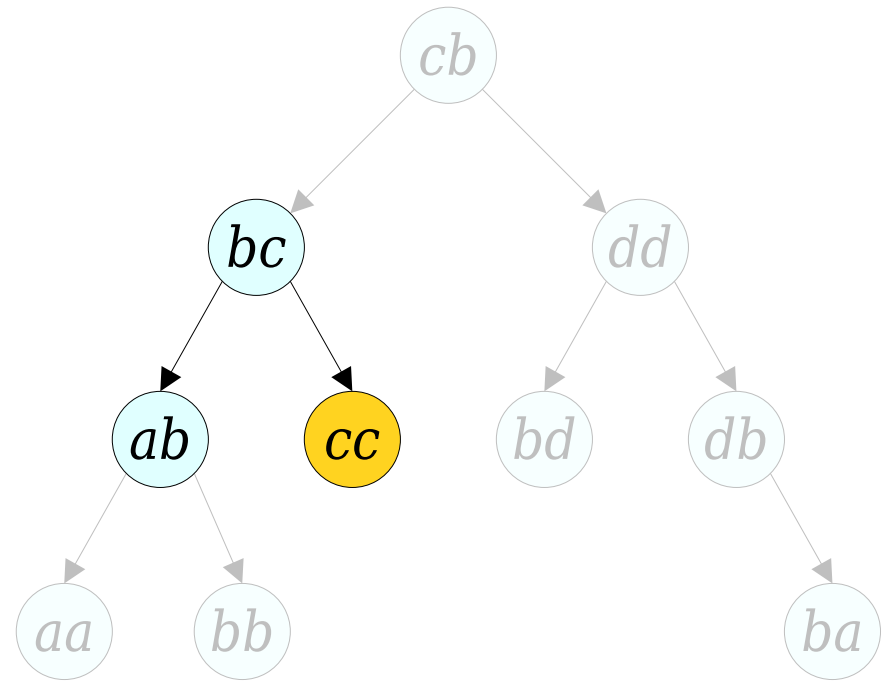
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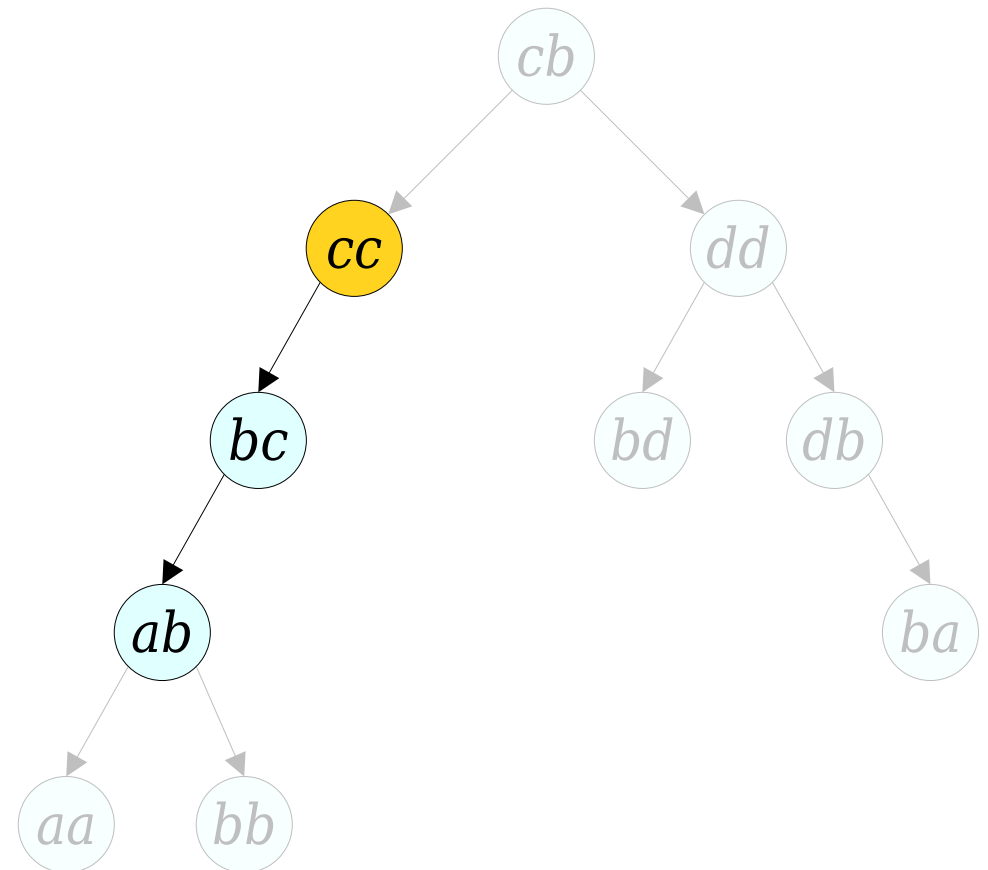
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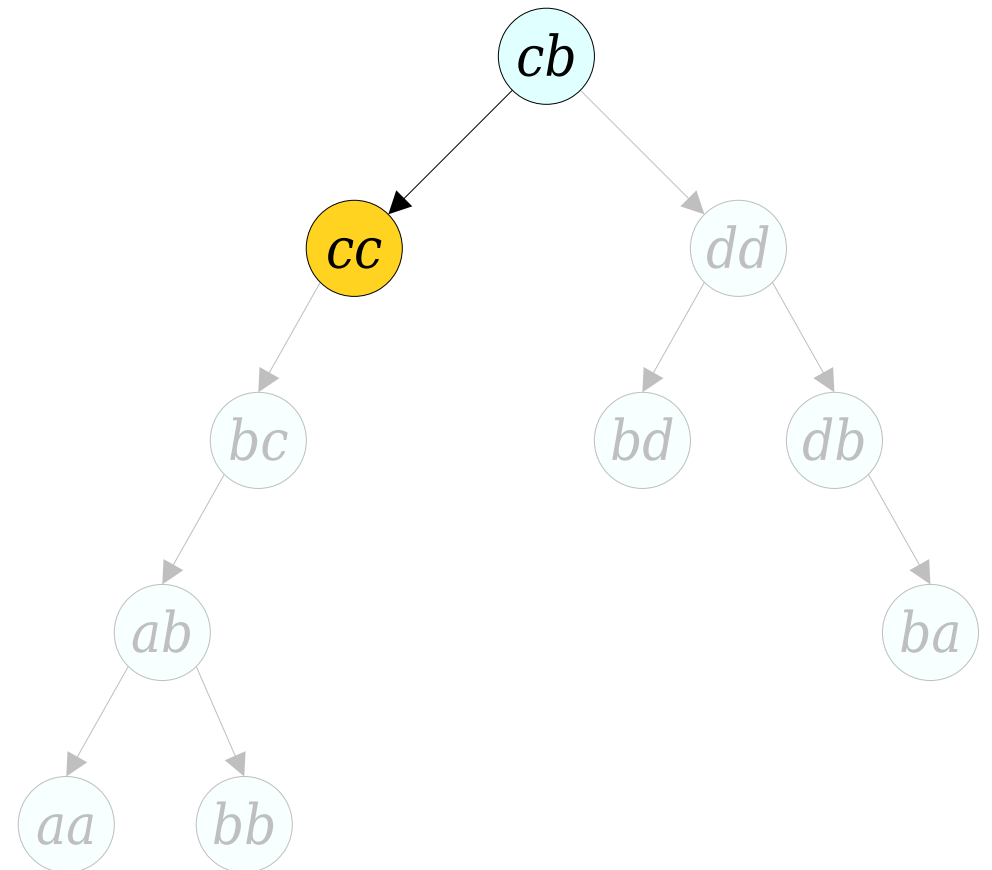
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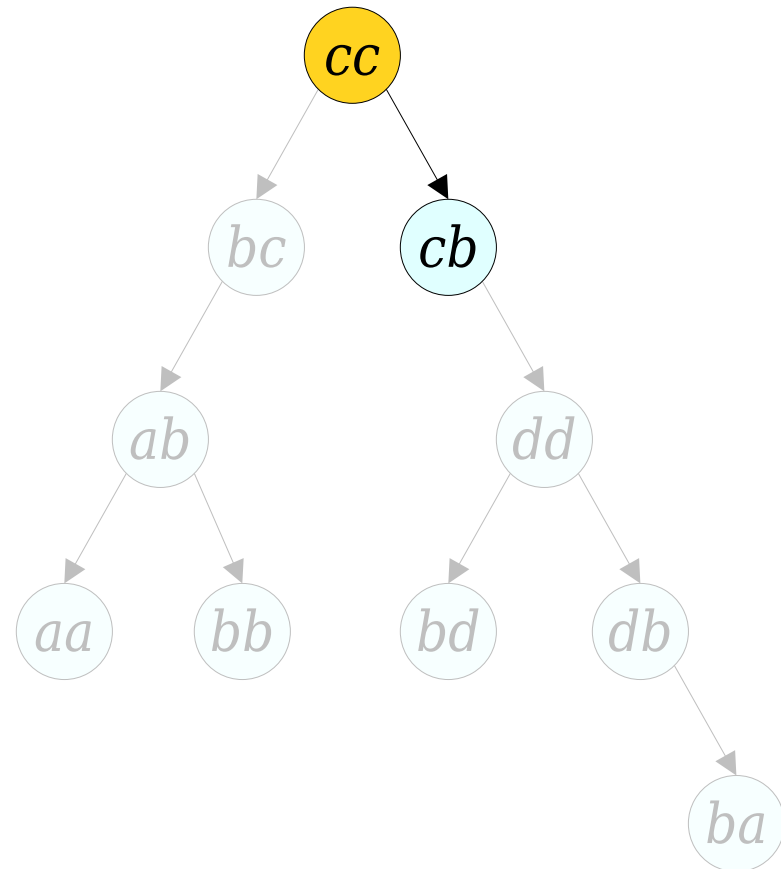
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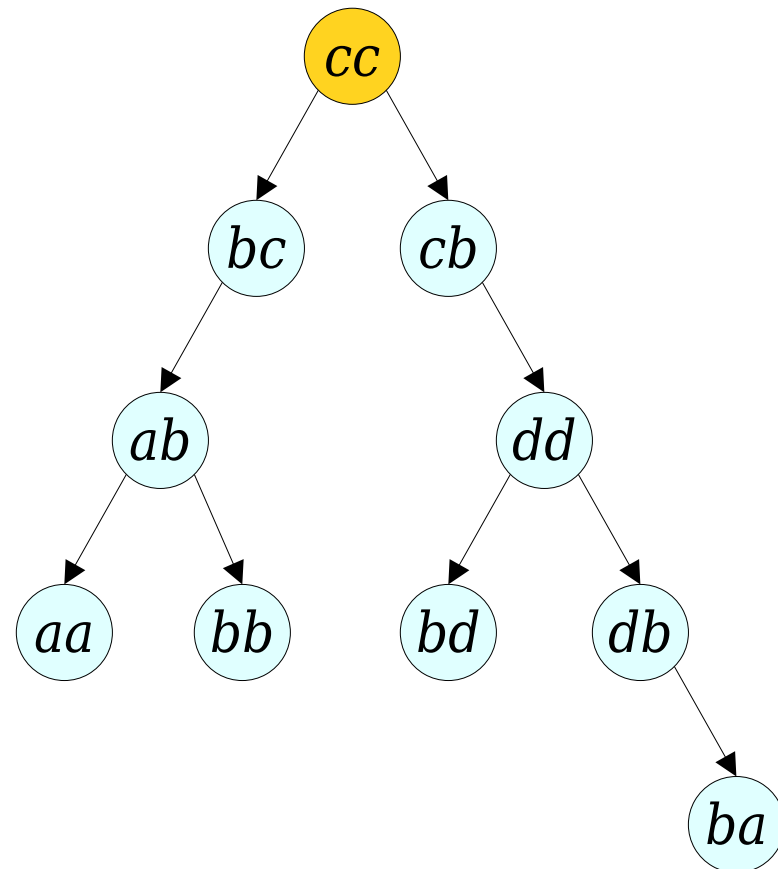
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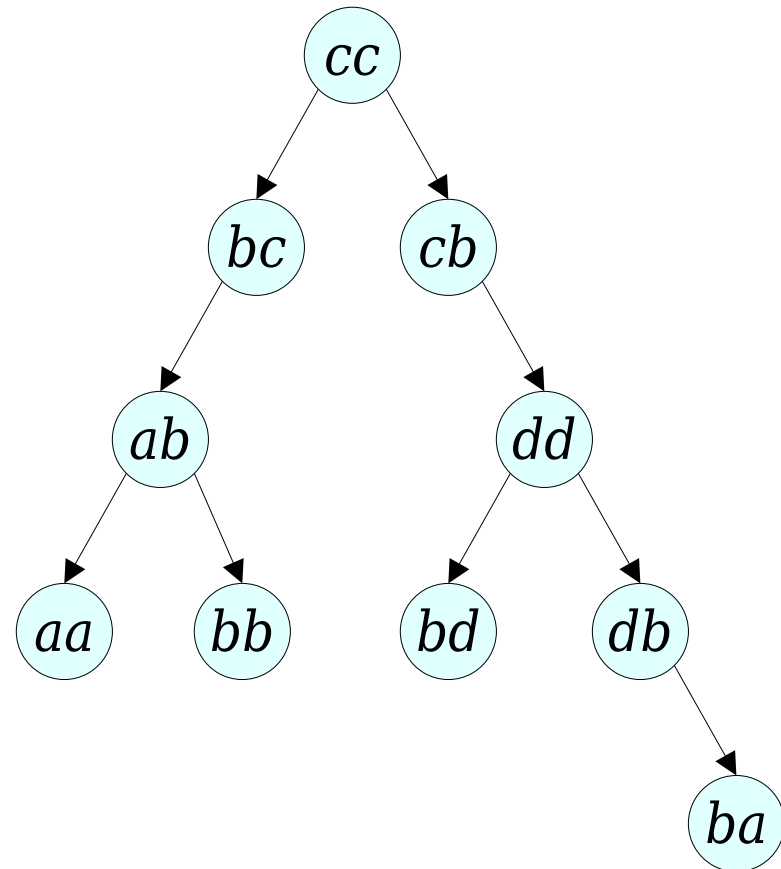
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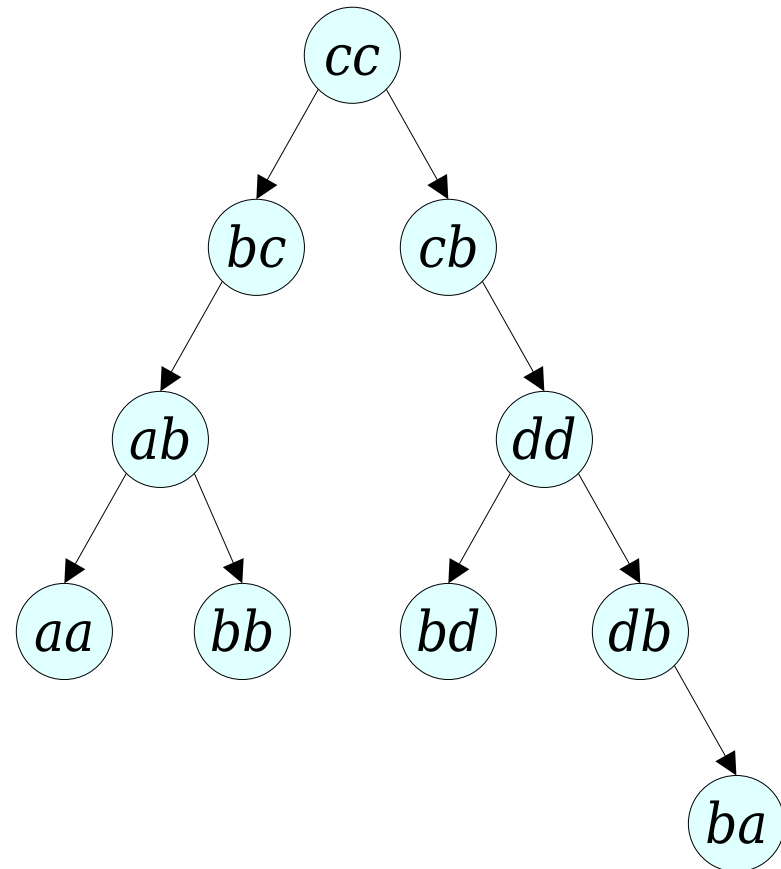
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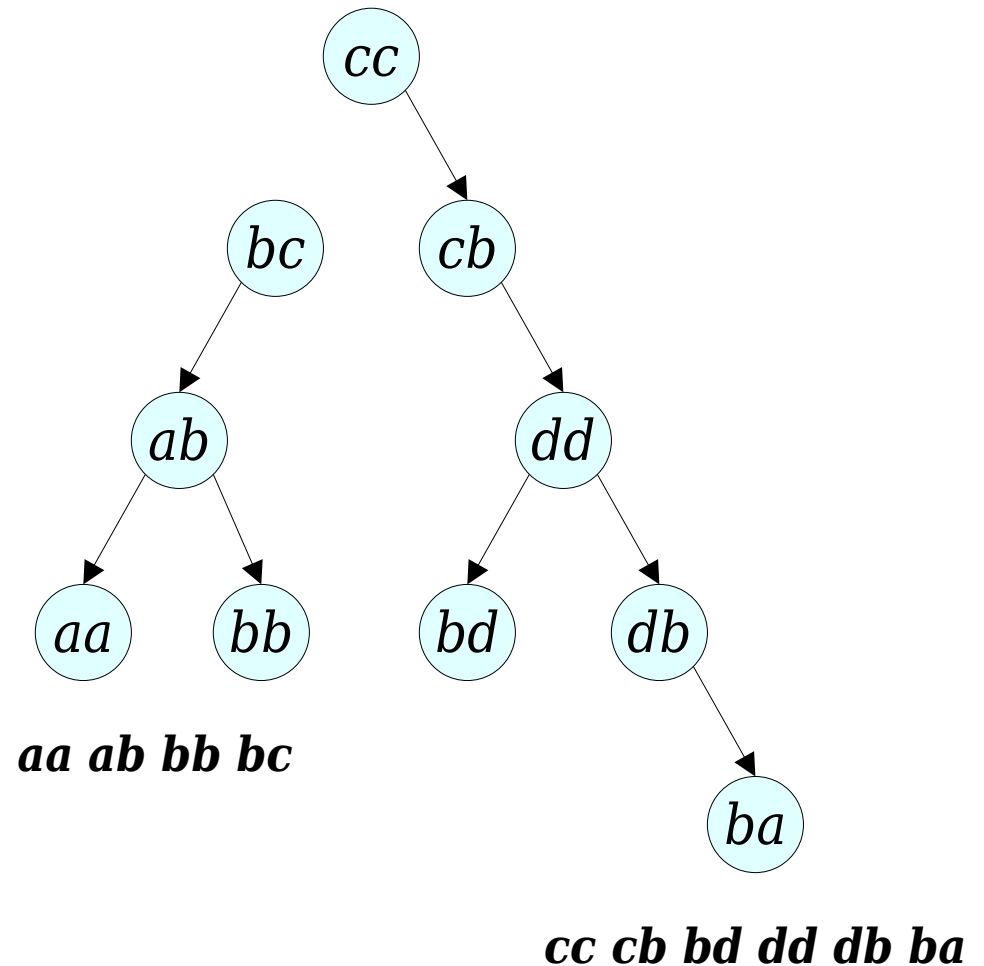
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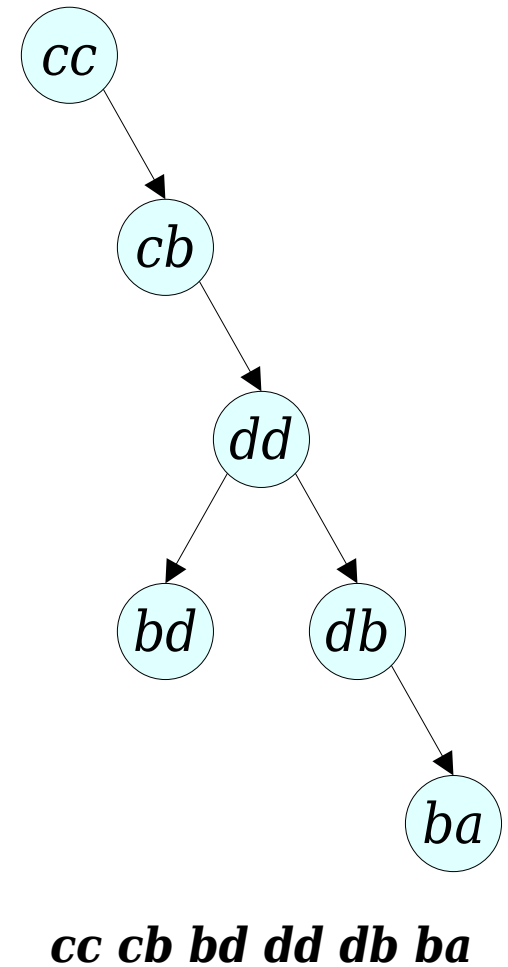
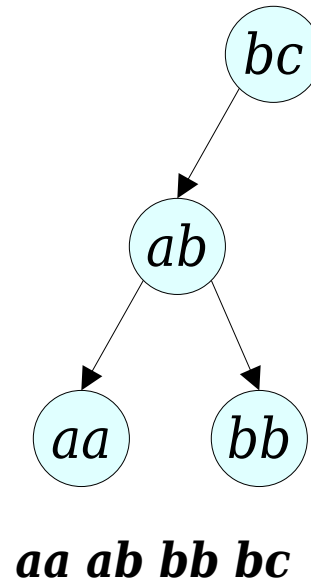
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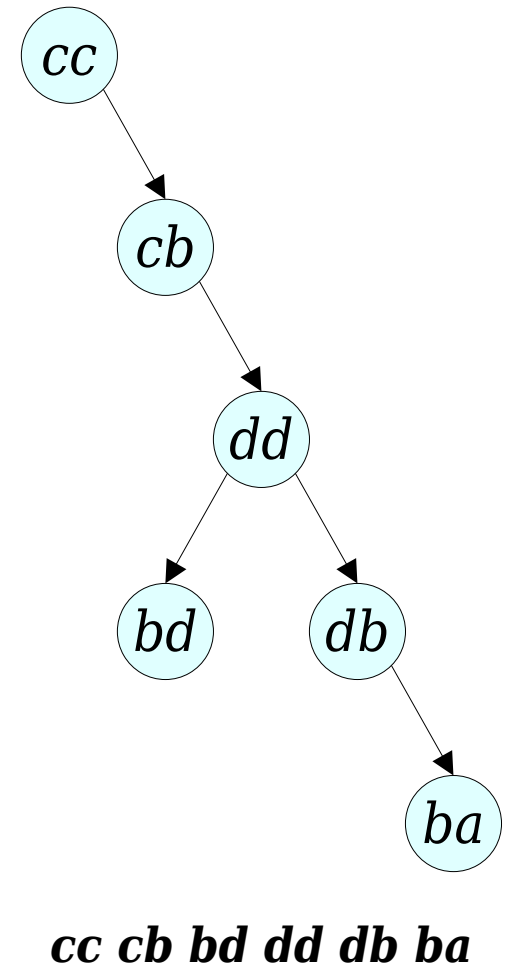
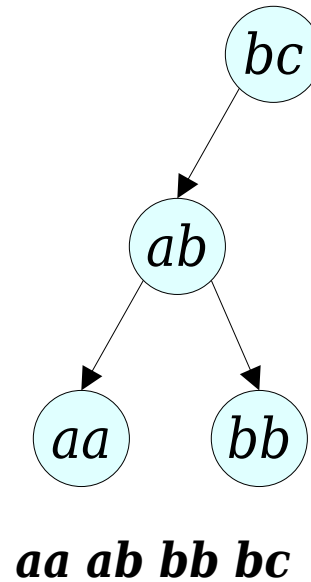
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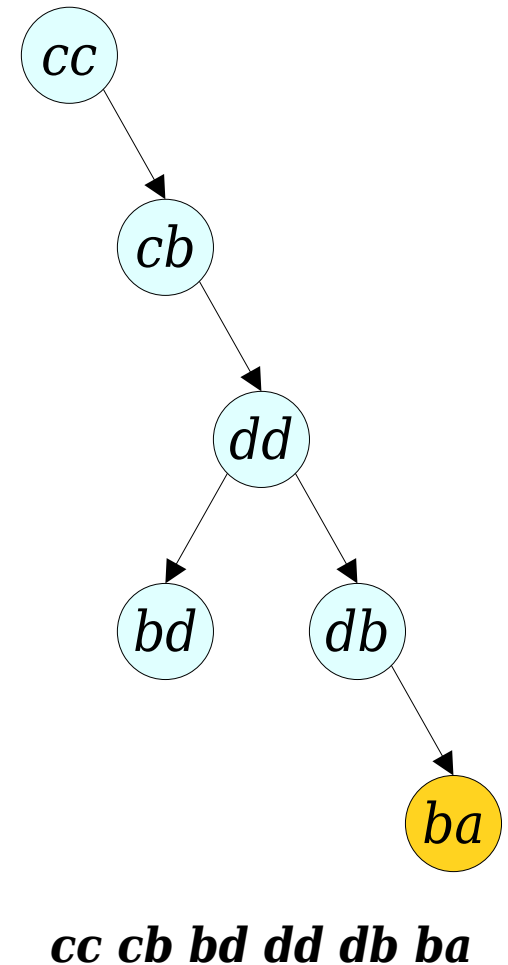
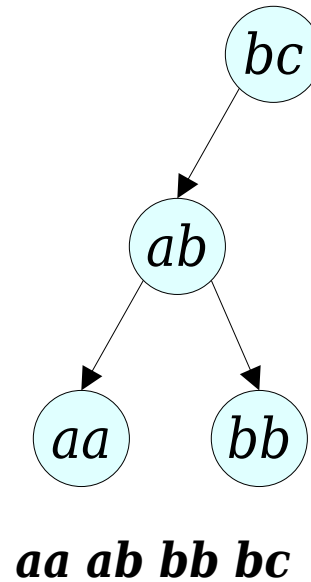
Euler Tour Trees

- To *reroot*(x):
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 - Splay the rightmost node in xx 's subtree.



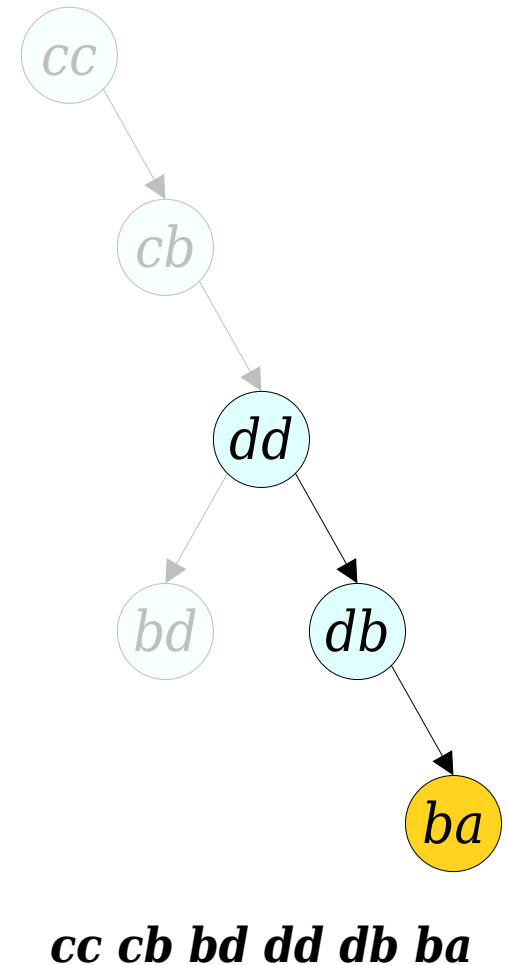
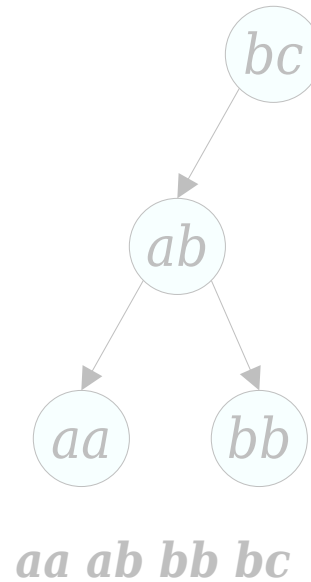
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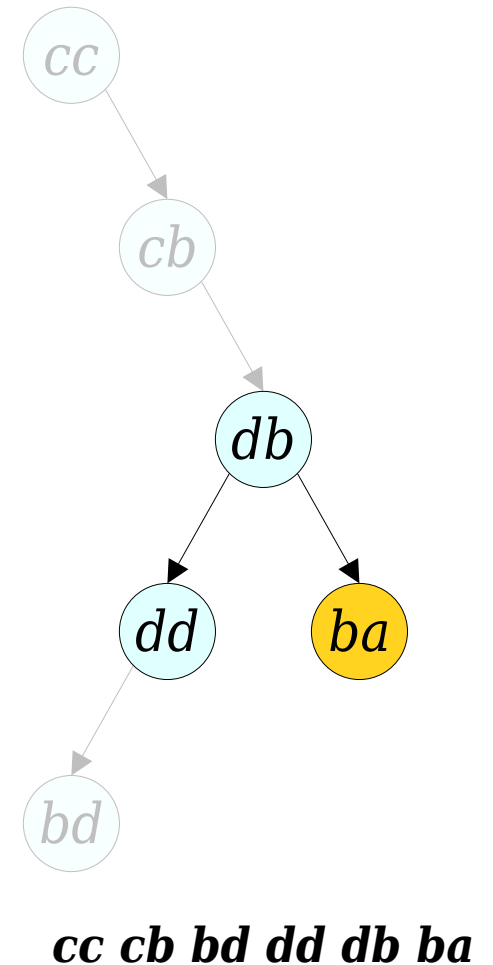
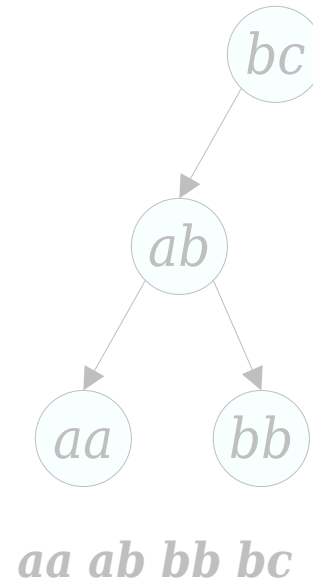
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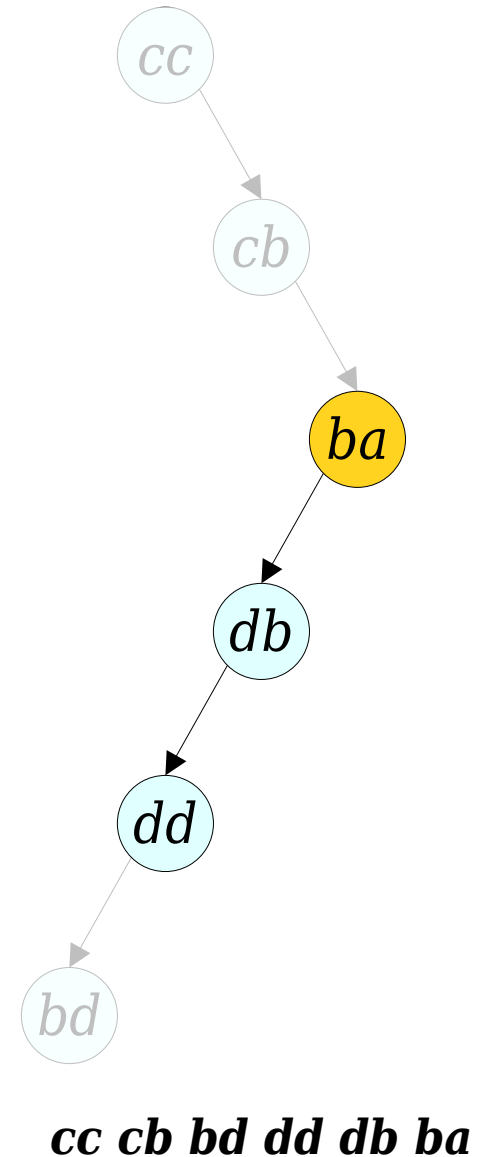
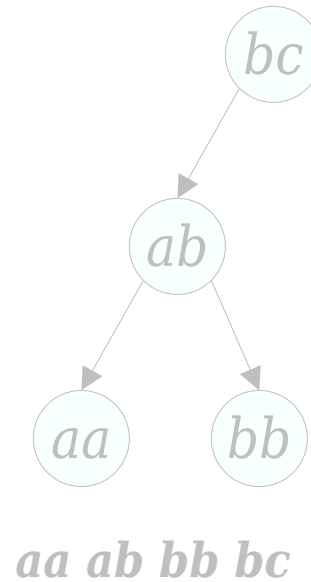
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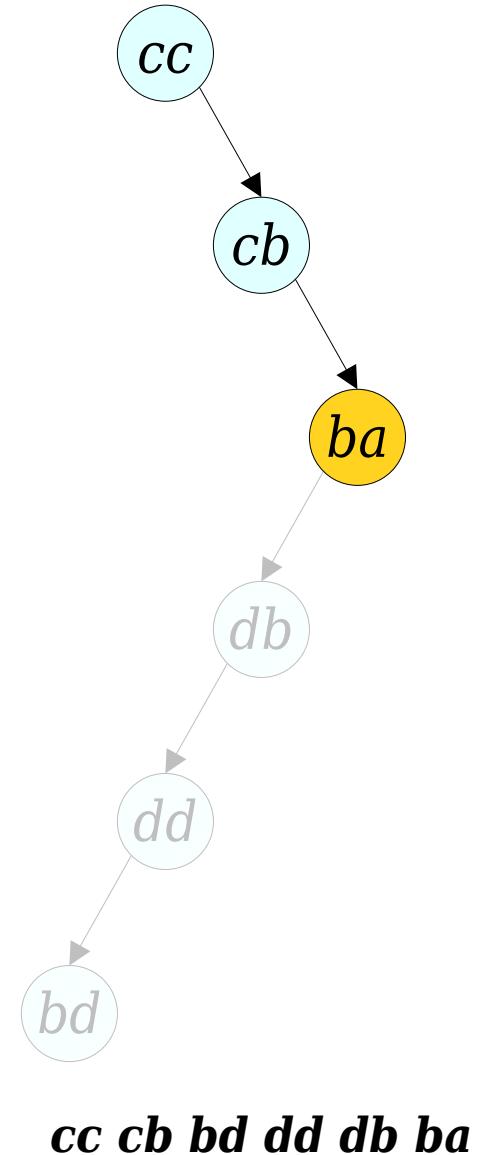
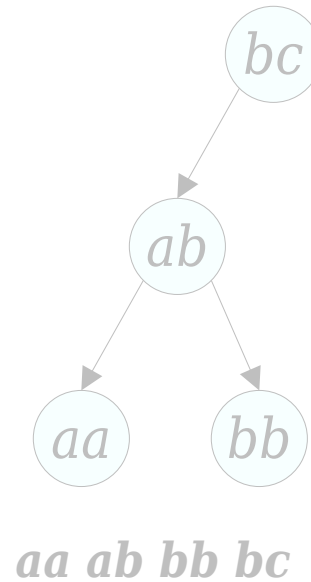
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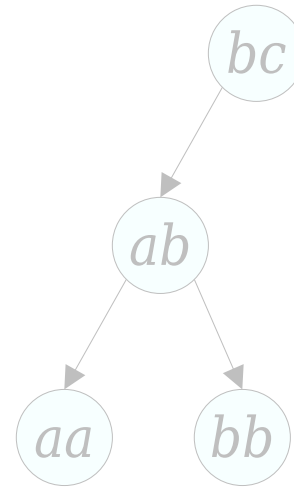
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 - Splay the rightmost node in xx 's subtree.

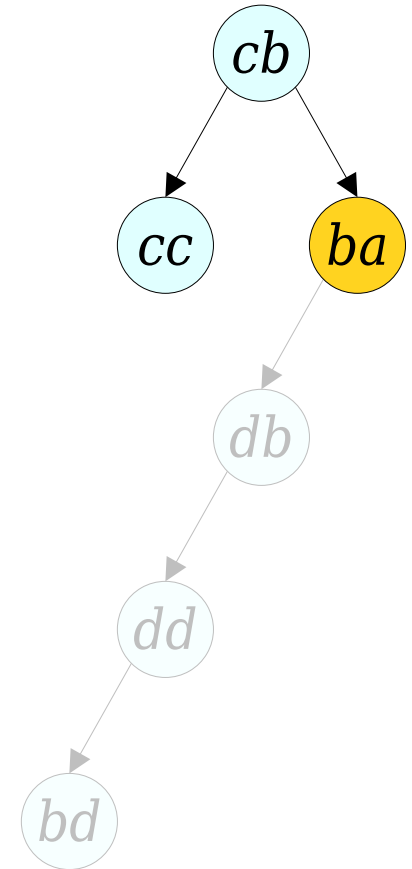


Euler Tour Trees

- To *reroot*(x):
 - Splay xx .
 - Disconnect xx 's left child tree T .
 - Splay the rightmost node in xx 's subtree.



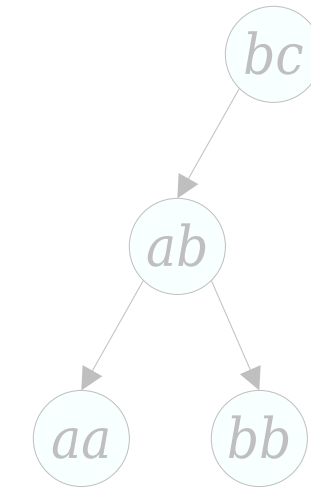
aa ab bb bc



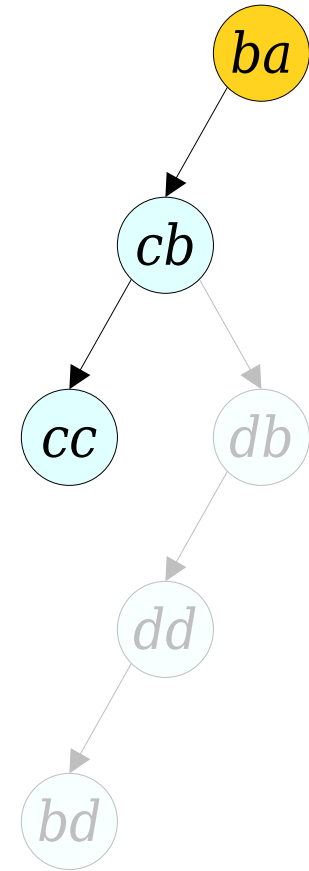
cc cb bd dd db ba

Euler Tour Trees

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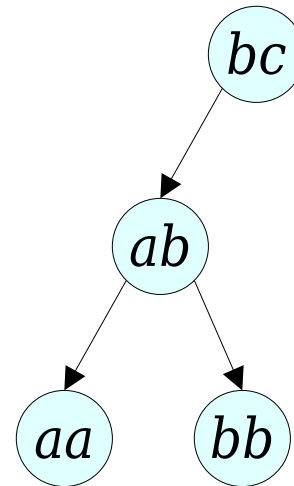
aa ab bb bc



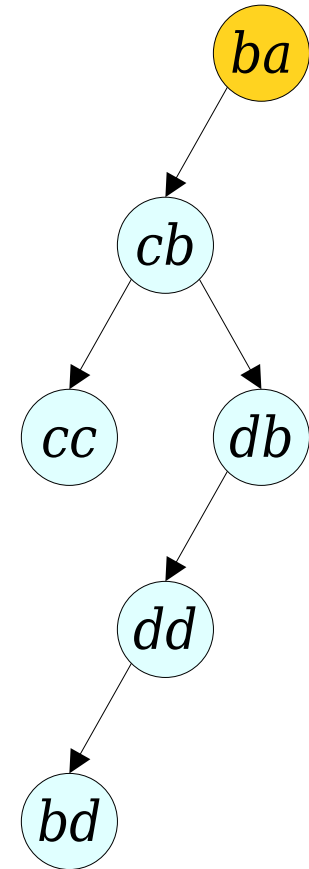
cc cb bd dd db ba

Euler Tour Trees

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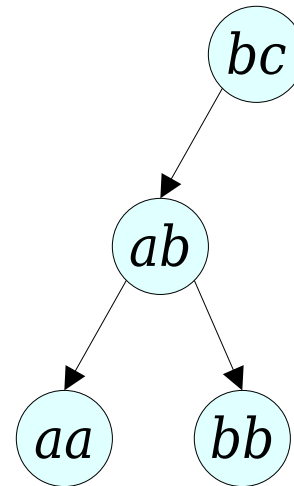
aa ab bb bc



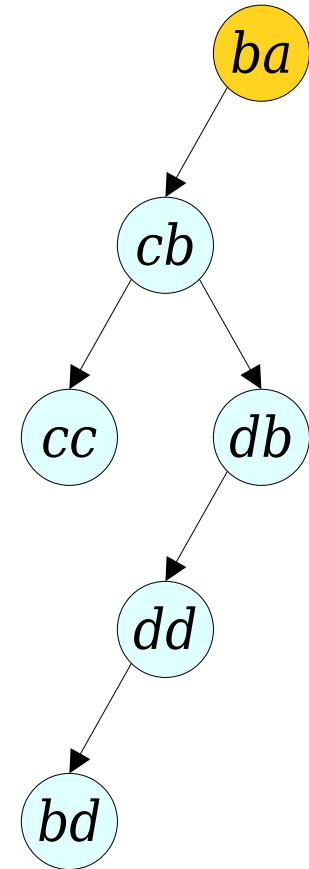
cc cb bd dd db ba

Euler Tour Trees

- To *reroot*(x):
 - Splay xx .
 - Disconnect xx 's left child tree T .
 - Splay the rightmost node in xx 's subtree.
 - Make T the right child of the root.



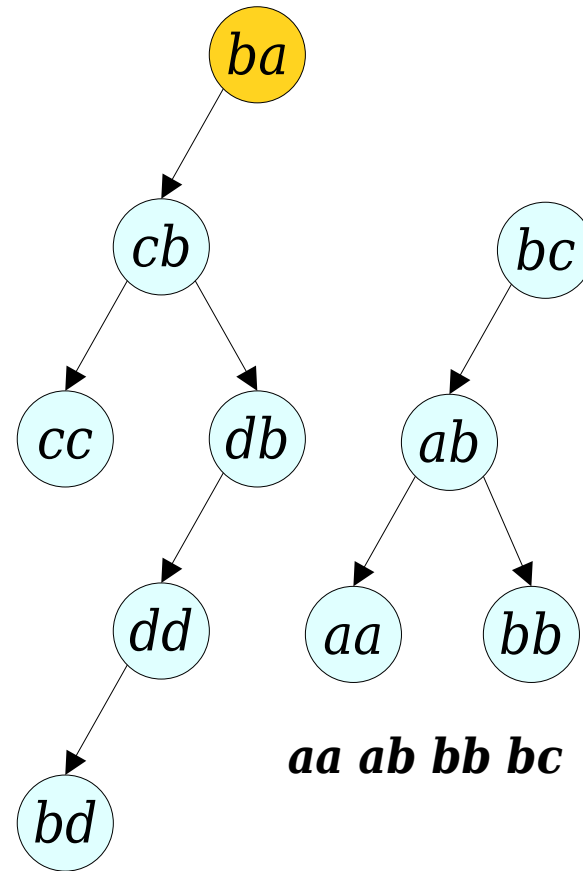
aa ab bb bc



cc cb bd dd db ba

Euler Tour Trees

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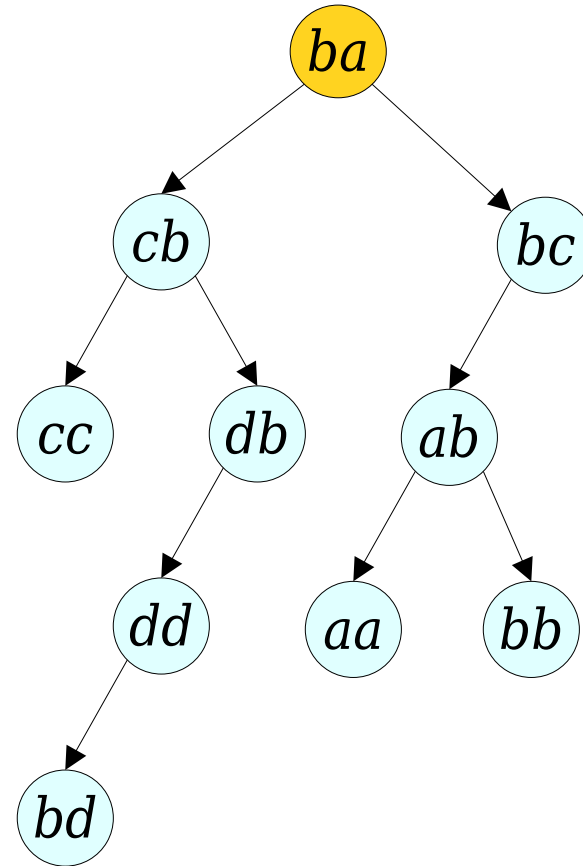


aa ab bb bc

cc cb bd dd db ba

Euler Tour Trees

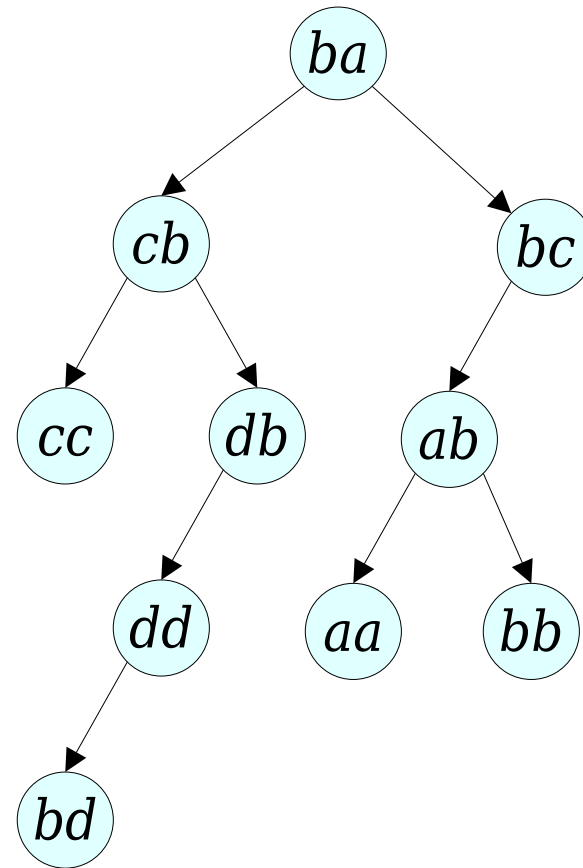
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cc cb bd dd db ba aa ab bb bc

Euler Tour Trees

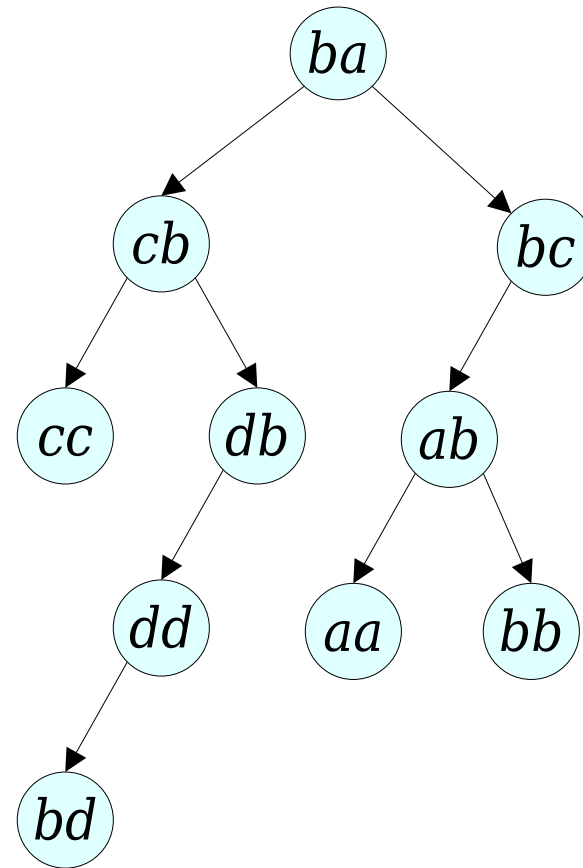
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cc cb bd dd db ba aa ab bb bc

Euler Tour Trees

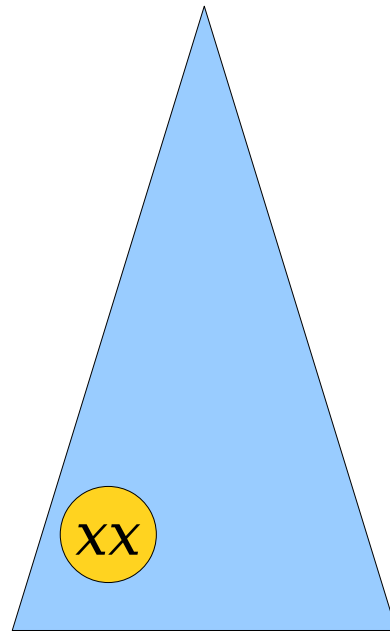
- To *reroot*(x):
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 - Make T the right child of the root.
- Amortized cost:
 $O(\log n)$.



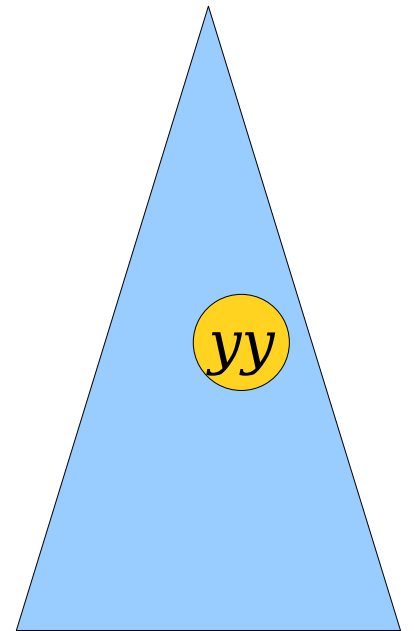
cc cb bd dd db ba aa ab bb bc

Euler Tour Trees

- To *link*(x, y):



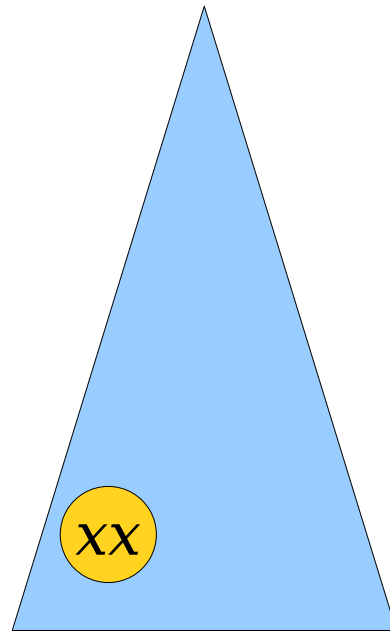
cc cd ... dc



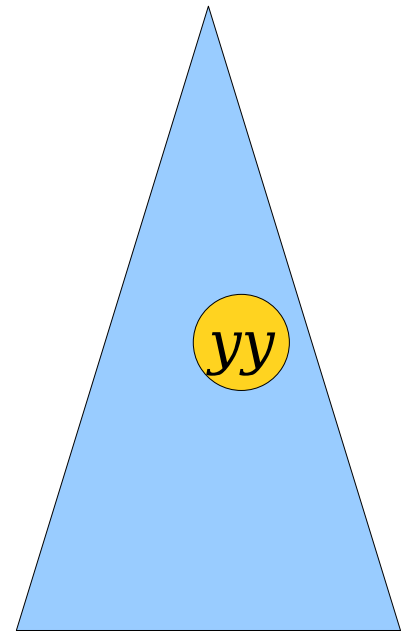
jj jk ... jk

Euler Tour Trees

- To *link*(x, y):
 - *reroot*(x) and *reroot*(y).



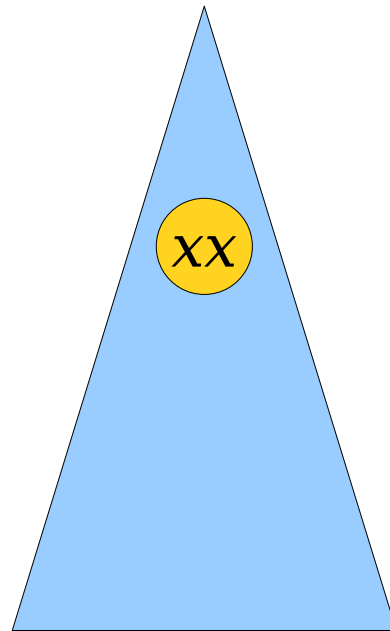
cc cd ... dc



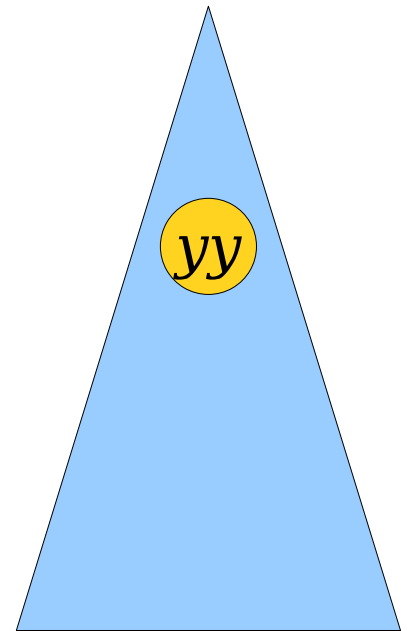
jj jk ... jk

Euler Tour Trees

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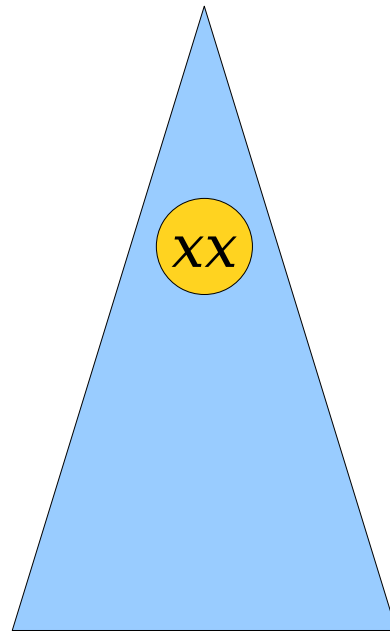
xx xa ... ax



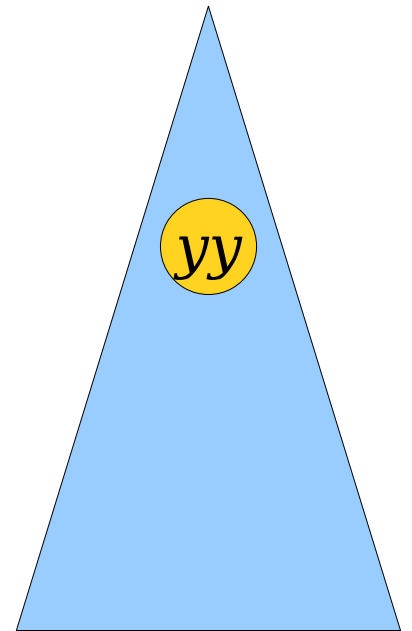
yy yf ... fy

Euler Tour Trees

- To *link*(x, y):
 - *reroot*(x) and *reroot*(y).
 - Add xy as the rightmost node of x 's tree.



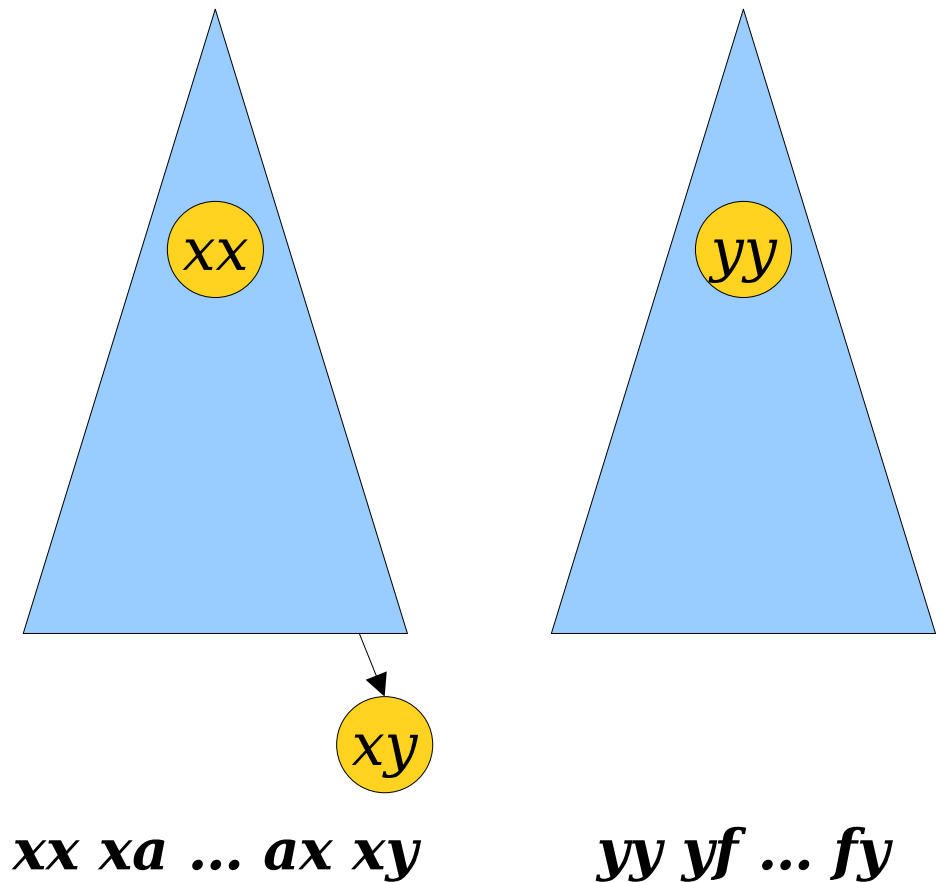
xx xa ... ax



yy yf ... fy

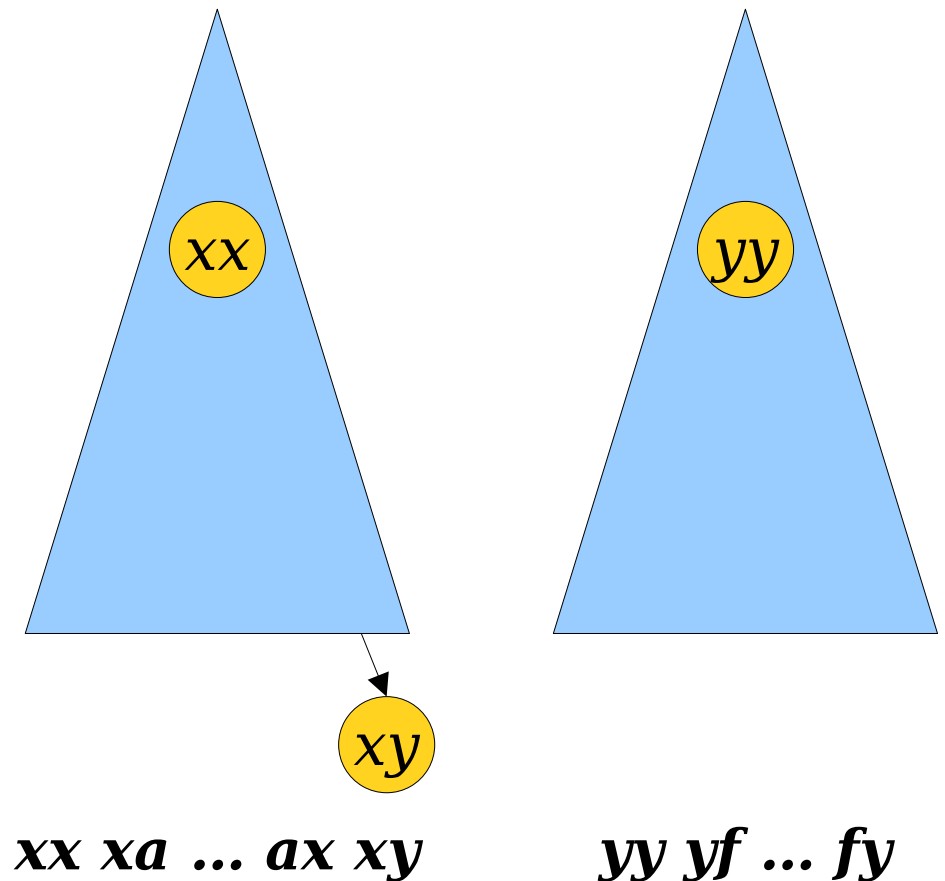
Euler Tour Trees

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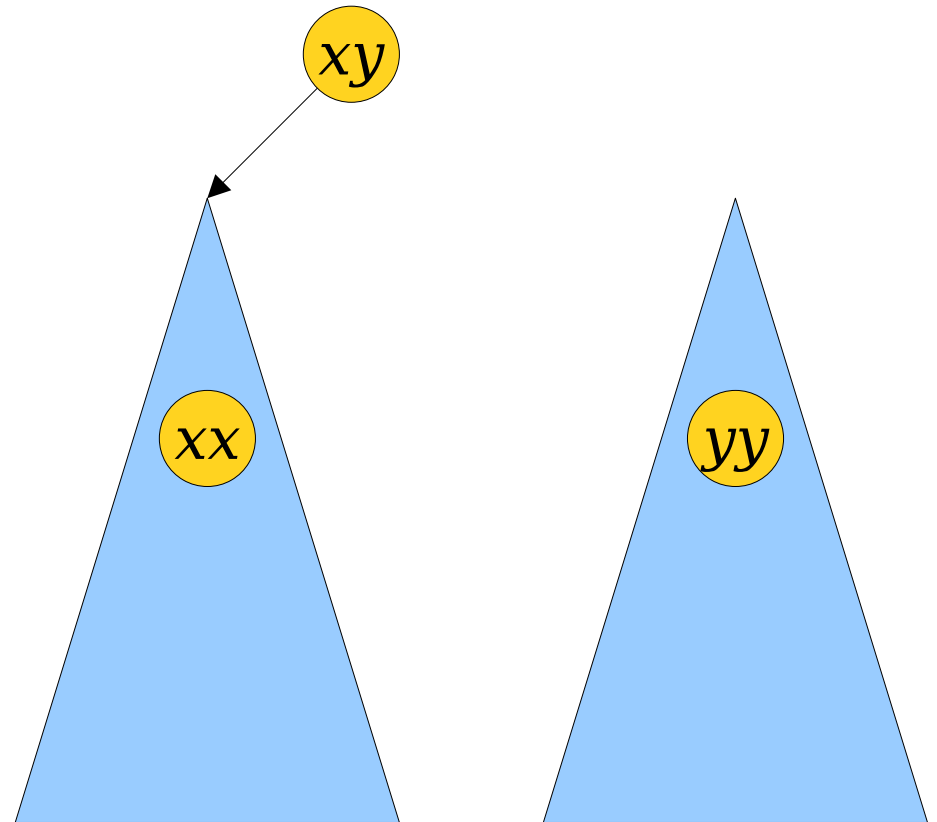
Euler Tour Trees

- To *link*(x, y):
 - *reroot*(x) and *reroot*(y).
 - Add xy as the rightmost node of x 's tree.
 - Splay xy .



Euler Tour Trees

- To *link*(x, y):
 - *reroot*(x) and *reroot*(y).
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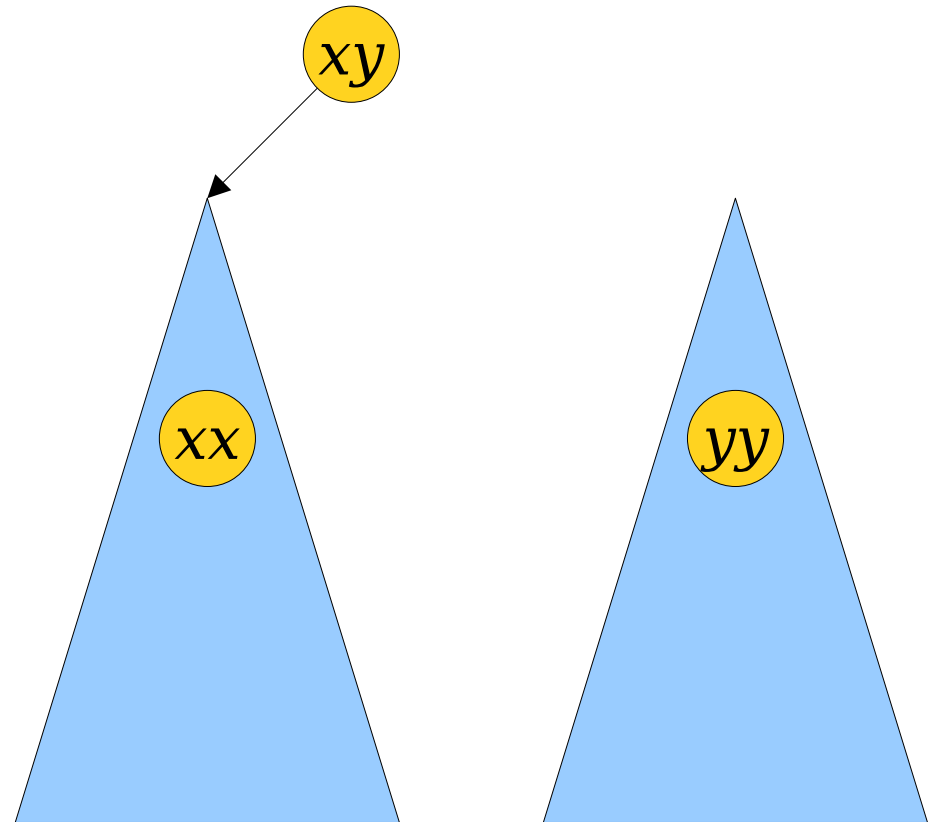


$xx \ x_a \ \dots \ a_x \ xy$

$yy \ y_f \ \dots \ f_y$

Euler Tour Trees

- To *link*(x, y):
 - *reroot*(x) and *reroot*(y).
 - Add xy as the rightmost node of x 's tree.
 - Splay xy .
 - Set yy 's tree as xy 's right child.

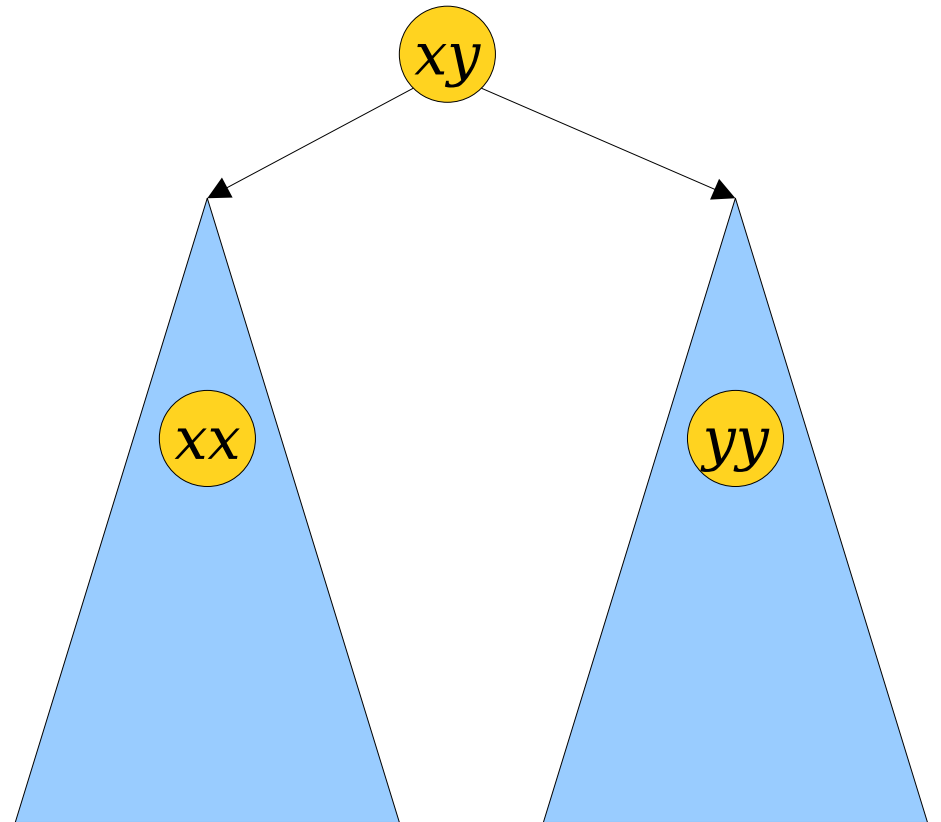


$xx \ x_a \ \dots \ a_x \ xy$

$yy \ y_f \ \dots \ f_y$

Euler Tour Trees

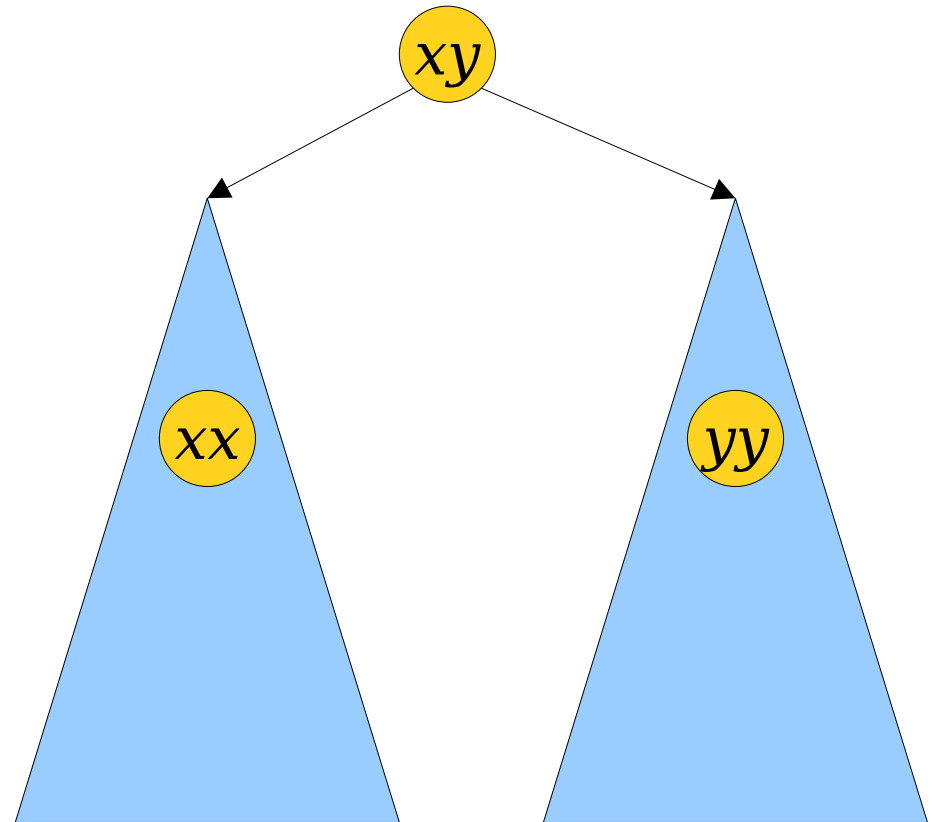
- To *link*(x, y):
 - *reroot*(x) and *reroot*(y).
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xx xa ... ax xy yy yf ... fy

Euler Tour Trees

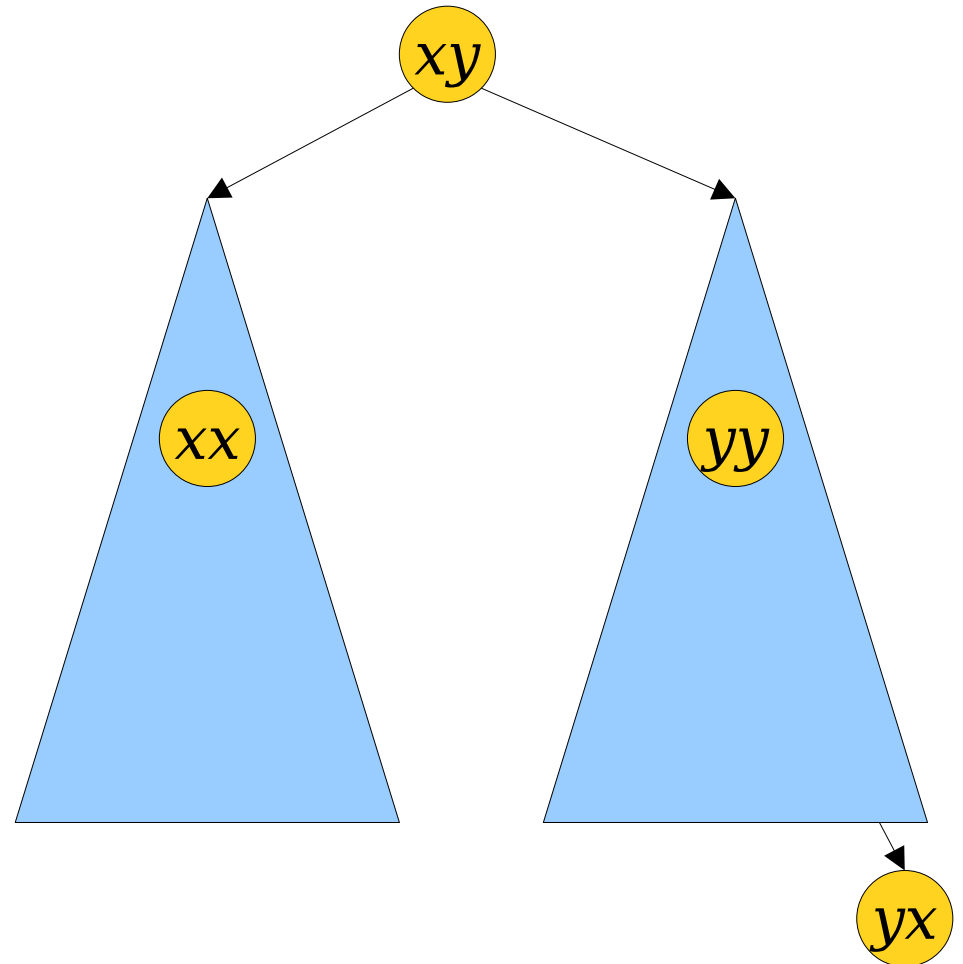
- To *link*(x, y):
 - *reroot*(x) and *reroot*(y).
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 - Splay xy .
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$xx \ x_a \ \dots \ a_x \ xy \ yy \ y_f \ \dots \ f_y$

Euler Tour Trees

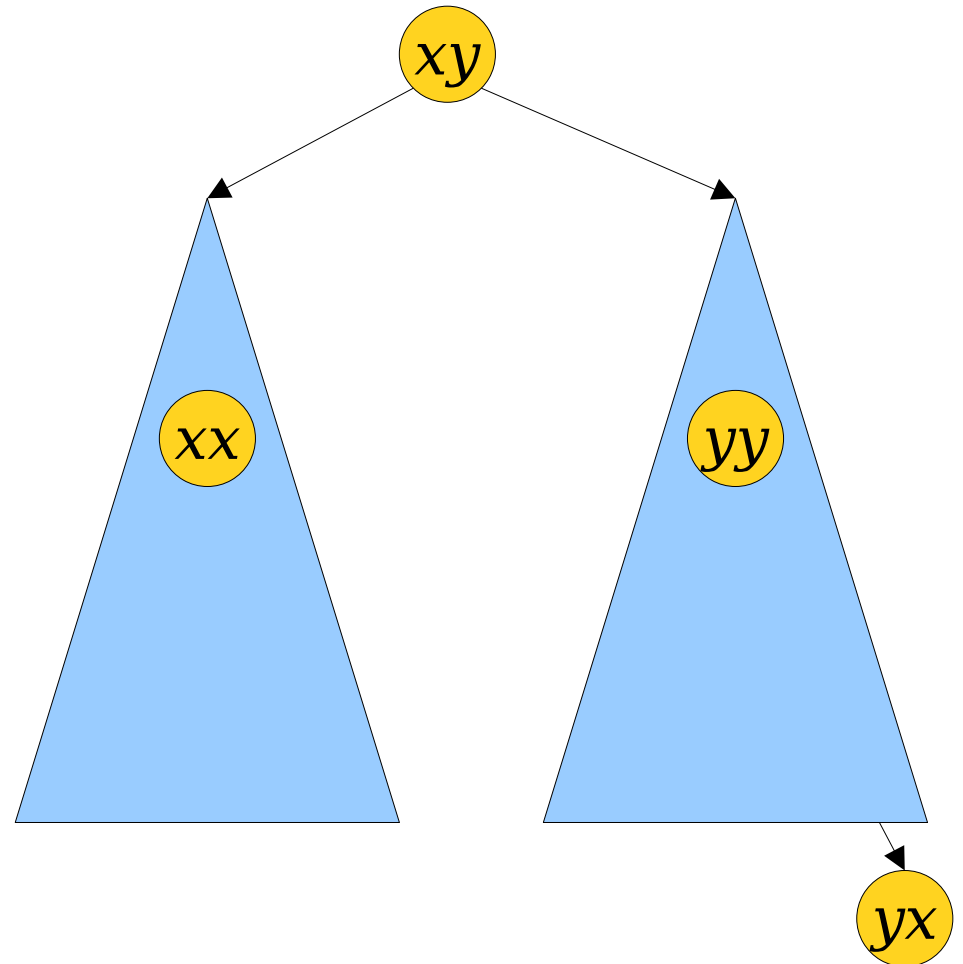
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Euler Tour Trees

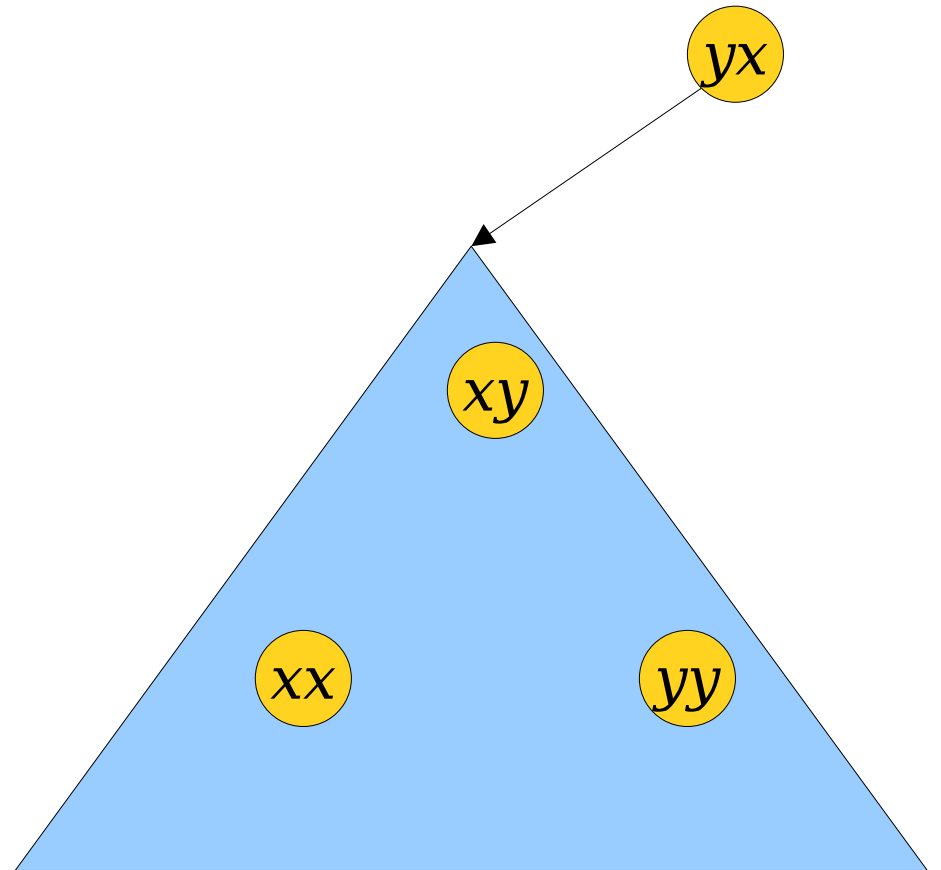
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$xx \ x_a \ \dots \ a_x \ xy \ yy \ y_f \ \dots \ f_y \ yx$

Euler Tour Trees

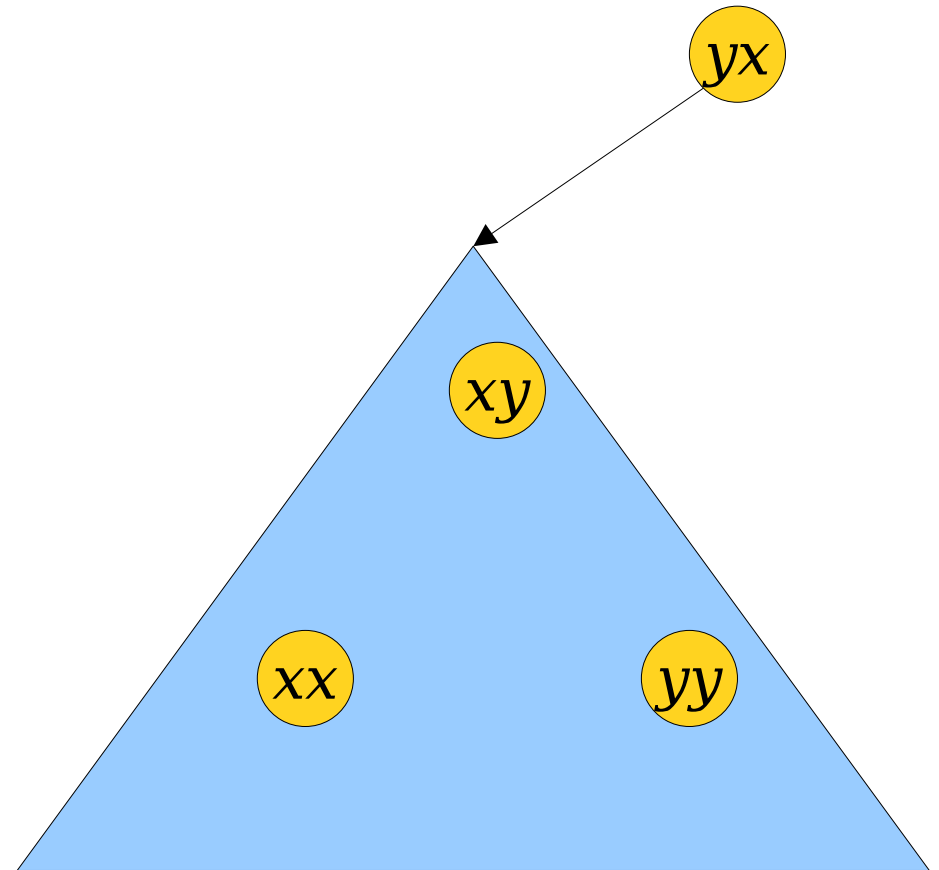
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$xx \ x_a \ \dots \ a_x \ xy \ yy \ y_f \ \dots \ f_y \ yx$

Euler Tour Trees

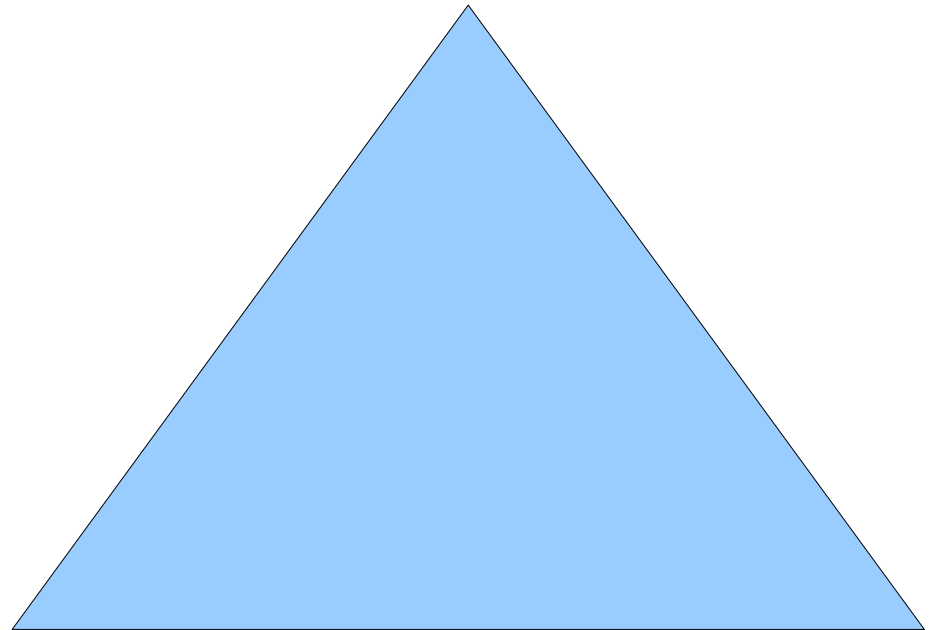
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- Amortized cost:
 $O(\log n)$.



$xx \ x_a \ \dots \ a_x \ xy \ yy \ y_f \ \dots \ f_y \ yx$

Euler Tour Trees

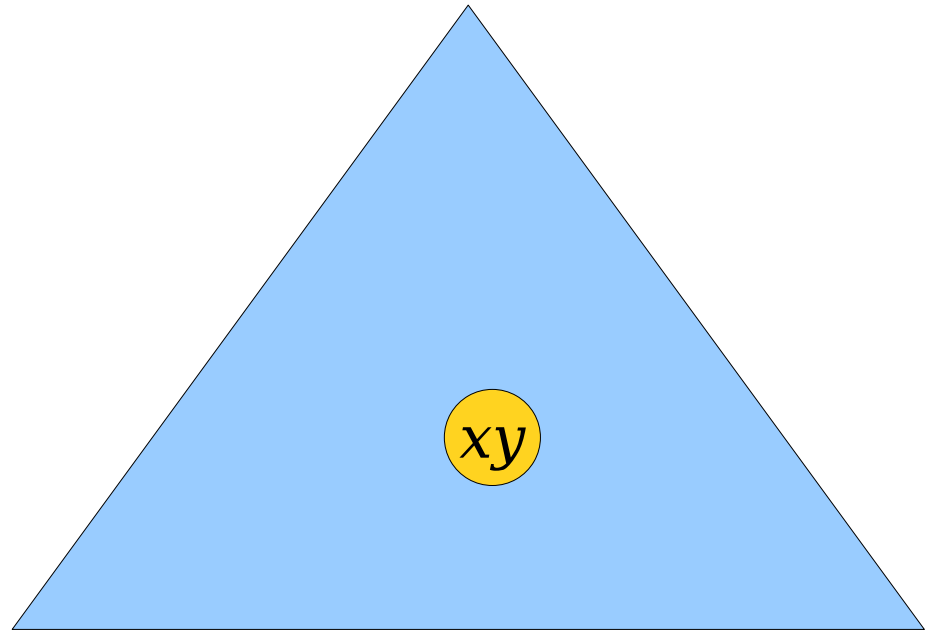
- To *cut*(x, y):



aa ab ... cx xy yy yf ... fy yx xt ... ba

Euler Tour Trees

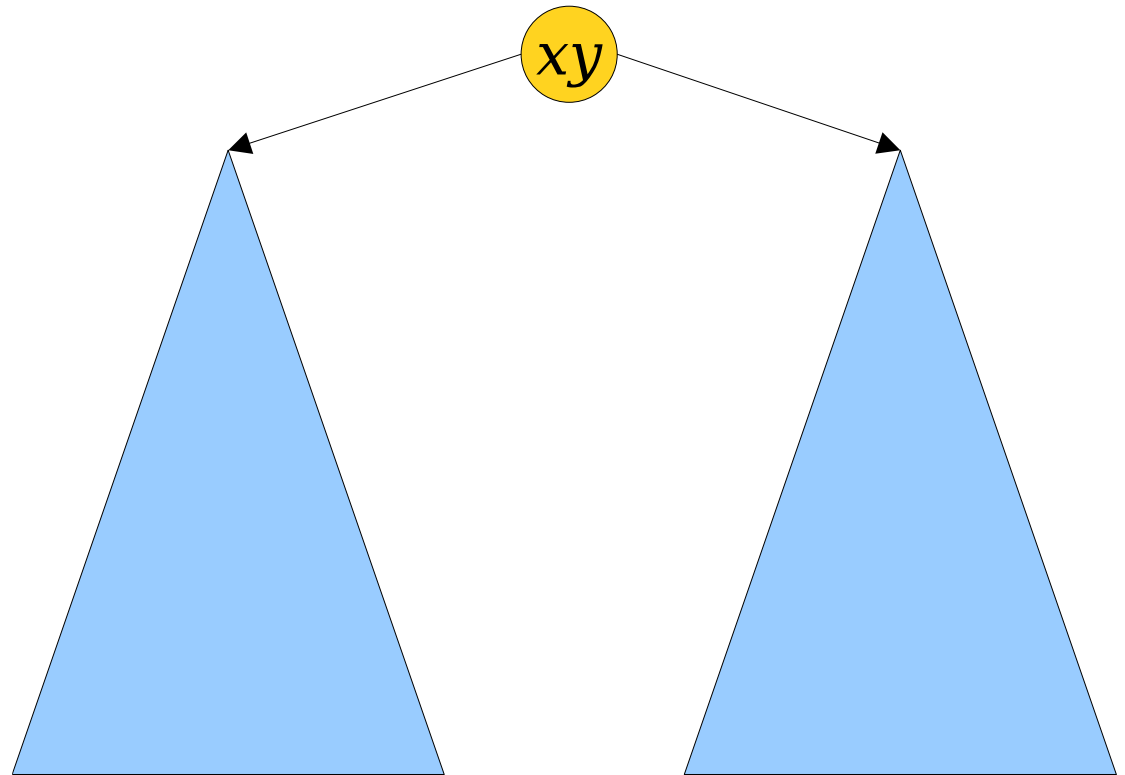
- To *cut*(x, y):
 - Splay xy .



aa ab ... cx xy yy yf ... fy yx xt ... ba

Euler Tour Trees

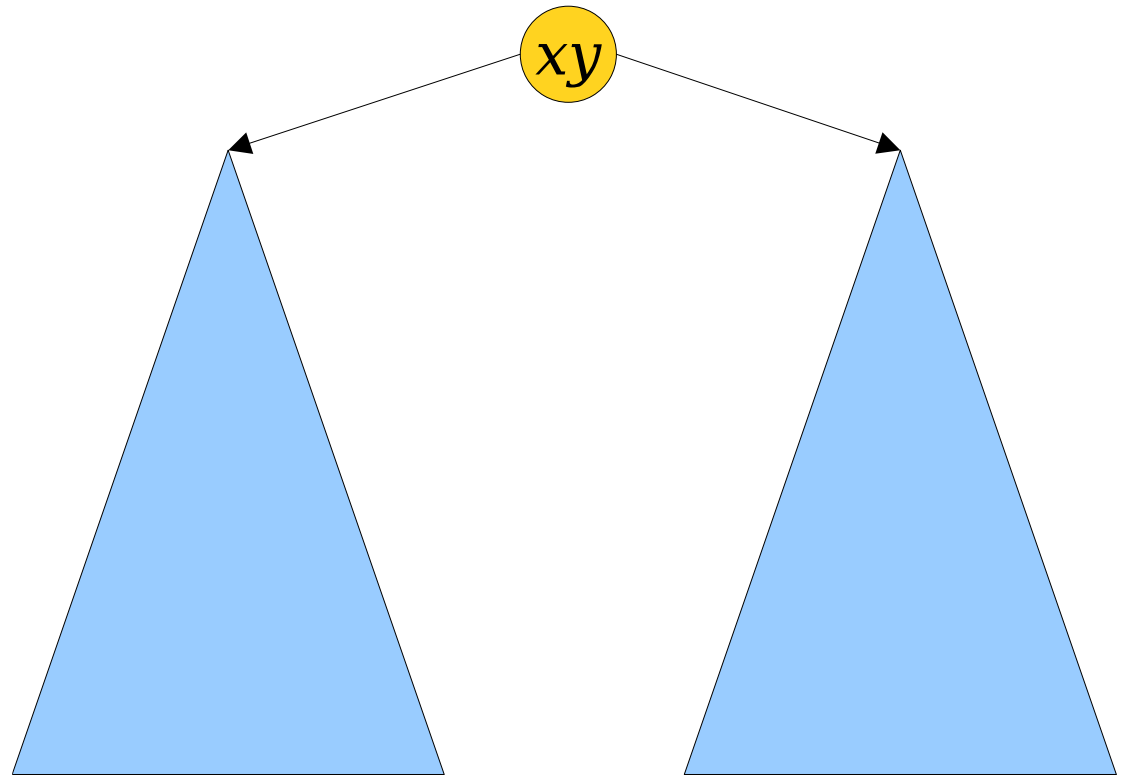
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aa ab ... cx xy yy yf ... fy yx xt ... ba

Euler Tour Trees

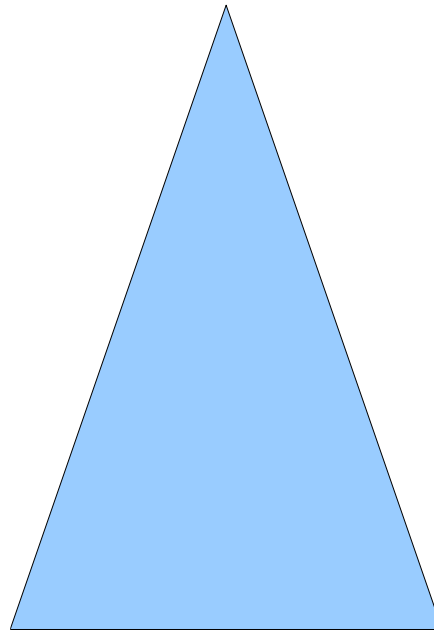
- To *cut*(x, y):
 - Splay xy .
 - Delete xy .



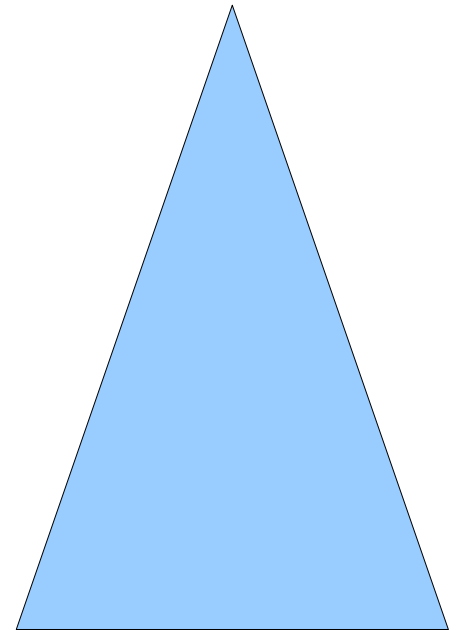
aa ab ... cx xy yy yf ... fy yx xt ... ba

Euler Tour Trees

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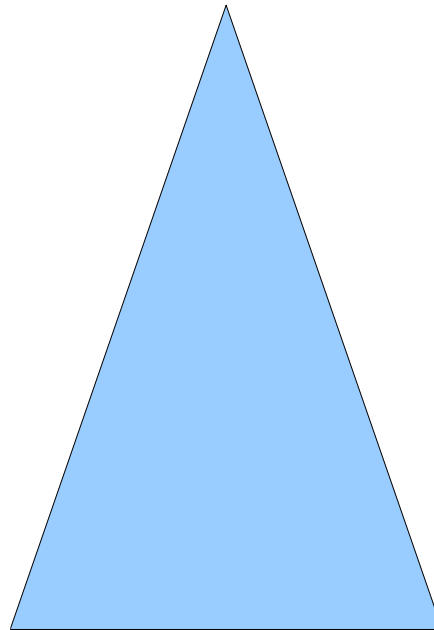
aa ab ... cx



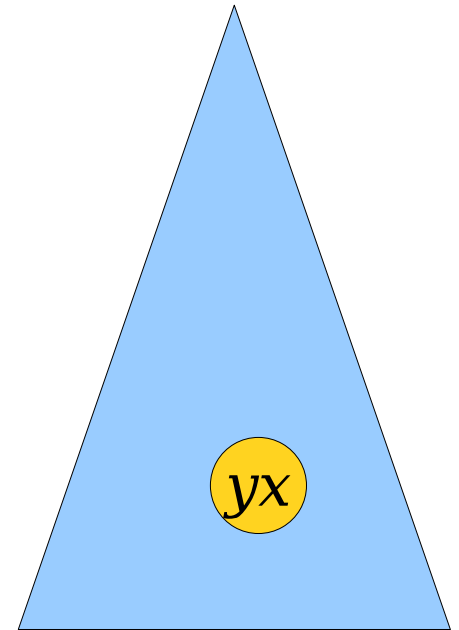
yy yf ... fy yx xt ... ba

Euler Tour Trees

- To **cut**(x, y):
 - Splay xy .
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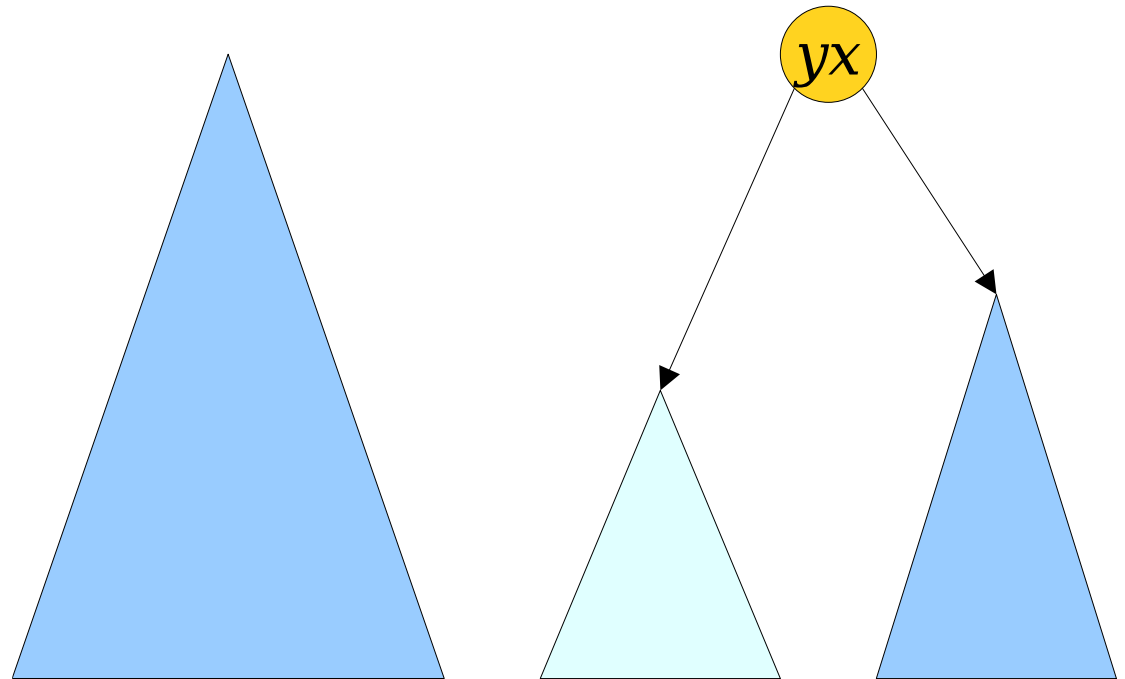
aa ab ... cx



yy yf ... fy yx xt ... ba

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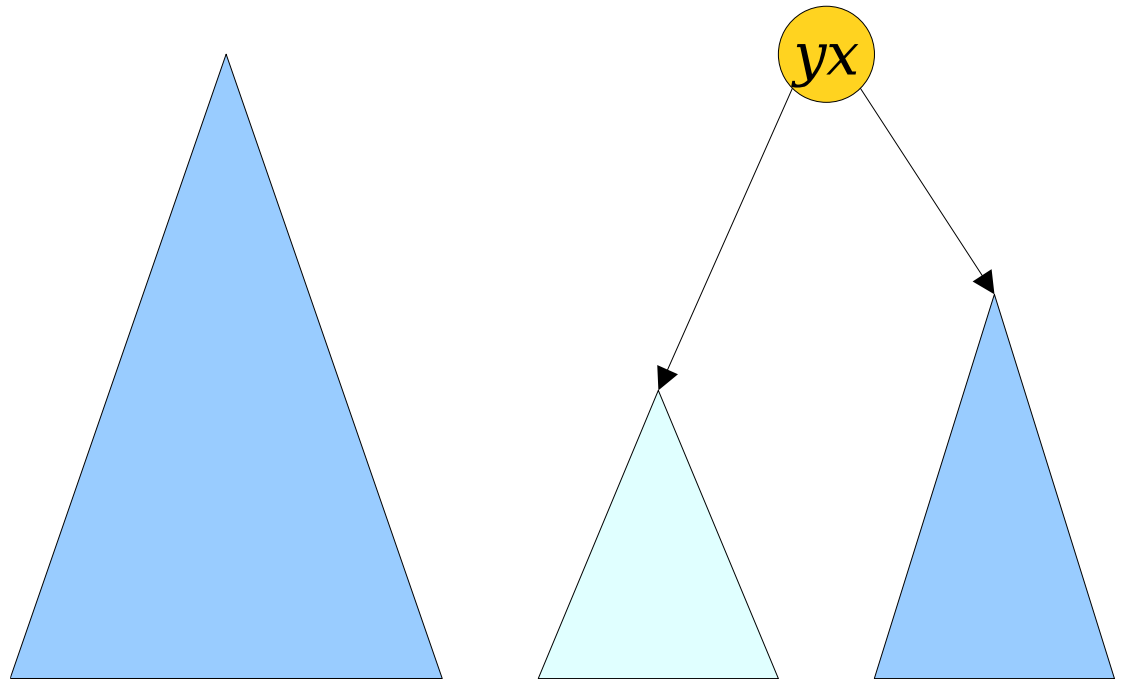


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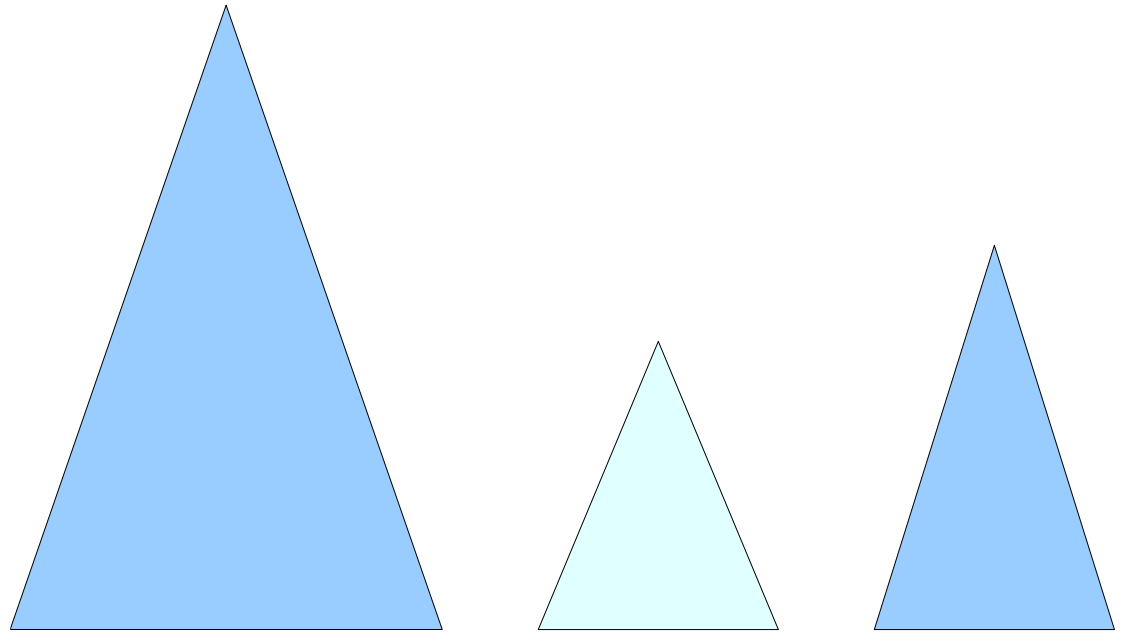


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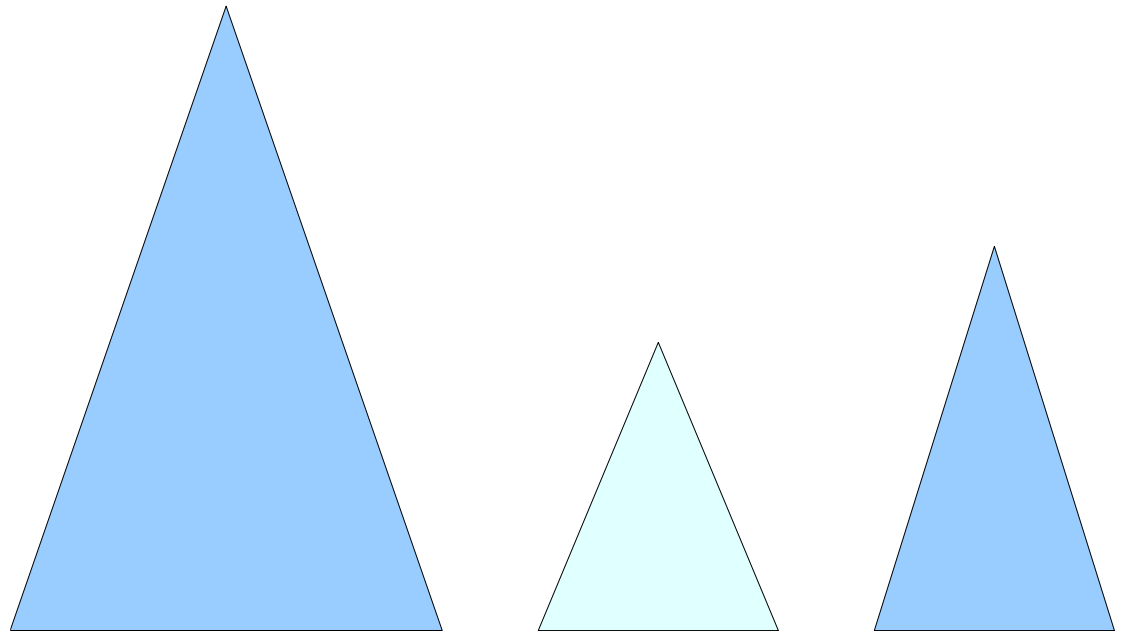
aa ab ... cx

yy yf ... fy

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Euler Tour Trees

- To *cut*(x, y):
 - Splay xy .
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 - Let T_1 and T_2 be the trees on the left and right.



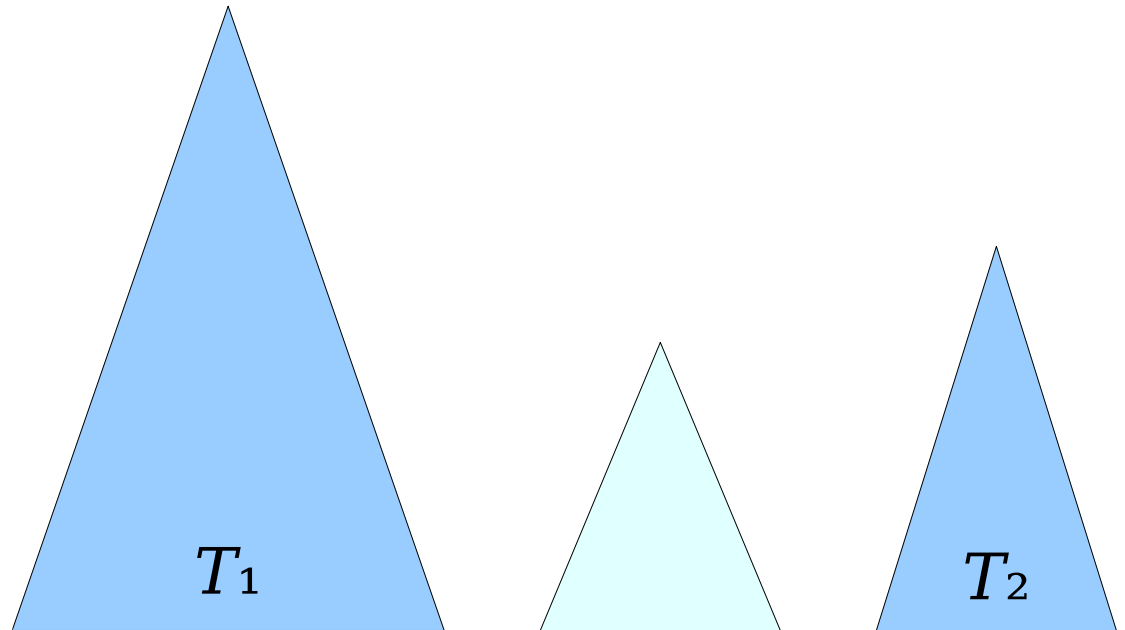
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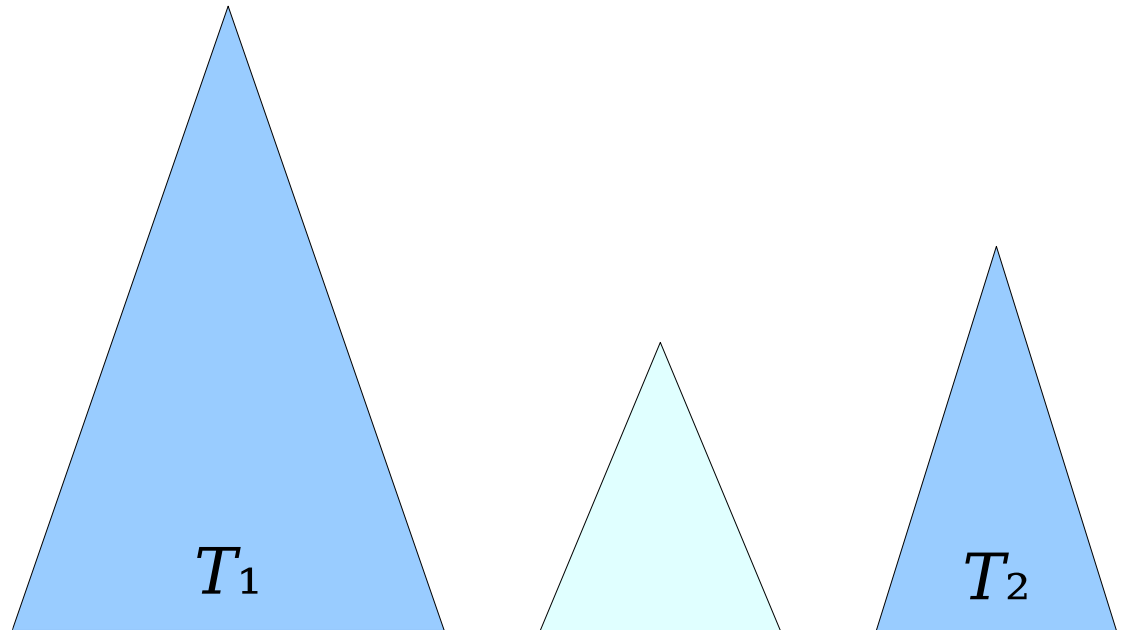
$aa \ ab \ \dots \ cx$

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$xt \ \dots \ ba$

Euler Tour Trees

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 - Splay xy .
 - Delete xy .
 - Splay yx .
 - Delete yx .
 - Let T_1 and T_2 be the trees on the left and right.
 - Splay the rightmost node of T_1 .



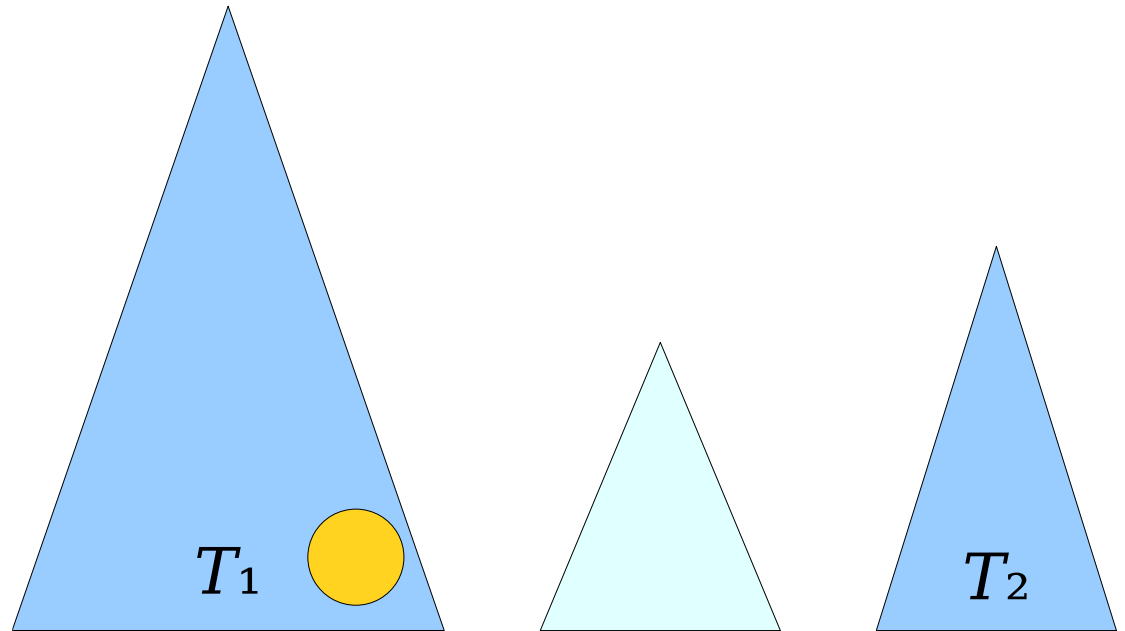
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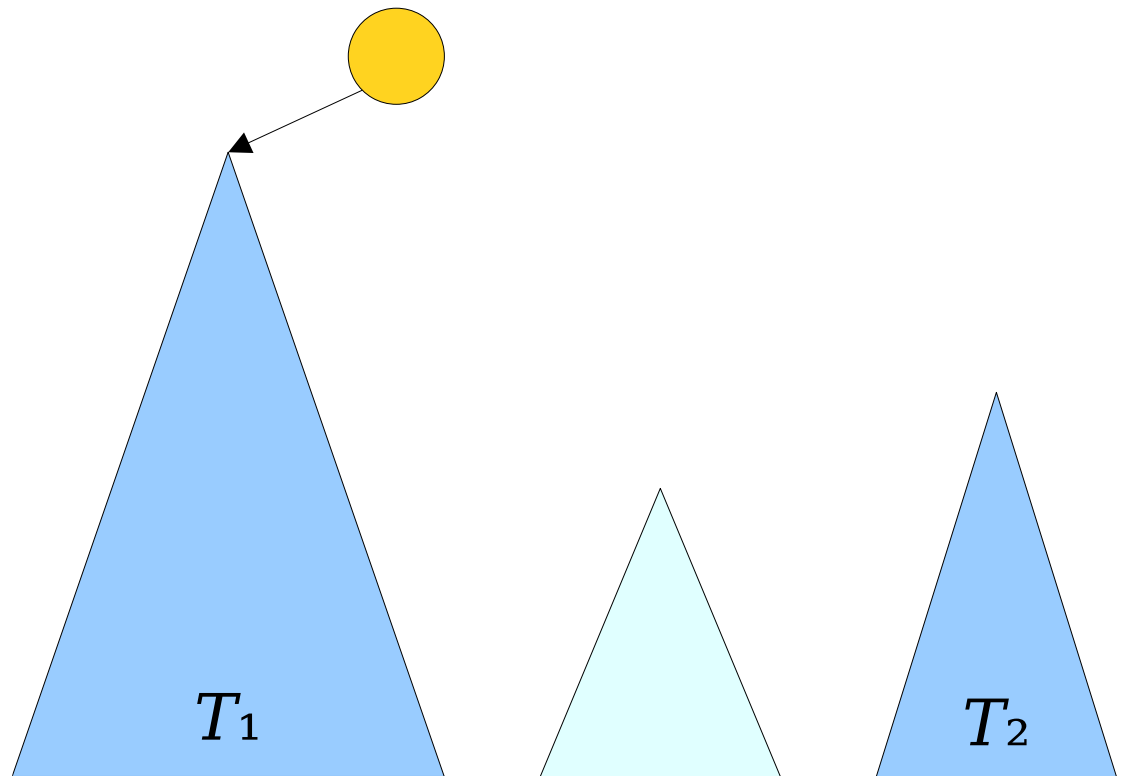
$aa\ ab\ \dots\ cx$

$yy\ yf\ \dots\ fy$

$xt\ \dots\ ba$

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- To **cut**(x, y):
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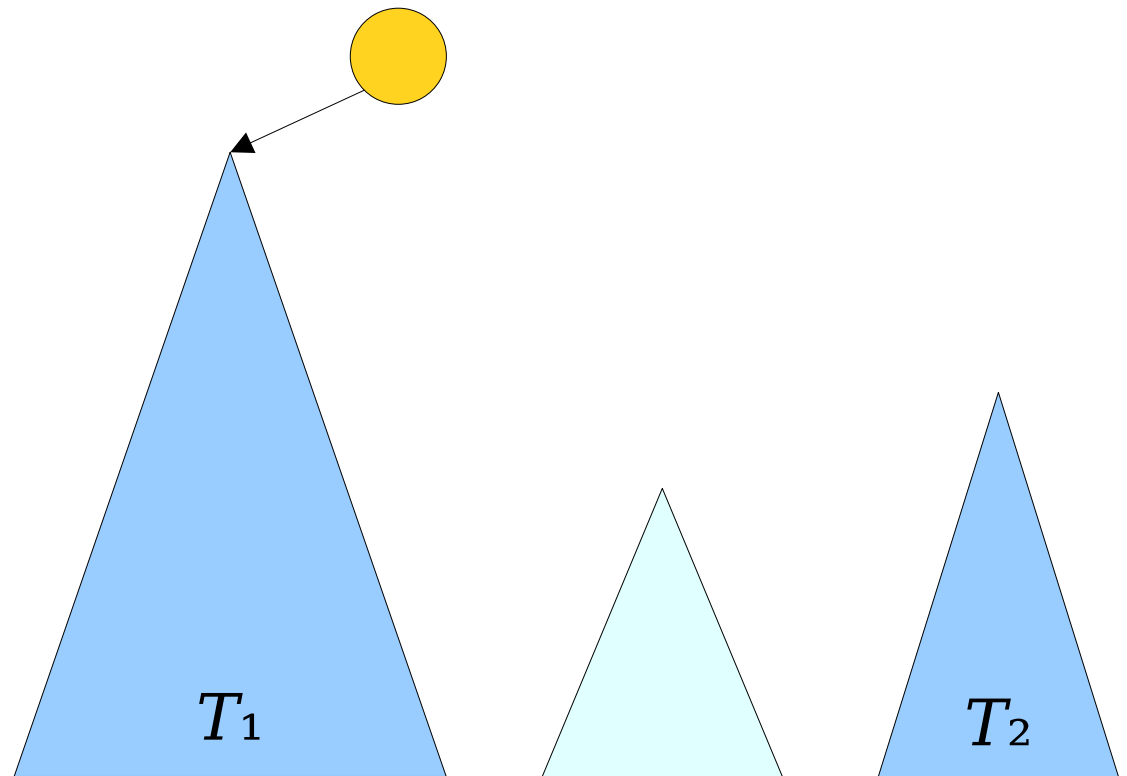
$aa \ ab \ \dots \ cx$

$yy \ yf \ \dots \ fy$

$xt \ \dots \ ba$

Euler Tour Trees

- To *cut*(x, y):
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 - Let T_1 and T_2 be the trees on the left and right.
 - Splay the rightmost node of T_1 .
 - Attach T_2 as the right child of that node.



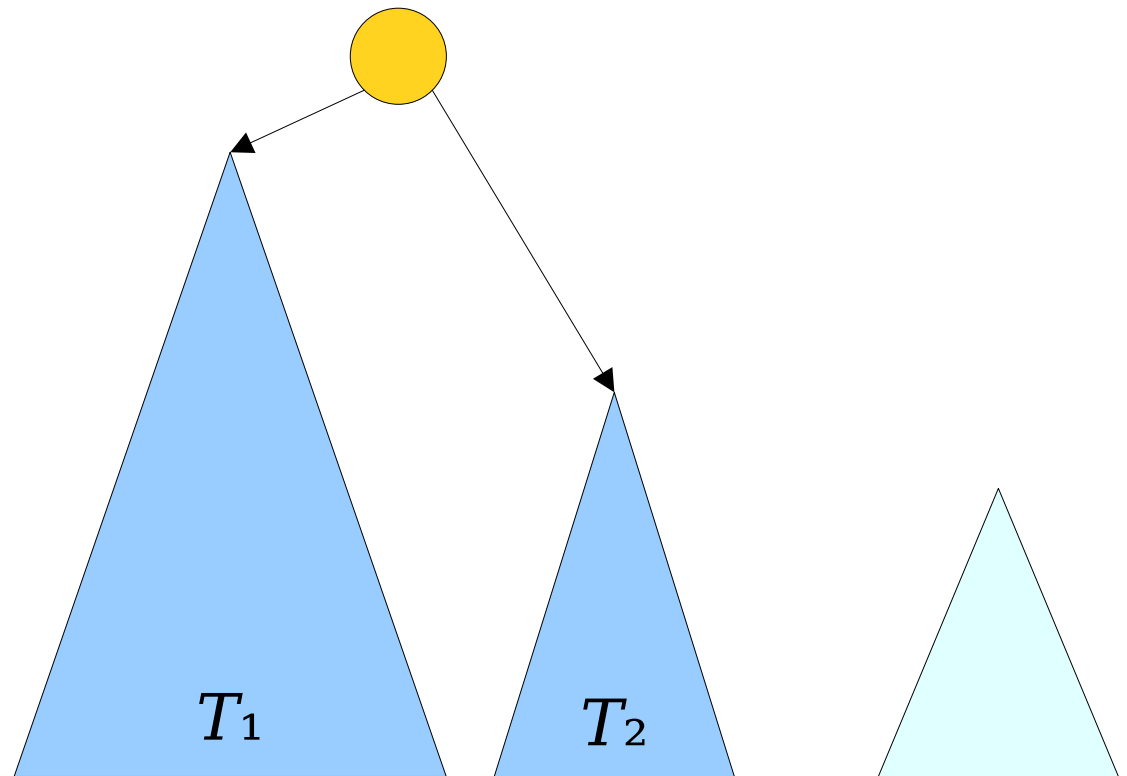
aa ab ... cx

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Euler Tour Trees

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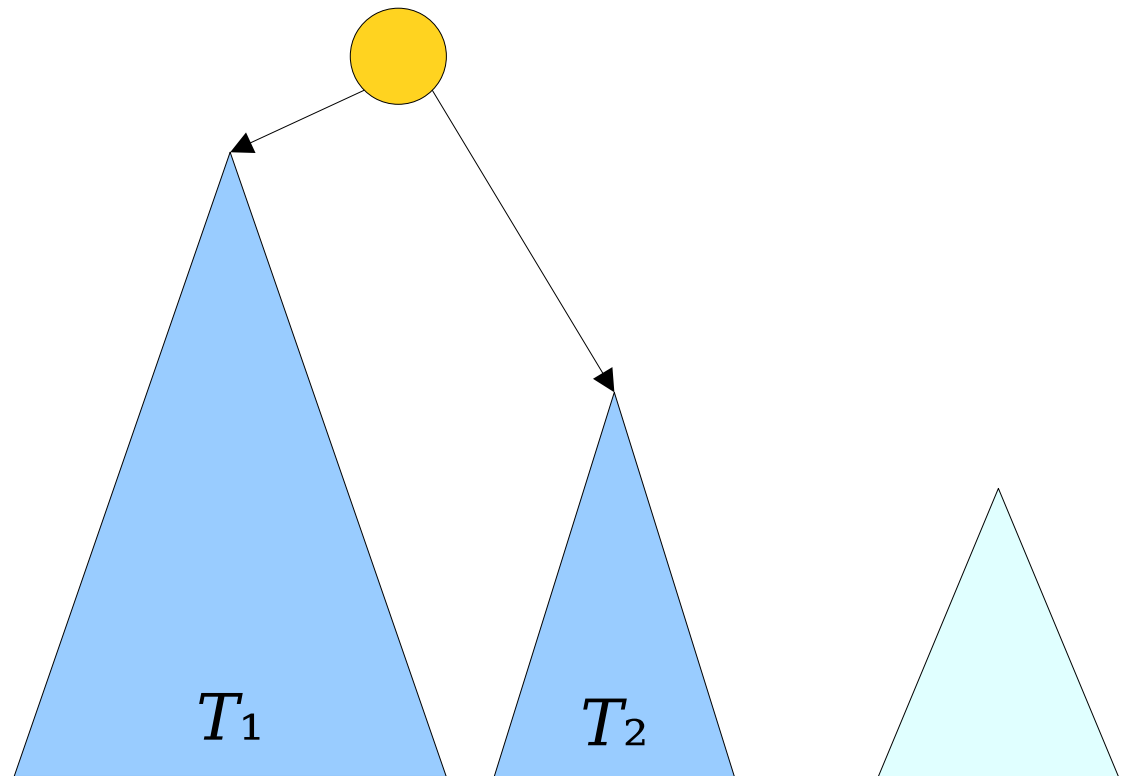


aa ab ... cx xt ... ba

yy yf ... fy

Euler Tour Trees

- To *cut*(x, y):
 - Splay xy .
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 - Splay yx .
 - Delete yx .
 - Let T_1 and T_2 be the trees on the left and right.
 - Splay the rightmost node of T_1 .
 - Attach T_2 as the right child of that node.
- Amortized cost: **$O(\log n)$** .



aa ab ... cx xt ... ba

yy yf ... fy

Euler Tour Trees

- With all things said and done, we get the following amortized runtimes for each operation:
 - ***are-connected***: $O(\log n)$
 - ***link***: $O(\log n)$
 - ***cut***: $O(\log n)$
- These bounds can be made worst-case efficient using different types of balanced BSTs instead of splay trees, but splaying is probably the fastest way to do this.

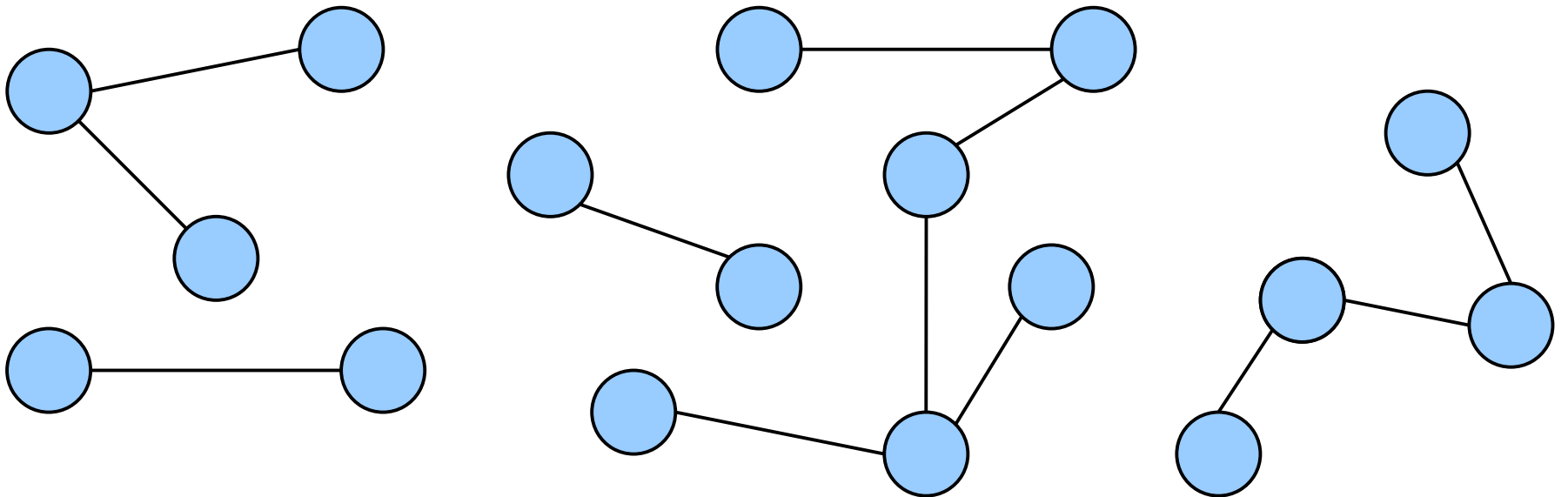
Extending Euler Tour Trees

Extending Euler Tour Trees

- We now have a (relatively) simple and fast data structure for solving dynamic connectivity in forests.
- What else can we do with them?

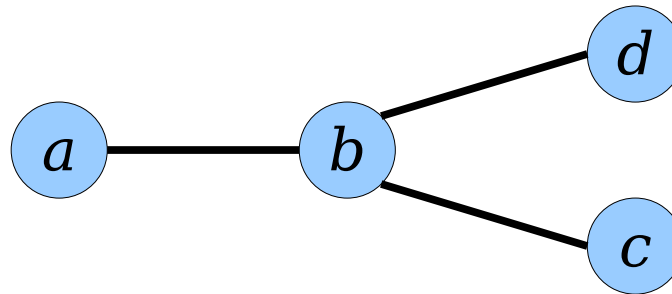
Extending Euler Tour Trees

- Suppose we want to add an operation *size*(x) that returns the number of nodes in the tree containing x .
- How might we accomplish this?

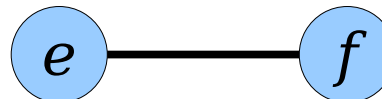


Tree Sizes

- We can determine *size*(x) as follows:
 - Figure out which Euler tour xx is in.
 - Count how many nodes of the form zz it contains.
- A naive implementation of this algorithm might take time $\Theta(n)$ if all nodes are in the same tree. Can we do better?



aa ab bb bc cc cb bd dd db ba



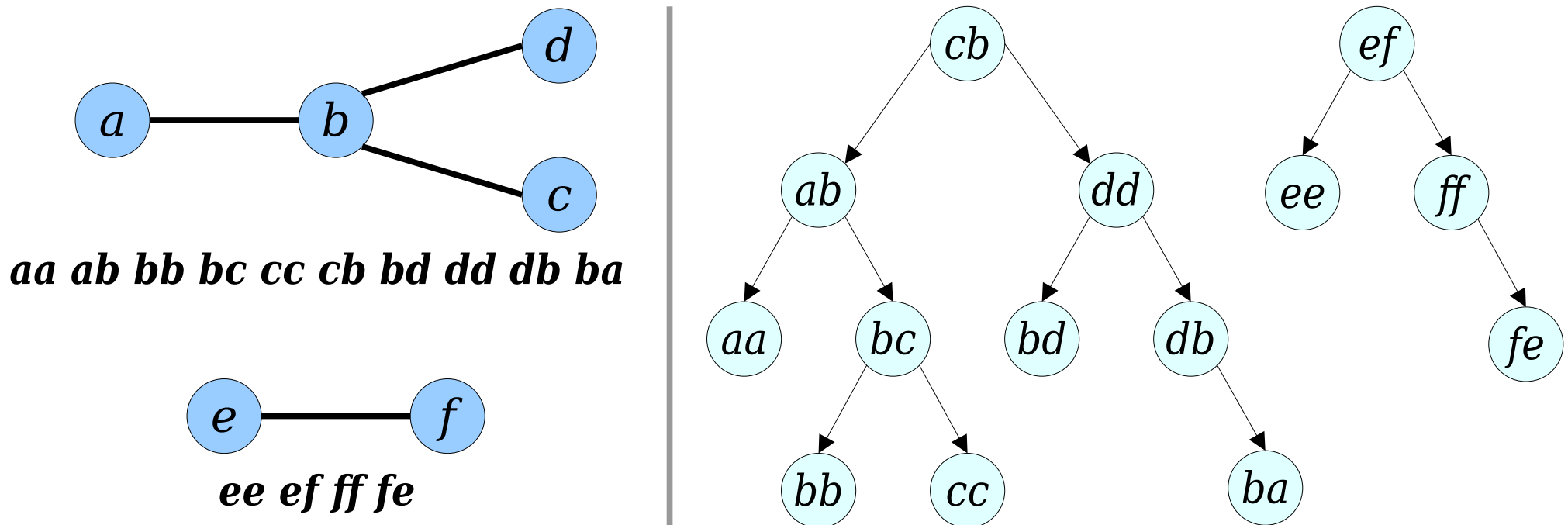
ee ef ff fe

Tree Sizes

- We're storing our Euler tours in balanced BSTs.
- We want to be able to answer the following question about a given BST:

How many nodes of the form xx are in this BST?

- This can be done in time $O(\log n)$. How?



Tree Sizes

- We're storing our Euler tours in balanced BSTs.
- We want to be able to answer the following question about a given BST:

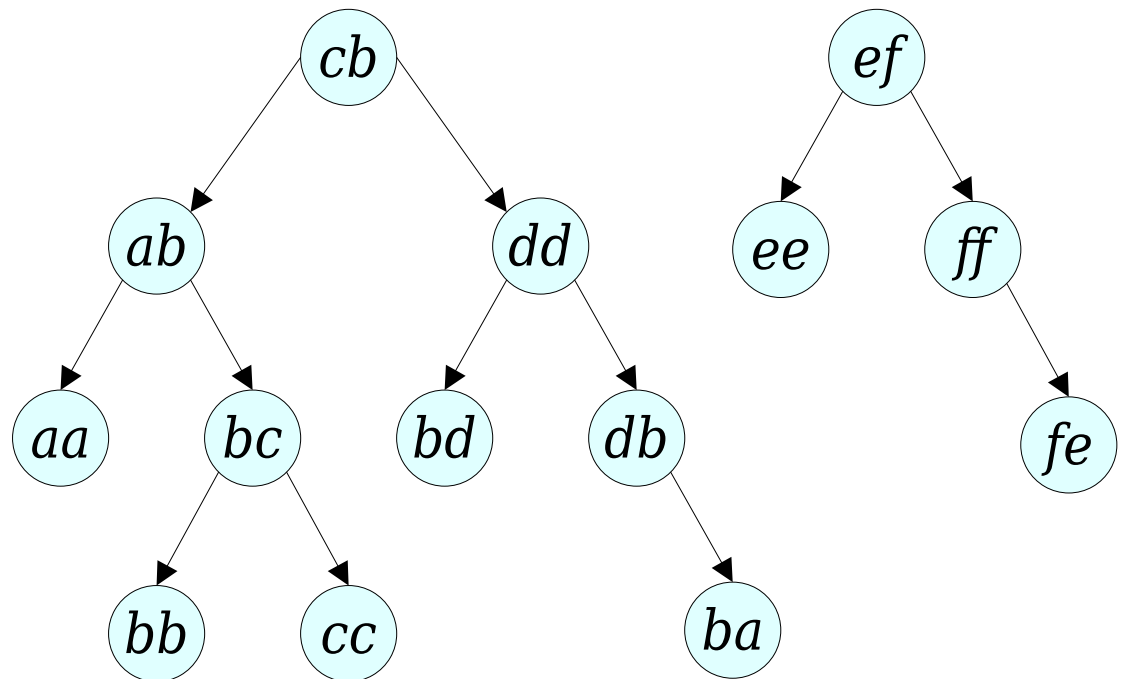
How many nodes of the form xx are in this BST?

- This can be done in time $O(\log n)$. How?

Answer at

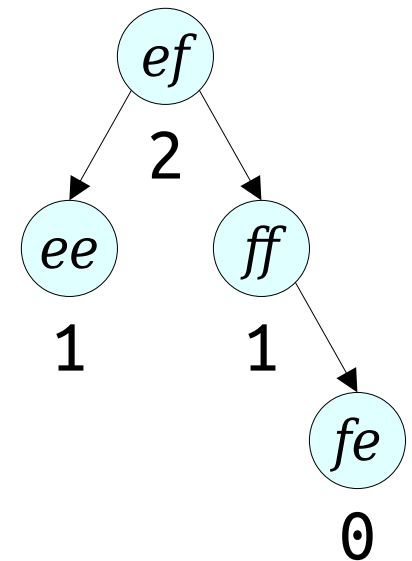
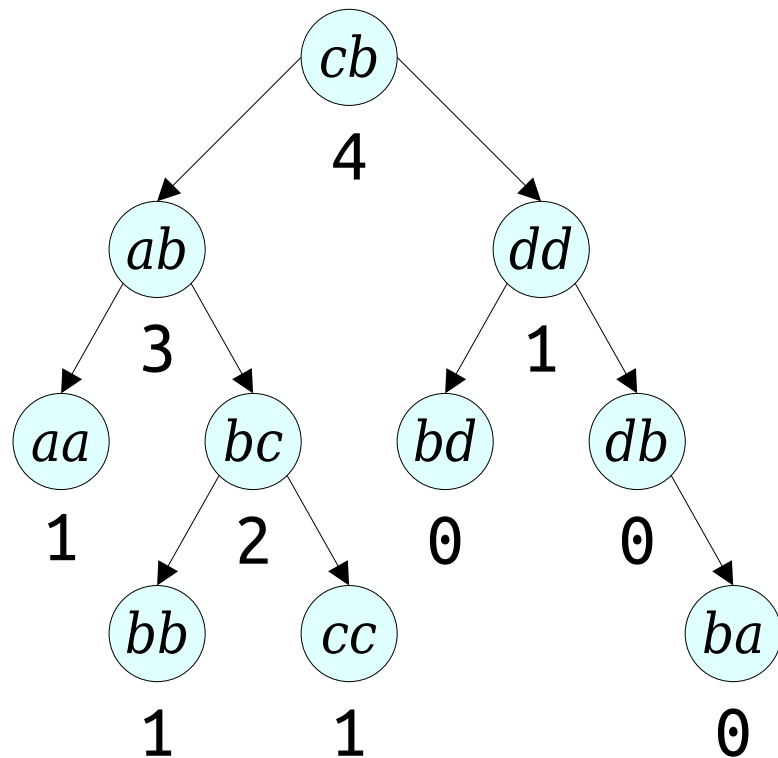
<https://pollev.com/cs166spr23>

ee ef ff fe



Tree Sizes

- **Idea:** Augment the BSTs holding our Euler tours.
- Specifically, each node stores the number of self-loops at or below it in the tree.
- This information can be maintained through rotations and after each splay tree operation.

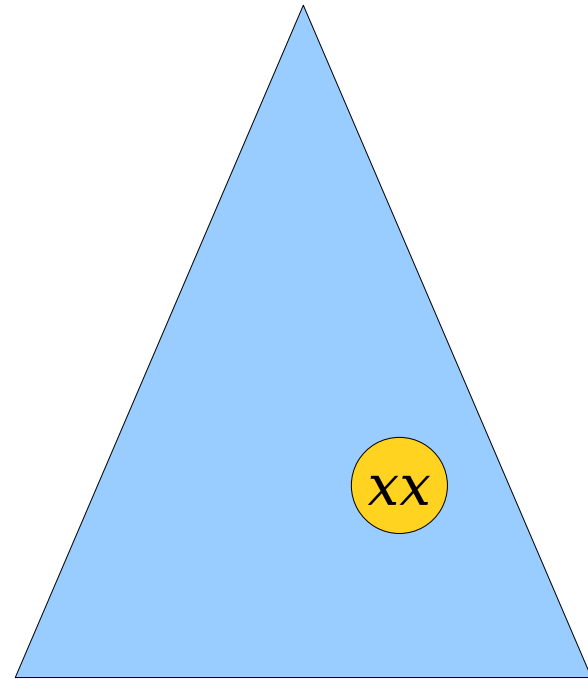


Tree Sizes

- To determine *size*(x):

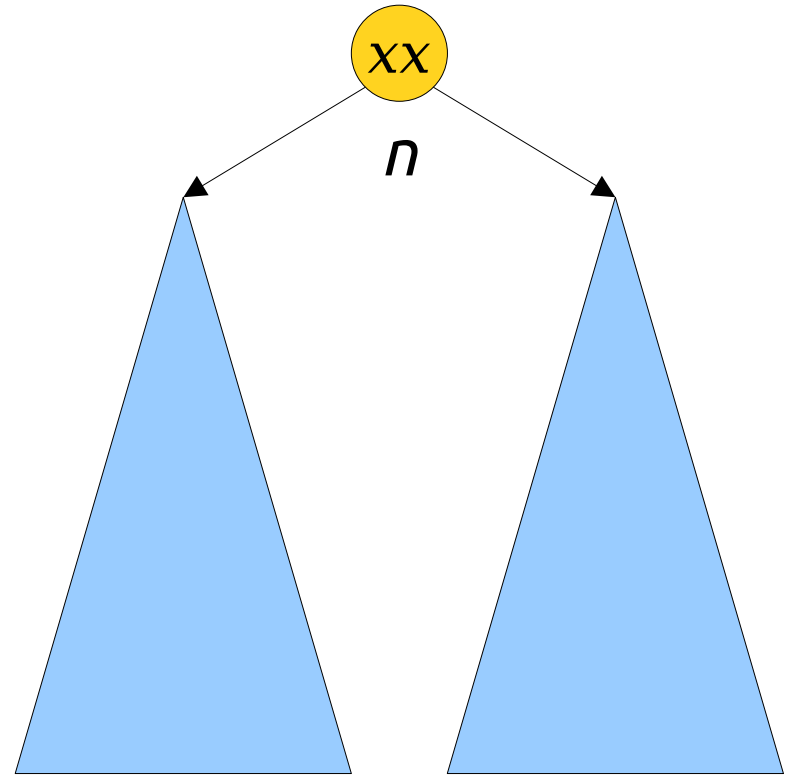
Tree Sizes

- To determine *size*(x):
 - Splay xx .



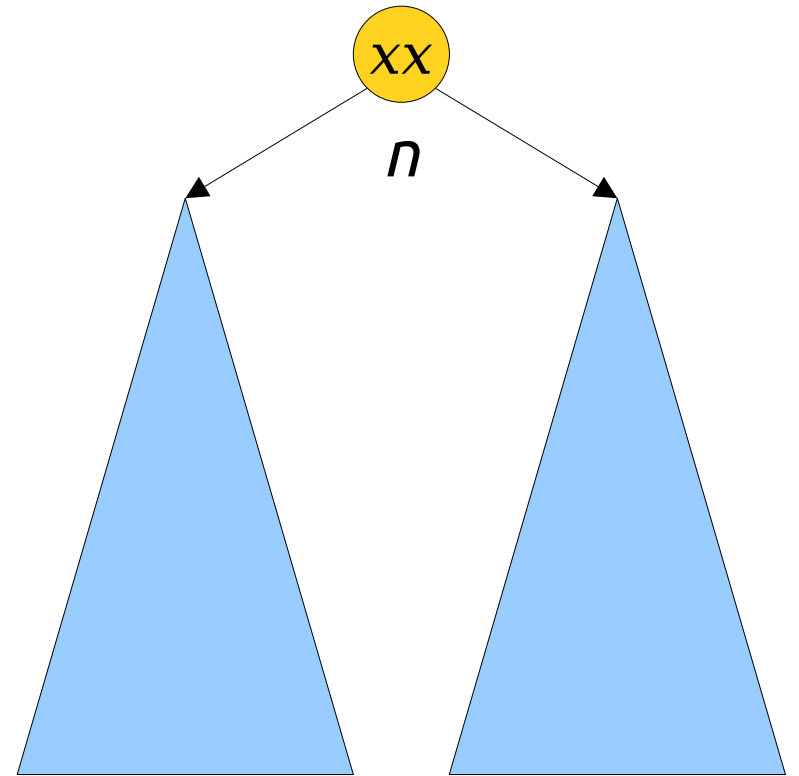
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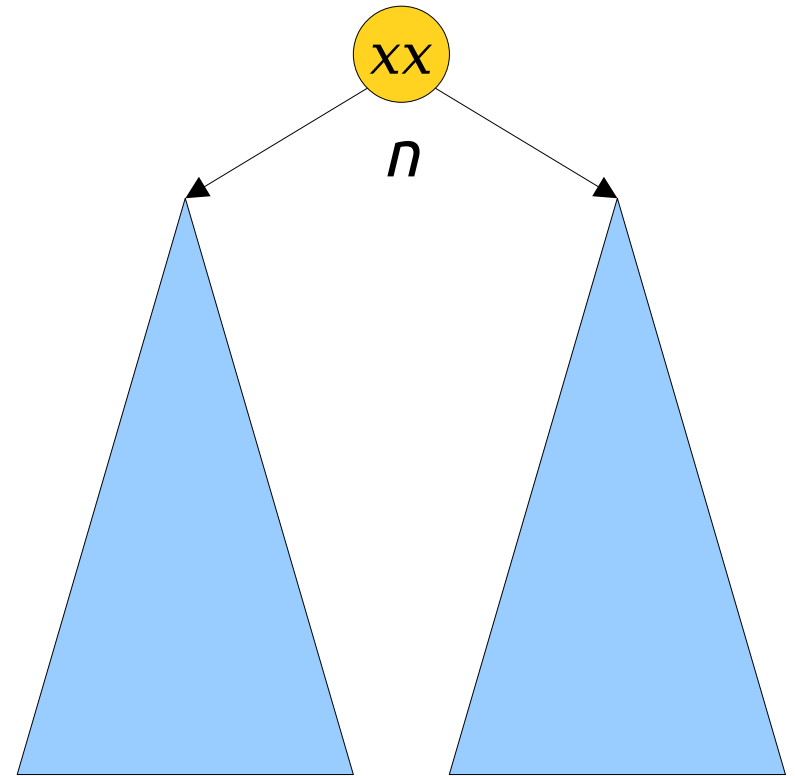
Tree Sizes

- To determine *size*(x):
 - Splay xx .
 - Return the augmented value in the node for xx .



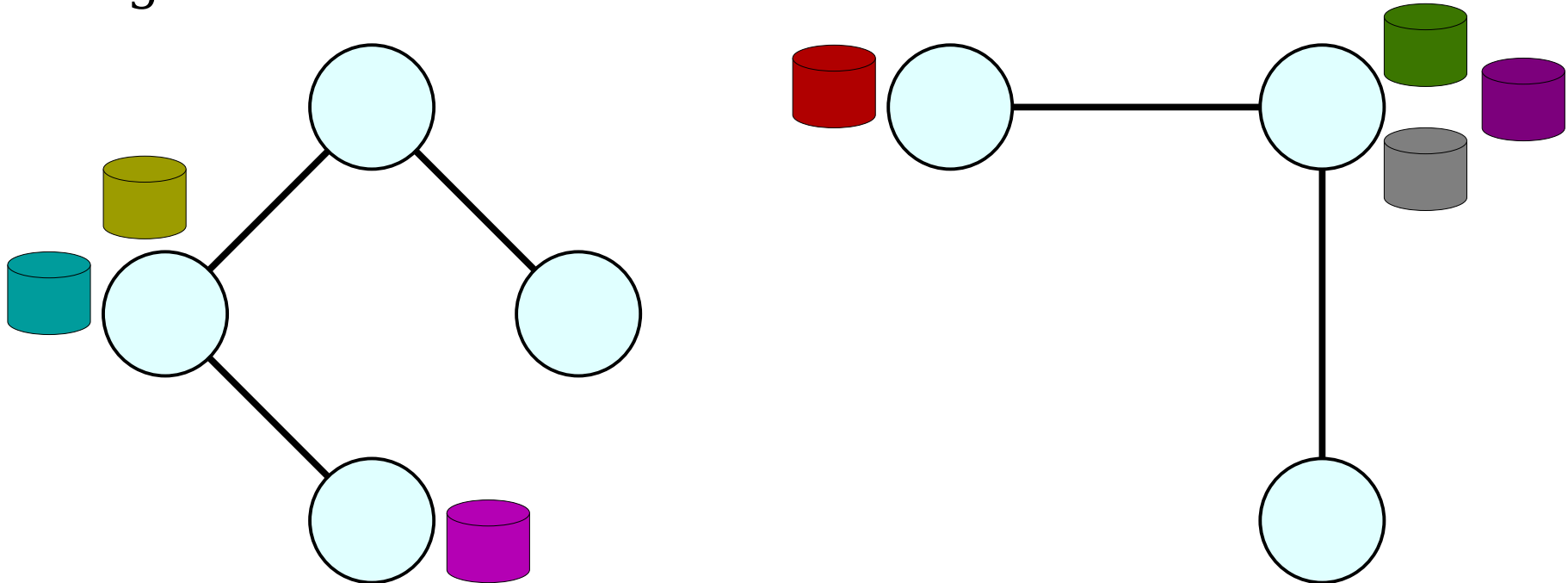
Tree Sizes

- To determine *size*(x):
 - Splay xx .
 - Return the augmented value in the node for xx .
- Amortized cost: **$O(\log n)$** .



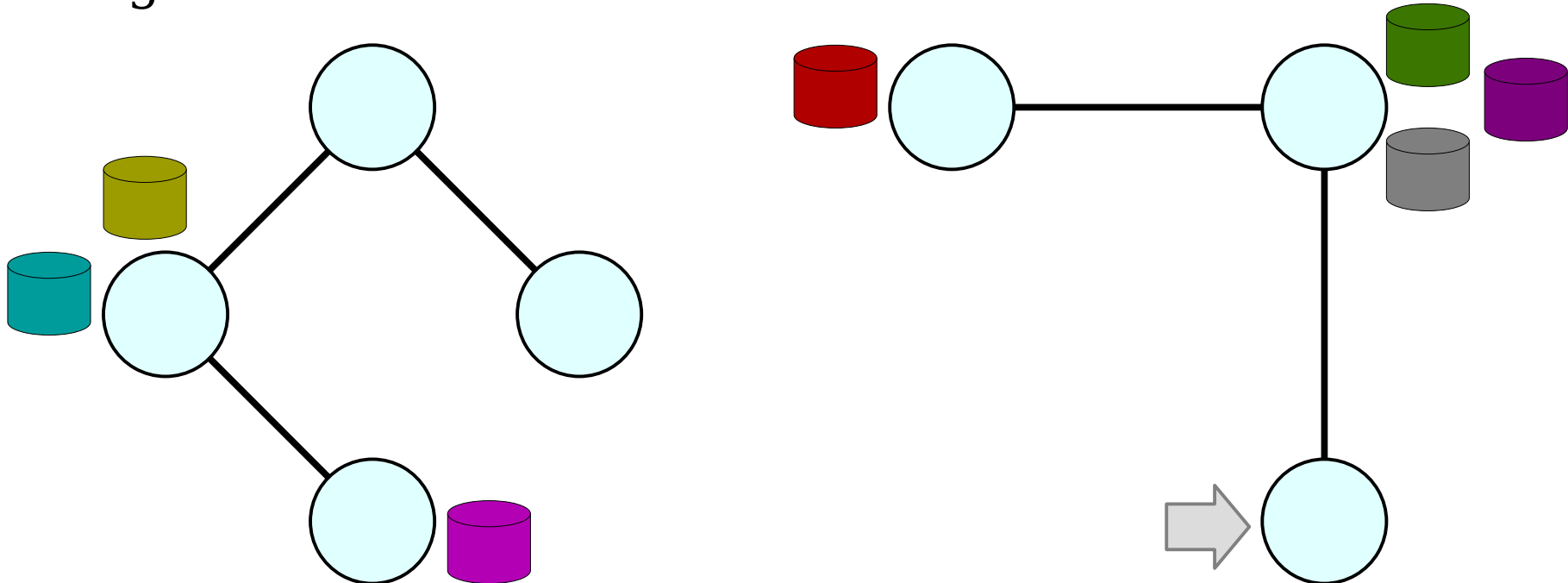
Extending Euler Tour Trees

- Suppose that each node represents a network router.
- We want to add these two operations:
 - ***add-packet***(x, p), which attaches packet p to node x ; and
 - ***remove-packet***(x), which removes and returns some packet reachable from x , chosen arbitrarily from all the options.
- How might we do this?



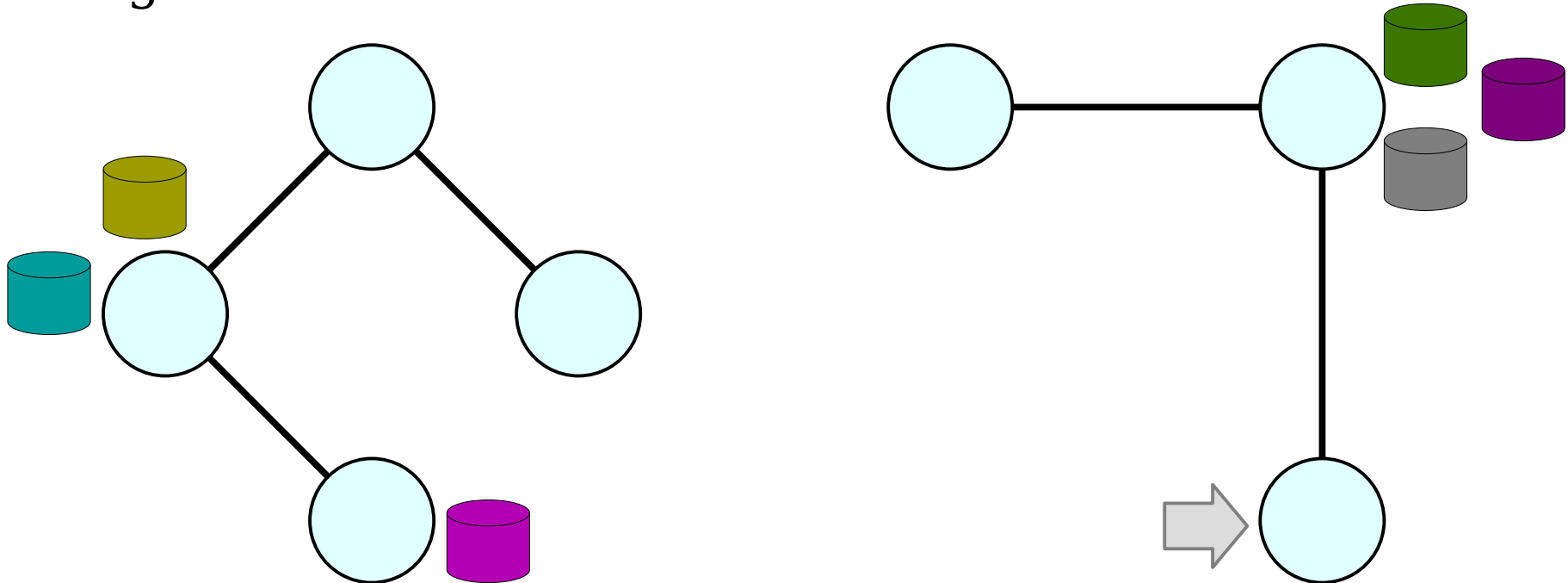
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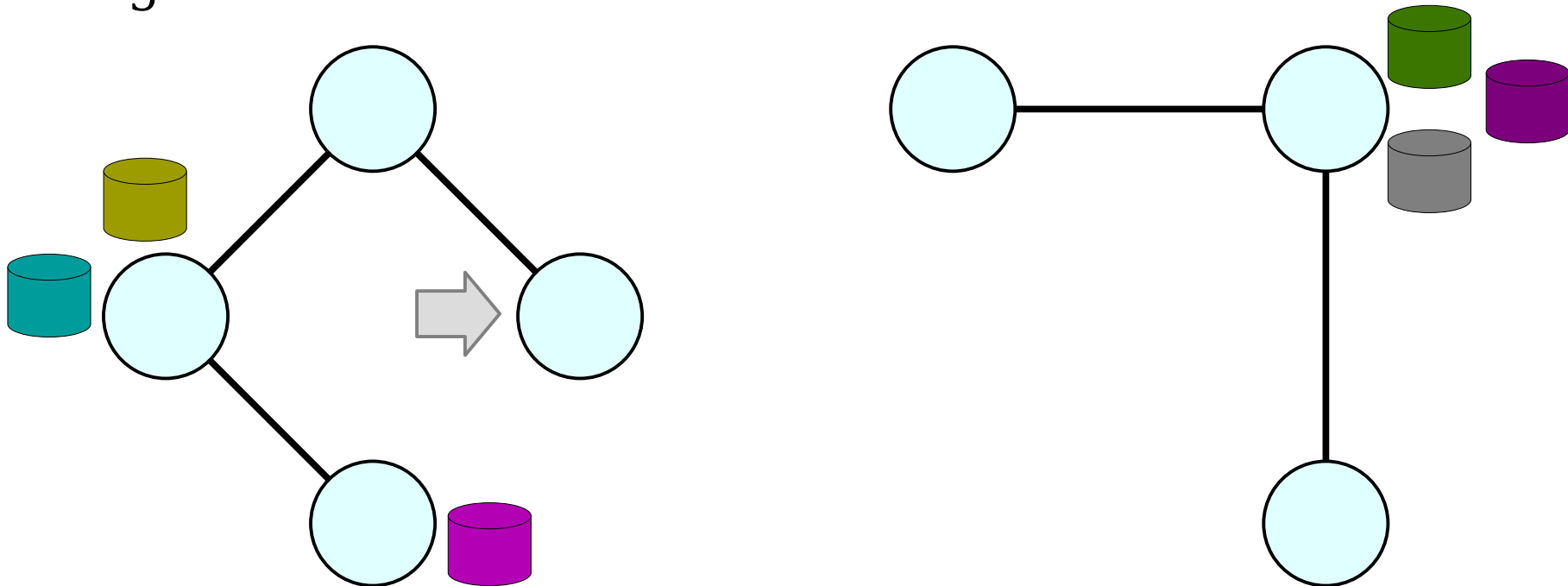
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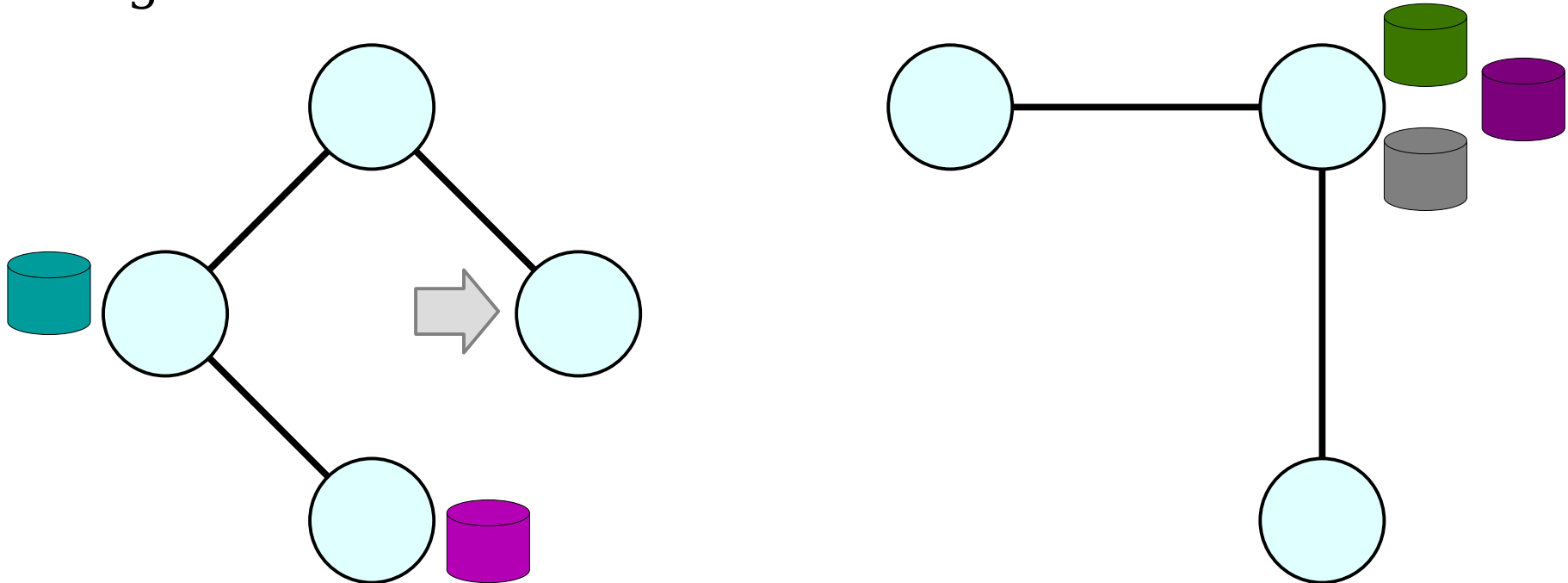
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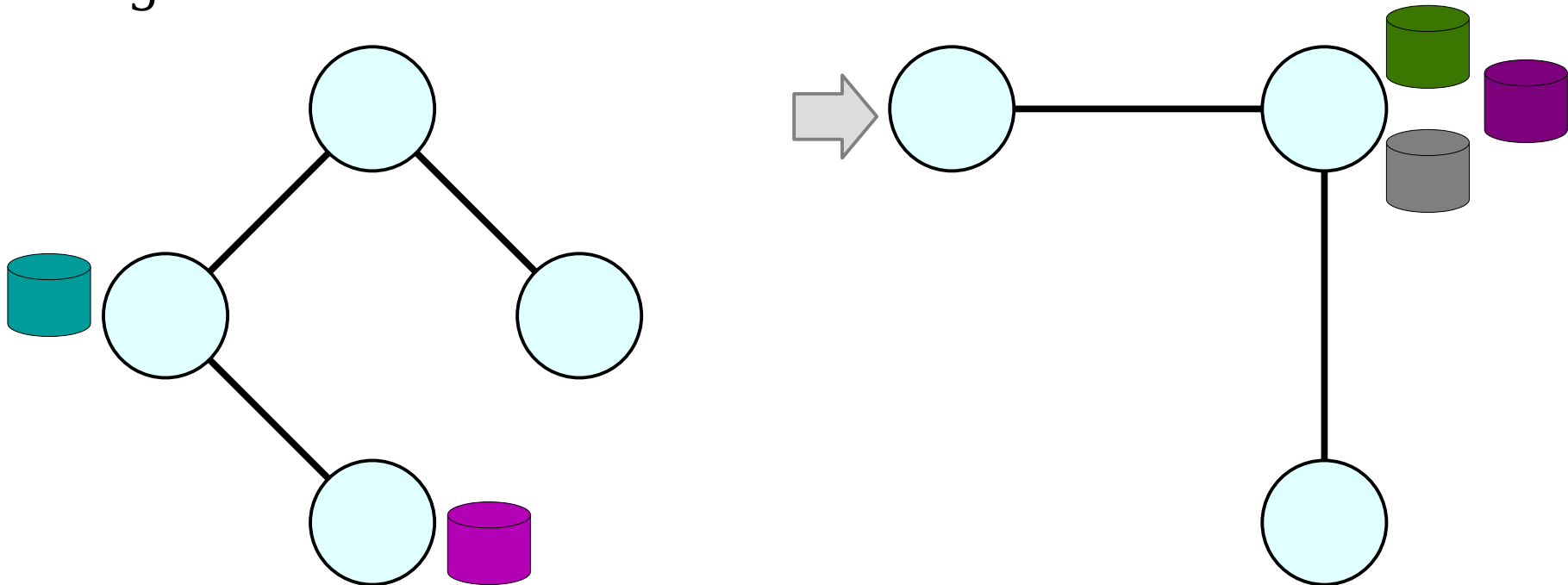
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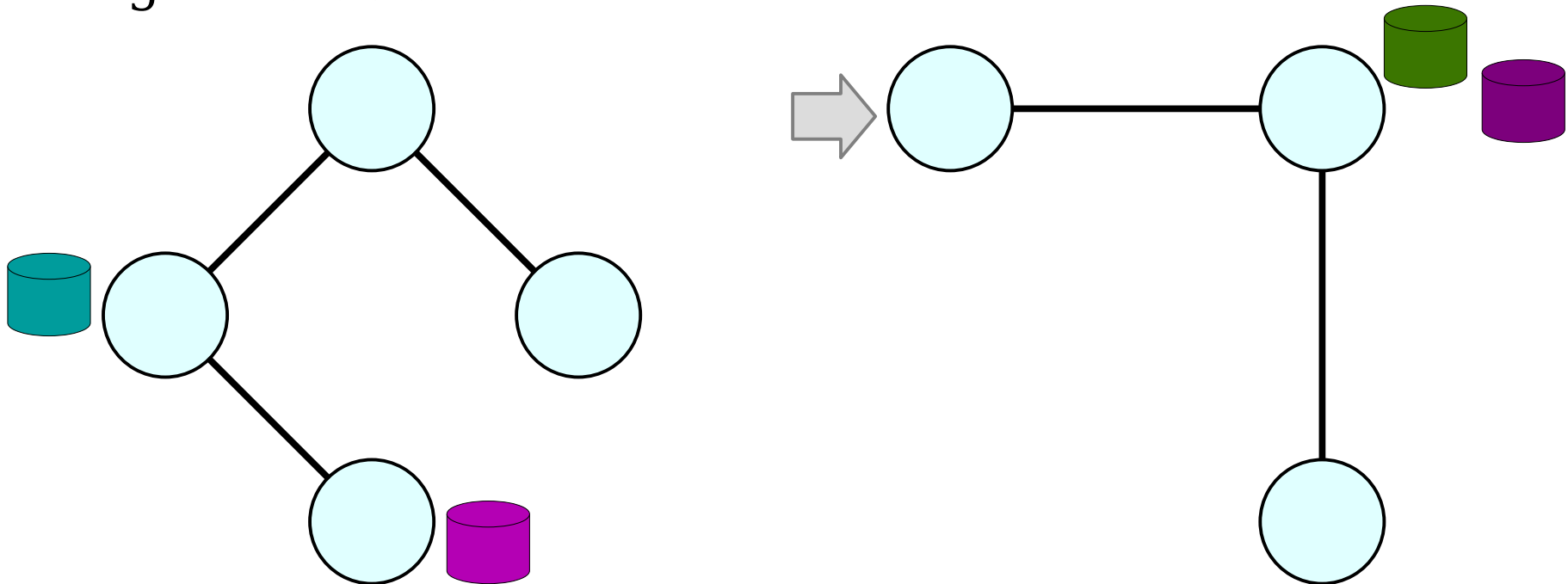
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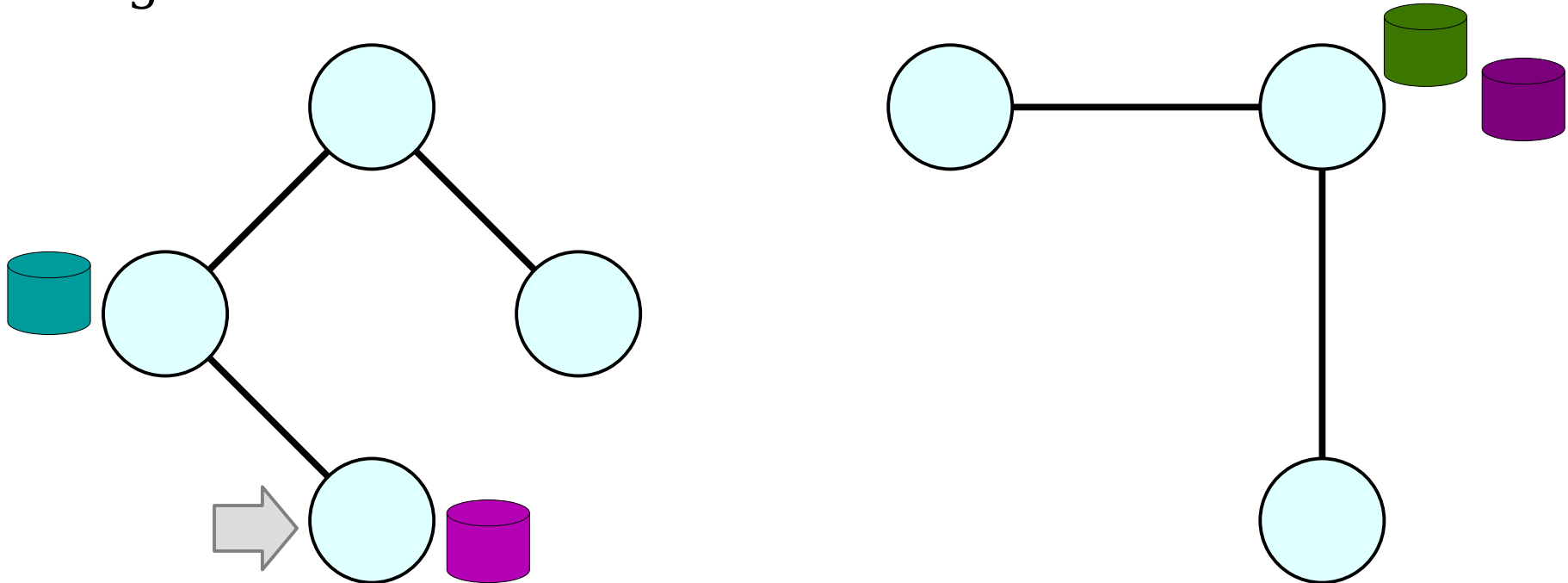
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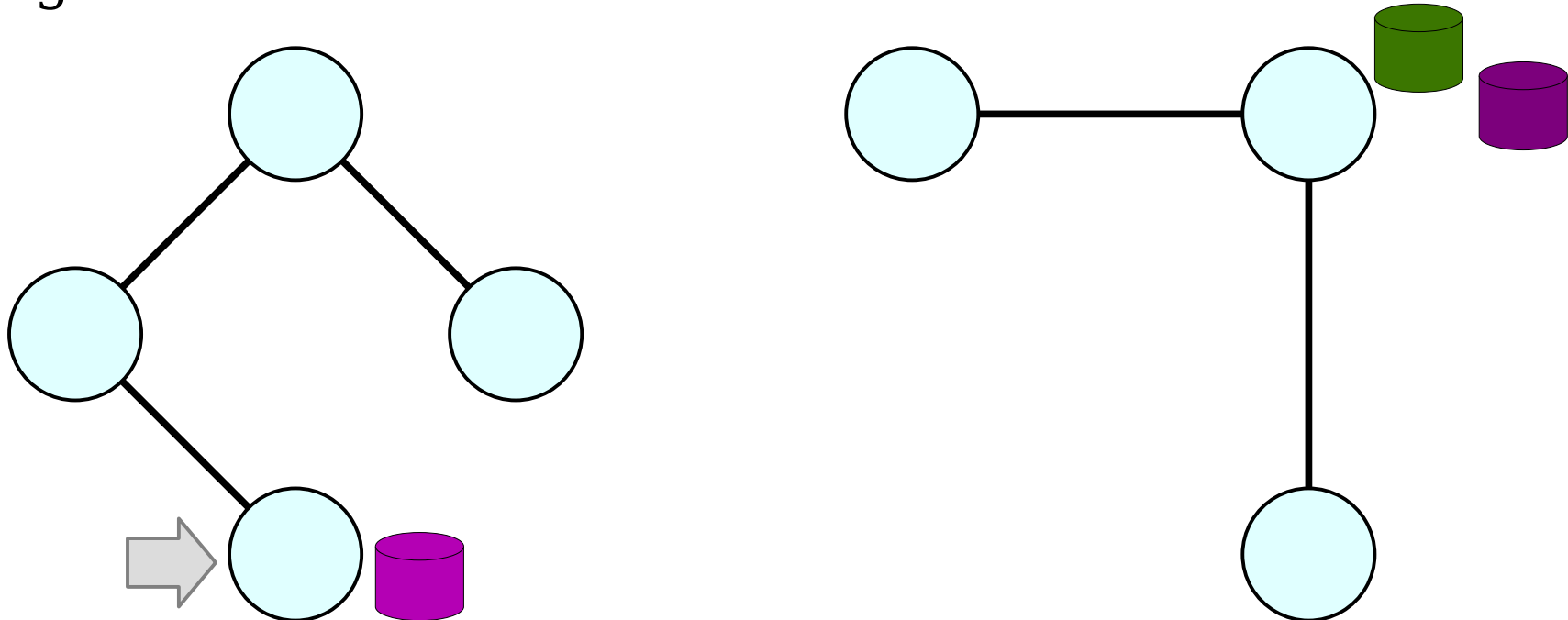
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- How might we do this?



Packet Finding

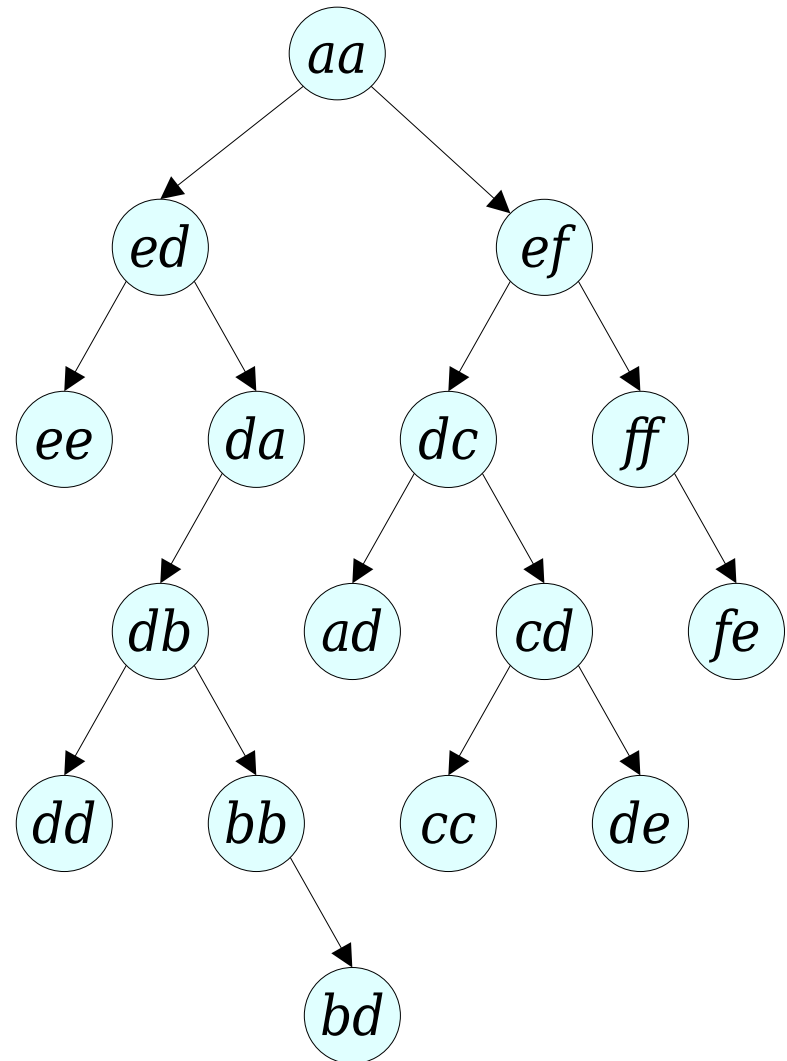
- Given the Euler tour representation of our trees, this essentially boils down to the following:

Augment a BST containing nodes and edges so that we can quickly identify a node with a packet.

- How might we do this?

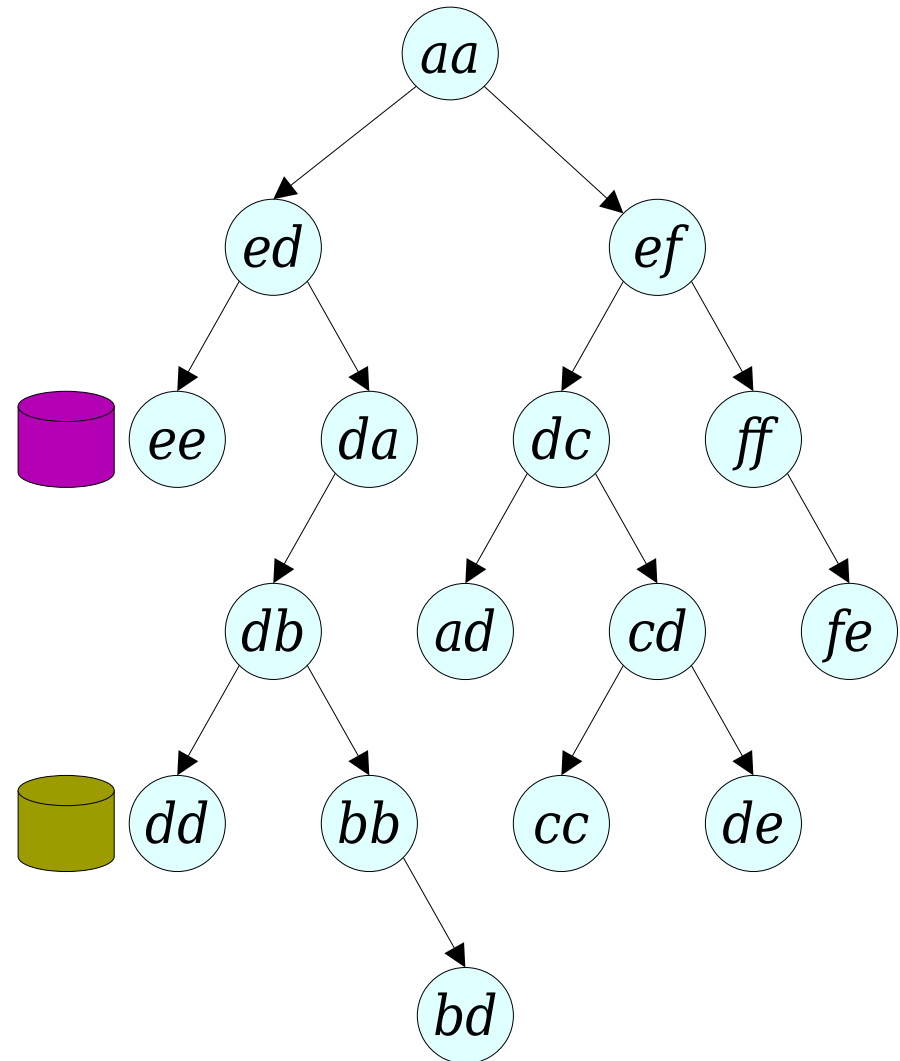
Packet Finding

- Augment each node xx with a list of the packets it stores.



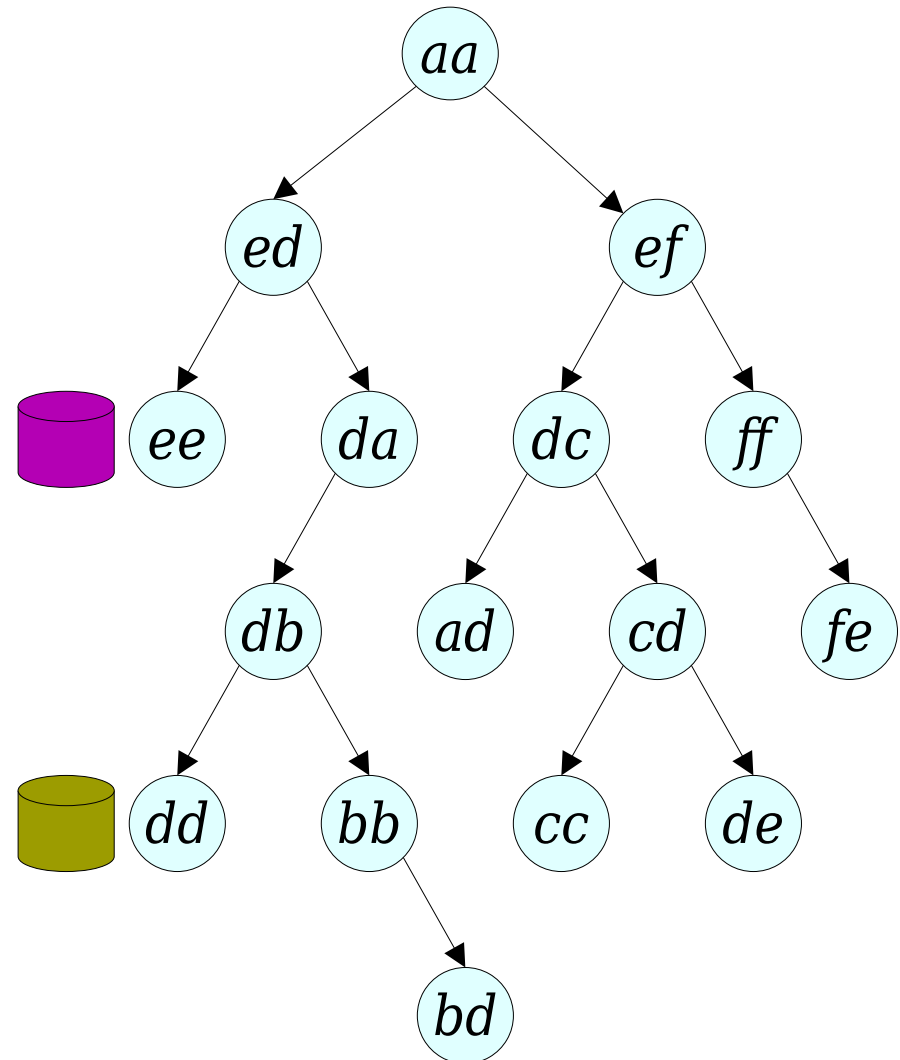
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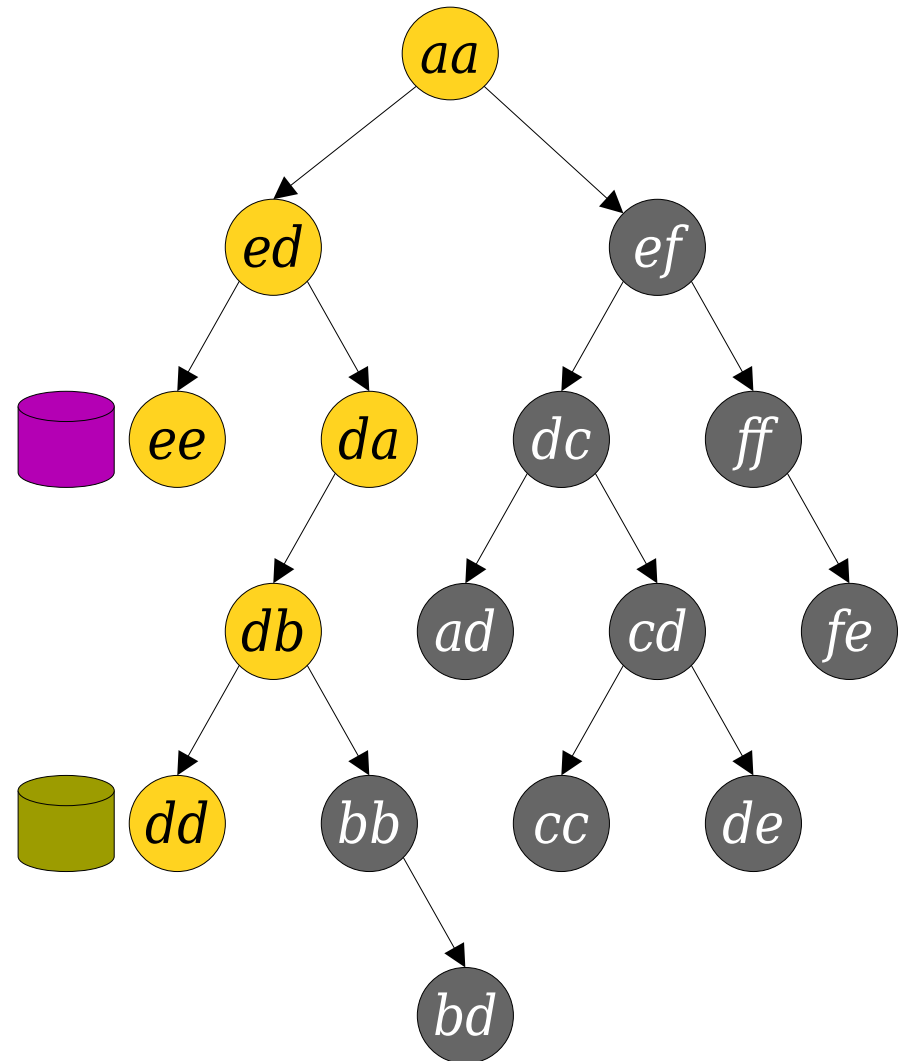
Packet Finding

- Augment each node xx with a list of the packets it stores.
- Augment each tree node with a bit indicating whether there's a packet in its subtree.



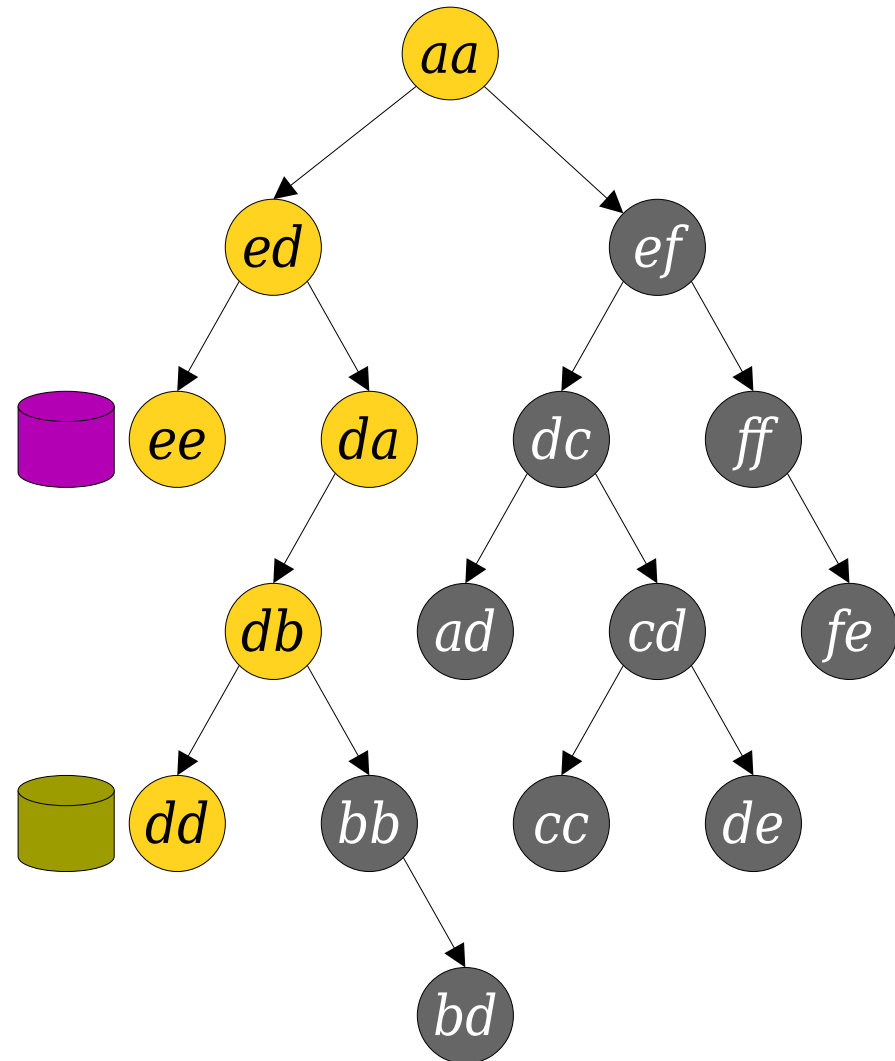
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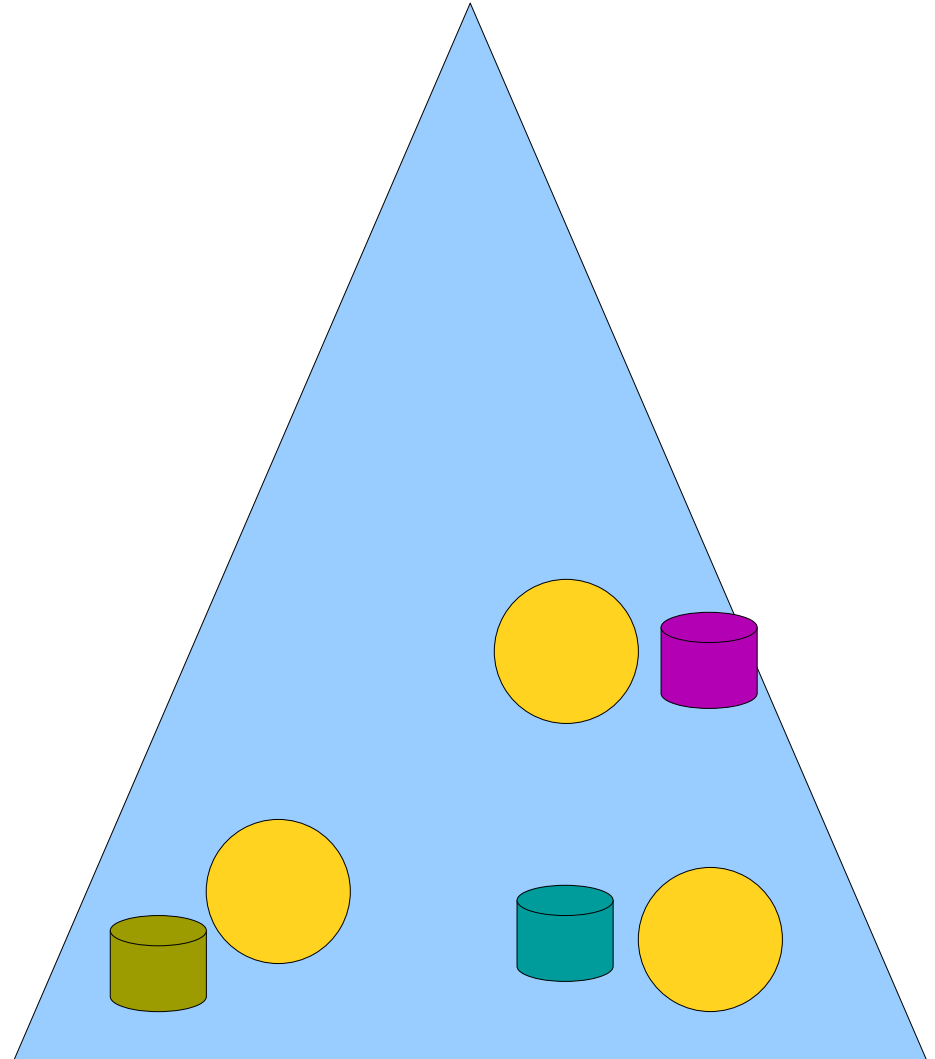
Packet Finding

- Augment each node xx with a list of the packets it stores.
- Augment each tree node with a bit indicating whether there's a packet in its subtree.
- We can use this latter information to quickly find nodes holding packets.



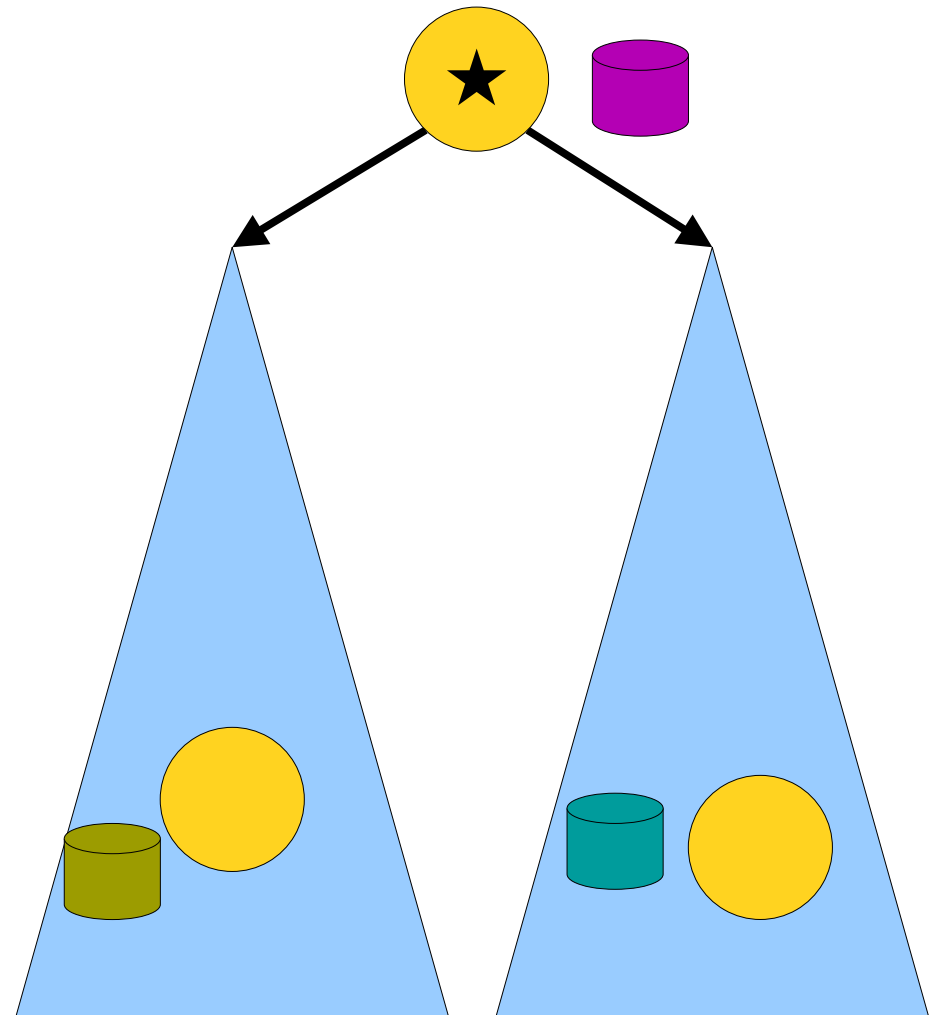
Packet Finding

- To find and remove a packet:



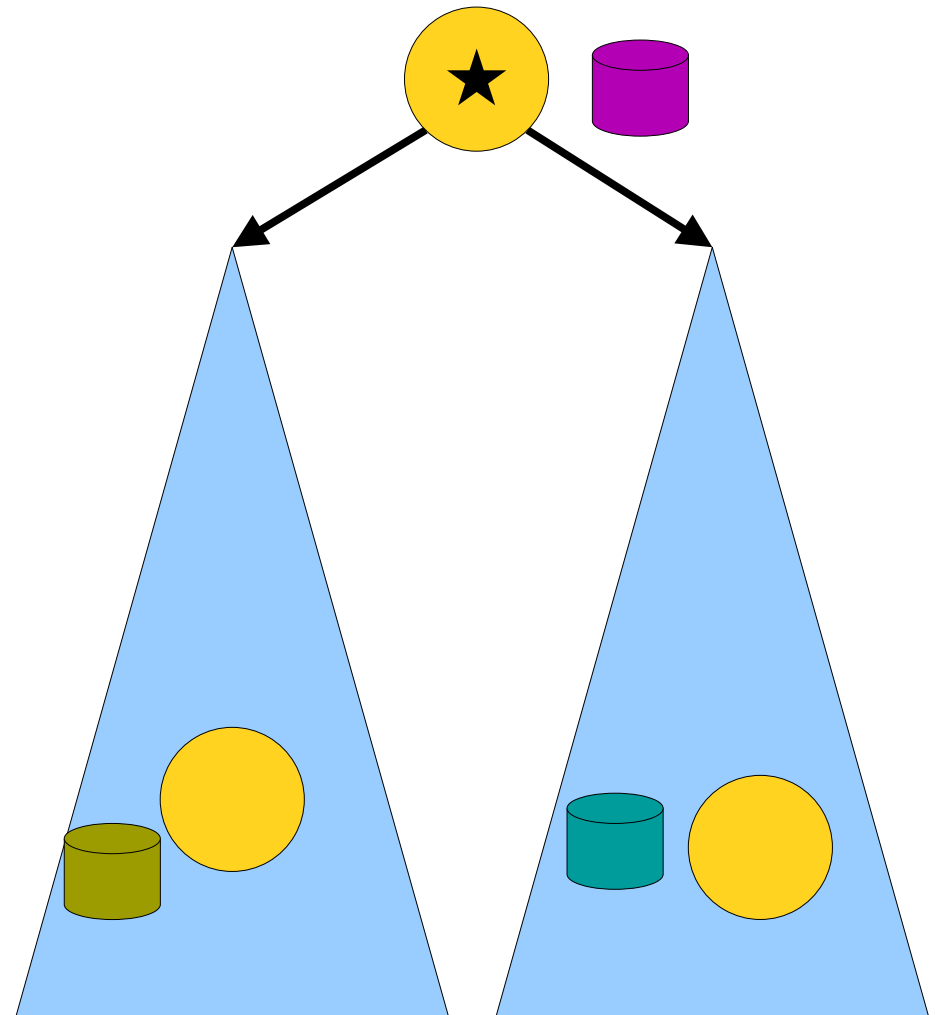
Packet Finding

- To find and remove a packet:
 - Walk from the root to any node containing a packet, using the augmentation to guide the search.
 - Splay that node to the root.



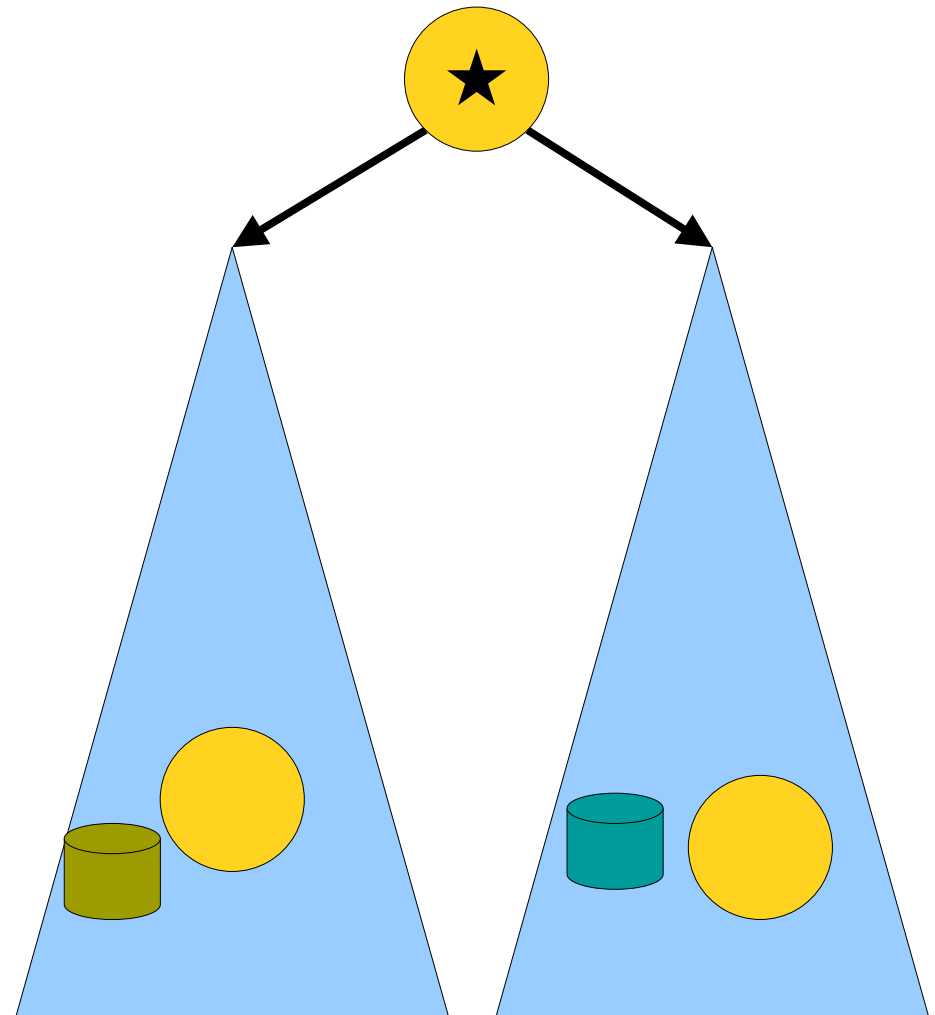
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- To find and remove a packet:
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 - Remove a packet from it, updating the root's augmentation.



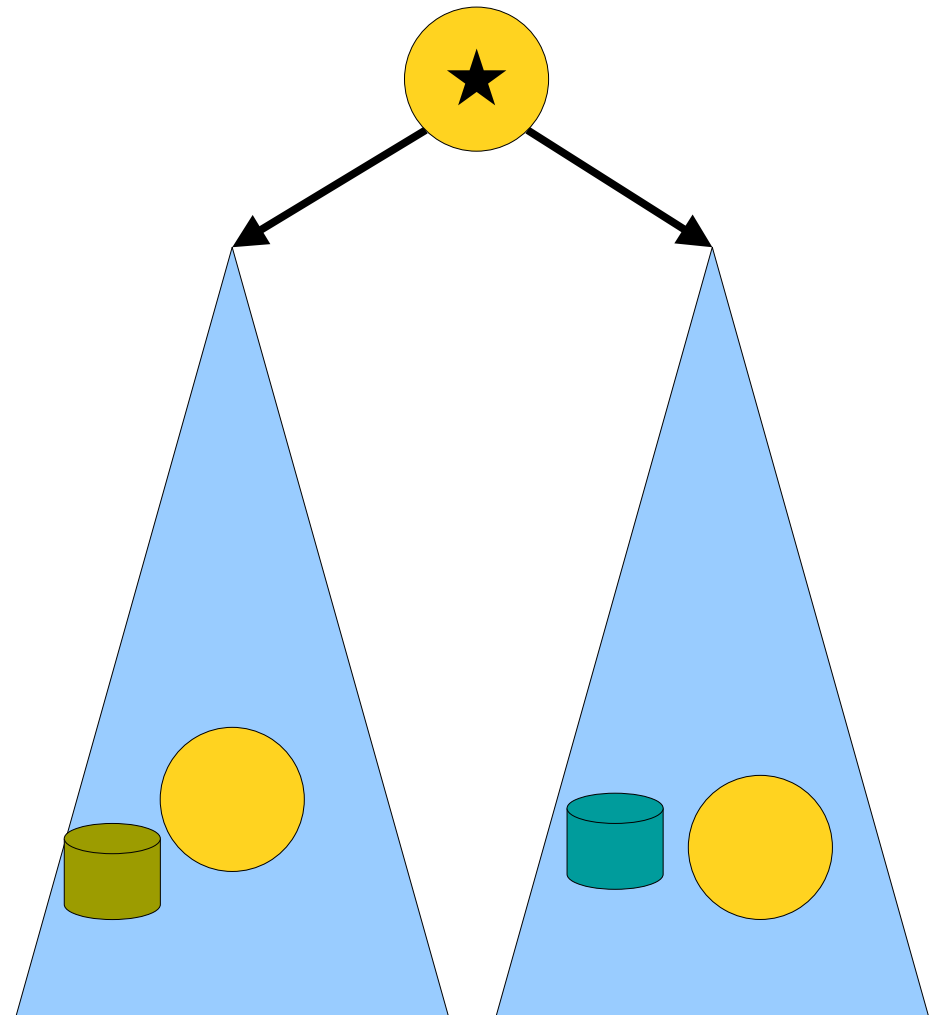
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 - Remove a packet from it, updating the root's augmentation.
- Amortized cost:
 $O(\log n)$.



Generalizing This Idea

- More generally, Euler tour trees play well with augmentations that care about global properties of individual trees.
- There's another way to use splay trees to encode dynamic trees (***st-trees***, also called ***link/cut trees***, though the later name is ambiguous) that works well for augmenting over ***paths*** in trees rather than trees as a whole.
- (Check out the Sleator/Tarjan paper for more details.)

Next Time

- ***Fully-Dynamic Connectivity***
 - Solving connectivity in general graphs, not just forests.
- ***“Blame It On The Little Guy”***
 - A surprisingly versatile algorithmic strategy.
- ***Holm’s Structure***
 - An elegant way to solve dynamic connectivity by harnessing augmented ETTs.